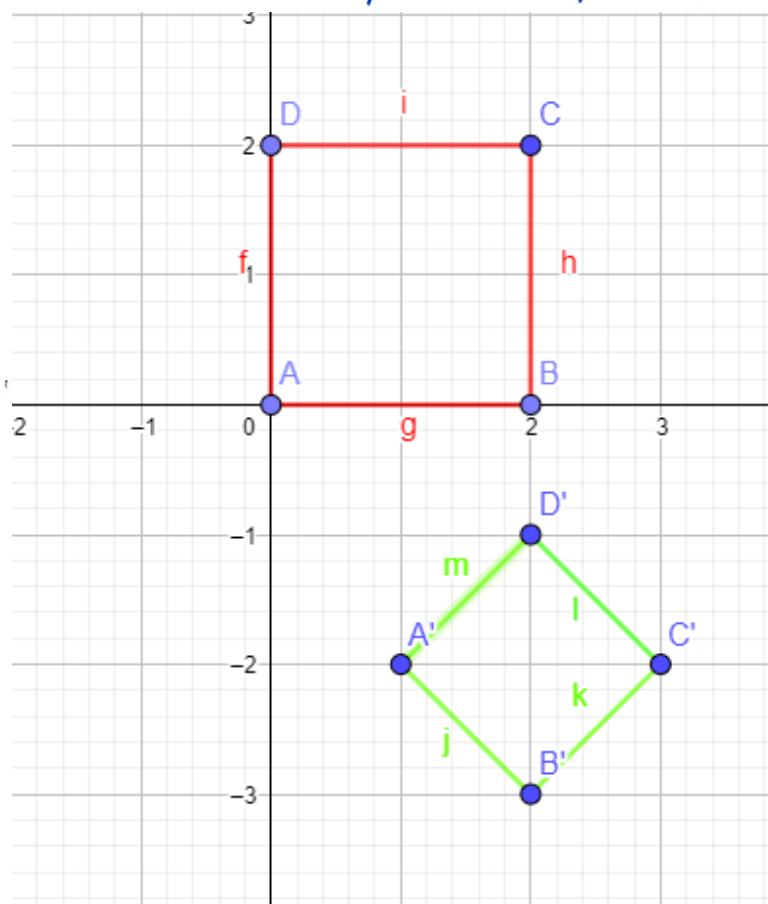


Problema 11.8

Se consideră pătratul $ABCD$, de vârfuri $A(0,0)$, $B(2,0)$, $C(2,2)$, $D(0,2)$. Demonstrați că patrulaterul $A'B'C'D'$ cu $A'(1,-2)$, $B'(2,-3)$, $C'(3,-2)$, $D'(2,-1)$ este, de asemenea, un pătrat și indicați o succintă de transformări geometrice care transformă primul pătrat în cel de-al doilea.



Demonstrație că $A'B'C'D'$ este pătrat.

$$\left. \begin{aligned} m_{A'D'} &= \frac{y_{D'} - y_{A'}}{x_{D'} - x_{A'}} = \frac{-1 - (-2)}{2 - 1} = 1 \\ m_{B'C'} &= \frac{y_{C'} - y_{B'}}{x_{C'} - x_{B'}} = \frac{-2 - (-3)}{3 - 2} = 1 \end{aligned} \right\} \Rightarrow A'D' \parallel B'C'$$

$$\left. \begin{aligned} m_{A'B'} &= \frac{y_{B'} - y_{A'}}{x_{B'} - x_{A'}} = \frac{-3 - (-2)}{2 - 1} = -1 \\ m_{C'D'} &= \frac{y_{C'} - y_{D'}}{x_{C'} - x_{D'}} = \frac{-2 - (-1)}{3 - 2} = -1 \end{aligned} \right\} \Rightarrow A'B' \parallel D'C'$$

\Rightarrow laturile opuse sunt paralele ①

$$m_{A'D'} = \frac{-1}{m_{A'B'}} \Rightarrow A'B' \perp A'D'$$

$$m_{B'C'} = \frac{-1}{m_{D'C'}} \Rightarrow B'C' \perp D'C'$$

\Rightarrow laturile oțierate sunt perpendiculare ②

$$A'B' = \sqrt{1+1} = \sqrt{2}$$

$$A'D' = \sqrt{1+1} = \sqrt{2}$$

$$C'D' = \sqrt{1+1} = \sqrt{2}$$

$$B'C' = \sqrt{1+1} = \sqrt{2}$$

} laturile sunt egale ③

①, ②, ③ $\Rightarrow A'B'C'D'$ este pătrat.

Transformări: Translație, Scalare, Rotatie.

Translația

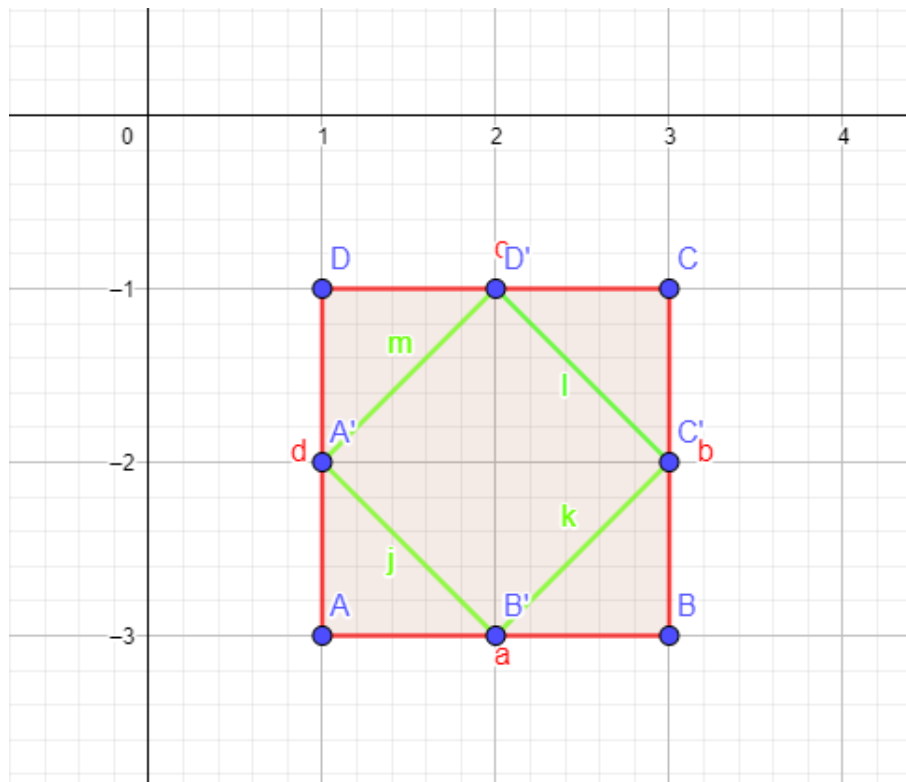
M centrul pătratului ABCD $\Rightarrow M(1, 1)$

N centrul pătratului A'B'C'D' $\Rightarrow N(2, -2)$

$$T(x, y) = \begin{pmatrix} 1 & 0 & x \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} \quad \text{cu } \vec{u}(x, y)$$

$$\overrightarrow{MN}(x_N - x_M, y_N - y_M) \Rightarrow \overrightarrow{MN}(1, -3)$$

$$\Rightarrow T(1, -3) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix}$$



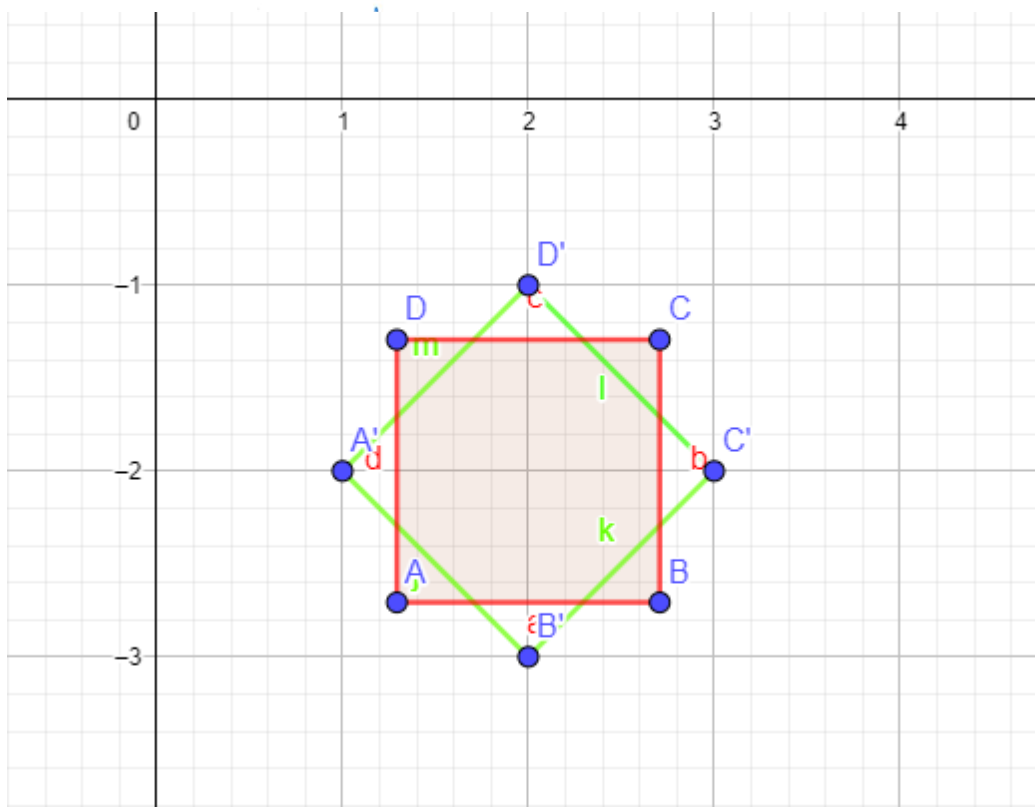
Solorea

Solore uniformă $\Rightarrow S_x = S_y = S$

$$\Rightarrow S(Q, s) = \begin{pmatrix} s & 0 & (1-s)q_1 \\ 0 & 1 & (1-s)q_2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$A'B' = \sqrt{2} \quad AB = 2 \Rightarrow S = \frac{A'B'}{AB} = \frac{\sqrt{2}}{2}$$

$$S(1, 1, \frac{\sqrt{2}}{2}) = \begin{pmatrix} \frac{\sqrt{2}}{2} & 0 & 1 - \frac{\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & 1 - \frac{\sqrt{2}}{2} \\ 0 & 0 & 1 \end{pmatrix}$$



Rotation

$$R(Q, \theta) = \begin{pmatrix} \cos \theta & -\sin \theta & q_1(1 - \cos \theta) + q_2 \sin \theta \\ \sin \theta & \cos \theta & -q_1 \sin \theta + q_2(1 - \cos \theta) \\ 0 & 0 & 1 \end{pmatrix}$$

$$\theta = 2\pi - \frac{\pi}{4} \Rightarrow \sin\left(2\pi - \frac{\pi}{4}\right) = \sin 2\pi \cos \frac{\pi}{4} - \sin \frac{\pi}{4} \cos 2\pi = -\frac{\sqrt{2}}{2}$$

$$\cos\left(2\pi - \frac{\pi}{4}\right) = \cos 2\pi \cos \frac{\pi}{4} + \sin 2\pi \sin \frac{\pi}{4} = \frac{\sqrt{2}}{2}$$

$$R(1, 1, 315^\circ) = \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 - \sqrt{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$T_R = T(1, -3) \cdot S(1, 1, \frac{\sqrt{2}}{2}) \cdot R(1, 1, 315^\circ)$$

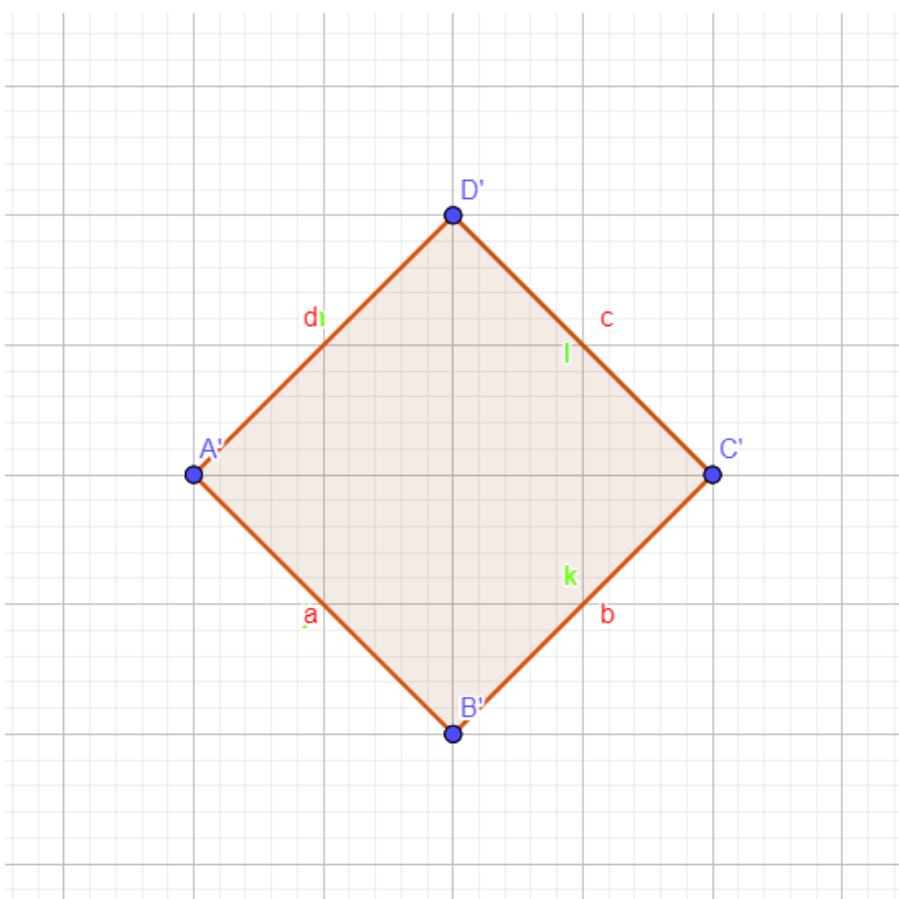
$$\overline{T_R} T(1, -3) \cdot S(1, 1, \frac{\sqrt{2}}{2}) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{\sqrt{2}}{2} & 0 & 1 - \frac{\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & 1 - \frac{\sqrt{2}}{2} \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{\sqrt{2}}{2} & 0 & 2 - \frac{\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & -2 - \frac{\sqrt{2}}{2} \\ 0 & 0 & 1 \end{pmatrix}$$

$$T \cdot S \cdot R = \begin{pmatrix} \frac{\sqrt{2}}{2} & 0 & 2 - \frac{\sqrt{2}}{2} \\ 0 & \frac{\sqrt{2}}{2} & -2 - \frac{\sqrt{2}}{2} \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 - \sqrt{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 \\ 0 & 0 & 1 \end{pmatrix} =$$

$$= \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & (1 - \sqrt{2})(2 - \frac{\sqrt{2}}{2}) + (-2 - \frac{\sqrt{2}}{2}) + 1 \\ -\frac{1}{2} & \frac{1}{2} & \frac{\sqrt{2}}{2} - 2 - \frac{\sqrt{2}}{2} \\ 0 & 0 & 1 \end{pmatrix} =$$

$$= \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 1 \\ -\frac{1}{2} & \frac{1}{2} & -2 \\ 0 & 0 & 1 \end{pmatrix} = T_R$$



Verificare

$$(A'B'C'D') = T_R \cdot (ABCA)$$

$$(A'B'C'D') = \begin{pmatrix} 1 & 2 & 3 & 2 \\ -2 & -3 & -2 & -1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$(ABCA) = \begin{pmatrix} 0 & 2 & 2 & 0 \\ 0 & 0 & 2 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

$$T_R = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 1 \\ -\frac{1}{2} & \frac{1}{2} & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$T_R \cdot (ABCA) = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 1 \\ -\frac{1}{2} & \frac{1}{2} & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 2 & 2 & 0 \\ 0 & 0 & 2 & 2 \\ 1 & 1 & 1 & 1 \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 2 & 3 & 2 \\ -2 & -3 & -2 & -1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$