



Department of Computer Science and Engineering

Data Structures and Object-Oriented Design

(CSE – 2050)

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CSE-2050 – Data Structures and Object-Oriented Design

Trees

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Quick Recap

- Trees
 - Root, Parent, Child, leaf node, Depth/level, etc
- Binary Search Trees
 - Each node can have at most two child
 - Parent is greater than the left and smaller than the right
- Operations –
 - Insert
 - Search – Max, Min
 - Delete – Leaf node, Node having one child, Node having two children
- Traversal – Pre-order, In-order, Post-order

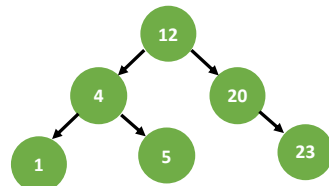
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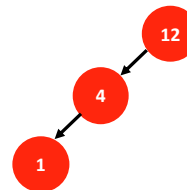
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Quick Recap

- Balanced and Imbalanced Trees



BALANCED TREE



IMBALANCED TREE

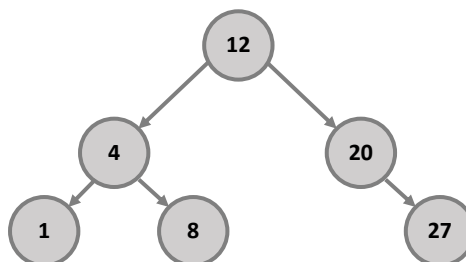


Binary Search Trees

- To determine whether the tree is balanced or not, we have to measure its height
- Height of a tree (or a node) is the longest path from the root (or from the node) to a leaf node

$$\text{height} = \max(\text{left child's height}, \text{right child's height}) + 1$$

The height of a NULL node is -1
 → leaf nodes have height 0.

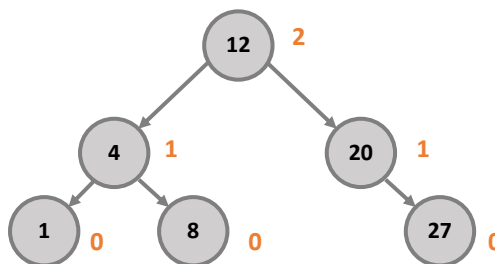


Binary Search Trees

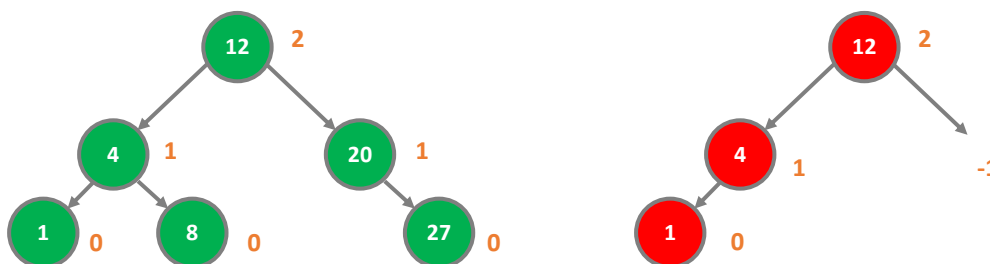
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Binary Search Trees

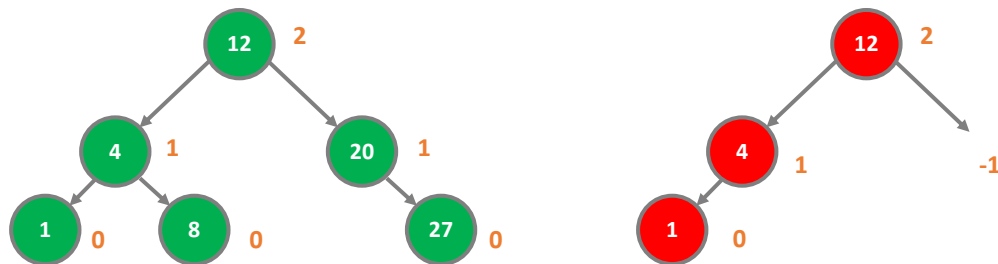


- Height of both trees is 2!

How can we determine programmatically which one of these trees is imbalanced?



Binary Search Trees



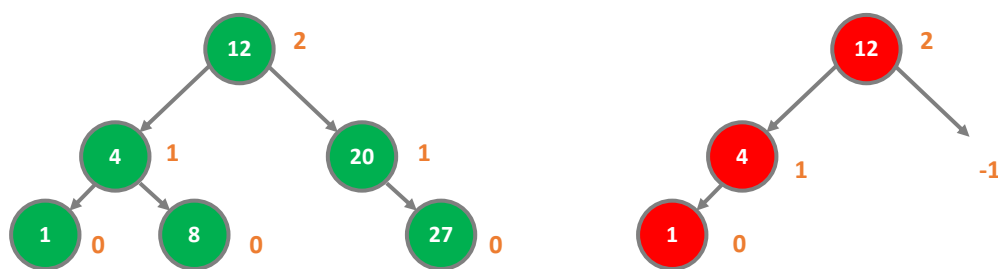
- Compare the heights of left and right subtrees by calculating the balance factor below:

$$\text{Balance factor: } h_{\text{left}} - h_{\text{right}}$$

- The tree heights on both sides can differ at most by 1



Binary Search Trees

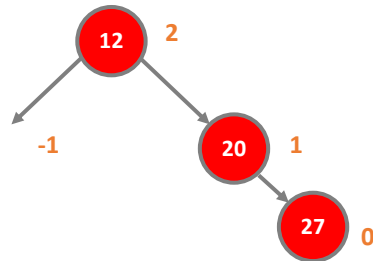


$$\text{Balance factor: } 1 - 1 = 0$$

$$\text{Balance factor: } 1 - (-1) = 2$$

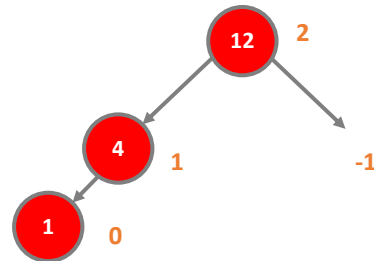


Binary Search Trees



Balance factor: $-1 - 1 = -2$

Right-heavy case
→ **Rotate left** to balance



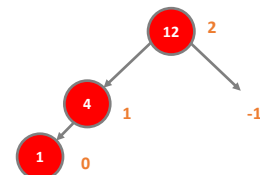
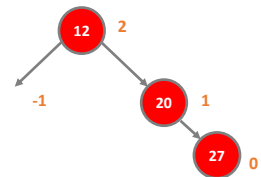
Balance factor: $1 - (-1) = 2$

Left-heavy case
→ **Rotate right** to balance



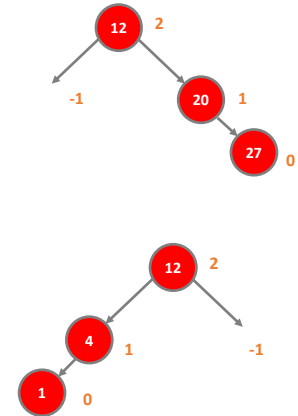
Binary Search Trees

- Keep tracking the height of each node in BST
- Calculate the balance factors for the nodes
- Make rotations if necessary to balance search trees
- -ve balance factor → right-heavy tree → rotate left
- +ve balance factor → left-heavy tree → rotate right



Binary Search Trees AVL Trees

- Keep tracking the height of each node in BST
- Calculate the balance factors for the nodes
- Make rotations if necessary to balance search trees
- -ve balance factor \rightarrow right-heavy tree \rightarrow rotate left
- +ve balance factor \rightarrow left-heavy tree \rightarrow rotate right
- Balanced data structure invented by Adelson-Velsky and Landis
- Has guaranteed $O(\log N)$ running time for all operations



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AVL Trees Rotations

- Right rotation on root node (with value 5)
- Left rotation on root node (with value 3)
- The BST properties remain same
- The in-order traversal remains same after rotations

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Trees

AVL Trees

Rotations
Case 1

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Trees

AVL Trees

Rotations
Case 1

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positive balance factors mean
left-heavy cases

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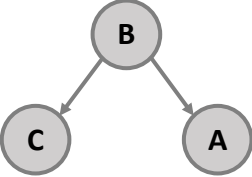
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AVL Trees


Rotations
Case 1

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```

graph TD
    B((B)) --> C((C))
    B --> A((A))
        
```

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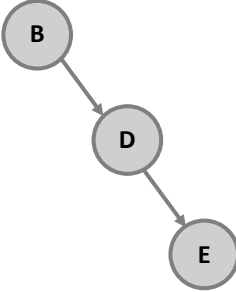
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AVL Trees


Rotations
Case 2

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```

graph TD
    B((B)) --> D((D))
    D --> E((E))
        
```

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AVL Trees Rotations

Case 2

negative balance factors mean
right-heavy cases

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AVL Trees Rotations

Case 2

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Trees

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AVL Trees Rotations

Case 3

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Trees

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AVL Trees Rotations

Case 3

Balance factor of root $\rightarrow 2$
 \rightarrow left-heavy

- Determine BF of left child
- if -ve
 - \rightarrow left-right heavy
 - \rightarrow Rotate parent left
 - \rightarrow Rotate grand-parent right
- if +ve
 - \rightarrow left-left heavy
 - \rightarrow Rotate grand-parent right

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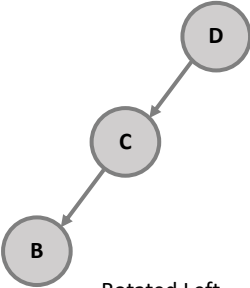
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AVL Trees

Rotations
Case 3

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Rotated Left

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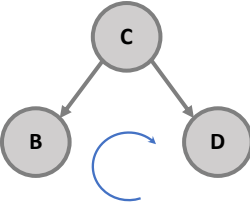
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AVL Trees

Rotations
Case 3

22



Rotated right

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AVL Trees

Rotations
Case 4

23

```

graph TD
    D((D)) --> F((F))
    F --> E((E))
        
```

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AVL Trees

Rotations
Case 4

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```

graph TD
    D((D)) --> NULL[NULL]
    D --> F((F))
    F --> E((E))
        
```

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Trees

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AVL Trees Rotations

Case 4

```
graph TD; D((D)) --> E((E)); E --> F((F));
```

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Trees

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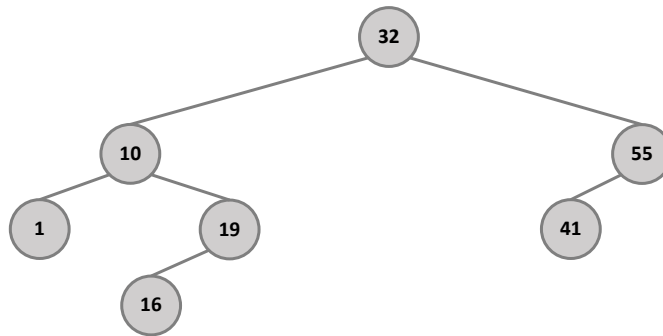
AVL Trees Rotations

Case 4

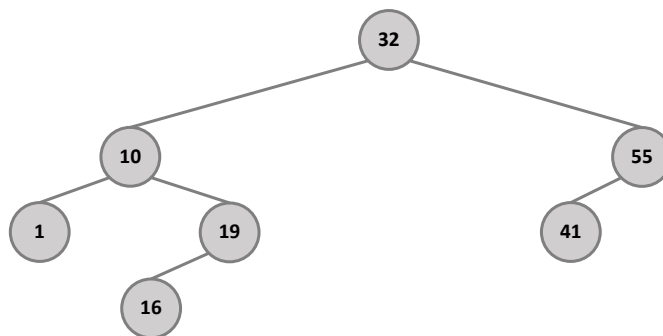
```
graph TD; E((E)) --> D((D)); E --> F((F));
```

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INSERT(12)



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AVL Trees Insertion
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INSERT(12)

```

graph TD
    32((32)) --- 10((10))
    32 --- 55((55))
    10 --- 1((1))
    10 --- 19((19))
    19 --- 16((16))
    55 --- 41((41))
        
```

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AVL Trees Insertion
30

INSERT(12)

```

graph TD
    32((32)) --- 10((10))
    32 --- 55((55))
    10 --- 1((1))
    10 --- 19((19))
    19 --- 16((16))
    55 --- 41((41))
        
```

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AVL Trees Insertion

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INSERT(12)

```
graph TD; 32((32)) --- 10((10)); 32 --- 55((55)); 10 --- 1((1)); 10 --- 19((19)); 19 --- 16((16)); 55 --- 41((41)); style 12 fill:#ffff00
```

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Trees

AVL Trees Insertion

32

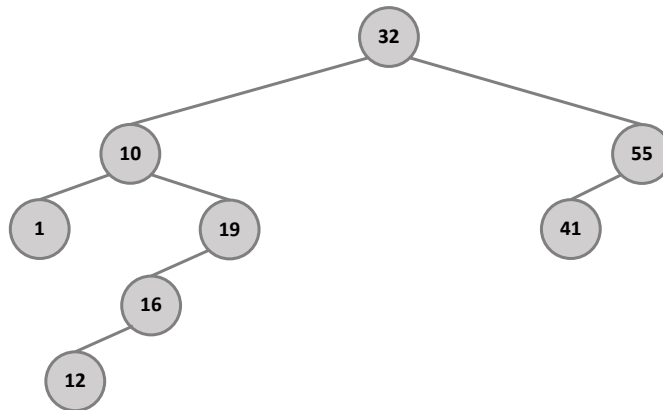
INSERT(12)

```
graph TD; 32((32)) --- 10((10)); 32 --- 55((55)); 10 --- 1((1)); 10 --- 19((19)); 19 --- 16((16)); 55 --- 41((41)); style 12 fill:#ffff00
```

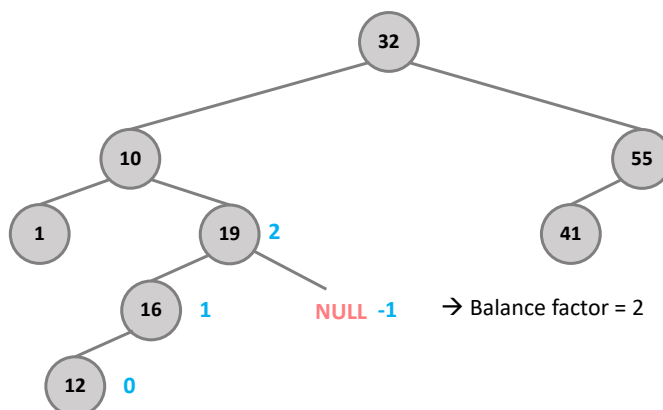
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32

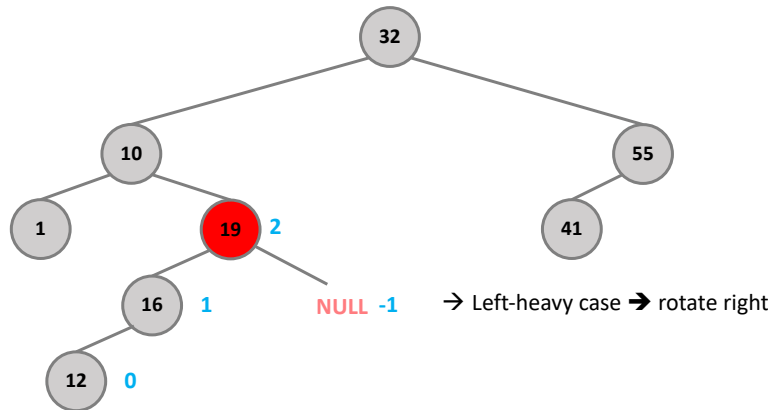
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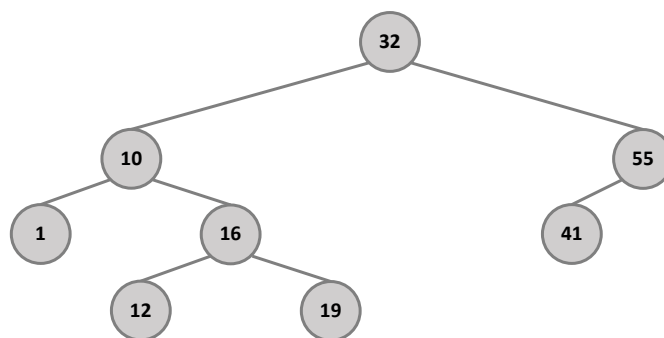
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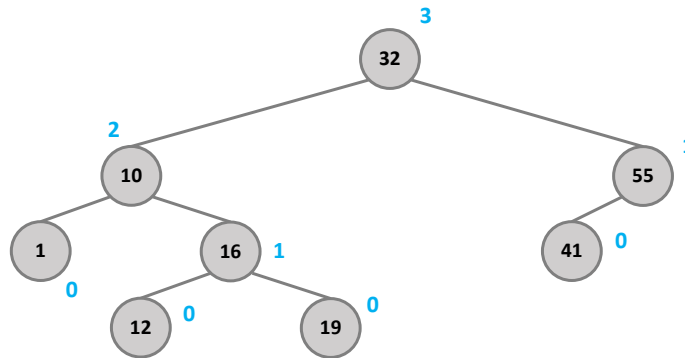
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INSERT(12)



INSERT(12)



Balance factor for every node differs by 1



- Implementation will be a part of assignment 3
 - Same as BST implementation except:
 - Height and Balance factor must be calculated for every node

