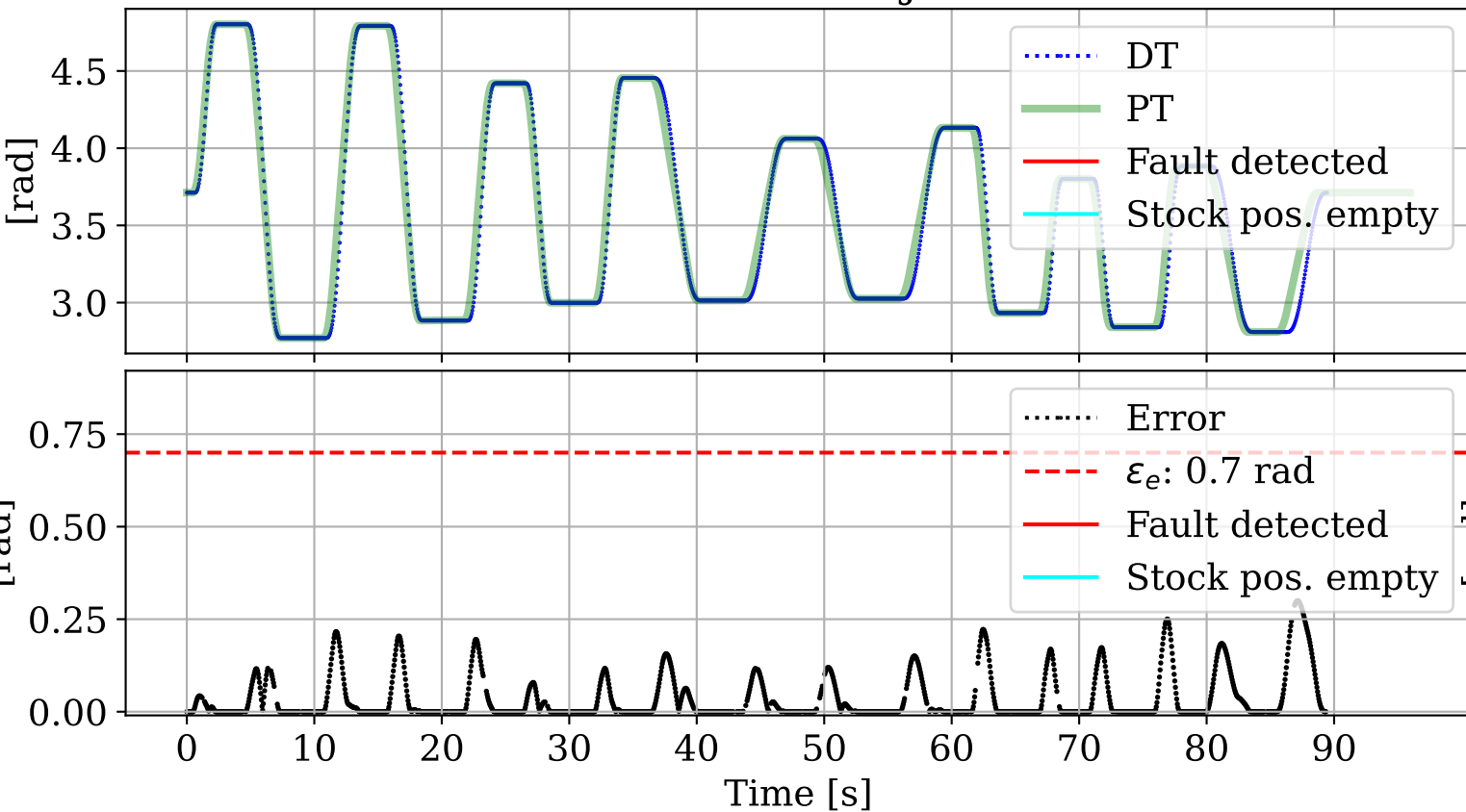


Position and error in joint 0



Position and error in joint 5

