

Andreas Ziegler

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 Please click here to find my full CV



About Me

I am a broadly trained roboticist with a passion for application-driven robotics, computer vision, and machine learning research.

I now seek to grow as an individual contributor while leveraging my leadership experience to foster team collaboration and drive impactful results. By shifting from individual achievements to collective success, I aspire to stimulate the fields of robotics, computer vision, and machine learning as a Postdoctoral Researcher.

Education

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|-------------------|--|
| 2021.06 – 2026.01 |  PhD., University of Tübingen, Germany in Robotics & Computer Vision.
Thesis: <i>Event-based Computer Vision for Fast Robot Control</i> |
| 2014.09 – 2018.04 |  MSc., ETH Zürich, Switzerland in Electrical Engineering.
Specialized in Robotics, Computer Vision, and Machine Learning |
| 2011.09 – 2012.08 |  BSc., Shanghai Jiao Tong University, China in Electrical Engineering & Chinese Language (Exchange Year). |
| 2009.09 – 2013.09 |  BSc., FHO (HSR), Switzerland in Electrical Engineering. |

Selected Research Publications (click here for more)

- 1 Gossard, T., Ziegler, A., & Zell, A. (2025, June). Tt3d: Table tennis 3d reconstruction. In *Proceedings of the ieee/cvf conference on computer vision and pattern recognition (cvpr) workshops*.
- 2 Ziegler, A., Joseph, D., Gossard, T., Moldovan, E., & Zell, A. (2025, June). Biasbench: A reproducible benchmark for tuning the biases of event cameras. In *2025 ieee/cvf conference on computer vision and pattern recognition workshops (cvprw)*.  doi:10.48550/arXiv.2504.18235
- 3 Ziegler, A., Vetter, K., Gossard, T., Tebbe, J., Otte, S., & Zell, A. (2025, May). Detection of fast-moving objects with neuromorphic hardware. In *2025 ieee international conference on robotics and automation (icra)*.  doi:10.48550/arXiv.2403.10677
- 4 Gossard, T., Krismer, J., Ziegler, A., Tebbe, J., & Zell, A. (2024, June). Table tennis ball spin estimation with an event camera. In *2024 ieee/cvf conference on computer vision and pattern recognition workshops (cvprw)*.  doi:10.48550/arXiv.2404.09870
- 5 Gossard, T., Ziegler, A., Kolmar, L., Tebbe, J., & Zell, A. (2024). Ewand: A calibration framework for wide baseline frame-based and event-based camera systems. In *2024 International Conference on Robotics and Automation (ICRA)*, IEEE. Retrieved from  <https://arxiv.org/pdf/2309.12685.pdf>
- 6 Gossard, T., Tebbe, J., Ziegler, A., & Zell, A. (2023, October). Spindoe: A ball spin estimation method for table tennis robot. In *2023 ieee/rsj international conference on intelligent robots and systems (iros)*.  doi:10.1109/iros55552.2023.10342178
- 7 Cieslewski, T., Ziegler, A., & Scaramuzza, D. (2019, October). Exploration without global consistency using local volume consolidation. In *Ifrr international symposium on robotics research (isrr), hanoi, 2019*, IFRR: IEEE. Retrieved from  <https://doi.org/10.5167/uzh-197724>

Employment History

- 2021.06 – 2025.11 ■ **PhD Candidate**, University of Tübingen, Germany.
In collaboration with Sony AI
- 2023.11 – 2024.03 ■ **Research Scientist Intern**, Sony AI, Zürich, Switzerland.
- 2022.08 – 2022.10 ■ **Computer Vision & Machine Learning Intern**, Prophesee, Paris, France.
- 2018.09 – 2021.05 ■ **Robotics Engineer**, MT-Robot AG, Zwingen, Switzerland.
- 2018.06 – 2018.09 ■ **Research Assistant**, Robotics and Perception Group, University of Zürich, Switzerland.
- 2018.04 – 2018.06 ■ **Research Associate Intern**, Disney Research Zürich, Zürich, Switzerland.
- 2018.02 – 2018.03 ■ **Research Assistant**, Laboratory for Orthopaedic Biomechanics, University and ETH Zürich, Switzerland.
- 2017.03 – 2017.08 ■ **Computer Vision & Robotics Research Intern**, Pix4D SA, Lausanne, Switzerland.
- 2013.08 – 2015.08 ■ **Research Assistant (partially Civil Service)**, Laboratory for Orthopaedic Biomechanics, University and ETH Zürich, Switzerland.
- 2013.11 – 2014.02 ■ **Research Assistant (Civil Service)**, Computer Assisted Research and Development, University Hospital Balgrist, Zürich, Switzerland.
- 2004.08 – 2008.08 ■ **Electronics Engineer Apprentice**, Hch. Künding & Cie. AG, Rüti ZH, Switzerland.

Independent Coursework & Training

- 2024.09 – 2024.11 ■ **Leadership Talent Academy**, University of Tübingen, Germany.
- 2024.10 ■ **NVC Workshops**, Connectin2Life, Switzerland.
- 2024.05 ■ **Search Inside Yourself: Emotional Intelligence for Leadership**, Swiss Engineering, Switzerland.

Skills

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| Languages | ■ German (native, C2), English (excellent, C1), French (good, B1), Korean (basics, A2), Chinese (basics, A1). |
| Coding | ■ C++, Python, Julia, C, Java |
| Libraries | ■ OpenCV, ROS1/2, numpy, PyTorch, Eigen, boost, DDS |

Awards and Media Coverage

Awards

- 2024 ■ **Scholarship for the Leadership Talent Academy**, Startup Center Tübingen & University of Tübingen.

Media Coverage

- 2023 ■ **Forscherteam der Uni Tübingen entwickelt Tischtennis-Roboter**, Schwäbisches Tagblatt.