

view_frames Result
Recorded at time: 4393.614

map

Broadcaster: /pioneer1/amcl
Average rate: 35.392 Hz
Most recent transform: 4394.573 (-0.959 sec old)
Buffer length: 2.769 sec

pioneer1/odom

Broadcaster: /gazebo
Average rate: 100.357 Hz
Most recent transform: 4393.606 (0.008 sec old)
Buffer length: 2.800 sec

pioneer1/base_link

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 153.874 Hz
Most recent transform: 4393.607 (0.007 sec old)
Buffer length: 2.801 sec

pioneer1/left_wheel

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/left_hub

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 153.874 Hz
Most recent transform: 4393.607 (0.007 sec old)
Buffer length: 2.801 sec

pioneer1/right_wheel

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/right_hub

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/back_sonar

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/front_sonar

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/top_plate

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/hokuyo_link

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 10.363 Hz
Most recent transform: 4393.579 (0.035 sec old)
Buffer length: 2.702 sec

pioneer1/swivel

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 10.363 Hz
Most recent transform: 4393.579 (0.035 sec old)
Buffer length: 2.702 sec

pioneer1/center_wheel

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/center_hubcap

Broadcaster: /pioneer1/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.599 (0.015 sec old)
Buffer length: 2.780 sec

pioneer1/chassis

Broadcaster: /pioneer2/amcl
Average rate: 40.087 Hz
Most recent transform: 4394.588 (-0.974 sec old)
Buffer length: 2.769 sec

pioneer2/odom

Broadcaster: /gazebo
Average rate: 100.357 Hz
Most recent transform: 4393.610 (0.004 sec old)
Buffer length: 2.800 sec

pioneer2/base_link

Broadcaster: /gazebo
Average rate: 149.589 Hz
Most recent transform: 4393.611 (0.003 sec old)
Buffer length: 2.801 sec

pioneer2/right_wheel

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/right_hub

Broadcaster: /gazebo
Average rate: 149.589 Hz
Most recent transform: 4393.611 (0.003 sec old)
Buffer length: 2.801 sec

pioneer2/left_wheel

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/left_hub

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/back_sonar

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/front_sonar

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/top_plate

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/hokuyo_link

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 9.993 Hz
Most recent transform: 4393.579 (0.035 sec old)
Buffer length: 2.702 sec

pioneer2/swivel

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 9.993 Hz
Most recent transform: 4393.579 (0.035 sec old)
Buffer length: 2.702 sec

pioneer2/center_wheel

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/center_hubcap

Broadcaster: /pioneer2/robot_state_publisher
Average rate: 50.360 Hz
Most recent transform: 4393.601 (0.013 sec old)
Buffer length: 2.780 sec

pioneer2/chassis