

Example 1

The script is presented with values for the transition matrix “a0” and initial state (within braces {} in “p0”) corresponding to Example 1 (Figs. 2 and 3 of the article):

```
a0 = {{1, 0, 0, 0}, {0.2, 0.1, 0.2, 0.5}, {0, 0.4, 0.4, 0.2}, {0.4, 0.3, 0, 0.3}};
```

```
p0 = DiscreteMarkovProcess[{0, 1/3, 1/3, 1/3}, a0];
```

To obtain the simulations corresponding to Examples 2 and 3 (Figs. 4 and 5 of the article) you must change the values of the transition matrix and initial state vector according to the data provided in section 3 of the article:

Example 2

```
a0 = {{1, 0, 0, 0, 0, 0, 0}, {0.1, 0, 0.3, 0.6, 0, 0, 0}, {0, 0.1, 0.5, 0.4, 0, 0, 0}, {0, 0.4, 0.6, 0, 0, 0, 0},  
{0.5, 0, 0, 0, 0.4, 0.1, 0}, {0, 0, 0, 0, 0.2, 0, 0.8}, {0, 0, 0, 0, 0.5, 0.3, 0.2}};
```

For FPT distribution corresponding to Fig 4 (below left), set initial state vector

```
p0 = DiscreteMarkovProcess[{0, 0, 0, 0, 1/3, 1/3, 1/3}, a0];
```

For FPT distribution corresponding to Fig 4 (below right), set initial state vector

```
p0 = DiscreteMarkovProcess[{0, 1/3, 1/3, 1/3, 0, 0, 0}, a0];
```

Example 3

```
a0 = {{1, 0, 0, 0, 0, 0, 0}, {0.1, 0, 0.3, 0.6, 0, 0, 0}, {0, 0.1, 0.5, 0.4, 0, 0, 0}, {0, 0.4, 0, 0, 0, 0, 0.6},  
{0.5, 0, 0, 0, 0.4, 0.1, 0}, {0, 0, 0, 0, 0.2, 0, 0.8}, {0, 0, 0, 0, 0.5, 0.3, 0.2}};
```

For FPT distribution corresponding to Fig 5, set initial state vector

```
p0 = DiscreteMarkovProcess[{0, 1/3, 1/3, 1/3, 0, 0, 0}, a0];
```