# Solutions to hw5 homework on Convex Optimization

https://web.stanford.edu/class/ee364a/homework.html

#### Andrei Keino

July 24, 2020

## 5.17

Robust linear programming with polyhedral uncertainty. Consider the robust LP:

minimize 
$$c^T x$$
 subject to 
$$\sup_{a \in P_i} a^T x \leq b_i, \ i = 1, ..., m$$

with variable  $x \in R^n$ , where  $P_i = \{a: C_i a \leq d_i\}$ . The problem data are  $a \in R^n$ ,  $C_i \in R^{m_i \times n}$ ,  $d_i \in R^{m_i}$ , and  $b \in R^m$ . We assume the polyhedra  $P_i$  are nonempty. Show that this problem is equivalent to the LP:

minimize 
$$c^T x$$
 subject to 
$$d_i^T z_i \leq b_i, \ i=1,...,m$$
 
$$C_i z_i = x, \ i=1,...,m$$
 
$$z_i \succeq 0, \ i=1,...,m$$

with variables  $x \in \mathbb{R}^n$ ,  $z_i \in \mathbb{R}^{m_i}$ , i = 1, ..., m. Hint: find the dual of the problem of maximizing  $a_i^T x$  over  $a_i \in P_i$  (with variable  $a_i$ ).

Solution:

The problem of maximizing  $a_i^T x$  over  $a_i \in P_i$  (with variable  $a_i$ ) is:

maximize 
$$a_i^T x$$
  
subject to  $a_i \in P_i$ , where  $P_i = \{a: C_i a \leq d_i\}$ 

or

minimize 
$$-a_i^T x$$
  
subject to 
$$C_i a_i \leq d_i$$

The Lagrange dual of this problem is:

minimize 
$$\sum_{i=1}^m \lambda_i d_i$$
 subject to 
$$C_i \lambda_i = x$$
 
$$\lambda_i \succeq 0$$

The optimal value of this problem is less or equal to  $b_i$ , so we have the equivalent problem to our LP:

minimize 
$$c^Tx$$
 subject to 
$$d_i^T\lambda_i \leq b_i, \ i=1,...,m$$
 
$$C_i\lambda_i = x, \ i=1,...,m$$
 
$$\lambda_i \succeq 0, \ i=1,...,m$$

## **5.40**

 $\rm E$  - optimal experiment design. A variation on two optimal experiment design problems of exercise 5.10 is the  $\rm E$  - optimal design problem:

minimize 
$$\lambda_{max}(\sum_{i=1}^p x_i v_i v_i^T)^{-1}$$
 subject to 
$$x\succeq 0,\ \mathbf{1}^T x=1$$

(See also §7.5.) Derive a dual for this problem first by reformulating it as:

minimize 
$$\frac{1/t}{\sum_{i=1}^{p} x_i v_i v_i^T \succeq t \boldsymbol{I}}$$
 subject to 
$$\sum_{i=1}^{p} x_i v_i v_i^T \succeq t \boldsymbol{I}$$
 
$$x \succeq 0, \ \boldsymbol{1}^T x = 1$$

with variables  $t \in R$ ,  $x \in R^p$  and domain  $R_{++} \times R^p$ , and applying Lagrange duality. Simplify the dual problem as much as you can.

Solution: Let us introduce a variable  $t \in R_{++}$ . Then for a matrix A, inequality  $\lambda_{max}(A^{-1}) \leq 1/t$  means  $A^{-1} \leq \frac{1}{t}I$ , or  $A \leq tI$ . Setting A to  $\sum_{i=1}^p x_i v_i v_i^T$  we get a problem:

minimize 
$$1/t$$
 subject to 
$$\sum_{i=1}^p x_i v_i v_i^T \succeq t \boldsymbol{I}$$
 
$$x \succeq 0, \ \boldsymbol{1}^T x = 1$$

The Lagrangian is:

$$L(x, t, Z, z) = 1/t - tr(Z(\sum_{i=1}^{p} x_i v_i v_i^T - t\mathbf{I})) - z^T x + \nu(\mathbf{1}^T x - 1) = 1/t + t tr(Z) + \sum_{i=1}^{p} x_i (-v_i^T Z v_i - z_i + \nu) - \nu$$

the infimum of x is bounded below only if  $-v_i^T Z v_i - z_i + \nu = 0$ . The

$$inf_{\nu}1/t + t \operatorname{tr}(Z) = \begin{cases} 2\sqrt{\operatorname{tr}(Z)}, & Z \succeq 0\\ -\infty, & \text{otherwise} \end{cases}$$

the dual function is

$$L(Z, z, \nu) = \begin{cases} 2\sqrt{tr(Z)} - \nu, & Z \succeq 0, \ -v_i^T Z v_i - z_i + \nu = 0, \\ -\infty, & \text{otherwise} \end{cases}$$

The dual problem:

maximize 
$$2\sqrt{tr(Z)} - \nu$$
 subject to 
$$v_i^T Z v_i + z_i \leq 0, \ i=1,...,p$$
 
$$Z \succeq 0, \ \nu \geq 0$$

We can define  $W = (1/\nu)Z$ 

maximize 
$$2\sqrt{\nu}\sqrt{tr(W)} - \nu$$
 subject to 
$$v_i^T W v_i \leq 1, \ i = 1, ..., p$$
 
$$W \succeq 0, \ \nu \geq 0$$

Maximizing over  $\nu$  we get  $\nu = tr(W)$ , so the problem is:

maximize 
$$tr(W)$$
 subject to 
$$v_i^T W v_i \leq 1, \ i=1,...,p$$
 
$$W \succ 0$$

### 6.3

Formulate the following approximation problems as LPs, QPs, SOCPs, or SDPs. The problem data are  $A \in \mathbb{R}^{n \times m}$  and  $b \in \mathbb{R}^m$ . The rows of A are denoted  $a_i^T$ .

(a) Deadzone-linear penalty approximation: minimize  $\sum_{i=1}^{m} \phi(a_i^T x - b_i)$ , where

$$\phi(u) = \begin{cases} 0, & |u| \le a \\ |u| - a, & |u| > a \end{cases}$$

where a > 0.

(b) Log-barrier penalty approximation: minimize  $\sum_{i=1}^{m} \phi(a_i^T x - b_i)$ , where

$$\phi(u) = \begin{cases} -a^2 log(1 - (u/a)^2), & |u| < a \\ \infty, & |u| \ge a \end{cases}$$

with a > 0.

(c) Huber penalty approximation: minimize  $\sum_{i=1}^{m} \phi(a_i^T x - b_i)$ , where

$$\phi(u) = \begin{cases} u^2, & |u| \le M \\ M(2|u| - M), & |u| > M \end{cases}$$

with M > 0.

(d) Log-Chebyshev approximation: minimize  $\max_{i=1,\dots,m} |log(a_i^T x) - log(b_i)|$ . We assume  $b \succ 0$ . An equivalent convex from is

minimize 
$$t$$
 subject to 
$$1/t \le a_i^T x/b_i \le t, \ i = 1, ..., m$$

with variables  $x \in \mathbb{R}^n$  and  $t \in \mathbb{R}$  and domain  $\mathbb{R}^n \times \mathbb{R}_{++}$ .

(e) Minimizing the sum of the largest k residuals:

minimize 
$$\sum_{i=1}^{k} |r|_{[i]}$$
 subject to 
$$r = Ax - b$$

where  $|r|_{[1]} \geq |r|_{[2]} \geq,..., \geq |r|_{[m]}$  are the numbers  $|r_1|, |r_2|,..., |r_m|$  sorted in decreasing order. (For k=1 this reduces to  $l_{\infty}$  - norm approximation; for k=m this reduces to  $l_1$  norm approximation.) Hint: See exercise 5.19.

Solution:

(a) Introduce the variable  $y \in R^m$  so that  $|a_i^T x - b_i| \le |a + y_i|, y_i \ge 0$  then we have equivalent problem:

minimize 
$$\mathbf{1}^T y$$
 subject to 
$$-y-a\mathbf{1} \preceq Ax-b \preceq y+a\mathbf{1}$$
 
$$y \succeq 0$$

(b)

Introduce the variable y = Ax - b,  $t_i \le (1 - y_i/a)(1 + y_i + a)$ , and add inequality  $-a \le y_i \le a$  this problem will transform to:

maximize 
$$\prod_{i=1}^m t_i^2$$
 subject to 
$$y=Ax-b$$
 
$$t_i \leq (1-y_i/a)(1+y_i/a), \ i=1,...,m$$
 
$$-1 \leq y_i/a \leq 1, \ i=1,...,m$$

with variables  $t, y \in \mathbb{R}^m$ ,  $x \in \mathbb{R}^n$ . Next assume that  $m = 2^k$ . It can be done without loss of generality, as in other case we always can add missing components of  $y_i$  as unity values  $(a_i = 0 \text{ and } b_i = -1)$ . Lets transform this problem for m = 4.

maximize 
$$(t_1t_2t_3t_4)^2$$
 subject to 
$$y = Ax - b$$
 
$$t_i \leq (1 - y_i/a)(1 + y_i/a), \ i = 1, ..., m$$
 
$$-1 \leq y_i/a \leq 1, \ i = 1, ..., m$$

this problem is equivalent to:

maximize 
$$z_1z_2$$
 subject to 
$$z_1^2 \leq t_1t_2$$
 
$$z_2^2 \leq t_3t_4$$
 
$$y = Ax - b$$
 
$$t_i \leq (1-y_i/a)(1+y_i/a), \ i=1,...,m$$
 
$$-1 \leq y_i/a \leq 1, \ i=1,...,m$$

and also as:

maximize 
$$z$$
 subject to 
$$z^2 \leq z_1 z_2$$
 
$$z_1^2 \leq t_1 t_2$$
 
$$z_2^2 \leq t_3 t_4$$
 
$$y = Ax - b$$
 
$$t_i \leq (1 - y_i/a)(1 + y_i/a), \ i = 1, ..., m$$
 
$$-1 \leq y_i/a \leq 1, \ i = 1, ..., m$$

as it is easy to show that  $x^Tx \leq yz$  where  $x \in R^n, y, z \in R_+$  is equivalent to:

$$\left\| \begin{bmatrix} x \\ y - z \end{bmatrix} \right\|_2 \le y + z$$

overriding the first three inequalities with their norm analogue we have:

minimize 
$$-z$$
subject to 
$$\left\| \begin{bmatrix} z \\ z_1 - z_2 \end{bmatrix} \right\|_2 \le z_1 + z_2$$

$$\left\| \begin{bmatrix} z_1 \\ t_1 - t_2 \end{bmatrix} \right\|_2 \le t_1 + t_2$$

$$\left\| \begin{bmatrix} z_2 \\ t_3 - t_4 \end{bmatrix} \right\|_2 \le t_3 + t_4$$

$$y = Ax - b$$

$$t_i \le (1 - y_i/a)(1 + y_i/a), \ i = 1, ..., m$$

$$-1 \le y_i/a \le 1, \ i = 1, ..., m$$

which is Second Order Cone Program (SOCP).

(c) Lets show that this problem is equivalent to QP:

minimize 
$$\sum_{i=1}^{m} (u_i^2 + 2Mv_i)$$
 subject to 
$$-u - v \preceq Ax - b \preceq u + v$$
 
$$0 \preceq u \preceq M\mathbf{1}$$
 
$$v \succ 0$$

Proof: Lets fix x in our QP. For the optimum point we must have  $u_i + v_i = |a_i^T x - b_i|$ . In other case, if  $u_i + v_i > |a_i^T x b_i|$  and  $0 \le u_i \le M$  and  $v_i \ge 0$ , then as  $u_i$  and  $v_i$  are not both zero, we can decrease  $u_i$  and/or  $v_i$  without violating the constraints and the objective will be decreased also. So, at the optimum we have:

$$v_i = |a_i^T x - b_i| - u_i$$

Eliminating  $v_i$  yields equivalent problem:

minimize 
$$\sum_{i=1}^{m} (u_i^2 - 2Mu_i + 2M|a_i^T x - b_i|)$$
 subject to 
$$0 \leq u_i \leq \min(M, |a_i^T x - b_i|)$$

It  $M > |a_i^T x - b_i|$  the optimal choice for  $u_i$  is  $|a_i^T x - b_i|$ . In this case the objective function reduces to  $|a_i^T x - b_i|^2$ . Otherwise the optimal choice for  $u_i$  is M, and the objective function reduces to  $2M|a_i^T x - b_i| - M^2$ . So, we conclude that with  $\phi(a_i^T x - b_i)$  these problems are equivalent.