

## Blelloch 3

Goals: breadth-first search in parallel  
and purely functional

Goals:

- 1) sequential semantics but with parallelism  
(functional)
- 2) Cost model + provable bound
- 3) Work efficiency  $\rightarrow$  probably more important  
on lower # cores
- 4) low depth (span)
- 5) as simple as sequential
- 6) sequential as a side effect

Problem with pure array:


have to copy array to make a change

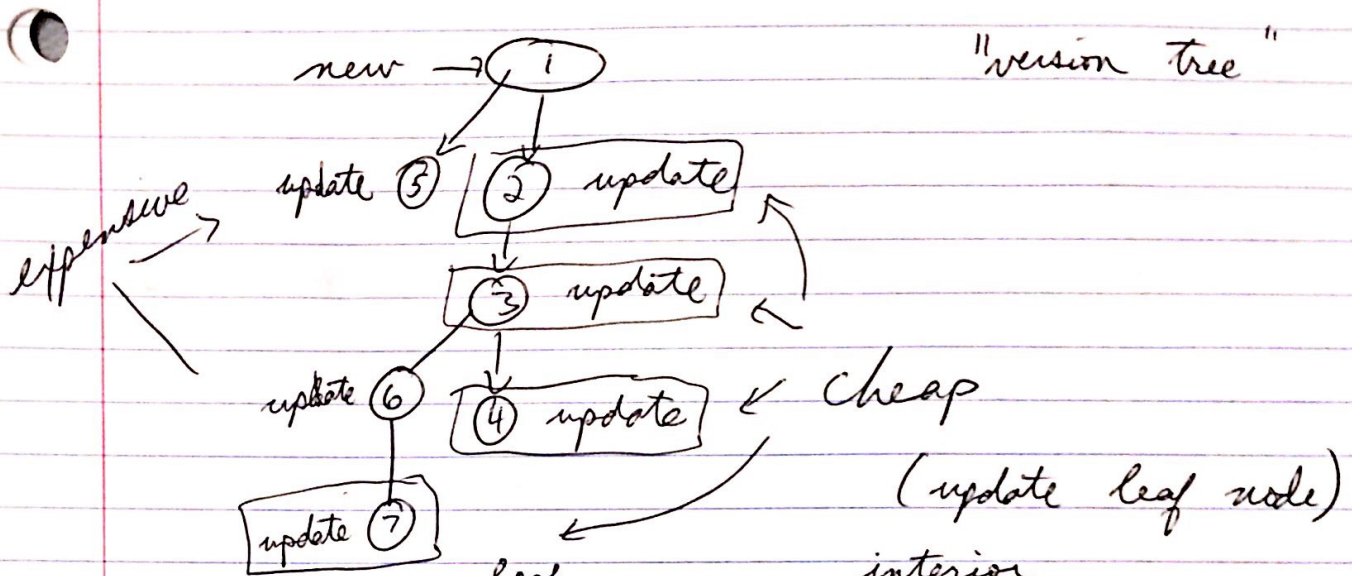
- 1) persistence "requires" copying

except: there is only one instance in use  
linear logic - single use  
but doesn't work for parallelism

Popl 17 purely funl arrays

- [language pure, cost model not pure, eg. Haskell]
- 2) keep a history of changes  
disting. version leaf vs version interior node

new  $\rightarrow$  



	leaf		interior	
$n =  A $	w	s	w	s
sub-A	$O(1)$	$O(1)$	$O(\log n)$	$O(\log n)$
update A	$O(1)$	$O(1)$	$O(n)$	$O(\log n)$
inject A, u	$O( u )$	$O(1)$	$O( u  + n)$	$O(\log n)$

Semantics  
store  $\delta : l \rightarrow \{+, -\}$  each version of array has label

$\uparrow$  leaf  $\nwarrow$  interior node

big-step semantics (or small step)

$\nwarrow$  return value  $\nwarrow$  work  $\nwarrow$  span/depth

$$\delta \ e \rightarrow \delta', v, w, d$$

$$\delta \xrightarrow{\text{update (set)}(A, u)} \delta'$$

$\uparrow$  seq. int  $\times$   $\alpha$  (update)



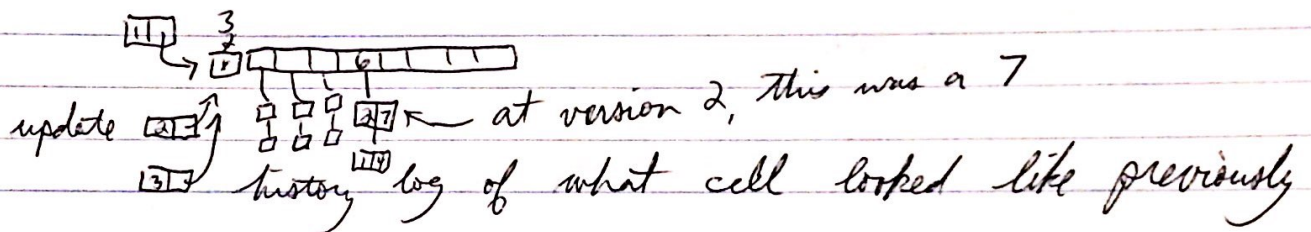
$$A = (a, \overset{\text{label}}{l}) \quad \delta[l \rightarrow +] \quad \text{new } l'$$

$$\delta, \text{update}(A, v) \rightarrow \delta[l \rightarrow -, l' \rightarrow +], (\text{update}(a, v), l'), 1, 1$$

$$W = O(1)$$

$$S = O(1)$$

ex.



do update in place  
store version history

if lookup with non-current version,  
find cell <sup>contents</sup> ~~version~~ in history w/ matching version

if update old version, copy contents of array

— amount of space never more than double  
if history is larger than array,  
then copy

never waste more than factor of 2  
constant space

amortize cost of copy  
by keeping history

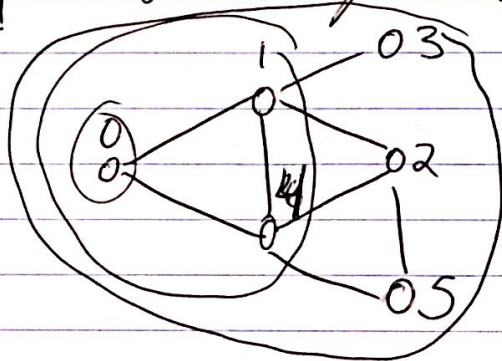
can do same trick w/ inject

tricky:  $e_1 \parallel e_2$

- both could update
- need to account for this, but it can be done

**BFS**

Breadth-first search



step 1: 0

step 2: 1, 4

step 3: 2, 3, 5

onion algorithm

1-away  
2-away  
3-away  
etc.

common, eg. Facebook  
bounded BFS

use queue to do BFS sequentially

better to consider BFS as searching  
each level in parallel

iterative where each iteration covers whole in level parallel

$$W = O(m+n)$$
$$S = O(d \cdot \log n)$$

$m = |\text{Edges}|$

$n = |\text{vertices}|$

$d = \text{diameter of graph}$

longest shortest path in graph  
people  $\sim 7$   
web graph  $\sim 40$



Repeat over levels:

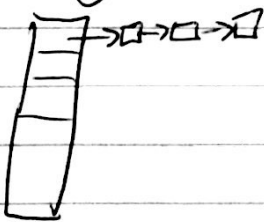
keep track of:  
F, P  
← frontier - list from prev level

P: <sup>tree:</sup> every vertex point to parent  
choose arbitrary when ambiguous

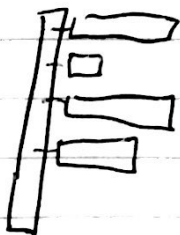
- 1) find all neighbors of F
- 2) filter those not already visited  
update P
- 3) remove duplicates
- 4) /

Graph representation

adjacency list, horrible for parallelism



use sequence of sequences  
could use trees



ex graph

$$G = \langle \langle 1, 4 \rangle, \langle 0, 2, 3, 4 \rangle, \langle 1, 4, 5 \rangle, \dots \rangle$$

frontier as sequence

$$F = \langle 1, 6 \rangle$$

(root points to itself)

$$P = \langle 0, 0, -1, -1, 0, -1 \rangle \quad \leftarrow -1 = \text{not visited}$$

one step  
cost is proportional to sum of degree of frontier  
after step:

$$F = \langle 3, 2, 5 \rangle$$

$$P = \langle 0, 0, 1, 1, 0, 4 \rangle$$

(there are work-inefficient algs for logarithmic depth)  
(unknown whether work-efficient w/ poly-log depth)

neighbors

$$N = \text{flatten} \left( \text{map} \left( \lambda x. G[x] \right) F \right) = \langle 0, 2, 3, 4, 0, 1, 2, 5 \rangle$$

(G[i] = neighbors of i) (can be done in parallel)

$$\text{tag}(S, v) = \text{map} \left( \lambda x. (x, v) \right) S$$

$$N = \text{flatten} \left( \text{map} \left( \lambda v. \text{tag}(G[v], v) \right) F \right) = \langle (0, 1), (2, 1), (3, 1), (0, 4), (1, 4), (2, 4), (5, 4) \rangle$$

$N' = \text{filter out ones already visited}$   
 $N' = \text{filter} (\lambda(u,v). P[v] \leq -1) N$

$\uparrow = -1$

-1 indicates has not been visited

$= \langle (2,1), (3,1), (2,4), (5,4) \rangle$

$N, N'$  - both computed in linear work  
 - both log span

$P' = \text{inject } P \ N'$  (inject takes later case when conflict)

final filter

note: inject - work proportional to # updates  
 requires sequence  
 $\hookrightarrow w = O(d \cdot n)$

here, never look back at previous ~~inject~~

every step is log span

$S = O(d \cdot \log n)$

filter, flatten