Progress report

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Overview

1 About me

2 Project introduction

About me

2014	Master in ITET at ETHZ
2012-2013	Civil service and work at IfB and CARD at Balgrist
2011-2012	Exchange year at Shanghai JiaoTong Univerity (SJTU)
2009-2013	Bachelor in Electrical Engineering at FHO
2004-2008	Apprenticeship as an electronic engineer

Previous semester project with AIT (D-INFK):
"Robust object tracking in 3D by fusing ultrawideband and vision"

Overview

Map Fusion for Collaborative UAV SLAM

The goal

To develop a pipeline to merge maps created by different Unmanned Aerial Vehicles (UAVs) operating in the same area
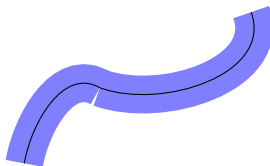
Usage

A common map is required for a team of UAVs to perform tasks, e.g. inspection, together.
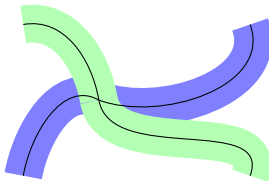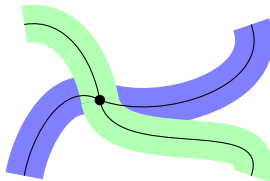
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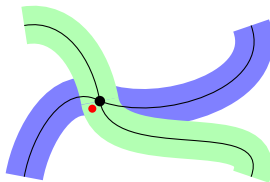
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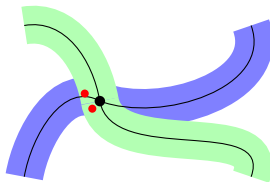
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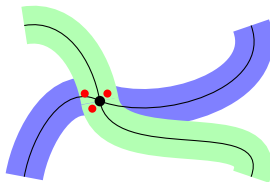
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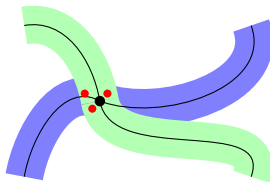
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- If enough overlaps are detected between two maps, these maps can be fused into one
- This fused map than can be used by multiple UAVs simultaneously

Thank you for your attention