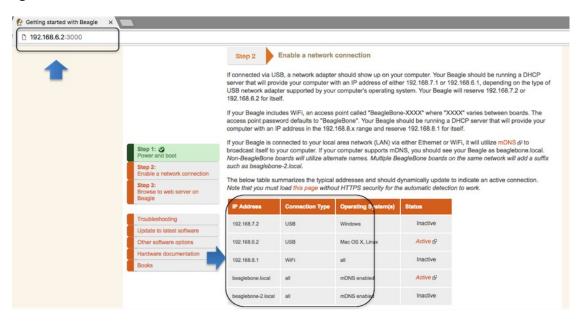


PocketBeagle® TechLab Cape Hands-On Coding Workshop

MicroSD software image and other materials available from bbb.io/techlab

See **bbb.io/start** for instructions on using Etcher.io to write a microSD card





Plug into the microUSB on PocketBeagle to provide power and a network connection. Look for the "heartbeat" pulse on the USR0 LED to know the board has Linux up-and-running.

Get to the Cloud9 IDE

- Served on port 3000
- Windows: http://192.168.7.2:3000
- Linux/Mac: http://192.168.6.2:3000

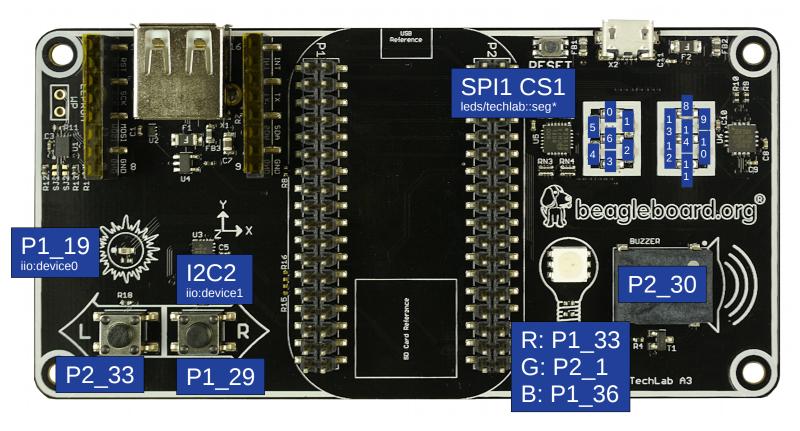


The **BeagleBoard.org Foundation** is a 501(c)(3) non-profit corporation existing to provide education in and collaboration around the design and use of open-source software and hardware in embedded computing.

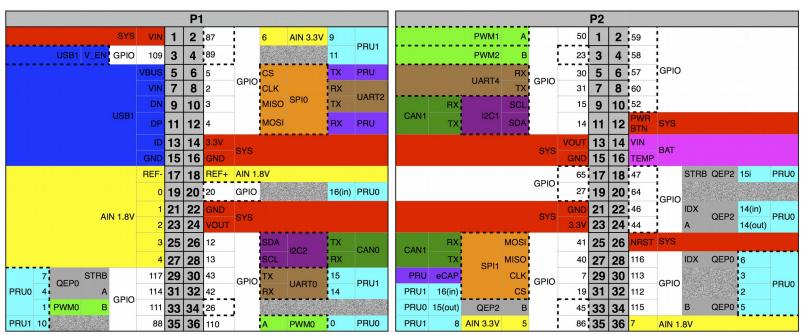


PocketBeagle® TechLab Cape Hands-On Coding Workshop

TechLab Wiring Summary



PocketBeagle Expansion Header Pin-out



Blink PocketBeagle on-board USRx LED

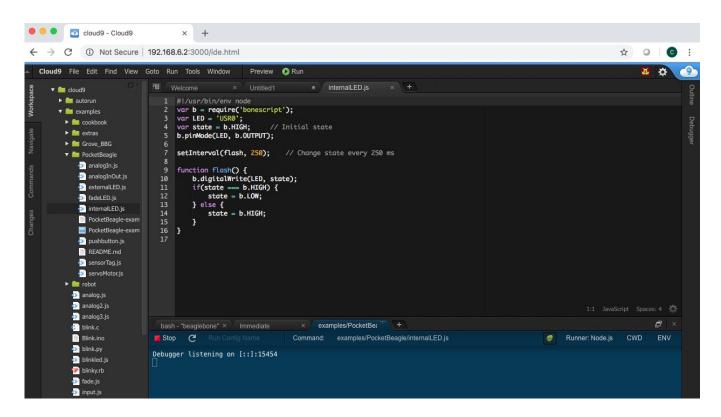
Goal: Blink USR3 LED on PocketBeagle.

Overview: BoneScript is a Node.js library customized for the Beagle family and featuring familiar Arduino function calls. Here we will use it to blink an LED built into your PocketBeagle.

Do this in the Cloud9 IDE:

- 1. Navigate to **TechLab/internalLED.js** and double-click on it.
- 2. Click the Run button in the toolbar to execute the script in the active file window
- 3. You will see the run configuration window open with a Stop button. Click the Stop button to halt the program.
- 4. Try changing the LED or blink time, save the program and run again.

TIP: Click the green bug to disable the debugger and begin execution quicker.



internalLED.js

}



Read a button

Goal: Sense the external world by reading a digital input.

Overview: Reading a switch attached to a GPIO (general purpose input/output) port is as easy as configuring the port as an input and attaching an interrupt handler to it. Note the buttons are "active low".

Do this in the Cloud9 IDE:

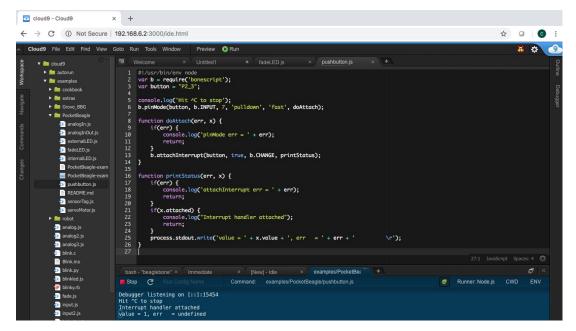
- 1. Navigate to **TechLab/pushbutton.js** and double-click on it.
- 2. Click the Run button in the toolbar to execute the script in the active file window
- 3. Press the "L" button on TechLab and check the output in the configuration window. Click the Stop button on the IDE to halt the program.

Challenge #1: Can you modify the program to read from the "R" button?

Challenge #2: Can you modify the program to toggle the USR3 LED?

Challenge #3: Can you modify the program to turn the USR3 LED on with the "L" button and off with the "R"

button?



pushbutton.js

```
#!/usr/bin/env node
var b = require('bonescript');
var button = "P2_33";
console.log('Hit ^C to stop');
b.pinMode(button, b.INPUT, 7, null, null, doAttach);
function doAttach(err, x) {
  if(err)
    consóle.log('pinMode err = ' + err);
     return:
    .attachInterrupt(button, true, b.CHANGE, printStatus);
function printStatus(err, x) {
  it(err)
     consóle.log('attachInterrupt err = ' + err);
     return;
  if(x.attached) {
  console.log("Interrupt handler attached");
     return:
  process.stdout.write('value = ' + x.value + '
                                                                    \r');
```

Read an analog sensor

Goal: Sense the external world by reading a variable analog input **Overview:** Reading a light sensor attached to an analog input pin.

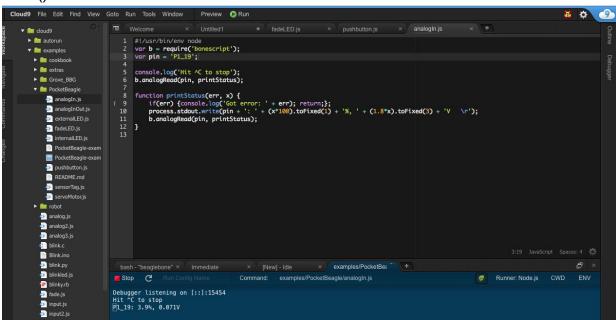
Do this in the Cloud9 IDE:

- 1. Navigate to **TechLab/analogIn.js** and double-click on it.
- 2. Click the Run button in the toolbar to execute the script in the active file window
- 3. Cover the light sensor and check the output in the configuration window. Click the Stop button to halt the program.

Challenge #1: Can you change how often the light sensor is read? What happens and why?

Challenge #2: Can you activate the USR3 LED based upon a voltage threshold from the light sensor?

Challenge #3: Try using the I2C accelerometer input from /sys/bus/iio/devices/iio:device1/in_accel_x_raw. Hint: use b.readTextFile()



analogIn.js

```
#!/usr/bin/env node
var b = require('bonescript');
var pin = 'P1_19';

console.log('Hit ^C to stop');
doAnalogRead();

function printStatus(err, x) {
   if(err) {console.log('Got error: ' + err); return;};
   process.stdout.write(pin + ': ' + (x*100).toFixed(1) +
        '%, ' + (1.8*x).toFixed(3) + 'V \r');
   setTimeout(doAnalogRead, 100);
}

function doAnalogRead() {
   b.analogRead(pin, printStatus);
}
```

Fade an LED

Goal: Utilize a hardware pulse-width-modulator (PWM) to light an LED with variable brightness

Overview: Linux provides LED drivers that understand how to utilize PWM drivers, making use of PocketBeagle's built-in PWM hardware. They are controlled with simple text files where you can set the brightness.

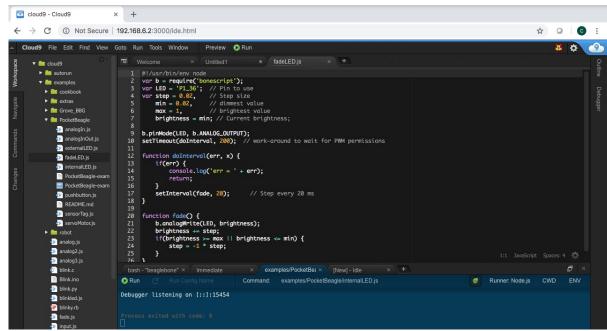
Do this in the Cloud9 IDE:

- 1. Navigate to **TechLab/fadeLED.js** and double-click on it.
- 2. Click the Run button in the toolbar to execute the script in the active file window
- 3. You will see the run configuration window open with a Stop button. Click the Stop button to halt the program.

Challenge #1: Try changing the fade interval, save the program and run again.

Challenge #2: Try using the light sensor input to set the LED brightness.

Challenge #3: Try using the I2C accelerometer input for all 3 color LEDs...



fadeLED.js

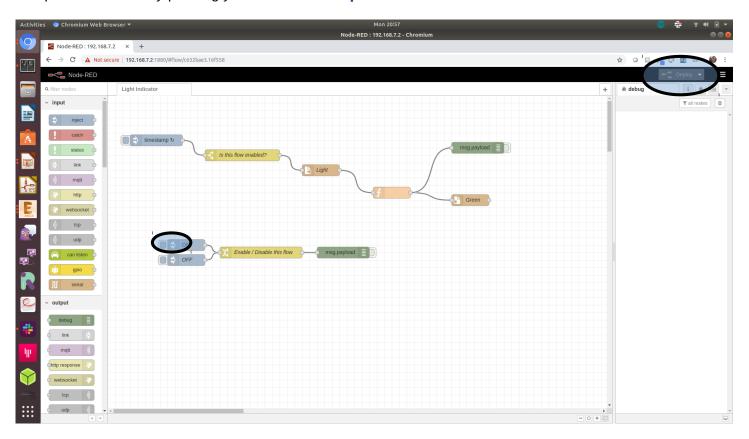
Using Node-RED to read and write files

Goal: Read light sensor data and output to green LED brightness

Overview: Node-RED is a flow-based development tool developed originally by IBM for wiring together hardware devices, APIs and online services as part of the Internet of Things. Node-RED provides a browser-based flow editor, which can be used to create JavaScript functions. Linux turns devices into virtual files, making Node-RED well suited to interacting with the physical world.

Do this:

1. Open Node-RED by pointing your browser to http://192.168.7.2:1880



- 2. Make sure the big "DEPLOY" button in the top right corner is greyed-out by clicking it. This makes sure any changes you've made have been started on your PocketBeagle. The program will run continuously.
- 3. Click the highlightable button to the left of the "ON". Cover the light sensor to notice the brightness of the green LED adjust.
- 4. Try double-clicking on each node to see the parameters used for the demo.
- 5. Click the highlightable button to the left of the "OFF" to stop adjusting the brightness of the green LED.
- 6. Explore

Challenge #1: Try updating the blue LED rather than the green LED. Remember to click the "DEPLOY" button to save and run your changes.

Challenge #2: Try reading from the I2C accelerometer rather than the light sensor.

Challenge #3: Use a "gpio in" node to use the status of the "L" or "R" buttons to update the LED.

Explore the Linux command line

Goal: Learn to send several basic commands to the shell

Overview: The true power of Linux to automate many aspects of your life cannot be achieved without some utilization of the command line shell. The Cloud9 IDE makes it easy to access this directly from your web browser. Another great resource for learning is **linuxcommand.org**.

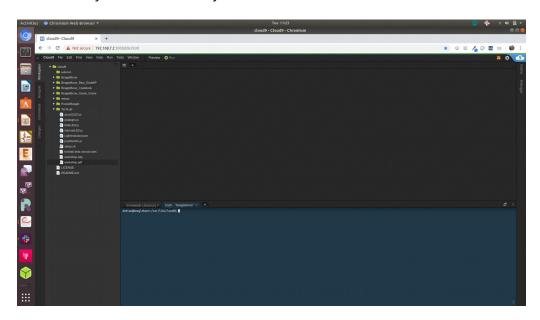
Do this in the Cloud9 IDE:

- 1. Click in the terminal window at the bottom half of the IDE. You can also open a new terminal by clicking the "+" in the window tabs and selecting "New Terminal".
- 2. Try typing in the "commands to try". Press <ENTER> after each command. Take note of how the prompt changes to show you the current active directory. Use the up and down arrows to cycle through commands you've typed before, in case you want to repeat any.

Challenge #1: Can you repeat the last command below that prints GPIO values and change the values?

Challenge #2: Using the "watch" command, can you monitor the I2C accelerometer status?

Challenge #3: Can you use the "config-pin" command to switch the red LED to a GPIO, set it high and low and then switch it back to PWM mode? What happens if the red LED is in GPIO mode and you change the brightness with the "/sys/class/leds" entry?



commands to try

cd /sys/class/leds
ls
echo 1 > techlab\:\:seg0/brightness
config-pin p1.33 pwm
echo 10 > techlab\:\:red/brightness

cd /sys/class/gpio
config-pin p1.29 gpio
cat gpio45/value gpio117/value

Some useful commands

pwd - show current directory cd - change current directory Is - list directory contents chmod - change file permissions chown - change file ownership cp - copy files mv - move files rm - remove files mkdir - make directory rmdir - remove directory cat - dump file contents less - progressively dump file vi - edit file (complex) nano - edit file (simple) head - trim dump to top tail - trim dump to bottom echo - print/dump value env - dump environment variables export - set environment variable history - dump command history grep - search dump for strings man - get help on command apropos - show list of man pages find - search for files tar - create/extract file archives gzip - compress a file gunzip - decompress a file du - show disk usage df - show disk free space mount - mount disks tee - write dump to file in parallel

hexdump - readable binary dumps