

ParallelismParallelism

- is an evaluation strategy
- deterministic

Concurrency

- is about managing events that happen at the same time
- nondeterministic

Parallel PCF (PPCF) Binary fork-joinExp $e ::= \dots$ x $S(e)$ z $\text{fix } x \{ \tau \} (x, e)$ $\text{par}(e_1, e_2; x_1, x_2, e)$ $\text{par } x_1 = e_1 \text{ and } x_2 = e_2 \text{ in } e$ Statics

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 \quad \Gamma, x_1 : \tau_1, x_2 : \tau_2 \vdash e : \tau}{\Gamma \vdash \text{par}(e_1, e_2; x_1, x_2, e) : \tau}$$

Sequential Dynamics

$$\frac{e_1 \mapsto e'_1}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{seq}} \text{par}(e'_1, e_2; x_1, x_2, e)}$$

$$\frac{e_1 \text{ val} \quad e_2 \text{ val}}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto [e_1, e_2 / x_1, x_2] e}$$

Sequential Dynamics

$$\frac{e_1 \mapsto_{\text{seq}} e_1'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{seq}} \text{par}(e_1', e_2; x_1, x_2, e)}$$

$$\frac{e_1 \text{ val } e_2 \mapsto_{\text{seq}} e_2'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{seq}} \text{par}(e_1, e_2'; x_1, x_2, e)}$$

$$\frac{e_2 \text{ val } e_1 \mapsto_{\text{seq}} e_1'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{seq}} \text{par}(e_1', e_2; x_1, x_2, e)}$$

$$\frac{e_1 \text{ val } e_2 \text{ val}}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{seq}} [e_1, e_2 / x_1, x_2] e}$$

Parallel Dynamics

$$\frac{e_1 \mapsto_{\text{par}} e_1' \quad e_2 \mapsto_{\text{par}} e_2'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{par}} \text{par}(e_1', e_2'; x_1, x_2, e)}$$

$$\frac{e_1 \text{ val } e_2 \mapsto_{\text{par}} e_2'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{par}} \text{par}(e_1, e_2'; x_1, x_2, e)}$$

$$\frac{e_2 \text{ val } e_1 \mapsto_{\text{par}} e_1'}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto_{\text{par}} \text{par}(e_1', e_2; x_1, x_2, e)}$$

$$\frac{e_1 \text{ val } e_2 \text{ val}}{\text{par}(e_1, e_2; x_1, x_2, e) \mapsto [e_1, e_2 / x_1, x_2] e}$$

Theorem Assume e is well-typed (so terminates). Then

$$e \xrightarrow[\text{par}]{*} v \quad \text{iff} \quad e \xrightarrow[\text{seq}]{*} v$$

Proof: show 1) $e \xrightarrow[\text{seq}]{*} v \quad \text{iff} \quad e \Downarrow v$

2) $e \xrightarrow[\text{par}]{*} v \quad \text{iff} \quad e \Downarrow v$

Eval Dynamics

$$\frac{e_1 \Downarrow v_1 \quad e_2 \Downarrow v_2 \quad [v_1 v_2 / x_1 x_2] e \Downarrow v}{\text{par}(e_1 e_2; x_1 x_2 e) \Downarrow v}$$

Lemma 1 $e \Downarrow v$ implies $e \xrightarrow[\text{seq}]{*} v$

Proof: induction on $e \Downarrow v$

Case: Rule for par:

Then $e = \text{par}(e_1; e_2; x_1 x_2 e')$

and $e_1 \Downarrow v_1, e_2 \Downarrow v_2, [v_1 v_2 / x_1 x_2] e' \Downarrow v$

IH: $e_1 \xrightarrow[\text{seq}]{*} v_1, e_2 \xrightarrow[\text{seq}]{*} v_2, [v_1 v_2 / x_1 x_2] e' \xrightarrow[\text{seq}]{*} v$

(Then use the rules above for Sequential Dynamics.)

Show $\text{par}(e_1 e_2; x_1 x_2 e) \xrightarrow[\text{seq}]{*} v$

1) By ind. on n_1 $\text{par}(e_1 e_2; x_1 x_2 e) \xrightarrow[\text{seq}]{n_1} \text{par}(v_1 e_2; x_1 x_2 e)$

2) By ind. on n_2 $\text{par}(v_1 e_2; x_1 x_2 e) \xrightarrow[\text{seq}]{n_2} \text{par}(v_1 v_2; x_1 x_2 e)$

3) use rule

$$\text{par}(v_1 v_2; x_1 x_2 e) \xrightarrow{\quad} [v_1 v_2 / x_1 x_2] e$$

Then,

$$[v_1 v_2 / x_1 x_2] e \xrightarrow[\text{seq}]{*} v \quad \text{by IH}$$

Lemma 2

$e \xrightarrow[\text{seq}]^* v$ and $v \text{ val}$ implies $e \Downarrow v$

Proof: show $e \xrightarrow[\text{seq}]^* e'$ and $e' \Downarrow v$ implies $e \Downarrow v$.

EXERCISE!

Cost Semantics

GOAL: cost semantics $e \Downarrow^k v$
where k describes both
Seq and parallel costs.

Cost Graph

$c := \begin{matrix} 1 & \text{unit cost} \\ 0 & \text{zero cost} \end{matrix}$

$c_1 \otimes c_2$ parallel combination

$c_1 \oplus c_2$ sequential combination

Work (seq cost)

$$wk(1) = 1$$

$$wk(0) = 0$$

$$wk(c_1 \otimes c_2) = wk(c_1) + wk(c_2)$$

$$wk(c_1 \oplus c_2) = wk(c_1) + wk(c_2)$$

Depth (parallel cost)

$$dp(1) = 1$$

$$dp(0) = 0$$

$$dp(c_1 \otimes c_2) = \max\{dp(c_1), dp(c_2)\}$$

$$dp(c_1 \oplus c_2) = dp(c_1) + dp(c_2)$$

Eval Rules

$$\begin{array}{c}
 \frac{}{z \Downarrow^0 z} \quad \frac{e \Downarrow^c v}{s(c) \Downarrow^c s(v)} \quad \frac{}{\lambda(x:\tau) e \Downarrow^0 \lambda(x:\tau) e} \quad \frac{[\text{fix } \{ \tau \} (x.e) / x] e \Downarrow^c v}{\text{fix } \{ \tau \} (x.e) \Downarrow^{c \oplus 1} v} \\
 \\
 \frac{e_1 \Downarrow^{c_1} \lambda(x:\tau) e \quad e_2 \Downarrow^{c_2} v_2 \quad [v_2 / x] e \Downarrow^{c_3} v}{e_1(e_2) \Downarrow^{c \oplus c_2 \oplus c_3 \oplus 1} v} \quad \frac{e_1 \Downarrow^{c_1} v \quad e_2 \Downarrow^{c_2} v_2 \quad [v_1 v_2 / x_1 x_2] e \Downarrow^{c_3} v}{\text{par}(e_1 e_2 x_1 x_2 e) \Downarrow^{(c \oplus c_1) \oplus c_2 \oplus c_3 \oplus 1} v}
 \end{array}$$

Theorem

a) If $e \Downarrow^c v$ then $e \xrightarrow[\text{seq}]{\text{wk}(c)} v$ and $e \xrightarrow[\text{par}]{\text{dp}(c)} v$.

b) If $e \xrightarrow[\text{seq}]{w} v$ then $e \Downarrow^c v$ for some c and $\text{wk}(c) = w$.

c) If $e \xrightarrow[\text{par}]{d} v$ then $e \Downarrow^c v$ for some c and $\text{dp}(c) = d$.

Jan Hoffman (Lect 5 conclusion)

Bounded Implementations

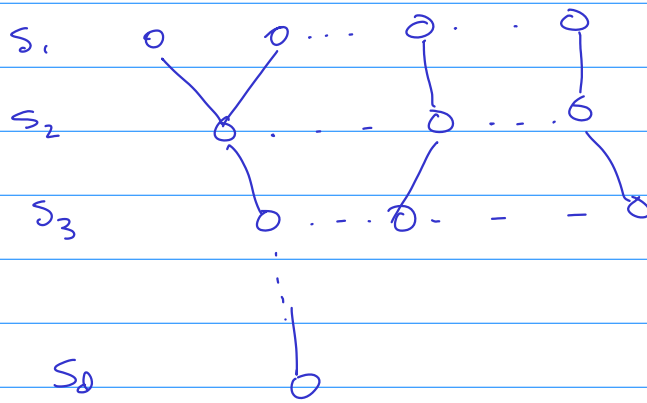
Prototypical Result: Brent's Theorem

Machine Model: shared-memory
multiprocessor (SMP)

- some fixed $p > 0$ processors
- shared memory w/ constant time access
- constant time synchronization mechanism

Theorem If $e \Downarrow^c v$ with $wk(c) = w$ and $dp(c) = d$, then e can be evaluated on an SMP in time $O(\frac{w}{p} + d)$.

"Proof"



$$\sum_{i=1}^d \left\lceil \frac{s_i}{p} \right\rceil \leq \sum_{i=1}^d \frac{s_i}{p} + 1 = \frac{\sum_{i=1}^d s_i}{p} + d = \frac{w}{p} + d$$

But what does big O mean here?
what is n ?