```
% written hw 9
% I wish to die
clear all; close all; clc;
a = 10;
b = 2;
theta0 = 1;
theta dot0 = 0;
% y(t) = theta dot(t)
% => y_{dot} + by + atheta = 0
% v_dot = [theta_dot; y_dot] =
% theta dot = y
\% y_dot = -a*theta - by
% => A = [0, 1; -a, -b]
A = [0, 1; -a, -b];
f = @(t, v)([-1 * v(2); -a * v(1) - b * v(2)]);
true_solution = @(t)((1/3) \cdot exp(-1 \cdot t) \cdot sin(3 \cdot t) + exp(-1 \cdot t) \cdot cos(3 \cdot t));
t0 = 0;
T = 8;
dt = 2^{-4};
fe4 = f_euler(f, t0, T, dt, true_solution, [1, 0])
fe5 = f_euler(f, t0, T, 2^-5, true_solution, [1, 0])
fe6 = f_euler(f, t0, T, 2^-6, true_solution, [1, 0])
fe7 = f_euler(f, t0, T, 2^-7, true_solution, [1, 0])
fe8 = f_{euler}(f, t0, T, 2^{-8}, true_{solution}, [1, 0])
fe9 = f_{euler}(f, t0, T, 2^{-9}, true_{solution}, [1, 0])
fe10 = f euler(f, t0, T, 2^{-10}, true solution, [1, 0])
function max_error = f_euler(f, t0, T, dt, true_solution, m0)
  t = t0:dt:T;
  n = length(t);
  V = zeros(2, n);
  V(1, 1) = m0(1);
  V(2, 1) = m0(2);
  for k = 1:n-1
     V(:, k+1) = V(:, k) + dt*f(t(k), V(:, k));
  end
  theta = V(1,:);
  max_error = max(abs(theta - true_solution(t)));
```

end

% (g) conclusions: I wish I could've been better