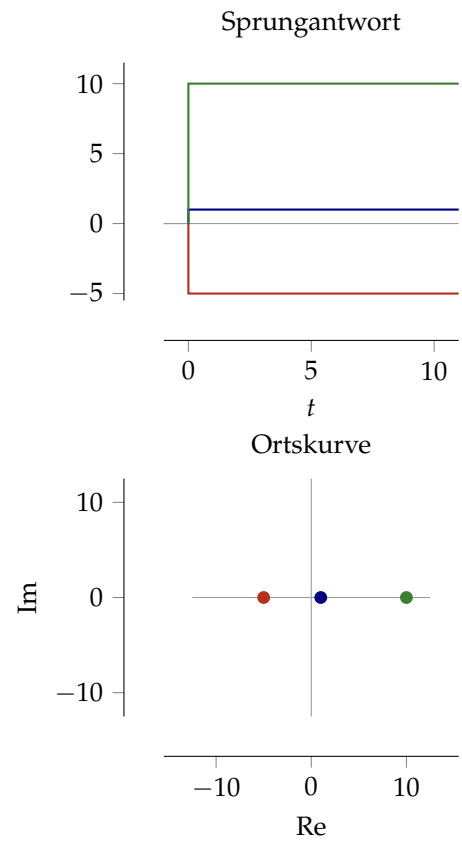
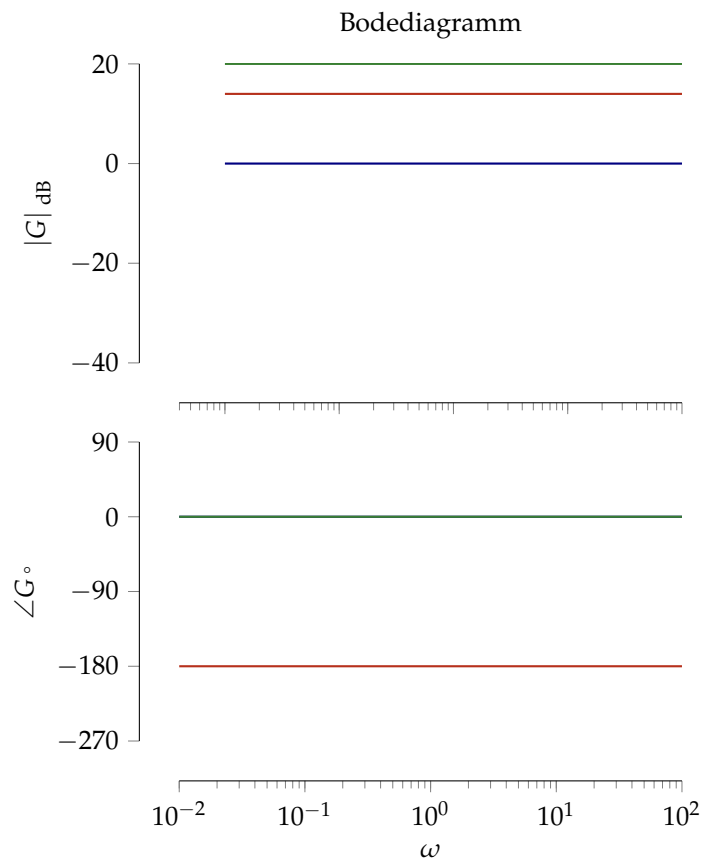


KONSTANTER FAKTOR : $y = ku$.

$$G = k \quad k = -5 \quad k = 1 \quad k = 10$$



REELLER POL : $\dot{y} + ay = u$.

$$G = \frac{1}{s+a}$$

$$\omega_g = |a| \Rightarrow$$

$$a = -1 \quad a = 0 \quad a = +1$$

$$\angle G(j\omega_g) = -45^\circ / -135^\circ$$

$$|G(j\omega_g)| = \frac{1}{\sqrt{2}} \approx -3 \text{ dB}$$

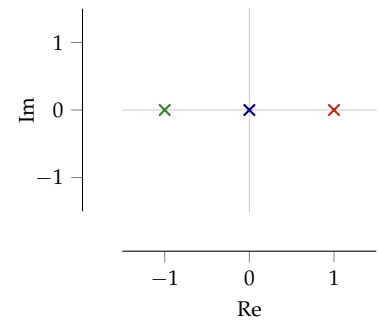
$$\omega \ll \omega_g :$$

$$|G| \approx \frac{1}{|a|}$$

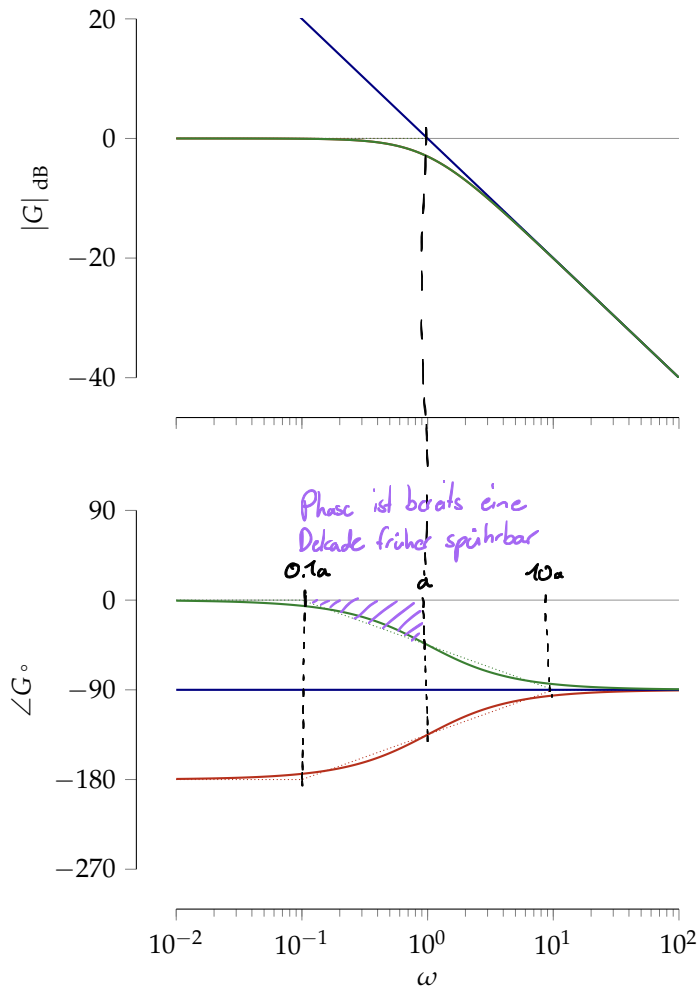
$$\omega_g \ll \omega :$$

$$|G| \propto -20 \text{ dB/Dek.}$$

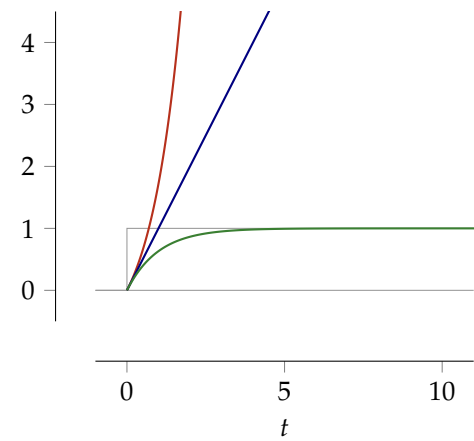
Pol-Nullstellenplan



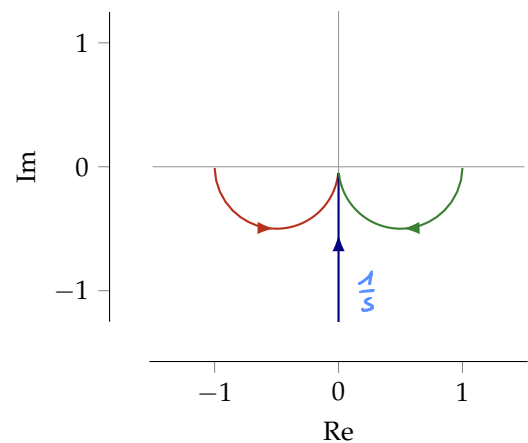
Bodediagramm



Sprungantwort



Ortskurve



KONJUGIERT KOMPLEXES POLPAAR : $\ddot{y} + 2a\dot{y} + by = u$.

$$\frac{1}{s^2 + 2\zeta\omega_0 s + \omega_0^2}$$

$$\omega_0 = 1 \quad \zeta = 1 \quad \zeta = 0.5 \quad \zeta = 0.1$$

$$\angle G(j\omega_0) = -90^\circ$$

$$\omega \ll \omega_0 :$$

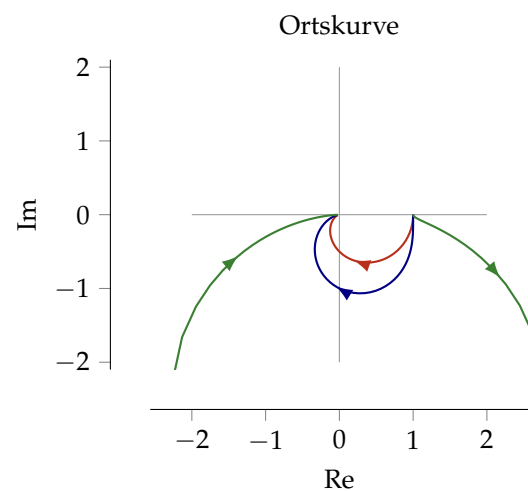
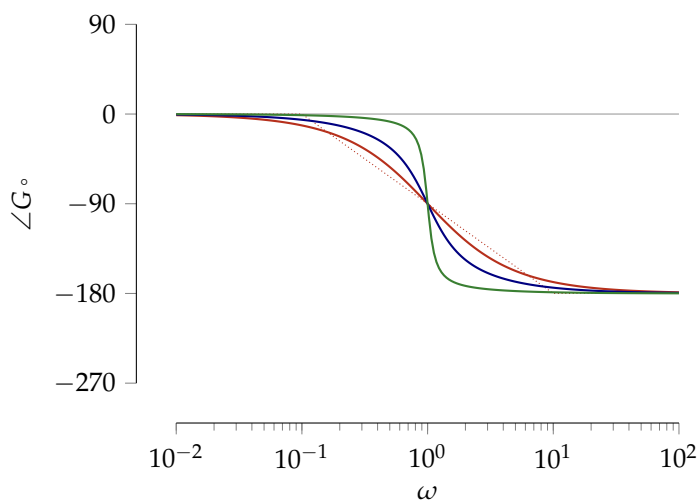
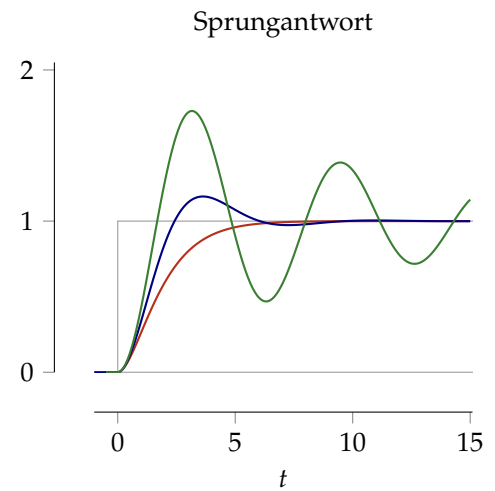
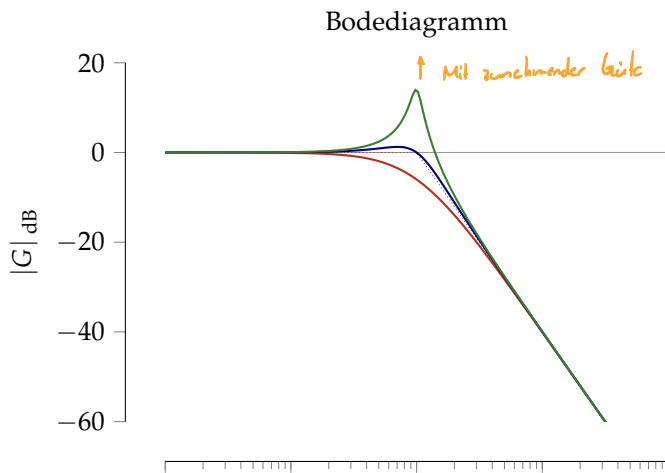
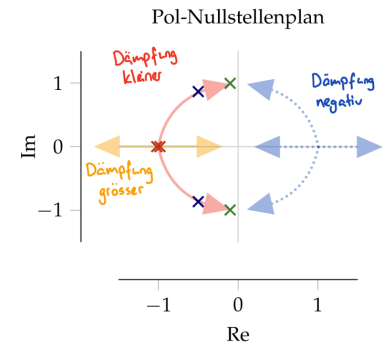
$$|G| \approx 1/\omega_0^2 \rightarrow \text{Konstante Dämpfung}$$

$$\omega_0 \ll \omega :$$

$$|G| \propto -40 \text{ dB/Dek.}$$

$$M_p = e^{-\pi\zeta/\sqrt{1-\zeta^2}}$$

$$\text{relatives Überschossen } \frac{\hat{h} - h_\infty}{h_\infty}$$



REELLE NULLSTELLE : $y = \dot{u} + au$.

$$G = s + a$$

$$a = -1 \quad a = 0 \quad a = +1$$

$$\omega_g = |a| \Rightarrow$$

$$\angle G(j\omega_g) = +45^\circ / +135^\circ$$

$$|G(j\omega_g)| = \sqrt{2} \approx +3 \text{ dB}$$

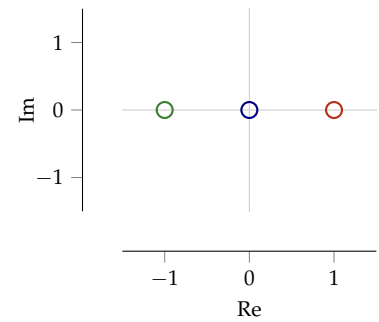
$$\omega \ll \omega_g :$$

$$|G| \approx |a|$$

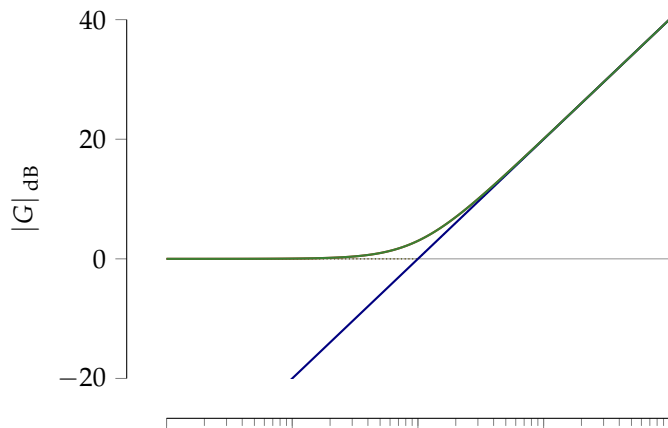
$$\omega_g \ll \omega :$$

$$|G| \propto +20 \text{ dB/Dek.} \quad \angle G \approx 90^\circ$$

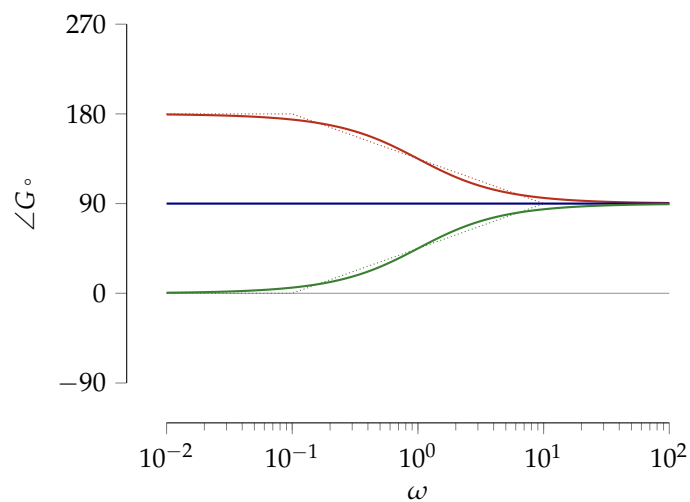
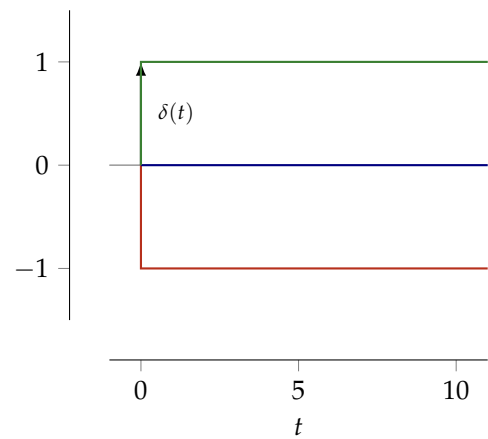
Pol-Nullstellenplan



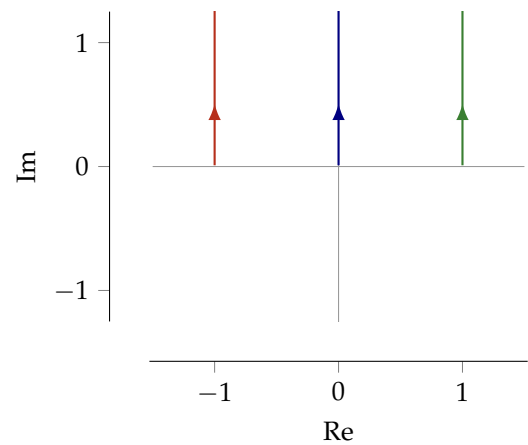
Bodediagramm



Sprungantwort



Ortskurve



KONJUGIERT KOMPLEXES NULLSTELLENPAAR : $y = \ddot{u} + a\dot{u} + bu$.

Nur theoretisch möglich

$$s^2 + \underbrace{2\zeta\omega_0}_{a}s + \underbrace{\omega_0^2}_{b}$$

$$\omega_0 = 1 \quad \zeta = 1 \quad \zeta = 0.5 \quad \zeta = 0.1$$

$$\angle G(j\omega_0) = +90]^\circ$$

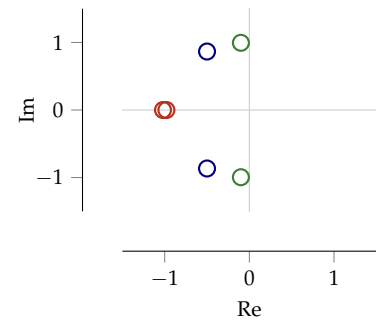
$$\omega \ll \omega_0 :$$

$$|G| \approx \omega_0^2$$

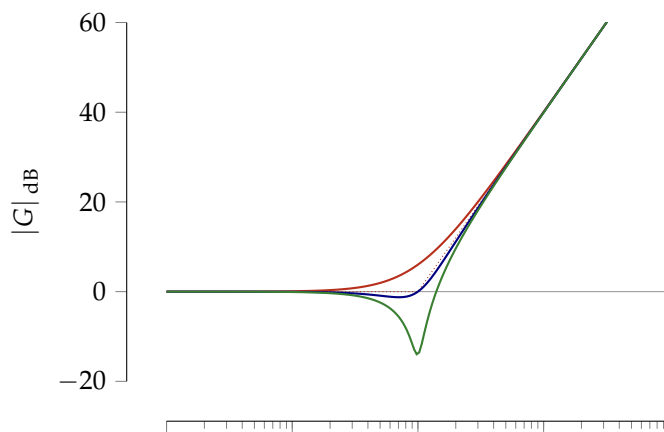
$$\omega_0 \ll \omega :$$

$$|G| \propto +40 \text{ dB/Dek.}$$

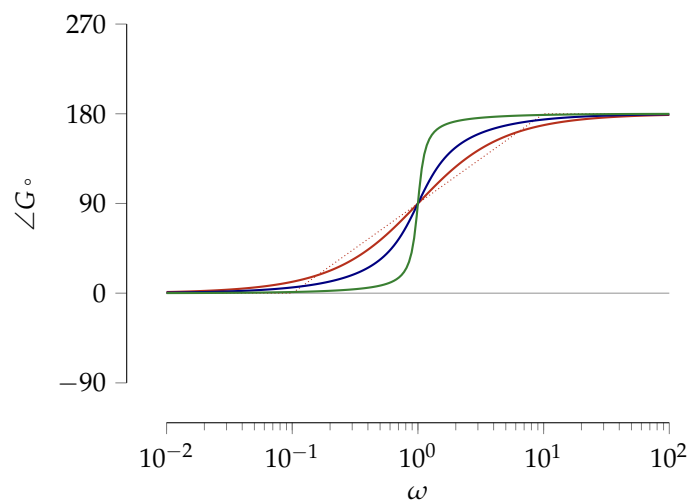
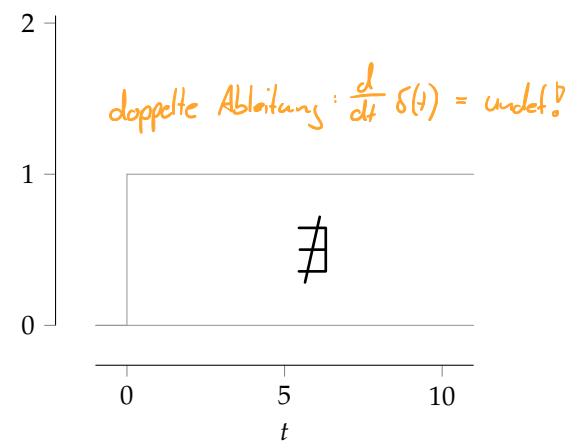
Pol-Nullstellenplan



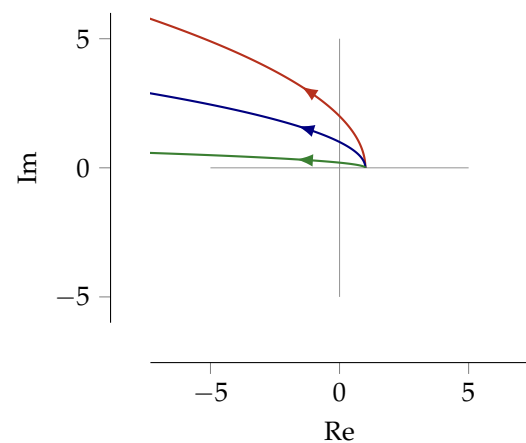
Bodediagramm



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TOTZEIT, VERZÖGERUNG : $y(t) = u(t - \tau)$.

$$G = e^{-s\tau} \quad \tau > 0$$

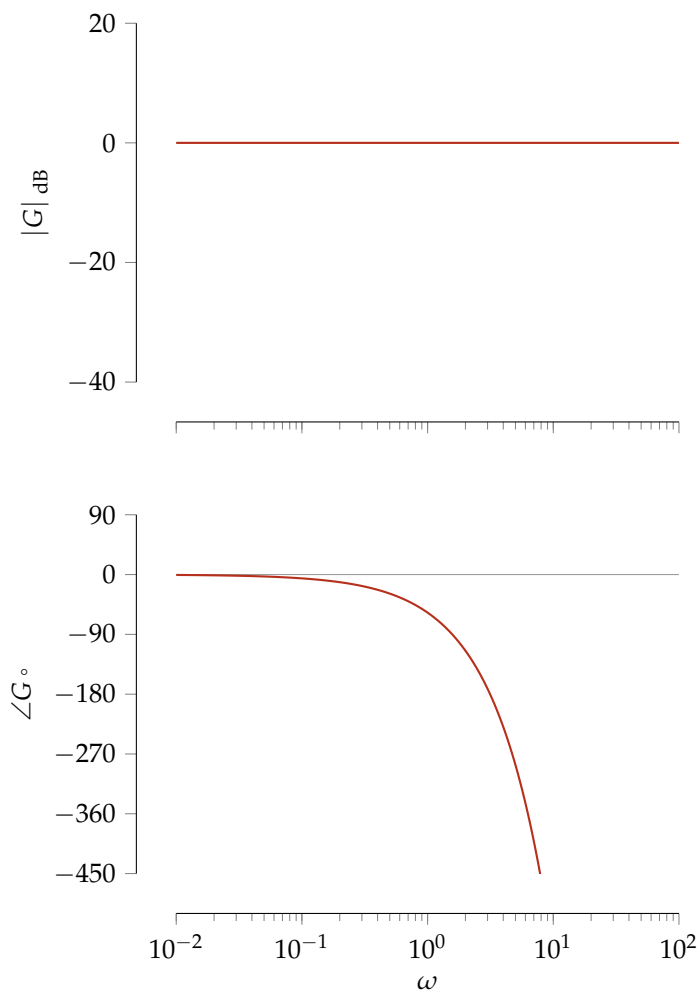
$$\tau = 1$$

$$\angle G(j\omega) = -\omega\tau$$

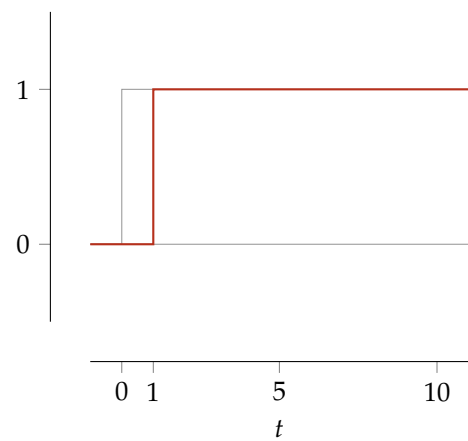
$$|G| = 1 = 0 \text{ dB}$$

$$e^{-s\tau} = \lim_{n \rightarrow \infty} \frac{1}{(1 + s\frac{\tau}{n})^n}$$

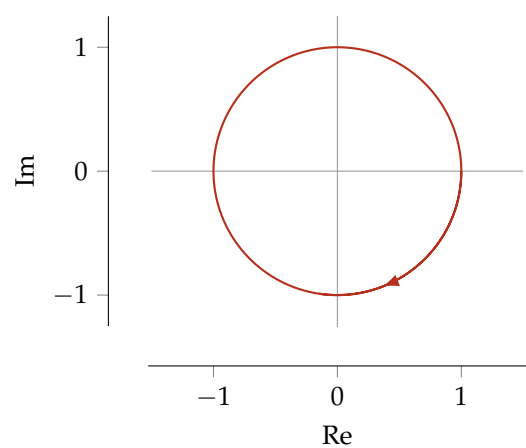
Bodediagramm



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VERKETTUNG – BEISPIEL.

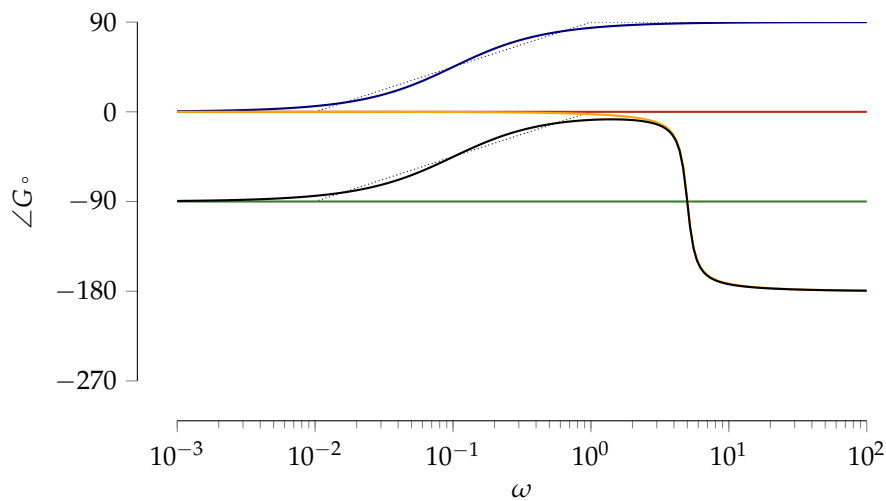
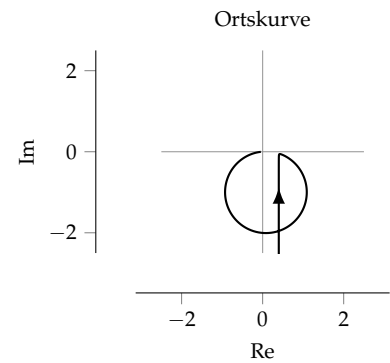
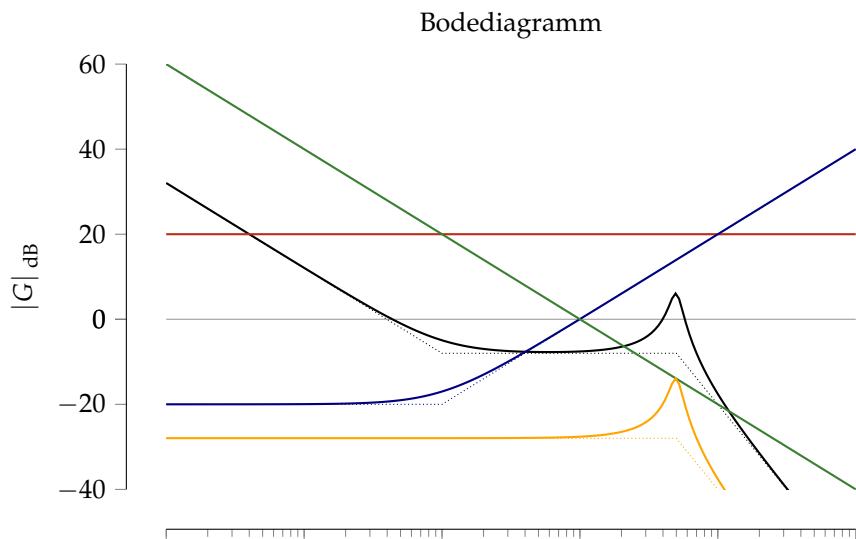
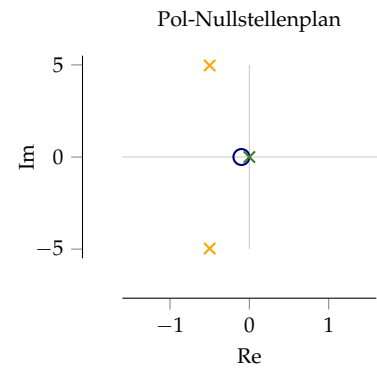
$$G = \frac{10s+1}{s^3+s^2+25s} = \underbrace{10}_{G_1} \cdot \underbrace{(s+0.1)}_{G_2} \cdot \underbrace{\frac{1}{s}}_{G_3} \cdot \underbrace{\frac{1}{s^2+s+25}}_{G_4}$$

$$G_1 = 10$$

$$G_2 = (s+0.1)$$

$$G_3 = \frac{1}{s}$$

$$G_4 = \frac{1}{s^2+s+25} = \frac{1}{s^2+2\zeta\omega_0s+\omega_0^2} \quad \text{mit } \omega_0 = 5, \zeta = 0.1$$



ADDITION – BEISPIEL PID.

$$u = k_p e + k_i \int_0^t e(\tau) d\tau + k_d \frac{de}{dt}$$

$$u = k_p e + k_i \frac{1}{s} e + k_d s e$$

$$G = \frac{u}{e} = k_p + k_i \frac{1}{s} + k_d s = \frac{k_p s + k_i + k_d s^2}{s} = k \frac{(1 + sT_1)(1 + sT_2)}{s}$$

Graphen für $k = 1, T_1 = 0.1, T_2 = 10$ sowie $k_p = 10.1, k_i = 1, k_d = 1$

