Andreas Ziegler

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📄 Please click here to find my full CV

👤 About Me

I am a broadly trained roboticist with a passion for application-driven robotics, computer vision, and machine learning research.

I now seek to grow as an individual contributor while leveraging my leadership experience to foster team collaboration and drive impactful results. By shifting from individual achievements to collective success, I aspire to stimulate the fields of robotics, computer vision, and machine learning as a Postdoctoral Researcher.

🎓 Education

2021.06 –	🔖 **PhD., University of Tübingen, Germany** in Robotics & Computer Vision. Thesis: *Event-based Computer Vision for Fast Robot Control*
2014.09 – 2018.04	🔖 **MSc., ETH Zürich, Switzerland** in Electrical Engineering. Specialized in Robotics, Computer Vision, and Machine Learning
2011.09 – 2012.08	🔖 **BSc., Shanghai Jiao Tong University, China** in Electrical Engineering & Chinese Language (Exchange Year).
2009.09 – 2013.09	🔖 **BSc., FHO (HSR), Switzerland** in Electrical Engineering.

📕 Selected Research Publications (click here for more)

1 Gossard, T., Ziegler, A., & Zell, A. (2025, June). Tt3d: Table tennis 3d reconstruction. In *Proceedings of the ieee/cvf conference on computer vision and pattern recognition (cvpr) workshops*.

2 Ziegler, A., Joseph, D., Gossard, T., Moldovan, E., & Zell, A. (2025, June). Biasbench: A reproducible benchmark for tuning the biases of event cameras. In *2025 ieee/cvf conference on computer vision and pattern recognition workshops (cvprw)*. 🔗 doi:10.48550/arXiv.2504.18235

3 Ziegler, A., Vetter, K., Gossard, T., Tebbe, J., Otte, S., & Zell, A. (2025, May). Detection of fast-moving objects with neuromorphic hardware. In *2025 ieee international conference on robotics and automation (icra)*. 🔗 doi:10.48550/arXiv.2403.10677

4 Gossard, T., Krismer, J., Ziegler, A., Tebbe, J., & Zell, A. (2024, June). Table tennis ball spin estimation with an event camera. In *2024 ieee/cvf conference on computer vision and pattern recognition workshops (cvprw)*. 🔗 doi:10.48550/arXiv.2404.09870

5 Gossard, T., Ziegler, A., Kolmar, L., Tebbe, J., & Zell, A. (2024). Ewand: A calibration framework for wide baseline frame-based and event-based camera systems. In *2024 International Conference on Robotics and Automation (ICRA)*, IEEE. Retrieved from 🔗 https://arxiv.org/pdf/2309.12685.pdf

6 Gossard, T., Tebbe, J., Ziegler, A., & Zell, A. (2023, October). Spindoe: A ball spin estimation method for table tennis robot. In *2023 ieee/rsj international conference on intelligent robots and systems (iros)*. 🔗 doi:10.1109/iros55552.2023.10342178

7 Cieslewski, T., Ziegler, A., & Scaramuzza, D. (2019, October). Exploration without global consistency using local volume consolidation. In *Ifrr international symposium on robotics research (isrr), hanoi, 2019*, IFRR: IEEE. Retrieved from 🔗 https://doi.org/10.5167/uzh-197724

💼 Employment History

2021.06 –	**PhD Candidate,** University of Tübingen, Germany. In collaboration with Sony AI
2023.11 – 2024.03	**Research Scientist Intern,** Sony AI, Zürich, Switzerland.
2022.08 – 2022.10	**Computer Vision & Machine Learning Intern,** Prophesee, Paris, France.
2018.09 – 2021.05	**Robotics Engineer,** MT-Robot AG, Zwingen, Switzerland.
2018.06 – 2018.09	**Research Assistant,** Robotics and Perception Group, University of Zürich, Switzerland.
2018.04 – 2018.06	**Research Associate Intern,** Disney Research Zürich, Zürich, Switzerland.
2018.02 – 2018.03	**Research Assistant,** Laboratory for Orthopaedic Biomechanics, University and ETH Zürich, Switzerland.
2017.03 – 2017.08	**Computer Vision & Robotics Research Intern,** Pix4D SA, Lausanne, Switzerland.
2013.08 – 2015.08	**Research Assistant (partially Civil Service),** Laboratory for Orthopaedic Biomechanics, University and ETH Zürich, Switzerland.
2013.11 – 2014.02	**Research Assistant (Civil Service),** Computer Assisted Research and Development, University Hospital Balgrist, Zürich, Switzerland.
2004.08 – 2008.08	**Electronics Engineer Apprentice,** Hch. Künding & Cie. AG, Rüti ZH, Switzerland.

🎓 Independent Coursework & Training

2024.09 – 2024.11	**Leadership Talent Academy**, University of Tübingen, Germany.
2024.10	**NVC Workshops**, Connectin2Life, Switzerland.
2024.05	**Search Inside Yourself: Emotional Intelligence for Leadership**, Swiss Engineering, Switzerland.

⭐ Skills

Languages	German (native, C2), English (excellent, C1), French (good, B1), Korean (basics, A2), Chinese (basics, A1).
Coding	C++, Python, Julia, C, Java
Libraries	OpenCV, ROS1/2, numpy, PyTorch, Eigen, boost, DDS

🎗 Awards and Media Coverage

🎗 Awards

2024	**Scholarship for the Leadership Talent Academy**, Startup Center Tübingen & University of Tübingen.

🎗 Media Coverage

2023	**Forscherteam der Uni Tübingen entwickelt Tischtennis-Roboter**, Schwäbisches Tagblatt.