

Department of Computer Science and Engineering

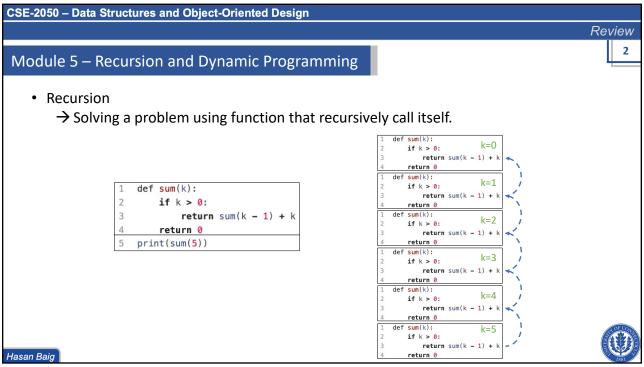
Data Structures and Object-Oriented Design

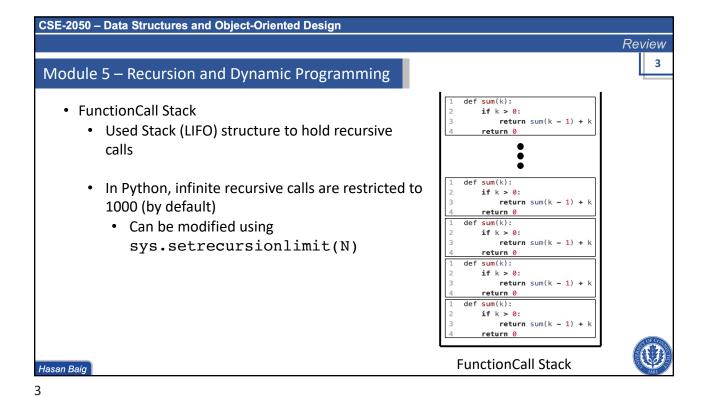
(CSE - 2050)

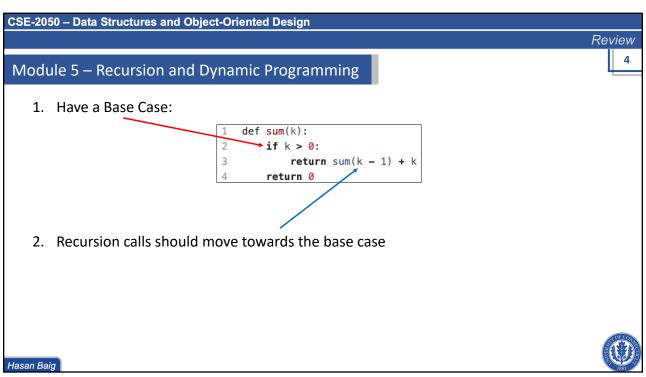
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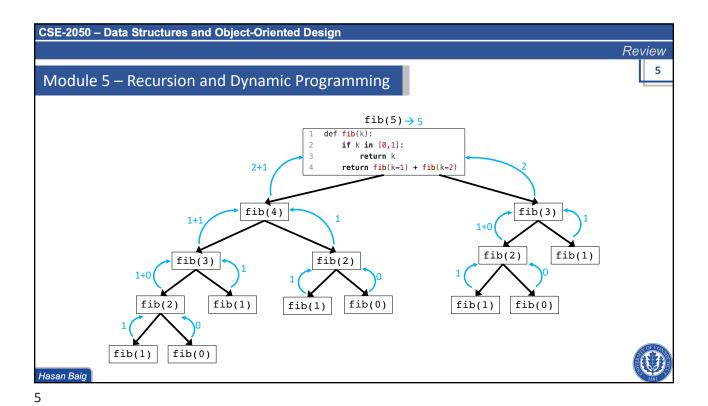
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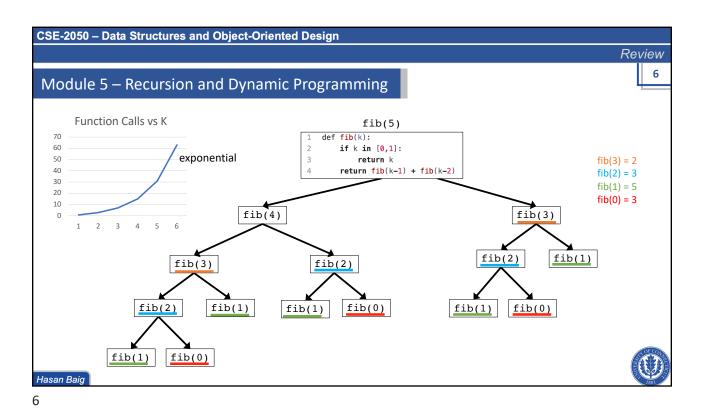
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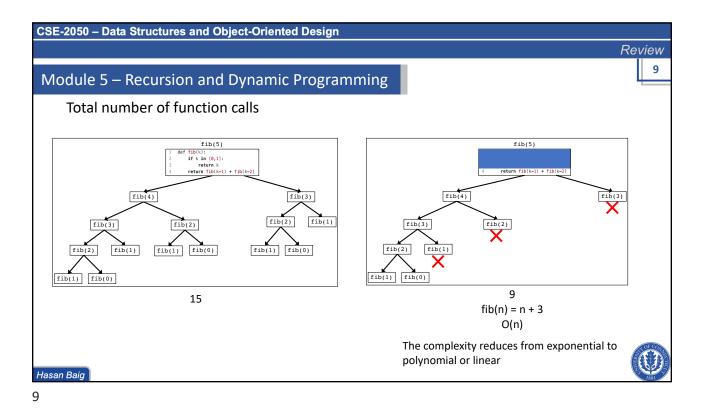


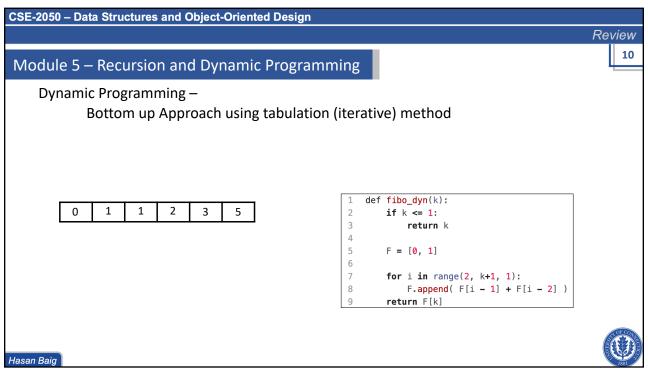




Module 5 – Recursion and Dynamic Programming Memoization • Avoid making a function call again which has already been executed by: • storing the intermediate solution of subproblems and use them later wherever needed • Also called Top-down approach which uses recursion + caching

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Review

Module 6 – Searching and Sorting

Binary Search

Search for an element in a <u>sorted</u> array by dividing the search interval in half.

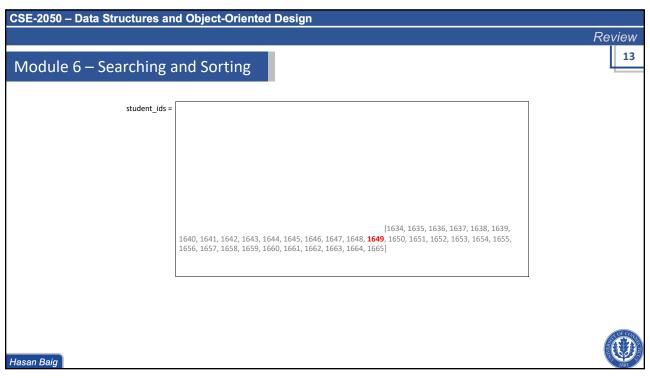
- 1. Start by examining the middle item \rightarrow return if it is the required item
- 2. If the required item is less than the middle item, disregard the upper half of the search space. If it is greater than the middle item, disregard the lower half of the search space.
- 3. Repeat until the required item is found or until the search space becomes empty

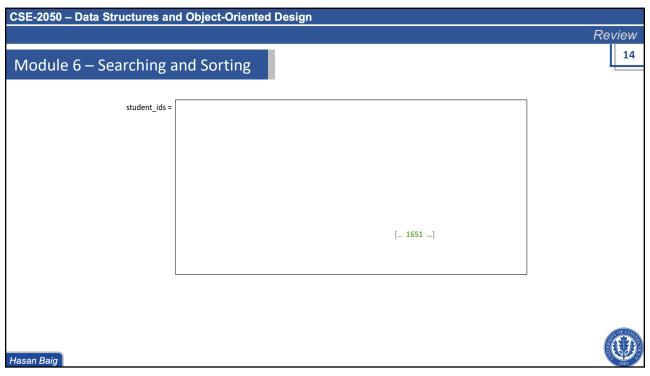


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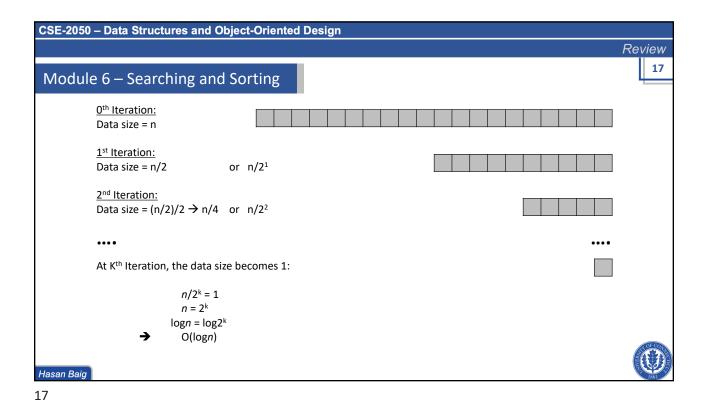
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                                                                                            Review
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Module 6 – Searching and Sorting
                           def BS(L, item):
                               if len(L) == 0:
                                   return False
                               mid_index = len(L) // 2
                               if item == L[mid_index]:
                                   return True
                               elif item < L[mid_index]:</pre>
                                   return BS(L[ : mid_index], item)
                               else:
                                   return BS(L[mid_index + 1 : ], item)
                                           Using Slicing → O(n)
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Module 6 – Searching and Sorting
                   def BS_improved(L, item, lower, upper):
                       if lower > upper:
                           return False
                       else:
                           mid_index = (lower + upper) // 2
                           if item == L[mid_index]:
                               return True
                           elif item < L[mid_index]:</pre>
                                return BS_improved(L, item, lower, mid_index - 1)
                                return BS_improved(L, item, mid_index + 1, upper)
                                             Slicing removed
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```



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Module 6 – Searching and Sorting

Selection Sort Algorithm

- Selection sort algorithm is another approach of sorting data in O(n²) quadratic running time
- · We can either find the smallest item and place it in the beginning

OR

Find the biggest item and move it to end

• Selection sort is better for applications where less number of write operations are required



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CSE-2050 – Data Structures and Object-Oriented Design Review 20 Module 6 – Searching and Sorting **Insertion Sort Algorithm** Online algorithm – sort array as it receives data (example from web) def insertion_sort(L): 1 2 for i in range(1 ,len(L)): j = i3 4 while j>0 and L[j] < L[j-1]: 5 L[j-1], L[j] = L[j], L[j-1]6 j -= 1 Hasan Baig

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Module 6 – Searching and Sorting

Bubble sort

- Iterates over every pair in collection, swaps out of order pairs
- After x iterations, the last x items are in their final (sorted) place

Selection sort

- Iterates over every unsorted item in collection, selects the next smallest/biggest
- After x iterations, the last x items are in their final (sorted) place

Insertion sort

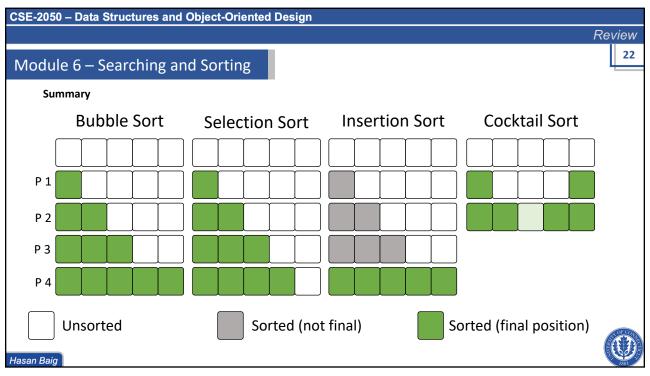
- Iterates over a progressively growing sorted section of the list
- Bubbles the next un-sorted item into place
- After x iterations, the first x items are sorted but may not be in their final place.

Cocktail sort

- Invariant of bubble sort
- After x iterations, smallest and largest elements are placed at the right place



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Module 7 – Divide and Conquer

- Divide and Conquer is a paradigm for algorithm design and consists of the following three steps:
- **1.** Divide: Divide the input data D into two or more disjoint subsets, D_1 and D_2 .
- **2.** Conquer: Recursively solve the subproblems associated with the subsets, D_1 and D_2 .
- 3. Combine: Take the solutions to the subproblems, D_1 and D_2 , and merge them into a solution to the original problem D.

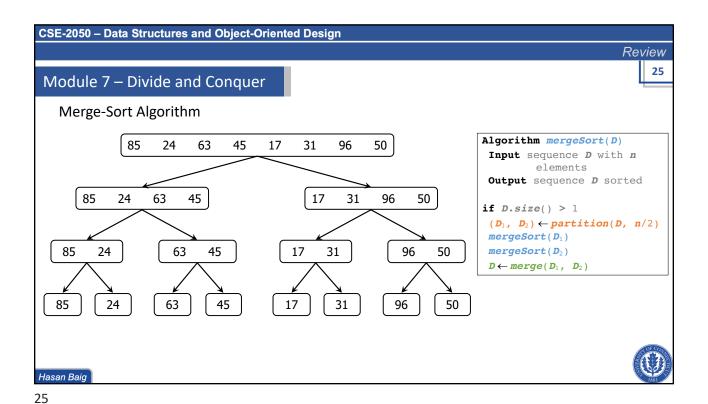
Base case: Base case for the recursion are subproblems of size 0 or 1.

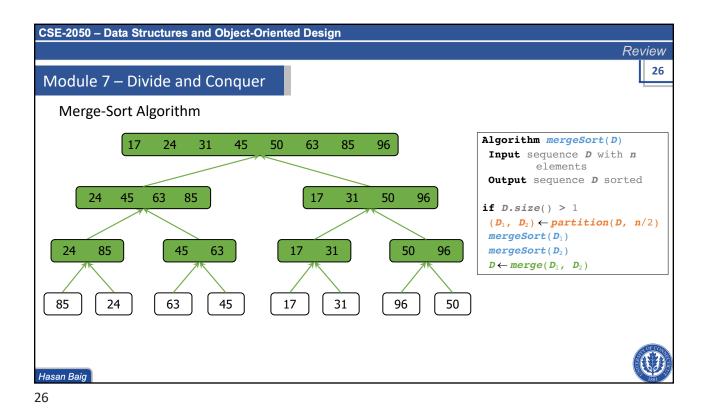


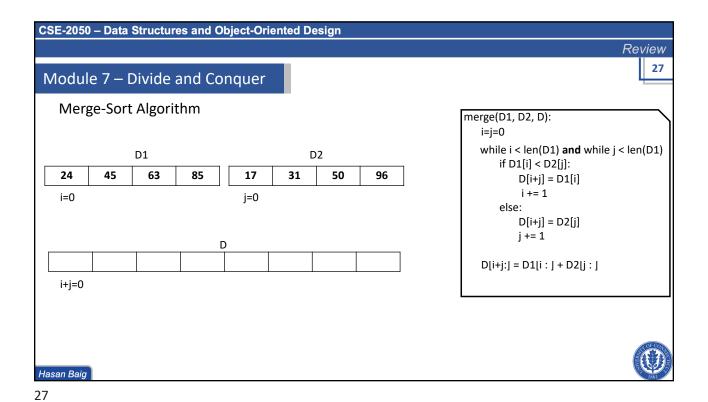
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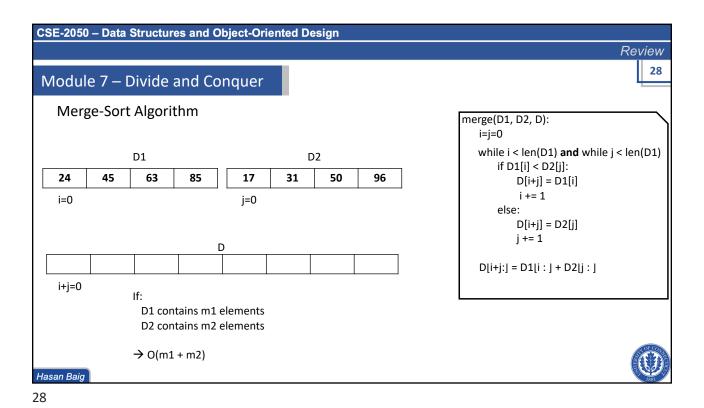
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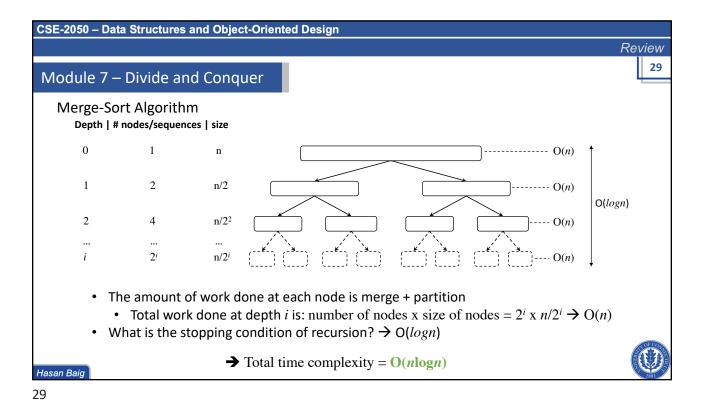
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                                                                                                                  Review
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 Module 7 – Divide and Conquer
    Merge-Sort Algorithm
                                                                                   Algorithm mergeSort(D)
                                                                                    Input sequence D with n
                85
                       24
                              63
                                     45
                                            17
                                                   31
                                                          96
                                                                 50
                                                                                              elements
                                                                                    \textbf{Output} \text{ sequence } \textbf{\textit{D}} \text{ sorted}
                                                                                   if D.size() > 1
                                                                                    (D_1, D_2) \leftarrow partition(D, n/2)
                                                                                    mergeSort(D_1)
                                                                                    mergeSort(D_2)
                                                                                    D \leftarrow merge(D_1, D_2)
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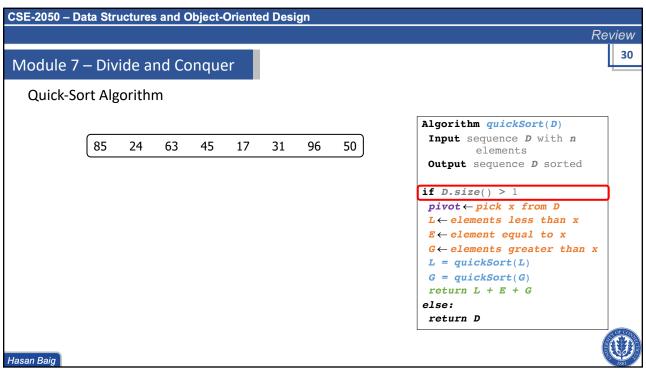


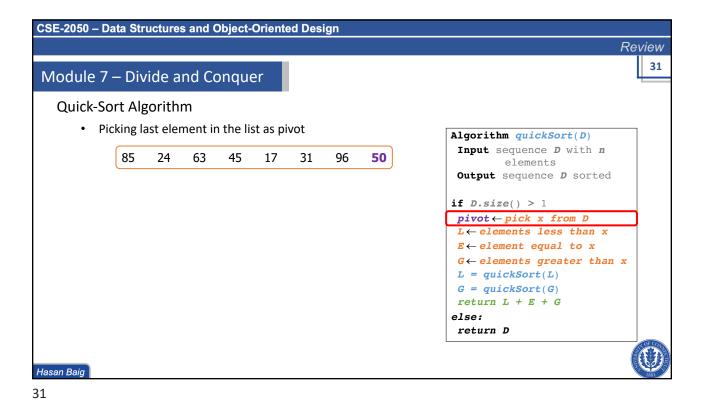


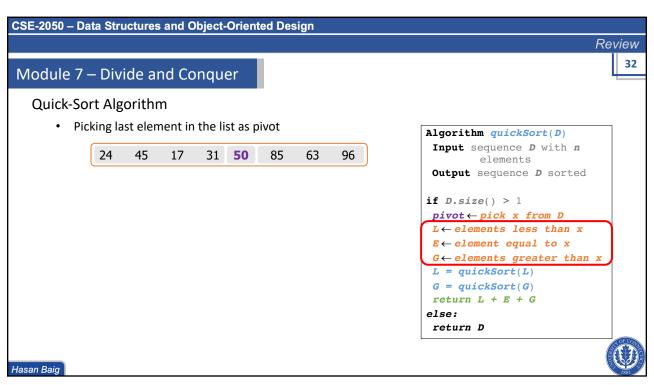


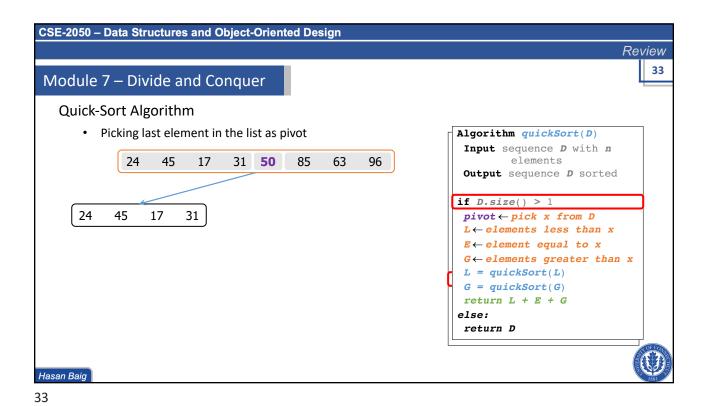


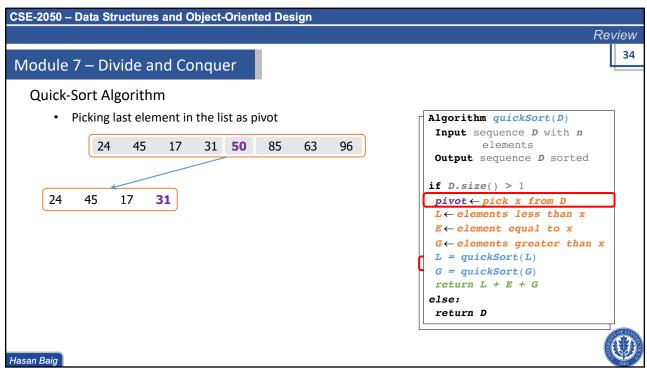


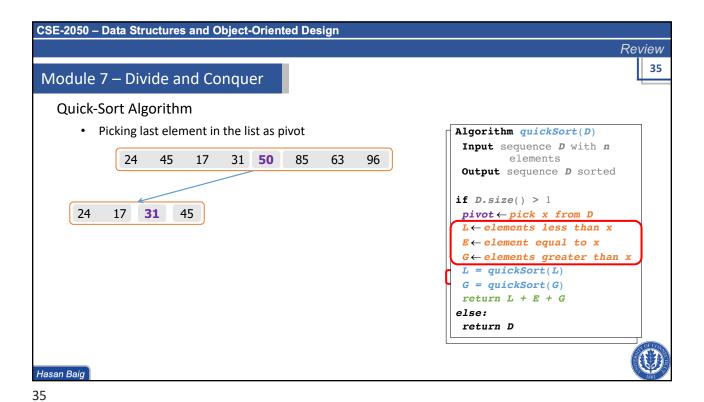


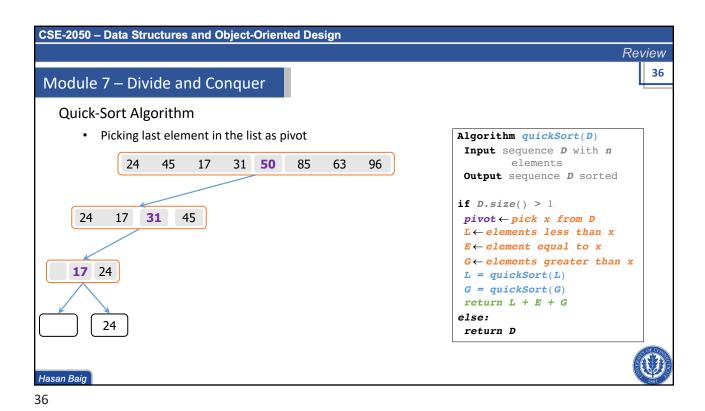


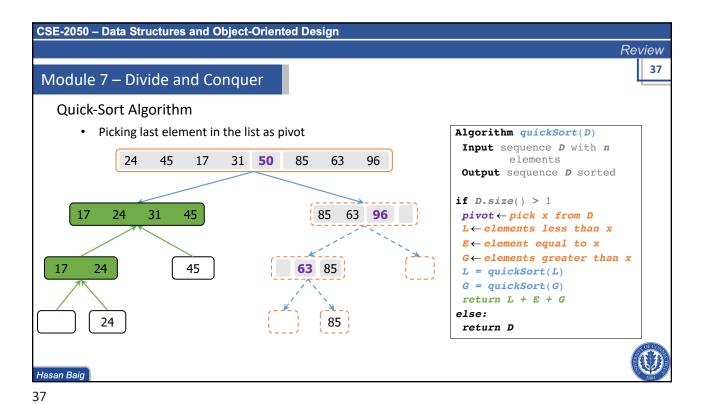


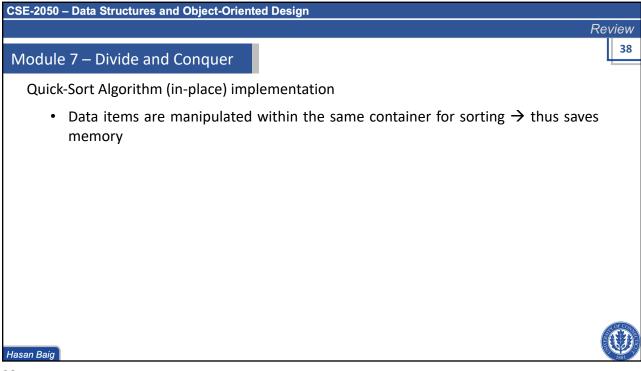


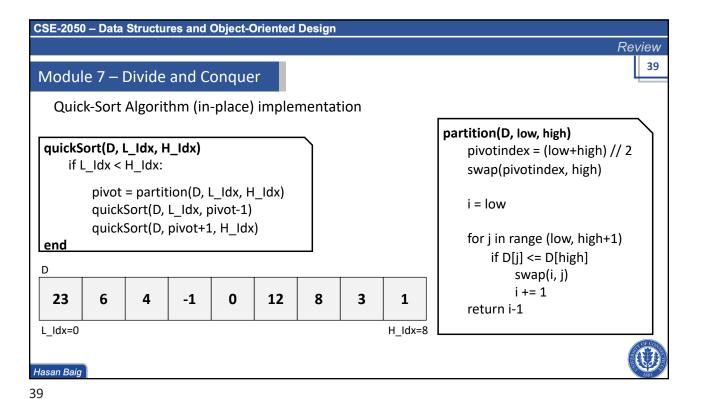


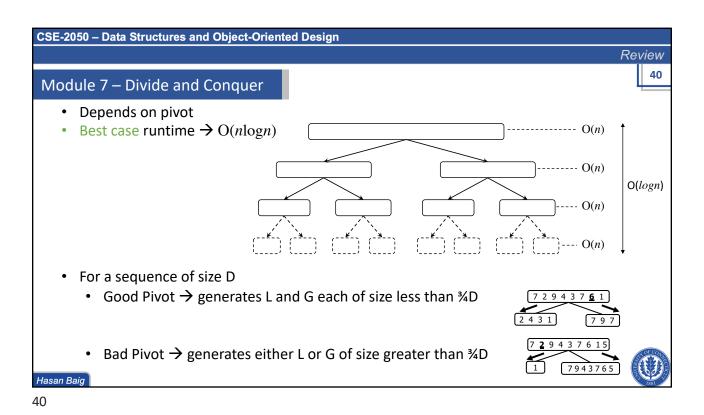


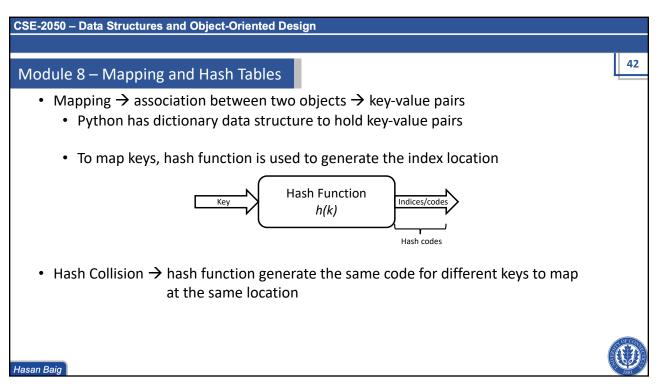












Module 8 – Mapping and Hash Tables Collision Handling scheme • Separate Chaining • Instead of having a single object at each location in hash table, we conceptualized to have buckets Module 8 – Mapping and Hash Tables Instead of having a single object at each location in hash table, we conceptualized to have buckets In Worst case:

• Time to search a key in the bucket depends on the size of bucket:

• Time to search for the bucket is O(1)

For size $n \rightarrow O(n)$

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Module 8 – Mapping and Hash Tables Collision Handling scheme Open addressing – Linear Probing Inserting an element (k,v) at M[j] j is the index generated by hash function If jth place is occupied, we try M[(j+1) % N] If this place is also occupied, we next try M[(j+2) % N], and so on

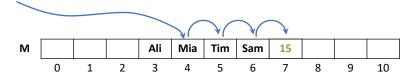
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Module 8 – Mapping and Hash Tables

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Collision Handling scheme

- Inserting a new element with key k = 15 → k mod N → 15 mod 11 = 4
- This new item should be placed at location 4



- This requires additional implementation to search for an existing key
- Accessing cell array is analogous to <u>probing</u> the bucket to find its content

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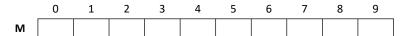
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Module 8 – Mapping and Hash Tables

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- A good hash function index "n" items of a map in a bucket array of capacity "N"
 → The expected size of a bucket is n/N
- The ration $\lambda = n/N$ is called "Load Factor" of the hash table
 - Bounded by a small constant (preferably below 1)
 - Example:
 - n = 15
 - N = 10
 - $\rightarrow \lambda = 1.5 \rightarrow \text{collision}$



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