

Raspberry Pi wireless communication

Initial objective [🔗](#)

The goal was to establish wireless communication between a computer (running ROS) and a Raspberry Pi using ROS topics. The computer would act as the **publisher** and the Raspberry Pi as the **subscriber**, both communicating over Wi-Fi.

Issue encountered [🔗](#)

While attempting to implement ROS communication, a key issue arose:

- The computer uses Ubuntu on WSL2, which creates a separate virtual network (subnet) from the physical network.
- As a result, the Raspberry Pi and the computer could not directly communicate over ROS.

Alternative solution adopted [🔗](#)

To overcome this network limitation, a functional alternative was implemented using Python scripts with TCP sockets. This approach maintains the core objective of enabling wireless communication and simulates the publisher/subscriber model.

Steps taken [🔗](#)

1. Network setup [🔗](#)

- Both the computer and the Raspberry Pi were connected to the **same Wi-Fi network**.

📌 For the connection between both devices to be successful, it is necessary to disable the firewall on the computer.

- To get the IP on a Windows system check the IPv4 row executing the `ipconfig` command in the command prompt (cmd):

```
1 ipconfig
2 [...]
3 Wireless LAN adapter WiFi:
4
5     Connection-specific DNS Suffix  . :
6     Link-local IPv6 Address . . . . . : fe80::bbfe:6a34:a2c0:d8fe%15
7     IPv4 Address. . . . . : 192.168.1.138
8     Subnet Mask . . . . . : 255.255.255.0
9     Default Gateway . . . . . : 192.168.1.1
```

In modern Linux-based OS, it is possible to use `ip a` in a similar fashion.

- Network connectivity was confirmed using `ping` from the computer to the Raspberry Pi.

```
1 pc to raspberry ping 192.168.1.139
2
3 Haciendo ping a 192.168.1.139 con 32 bytes de datos:
4 Respuesta desde 192.168.1.139: bytes=32 tiempo=8ms TTL=64
5 Respuesta desde 192.168.1.139: bytes=32 tiempo=9ms TTL=64
6 Respuesta desde 192.168.1.139: bytes=32 tiempo=9ms TTL=64
```

```
1 raspberry to pc ping 192.168.1.135
2 PING 192.168.1.135 (192.168.1.135) 56(84) bytes of data.
3 64 bytes from 192.168.1.135: icmp_seq=1 ttl=128 time=5.84 ms
4 64 bytes from 192.168.1.135: icmp_seq=2 ttl=128 time=9.38 ms
5 64 bytes from 192.168.1.135: icmp_seq=3 ttl=128 time=4.99 ms
```

```
6 ^C
7 --- 192.168.1.135 ping statistics ---
8 3 packets transmitted, 3 received, 0% packet loss, time 5ms
9 rtt min/avg/max/mdev = 4.988/6.736/9.379/1.902 ms
```

 Mind that the local IP addresses most likely will differ from different execution/connections to the network.

2. Code Implementation [↗](#)

Publisher `script` (Windows `computer`) [↗](#)

The following `Python` script was used to run the **publisher** on the `Windows` machine. It opens a server `socket`, accepts incoming connections, and allows the user to type messages that are sent to the connected client:

```
1 import socket
2 import threading
3
4 HOST = '0.0.0.0'
5 PORT = 65432
6
7 clients = []
8 clients_lock = threading.Lock()
9
10 def handle_client(conn, addr):
11     print(f"[Connected by {addr}]")
12     try:
13         while True:
14             data = conn.recv(1024)
15             if not data:
16                 break
17             print(f"Message received from {addr}: {data.decode()}")
18     except ConnectionResetError:
19         print(f"Connection closed by {addr}")
20     finally:
21         with clients_lock:
22             clients.remove(conn)
23         conn.close()
24         print(f"Connection with {addr} closed")
25
26 with socket.socket(socket.AF_INET, socket.SOCK_STREAM) as s:
27     s.bind((HOST, PORT))
28     s.listen()
29     print(f"[Server listening on {HOST}:{PORT}]")
30
31     def accept_clients():
32         while True:
33             conn, addr = s.accept()
34             with clients_lock:
35                 clients.append(conn)
36             threading.Thread(target=handle_client, args=(conn, addr), daemon=True).start()
37
38     threading.Thread(target=accept_clients, daemon=True).start()
39
40     print("You can send messages to all connected clients.")
41
42     while True:
43         msg = input("Message to send: ")
```

```
44     with clients_lock:
45         for client in clients:
46             try:
47                 client.sendall(msg.encode())
48             except Exception as e:
49                 print(f"Error sending to client: {e}")
```

Subscriber script (Raspberry Pi) [🔗](#)

The following Python script was used to run the **subscriber** on the Raspberry Pi . It connects to the publisher's IP and prints any messages received:

```
1  import socket
2
3  WINDOWS_IP = '192.168.1.135'
4  PORT = 65432
5  with socket.socket(socket.AF_INET, socket.SOCK_STREAM) as s:
6      s.connect((WINDOWS_IP, PORT))
7      print(f"Connected to the server at {WINDOWS_IP}:{PORT}")
8      while True:
9          data = s.recv(1024)
10         if not data:
11             print("Connection closed by the server.")
12             break
13         print("Message received:", data.decode())
```

3. Functionality test [🔗](#)

- The publisher script was executed on the Windows computer.

```
1  py publisher_server_windows.py
```

- The subscriber script was ran on the Raspberry Pi .

```
1  python3 subscriber_raspberry.py
```

- Messages typed in the publisher were displayed in real time on the Raspberry Pi terminal.

Output on Raspberry Pi :

```
1  Connected to the server at 192.168.1.135:65432
2  Message received: hello
3  Message received: bye
```