

UART Interfacing on eYFi-Mega Board

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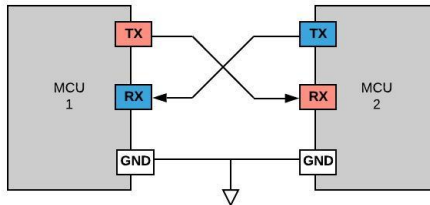
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 - ① Receive - RX
 - ② Transmit - TX



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① Data Packet

- Synchronization Bits
- Data Bits
- Parity Bits

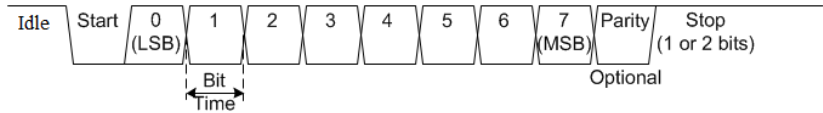
② Baud Rate



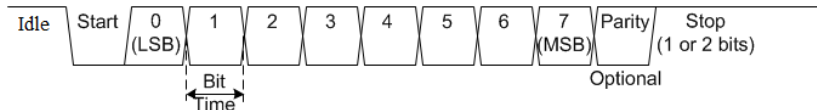
Data Packet



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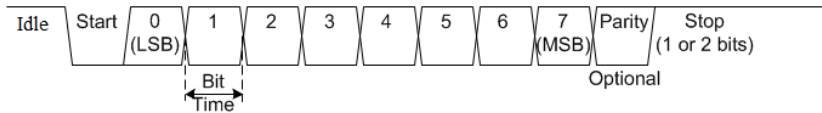


① Synchronization Bits

- Start (1 bit) - transition on idle data line from 1 to 0.
- Stop (1-2 bit/s) - transition back to idle state, holding the line at 1.



Data Packet



1 Synchronization Bits

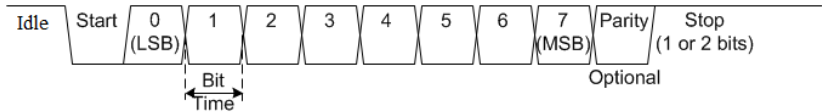
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2 Data Bits

- Number of data bits
- Endianness of data bits



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3 Parity Bits

- Low-level and simple form of error checking.
- It can be odd or even.



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- These baud rates are achieved in micro-controller by dividing the clock frequency.



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 - ➊ **9600** \Rightarrow Baud Rate
 - ➋ **8** \Rightarrow Number of data bits in a frame
 - ➌ **N** \Rightarrow No Parity bits
 - ➍ **1** \Rightarrow 1 Stop bit
 - ➎ "**H**" \Rightarrow ASCII value = **0b01001000**
 - ➏ "**i**" \Rightarrow ASCII value = **0b01101001**
 - ➐ **Endianness** \Rightarrow Little-endian, by default



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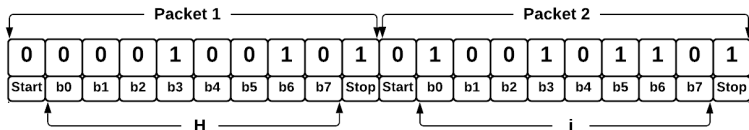
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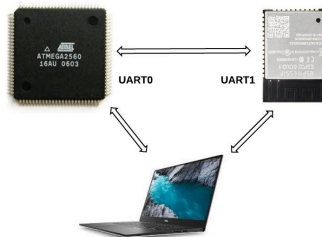
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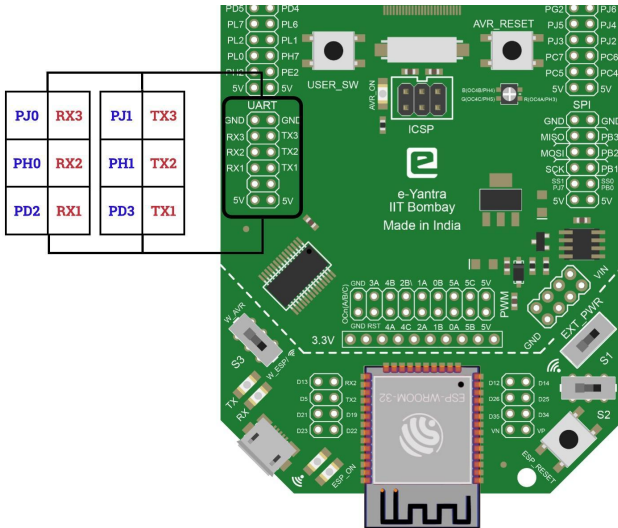
- Connection between ATmega2560 and PC
 - 1 TX0 → USB
 - 2 RX0 → USB
- Connection between ATmega2560 and ESP32
 - 1 ATmega2560:TX0 → ESP32:RX1
 - 2 ATmega2560:RX0 → ESP32:TX1



UART Header on eYFi-Mega Board



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Thank You!

Post your queries on: helpdesk@e-yantra.org

