# Simulating Time-Varying Performance

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2023-10-04

#### Libraries

```
library(ggplot2)
library(tibble)
```

## Functions used for analysis

```
params_mat <- function(k_1, tau_1, k_2, tau_2, change_days=NULL, days) {</pre>
  if (length(k_1) == length(tau_1) &&
      length(k_1) == length(tau_2) &&
      length(k_1) == length(k_2) &&
      length(k_1) == length(change_days)+1
    else {stop("check length of parameters")}
  out_matrix <- matrix(0, nrow = days, ncol = 4)</pre>
  colnames(out_matrix) <- c("k_1", "tau_1", "k_2", "tau_2")</pre>
  bound_1 <- 1; bound_2 <- days</pre>
  j <- 0 # counter for index of k_1, tau_1, etc
  for (elem in c(change_days, days)) {
    j <- j + 1
    bound_2 <- elem
    for (i in bound_1:bound_2) {
      out_matrix[i, ] <- c(k_1[[j]], tau_1[[j]], k_2[[j]], tau_2[[j]])</pre>
    }
    bound_1 <- elem
 return(out_matrix)
```

```
#' Title
#'
#' @param params_mat a n by 4 matrix, where n is the number of days
#' @param training_load an n dimensional vector
#'
#' @return an n? dimensional vector with the performance
#' @export
#'
```

```
#' @examples
perf_tv <- function(p_0, params_mat, training_load) {
    days <- nrow(params_mat)
    perf_out <- c(rep(NA, days))
    T_1 <- 0; T_2 <- 0
    for (i in 1:days) {
        T_1 <- exp(-1/params_mat[i, "tau_1"])*T_1 + training_load[[i]]
        T_2 <- exp(-1/params_mat[i, "tau_2"])*T_2 + training_load[[i]]
        perf_out[[i]] <- p_0 + params_mat[i, "k_1"]*T_1 - params_mat[i, "k_2"]*T_2
    }
    return(perf_out)
}</pre>
```

```
perf_plot <- function(p_0,</pre>
                       k_1,
                       tau_1,
                       k_2,
                       tau_2,
                       change_days = NULL,
                       days,
                       training_stim) {
  training_load <- c()</pre>
  limit <- 0
  if (training_stim[[1]] == "constant") {
    training_load <- c(rep(training_stim[[2]], days))</pre>
    k <- length(k_1)
    # See justification for this below
    limit -p_0 + training_stim[[2]]*k_1[[k]]/(1-exp(-1/tau_1[[k]])) -
      training_stim[[2]]*k_2[[k]]/(1-exp(-1/tau_2[[k]]))
  tmp_matrix <- params_mat(k_1,</pre>
                             tau_1,
                             k_2,
                             tau_2,
                             change_days,
                             days)
  modeled_performance <- perf_tv(p_0, tmp_matrix, training_load)</pre>
  tmp_data <- tibble(</pre>
    "day" = c(0:days),
    "performance" = c(p_0, modeled_performance),
    "limit" = c(rep(limit, days + 1))
  )
  plot \leftarrow ggplot(tmp data, aes(x = day)) +
    geom_line(aes(y = performance, color = "perf")) +
    geom_line(aes(y = limit, color = "lim"))
     scale_color_manual("Legend",
  #
                          values = c("lim" = "#e31a1c", # this color comes from the theme "Paired"
  #
                                      "perf" = "black"))
  plot
```

### Computing the limit of the model

I would like to compute the limit of the predicted performance for the time-invariant model Under the assumption of constant training load. We have

$$p(t) = p_0 + k_1 \sum_{i=1}^{t-1} e^{\frac{t-i}{\tau_1}} w(i) + k_2 \sum_{i=1}^{t-1} e^{\frac{t-i}{\tau_2}} w(i)$$

If w(i) = C for all i, then we can write

$$\sum_{i=1}^{t-1} e^{\frac{t-i}{\tau_1}} = e^{1/\tau_1} \sum_{i=1}^{t-1} e^{\frac{(t-1)-i}{\tau_1}} = e^{1/\tau_1} \left( -1 + \sum_{i=0}^{s} \left( e^{-1/\tau_1} \right)^i \right)$$

Finding the long-run limit of p(t) then amounts to computing

$$\sum_{i=0}^{\infty} \left( e^{-1/\tau_1} \right)^i = \frac{1}{1 - e^{-1/\tau_1}}$$

Notice that this is a convergent geometric series,  $e^{-1/\tau_1} < 1$  when  $\tau_1 > 1$  (which we have assumed). Therefore,

$$\sum_{i=1}^{t-1} e^{\frac{t-i}{\tau_1}} = e^{1/\tau_1} \left( -1 + \frac{1}{1 - e^{-1/\tau_1}} \right) = e^{1/\tau_1} \left( \frac{e^{-1/\tau_1}}{1 - e^{-1/\tau_1}} \right) = \frac{1}{1 - e^{-1/\tau_1}}$$

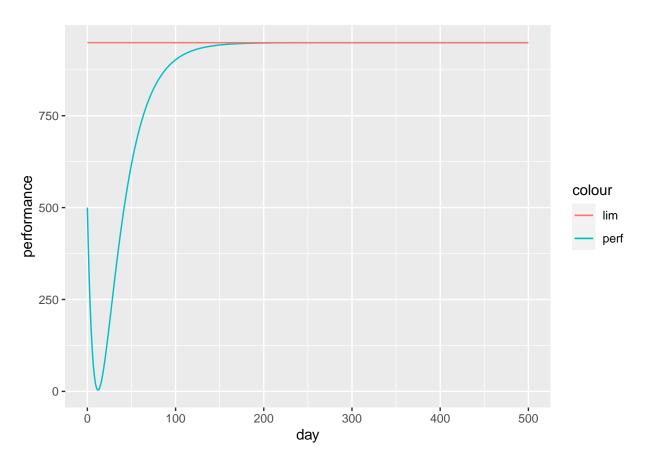
Therefore

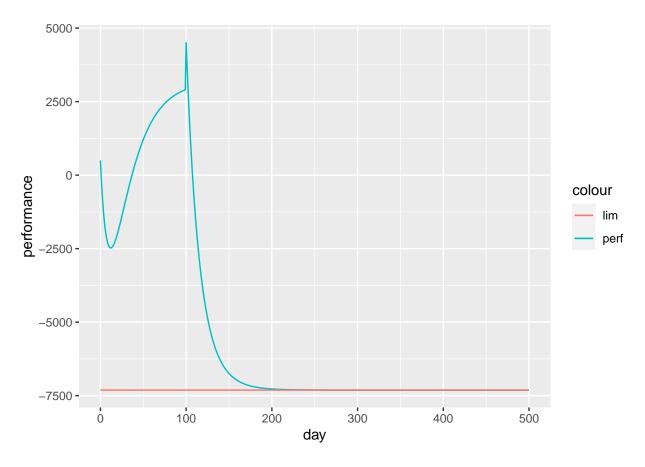
$$\lim_{t \to \infty} p(t) = p_0 + C \left( \frac{k_1}{1 - e^{-1/\tau_1}} - \frac{k_2}{1 - e^{-1/\tau_2}} \right)$$

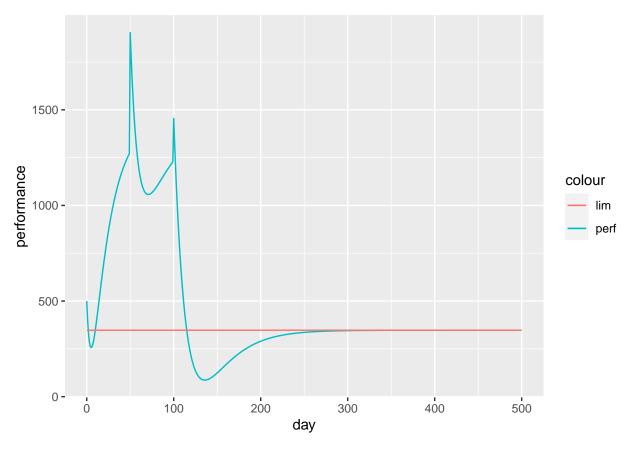
This is how we compute the red line in perf\_plot.

## Exploring the time, varying model

This is a time-invariant plot with our new function, to check that things are working correctly







To have the effects of an initial negative effect, and a long-run positive effect to a constant stimulus, it seems to be necessary that  $k_1 < k_2$  and  $\tau_1$  has to be much bigger than