### **Binary Search Trees**

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#### Maps

#### **Definition**

A **record** is a key-value pair: (k, v)

A map is an abstract data type for maintaining a set of records

- No two records cannot have the same key
- However, two records can have same values though
- Association of keys to values define a **mapping**: f(key) = value

#### **Examples of maps**

- UNF maintains a map of (N#, student information) records
- A social media company maintains a map of (email address, user account information) records
- An assembler maintains a symbol table (a map) of (opcode, hex) records
- A text-editor maintains a map of (color, RGB representation) records

#### How to implement a map?

#### **Common map operations**

- **Insert** a record (k, v)
- **Retrieve** a record having key k
- **Delete** a record having key k

#### Approach 1: maintain a sorted list of records

- Insertion. will take O(n) time for figuring out the correct spot for the record; then O(n) time for shifting items to the right to accommodate the new record; total time taken is O(n)
- **Retrieval.** will take  $O(\log n)$  time using binary search
- **Deletion.** will take  $O(\log n)$  time to locate it using a binary search; then then O(n) time for left shifting items to kill the empty spot; total time taken  $O(\log n) + O(n) = O(n)$

#### How to implement a map?

#### **Common map operations**

- **Insert** a record (k, v)
- **Retrieve** a record having key k
- **Delete** a record having key k

#### Approach 2: maintain an unsorted list of records

- **Insertion.** will take O(1) time (add at the end)
- **Retrieval.** will take O(n) time using a linear search; may need to search the whole list in the worst-case
- **Deletion.** will take O(n) time to locate it using a linear search; then O(n) time for left shifting items to kill the empty spot; total time taken  $O(\log n) + O(n) = O(n)$

#### **Our aim**

#### **Common map operations**

- **Insert** a record (k, v)
- **Retrieve** a record having key k
- **Delete** a record having key k

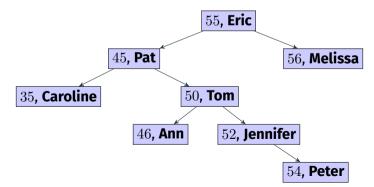
- $\blacksquare$  To accomplish the above three tasks in  $O(\log n)$  time each
- Balanced binary search trees is the solution; stay tuned ...

#### The map ADT

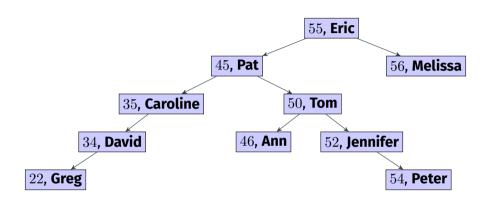
```
public interface MapADT<K,V> {
   boolean put(K key, V value); // adds a new record with key 'key' and value 'value'
   V remove(K key); // removes the record having key 'key'
   V get(K key); // return the value part of the record whose key is 'key'
   V updateValue(K key, V newValue); // updates the value part of the record whose key is 'key' with a new value
   int size(); // returns the number of records stored in the map
   void clear(); //Removes all records from the map
}
```

#### What is a Binary Search Tree?

- It is a binary tree where every node contains a <key, value> pair (a record); keys
  must be comparable but the values don't need to be
- Moreover, for every node p in the tree, the following 2 properties hold
  - f 1 Keys stored in the left subtree of p are < the key stored at p
  - **2** Keys stored in the right subtree of p are > the key stored at p



#### What is a Binary Search Tree?

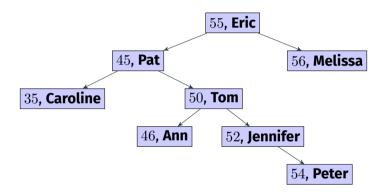


#### Use

BSTs can be used to implement **maps** and are commonly used for fast searching (typically need far less comparisons than lists)

#### An important property of BSTs

An inorder traversal of a BST always gives the sorted sequence based on the keys



#### **Inorder traversal**

35, Caroline; 45, Pat; 46, Ann; 50, Tom; 52, Jennifer; 54, Peter; 55, Eric; 56, Melissa

#### Searching

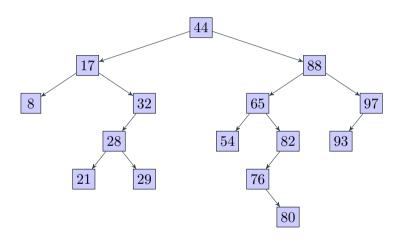
## Let's say you need to look for the record that has the key k; how will you do this?

#### **Algorithm**

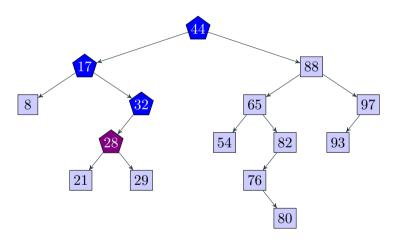
- Start at the root
- If the root's key is k, then search is successful
- ullet If  $k < {
  m root's}$  key, search recursively (or iteratively) in the left subtree of the root
- Otherwise, search recursively (or iteratively) in the right subtree of the root
- ullet If we have reached a null link, no record exists in the tree with key k

# To save space in the figures, we will write only the record keys inside the nodes and avoid the corresponding values

#### **Example**

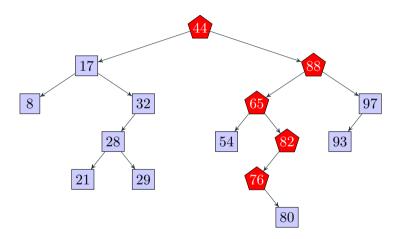


#### Example: search for 28



Found!

#### **Example: search for 68**



Not found; a null link is reached (the left link of 76)

#### Time complexity of searching

## O(h), where h is the height

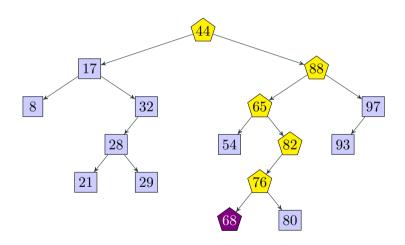
#### Insertion

#### How to insert a record into a BST having key k?

#### **Algorithm**

- Start at the root
- If the root is null, replace empty tree with a new tree with the new record as the root, and signal **SUCCESS**
- If k equals root's key, signal **FAILURE** since a record with key k already exists
- ullet If  $k < {
  m root's}$  key, insert recursively (or, iteratively) in the left subtree of the root
- Otherwise, insert recursively (or, iteratively) in the right subtree of the root

#### Example: insert 68



#### **Time complexity of insertion**

## O(h), where h is the height

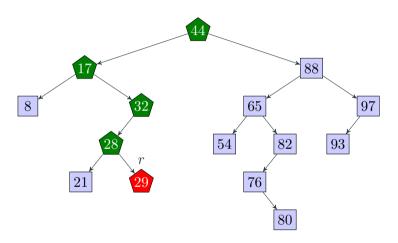
#### **Deletion**

#### How to delete the record from a BST having key k?

#### Idea

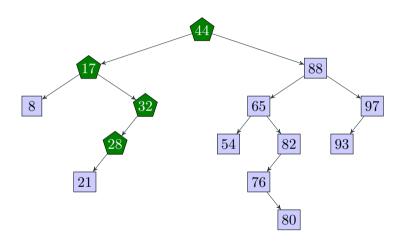
- ullet Traverse through the tree to find the record having key k
- If the record cannot be found, no action is needed
- Now assume that we have found the record that has key k at node r
  - $\mathbf{1}$  r is a leaf node (no child)
  - **2** r has exactly one child (either left or right)
  - 3 r has two children (both left and right)

#### Case 1: r is a leaf node, delete 29

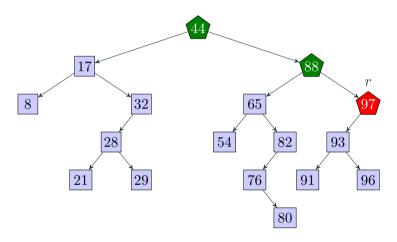


Easy! just delete it right away

#### Case 1: r is a leaf node, delete 29

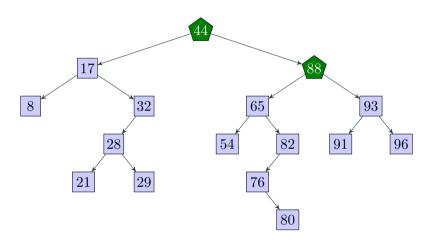


#### Case 2: r has one child, delete 97

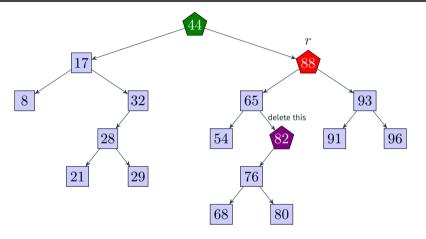


Make the parent of  $\boldsymbol{r}$  point to the only child of  $\boldsymbol{r}$  instead of  $\boldsymbol{r}$ 

#### Case 2: r has one child, delete 97



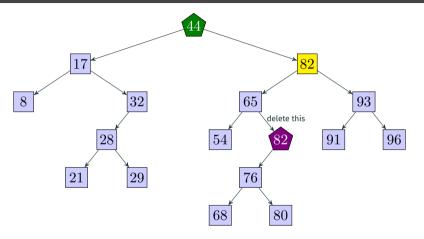
#### Case 3: r has two children, delete 88



Replace the record at r with the record at the inorder predecessor p of n; then delete p using Case 1 or 2, depending on the number of children of p. Note that the inorder predecessor is either a leaf node or has a left child only (no right child).

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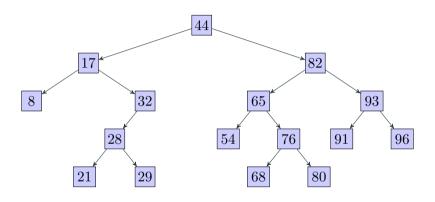
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#### Case 3: r has two children, delete 88



Replace the record at r with the record at the inorder predecessor p of n; then delete p using Case 1 or 2, depending on the number of children of p. Note that the inorder predecessor is either a leaf node or has a left child only (no right child).

#### Time complexity of deletion

## O(h), where h is the height

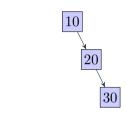
#### Code

See the class TreeMapBST

#### BSTs are not unique



Insertion sequence: 20, 10, 30



Insertion sequence: 10, 20, 30



#### **An application**

#### **Problem**

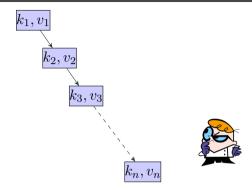
Given a text, find out the unique words in it along with their counts. We also need to output the distinct words with their count.

#### **A solution**

- ullet Use a BST T where the key-type is String and the value-type is Integer
- $\bullet$  For every word w in the text, first check if a node exists in T , where the stored key is w
  - ullet If such a node does not exist, insert a new node in T with key w and value 1
  - ullet If such a node exists in T, increment the stored value (essentially a counter) by 1

#### See the class WordCounter

#### Worst case scenario: skewed binary trees



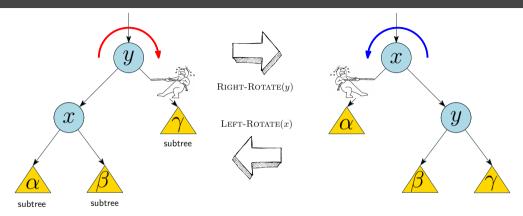
In this case,  $k_1 < k_2 < k_3 < \ldots < k_n$ So, in the worst-case, h = n - 1 = O(n)Therefore, searching, insertion, deletion take O(h) = O(n) time each! This is as bad as using singly linked-lists!

# Do something so that h remains bounded We aim for $h = O(\log n)$

A solution. use Red-Black trees

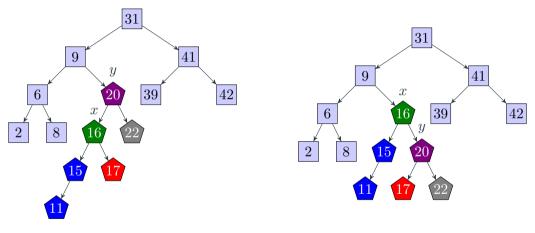
Red-Black trees are never skewed or close to being skewed unlike the plain binary search trees we just talked about

#### **Rotation on BSTs**



Rotations help in **reducing** height of BSTs; this means faster operations on BSTs A single rotation can be done in O(1) time Can be applied to any type of **self-balancing** BST (red-black, AVL, etc.)

#### An example of right rotation



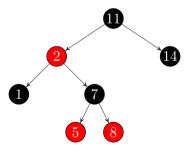
Height: 5 Height: 4

Note that the inorder traversal sequence remains the same!

#### **Definition**

A **red-black** tree is a self-balancing BST that maintains the following invariants:

- Every node is either red or black
- The root is black
- If a node is red, then both its children are black (The null references of the leaves are black)
- The number of black nodes in any path from the root to a leaf is the same



#### Height of a red-black tree

It can be shown mathematically (out of scope) that for red-black trees,

$$h = O(\log n)$$