Solutions to hw1 homework on Convex Optimization

https://web.stanford.edu/class/ee364b/homework.html

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1.1 (3 points)

For each of the following convex functions, determine the subdifferential set at the specified point.

(a)
$$f(x_1, x_2, x_3) = max(|x_1|, |x_2|, |x_3|)$$
 at $(x_1, x_2, x_3) = (0, 0, 0)$.

(b)
$$f(x) = e^{|x|}$$
 (x is scalar)

(c)
$$f(x_1, x_2) = max(x_1 + x_2 - 1, x_1 - x_2 + 1)$$
 at $(x_1, x_2) = (1, 1)$.

- (a) There will be a gap in differential at the points $\{x_1 = \pm x_2, x_2 = \pm x_3, x_1 = \pm x_3\}$. Subdifferential set $g(0,0,0) = \{[-1,1],[-1,1]\}$.
- (b) There will be a gap in differential at the point x = 0. Subdifferential set $g(0) = [-e^0, e^0] = [-1, 1]$.
- (c) There will be a gap in differential at the points $\{x_1+x_2-1=x_1-x_2+1\}$. Subdifferential set $g(1,1)=\{1,[-1,1]\}$.

1.3 (2 points)

Convex functions that are not subdifferentiable. Verify that the following functions, defined on the interval [0;1), are convex, but not subdifferentiable at x=0. (Hint: You can prove by contradiction.)

(a)
$$f(0) = 1$$
 and $f(x) = 0$ for $x > 0$.

(b)
$$f(x) = -x^p$$
 for some $p \in (0, 1)$

Solution.

- (a) Proof by contradiction. Suppose what function f(0) = 1 and f(x) = 0 for x > 0. has a supporting hyperplane at point x = 0, and g is the subgradient of f(x) in this point. Then at $x \ge 0$ the equation $f(x) \ge f(0) + gx$ must hold. For x > 0 this equation become $0 \ge 1 + gx$ or $gx \le -1$ for $x \ge 0$. This is impossible, because at x = 0 we must have $0 \le -1$ then.
- (b) Proof by contradiction. Suppose what function $f(x) = -x^p$ for some $p \in (0,1)$ has a supporting hyperplane at point x = 0, and g is the subgradient of f(x) in this point. Then $\forall x \geq 0$ the equation $f(x) \geq f(0) + gx$ must hold. This is impossible, as f(0) is ∞ (i.e. unlimited) and f(x) has a limited value, i.e g should be unlimited in this case.

1.2 (7 points)

For each of the following convex functions, explain how to calculate a subgradient at a given x.

(a)
$$f(x) = \max_{i=1,...,m} (a_i^T x + b_i).$$

(b)
$$f(x) = \max_{i=1,...,m} (|a_i^T x + b_i|)$$

(c) $f(x) = \max_{i=1,...,m} (-\log(a_i^T x + b_i)$. You may assume x is in the domain of f.

(d)
$$f(x) = \max_{0 \le t \le 1} (p(t))$$
 where $p(t) = x_1 + x_2t + \dots + x_nt^{n-1}$.

(e)
$$f(x) = x_{[1]} + \cdots + x_{[k]}$$
 where $x_{[i]}$ denotes the i - th largest element of x .

- (f) $f(x) = \min_{Ay \leq b} (||x^2 y^2||)$, , i.e., the square of the distance of x to the polyhedron defined by $Ay \leq b$. You may assume that the inequalities $Ay \leq b$ are strictly feasible. (Hint: You may use duality, and then use subgradient the rule for pointwise maximumum.
- (g) $f(x) = \max_{Ay \leq b}(y^t x)$, x, i.e., the optimal value of an LP as a function of the cost vector. (You can assume that the polyhedron defined $Ay \leq b$ is bounded.) (Hint: You may use the subgradient rule for pointwise maximum.