



Übersetzer für Parallele Systeme Compilers for Parallel Systems

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Literature

- * Randy Allen, Ken Kennedy. *Optimizing compilers for modern architectures*. Kaufmann, 2002.
- * Alfred V. Aho, Monica S. Lam, Ravi Sethi, Jeffrey D. Ullman, *Compilers: Principles, Techniques, & Tools (2nd Edition)*. Pearson Addison Wesley, 2007.
- * Michael J. Wolfe. *High-Performance Compilers for Parallel Computing*. Addison-Wesley, 1996.
- * Hans Zima, Barbara Chapman. *Supercompilers for Parallel and Vector Computers*. ACM Press, 1990.

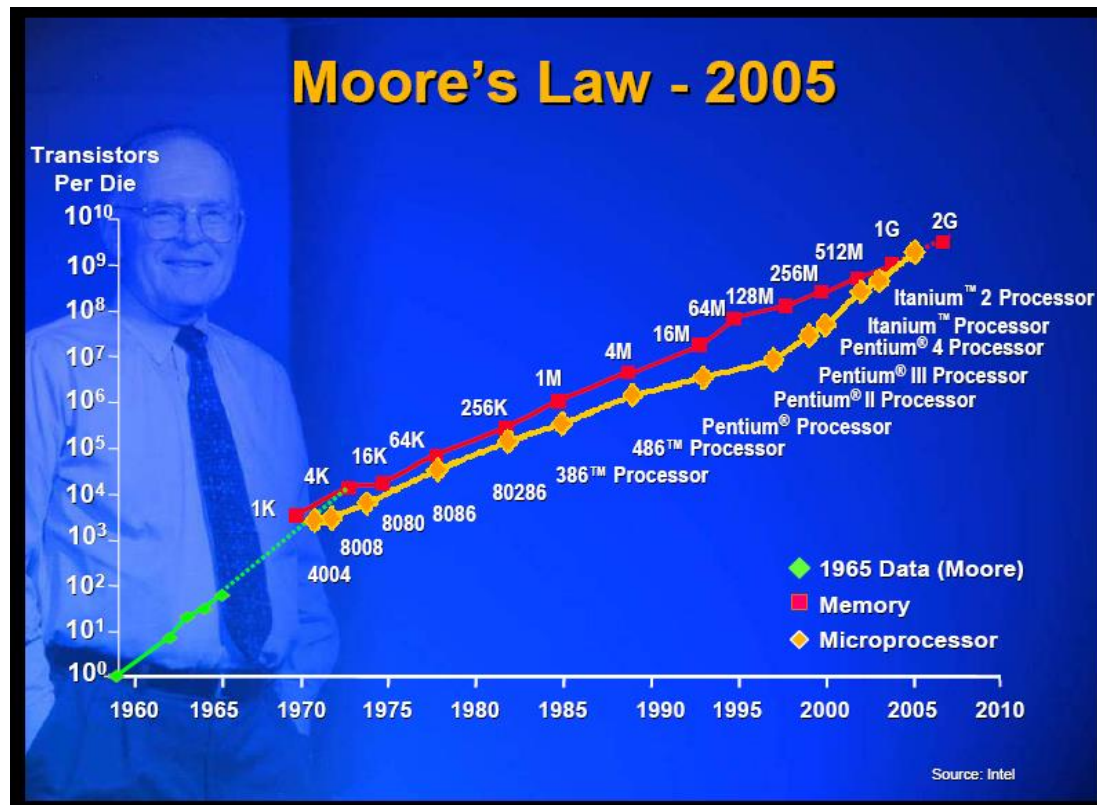


Parallel Computing Applications

- * Parallel Computing is a fundamental tool of science
 - * computational science and engineering is the “third pillar” of scientific discovery
 - * in addition to theory and experiments
- * Simulation instead of experiments for construction of models for natural phenomena
 - * collision of galaxies cannot be studied using experiments
- * Models are described by differential equations
 - * discretized and solved numerically
 - * finer discretization increases accuracy, e.g. spatial resolution of weather forecast models
 - * ever-increasing demand for computing power
 - * HPC High Performance Computing
- * Application areas
 - * biology, energy research, high energy physics, astrophysics, aerospace, automotive technologies, seismology, image processing, pattern matching, semiconductor technologies, VLSI design, tomography, genetic engineering, molecular simulation, drug design, ...

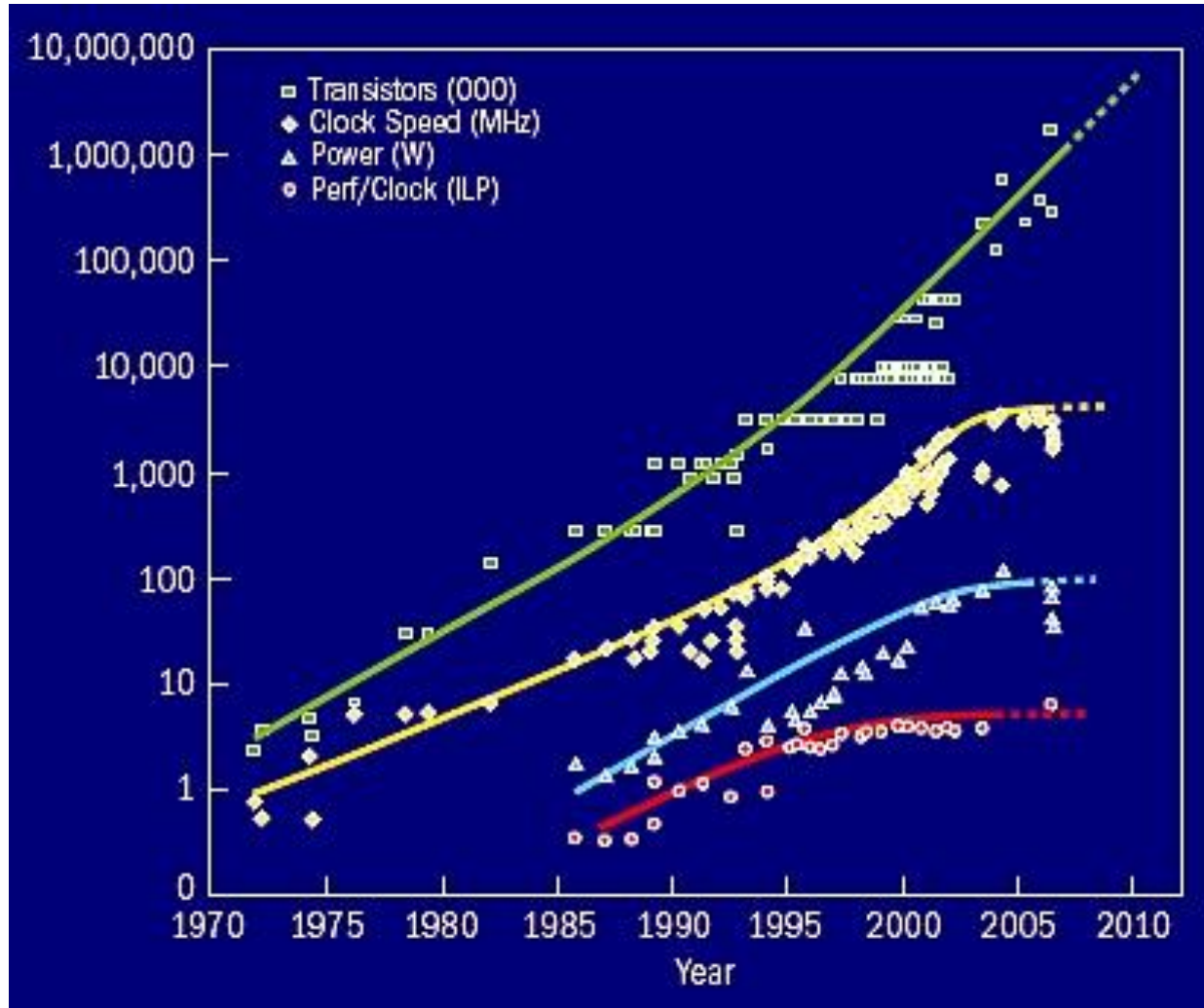
Moore's Law

Gordon Moore (co-founder of Intel), 1965: The number of transistors that can be placed inexpensively on an integrated circuit doubles approximately every two years.



Source: www.intel.com

Sources of Performance Improvements



- * Frequency scaling
 - ⇒ heat dissipation
- * Multiple functional units/superscalar: Instruction Level Parallelism ILP
 - ⇒ dependences between instructions
- * Multicore
 - ⇒ parallelism must be exploited by software

Source: D. Patterson, UC-Berkeley. Illustration A. Tovey, www.scidacreview.org



Simulation of the Human Brain

- * 1.73 billion virtual nerve cells connected to 10.4 trillion virtual synapses
 - * synapses were connected at random
 - * simulated network represents 1% of the neuronal network in the brain
- * Virtual synapse contains 24 bytes of memory
 - * 1 petabyte of main memory
 - * memory of 250.000 desktop PCs.
- * Simulation on **K computer**
 - * simulates 1 sec of brain activity in 40 min computing time
 - * 88.128 octacore nodes (705.024 cores)
 - * 10.5 petaflops ($10.5 \cdot 10^{15}$ floating point operations per second)
 - * full-scale simulation of the brain will require a computer 100.000 times faster

Source <http://io9.com/this-computer-took-40-minutes-to-simulate-one-second-of-1043288954>



Architectures and Programming

- * Vector/Array computers
 - * entire arrays handled with a single instruction
 - * programming paradigm close to sequential programming
- * Multiprocessing systems
 - * introduce additional dimension of programming complexity
 - * systems of processes
 - * individual sequential threads of execution
 - * running concurrently at unspecified speeds
 - * synchronization required to prevent deadlocks, race conditions, unintentional data sharing, ...



Programming Support

- * Languages: extensions to standard programming languages
 - * C/C++, Fortran, Java, ...
 - * Fortran 90 vector extensions for array manipulation
 - * High Performance Fortran HPF: sequential program + specification of data distribution
 - * explicit control of parallelism, e.g. Occam, Ada, ...
- * Interfaces and Libraries
 - * MPI, pthreads, Intel TBB, ...
- * Algorithms
- * Tools



Parallel Program Development

- * Programmer formulates concurrent algorithm explicitly, using language extensions and/or libraries
 - * machine specific vs. higher abstraction level
 - * shield user from details of concurrency management
- * Large body of existing sequential code
 - * e.g. legacy code
 - * manual transformation using language extensions is very time consuming



Compiler Support

- * “Supercompilers” perform automatic restructuring
 - * sequential program specifies computation
 - * transform same operations into parallel form
 - * program analysis to detect **hidden** concurrency
 - * vectorization - vector code
 - * parallelization - code for parallel computer
- * User supported transformation process
 - * restructuring guided by program annotations and assertions
 - * user supplies information and makes decisions
 - * semi-automatic parallelization
 - * interactive systems
- * Advantages
 - * development, verification, debugging of sequential programs is easier
 - * existing IDE's for sequential programming
 - * Supports portability between different parallel architectures



Limitations

- * Quality of parallelized program depends on structure of algorithm and target architecture
 - * mainly for data parallelism
- * Can only parallelize a given algorithm, not construct a new parallel algorithm, e.g. for sorting
 - * compilers do not change essential features of the algorithm
 - * scalable parallel algorithms can be qualitatively different from sequential algorithms
- * Vectorization well established
- * Parallelization more difficult
 - * complexity, variety, heterogeneity of parallel systems
- * Exploitation of machine specific features in source program impedes automatic parallelization



Data Dependence

- * Execution order in procedural languages is fixed
- * Change of order can affect program semantics
 - * hidden, implicit concurrency
 - $S_1 \ a=b+c$
 - $S_2 \ d=e*f$
 - * reverse order ? ok
 - * concurrent execution ? ok
- * Bernstein's conditions, 1966
 - * S_1 executed before S_2
 - * DEF_i ... variables written in S_i , USE_i ... variables read in S_i
 - * $(DEF_1 \cap USE_2) \cup (USE_1 \cap DEF_2) \cup (DEF_1 \cap DEF_2) = \emptyset$
 - true* *anti* *output* dependence



Control Dependence

- * Conditional statement

```
 $S_1$   if ( $a < 0$ ) then  
 $S_2$      $x = -y$   
      else  
 $S_3$      $x = y + 1$   
end if
```

- * S_2 and S_3 are **control** dependent on S_1
- * Condition in S_3 must be evaluated before execution of S_2 and S_3



Parallelizing Compiler Components

- * Front end
 - * scanning
 - * parsing
 - * (static) semantic analysis
 - * construction of intermediate representation (IR)
 - * attributed abstract tree
 - * symbol table
- * Based on IR
 - * program analysis
 - * flow analysis
 - * dependence analysis
 - * program normalization
 - * e.g. loops increment always 1



Program Analysis

- * Flow analysis

- * information about flow of scalar data
- * control flow analysis
- * data flow analysis
- * arrays treated as a whole

- * Dependence analysis

- * dependence relation between statements
- * constructs **dependence graph**
- * examines **array indices**
- * in general undecidable
- * effective tests available if indices are linear functions of loop variables



Transformation Component

- * Program transformations
- * Loop transformations
 - * loop interchange, - distribution, - unrolling, ...
- * Application determined by
 - * program properties
 - * analysis information
 - * target architecture
- * More or less specific to target architecture
- * Program analysis results are used for
 - * verification of preconditions (transformation specific)
 - * selection of „good“ transformations
 - * evaluation of effect of transformation after application



Example

* Sequential code

```
for i=100 to 1 step -1
    a[i-2] = b[i+1] + c[i]
    e[i]    = f[i-3] / a[i-2]
end for
```

* Loop normalization

```
for $i=1 to 100
    a[100+($i-1)*(-1)-2] = b[100+($i-1)*(-1)+1] +
                          c[100+($i-1)*(-1)]
    e[100+($i-1)*(-1)]   = f[100+($i-1)*(-1)- 3] /
                          a[100+($i-1)*(-1)- 2]
end for
```

i=0 dead code, if not read before next assignment to i



Example (2)

- * Dead code elimination, standardization, simplification

```
for i=1 to 100
  a[99-$i] = b[102-$i] + c[101-$i]  form:  $a_0 + a_1 * i$ 
  e[101-$i] = f[98-$i] / a[99-$i]
end for
```

- * Dependence analysis

```
for i=1 to 100
  a[99-$i] = b[102-$i] + c[101-$i]
  e[101-$i] = f[98-$i] / a[99-$i]  true dependence
end for
```

- * Loop distribution: generate loops with single statement body

```
for i=1 to 100
  a[99-$i] = b[102-$i] + c[101-$i]
end for
for i=1 to 100
  e[101-$i] = f[98-$i] / a[99-$i]
end for
```



Example (3)

- * Vector code generation can be applied to distributed loops

- * $a[1:u]$ denotes elements $\langle a[1], a[1+1], \dots, a[u] \rangle$

- * addition of all respective elements **concurrently**

$a[-1:98] = b[2:101] + c[1:100]$

$e[1:100] = f[-2:97] / a[-1:98]$