# EPIC: an Epidemic based dissemination algorithm for VANETs

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Technologies, mOdels, and Protocols for Cooperative Connected Cars (TOP-Cars)

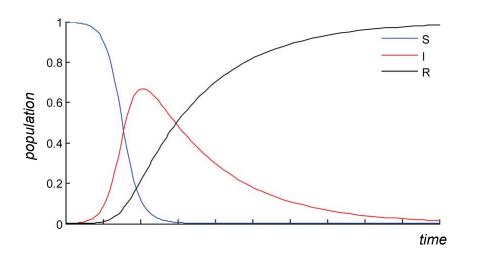
#### **Outline**

- 1. Motivation
- 2. Related work
- 3. Epidemic-style dissemination
- 4. EPIC
- 5. Performance evaluation
- 6. Results

#### **Motivation and Goals**

- Data dissemination in VANETs deals with complex network topology and can lead to inefficiencies and broadcast storm
- We can express efficiency of a dissemination process in terms of:
  - Ratio of vehicles which act as relay of vehicles in the target dissemination area
  - Data overhead carried by the network
- The main goal of our proposed dissemination algorithm is to maximize efficiency using only local information at nodes, plus any information that is collected by nodes through the background beaconing process carried out in VANETs.

#### Susceptible-Infected-Recovered Model



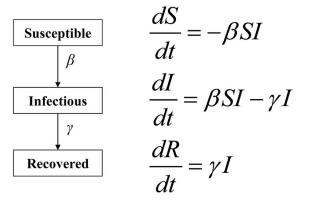
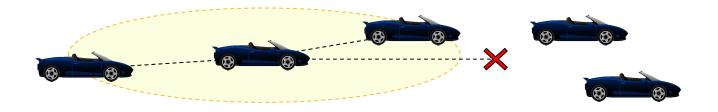


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#### Related work

- Data dissemination in vehicular networks: Challenges, solutions, and future perspectives, L. Aparecido
- Epidemic Algorithms for Reliable and Efficient Information Dissemination in Vehicular ad-hoc Networks, M. Nekovee
- Broadcast storm mitigation techniques in vehicular ad hoc networks, N.
   Wisitpongphan and et al.
- An Empirical Study of Epidemic Algorithms in Large Scale Multihop Wireless Networks, Deepak Ganesan et al.

#### **Epidemic-style dissemination**



- Vehicles in the network adopt the Susceptible-Infected-Recovered model for each disseminated message
- By epidemic algorithms, we refer to network protocols that allow rapid dissemination of information from a source through local interactions
- One key advantage that epidemic algorithms offer is that they do not need any information on the *complete* network topology

Procedure to be executed by vehicle *A* on message received by *B* For simplicity we consider the dissemination of a *single* message

```
1: procedure OnMessageReceipt
        if state = RECOVERED then
 3:
            return
        else if state = SUSCEPTIBLE then
 4:
            rcv_messages \leftarrow empty \ list
 5:
            state \leftarrow INFECTED
 6:
            timer \leftarrow \max \left\{ T_{min}, \ T_{max} \left( 1 - \frac{d_{AB}}{R_{max}} \right) \right\}
            rcv_messages.append(msg)
 8:
        else if state = INFECTED then
 9:
            rcv messages.append(msg)
10:
11:
        on timer expiry:
12:
        do relay \leftarrow EvaluatePositions(rcv messages)
13:
        if do_relay then
14:
            msg \leftarrow updateMsq(msg)
15:
            relayMessage(msg)
16:
        state \leftarrow RECOVERED
17:
```

Waiting phase rule: Set timer and keep buffering incoming messages until timer expiry

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Waiting phase rule: Set timer and keep buffering incoming messages until timer expiry

#### Packet header

ID	TTL	Emitters
4 Bytes	1 Byte	(14 · <i>n</i> ) Bytes

- We call emitter a vehicle which has already broadcast a message M
- If, during the waiting phase of vehicle v, the message was sent to v by a set S of vehicles, then geographical coordinates (8 Bytes) and MAC (6 Bytes) addresses of vehicles in S are appended to *emitters* field before the message relay by v
- M's header contains information about a subset vehicles which relayed it previously

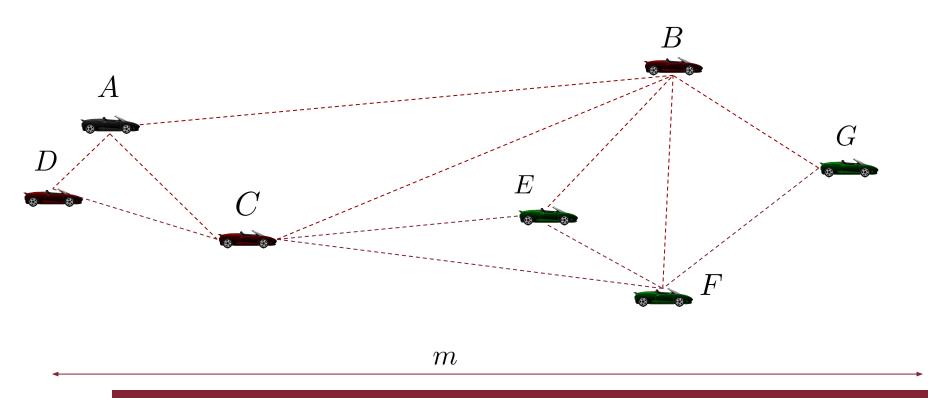
#### Procedure to be executed after the waiting phase

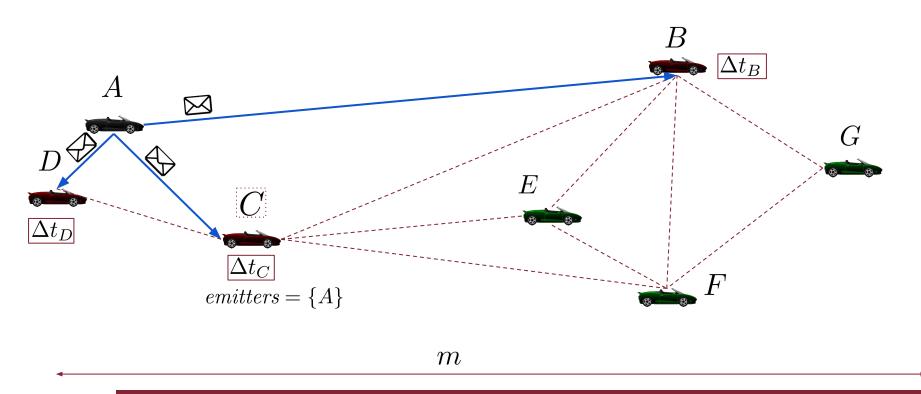
```
1: procedure EvaluatePositions
 2:
       input:
       rcv_messages ← list of msgs received during wait
 3:
 4:
       initialization:
 5:
       emitters ← list of GPS coordinates of each emitter in rcv_messages
 6:
 7:
       main:
8:
       for emitter in emitters do
 9:
           for coord in neighbors_coord do
10:
              if dist (emitter, coord) < R_{min} then
11:
                  neighbors coord. remove (coord)
12:
       if neighbors coord. length > \alpha·neighbors num then
13:
           return True
14:
       return False
15:
```

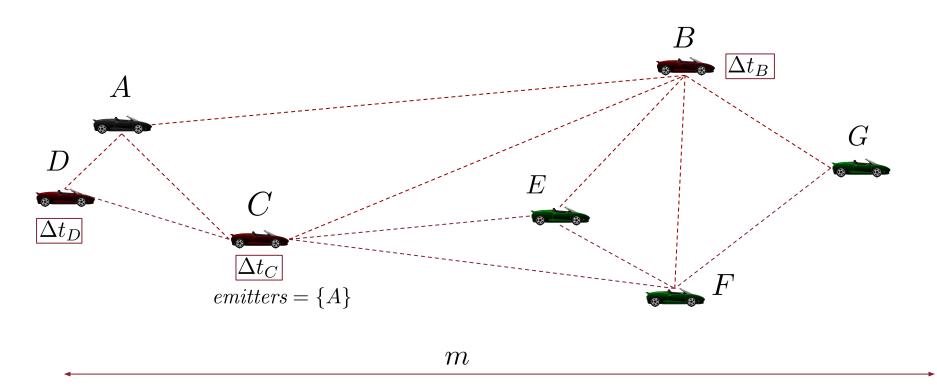
We say that a neighbor n is covered by an emitter  $e \in emitters$  if

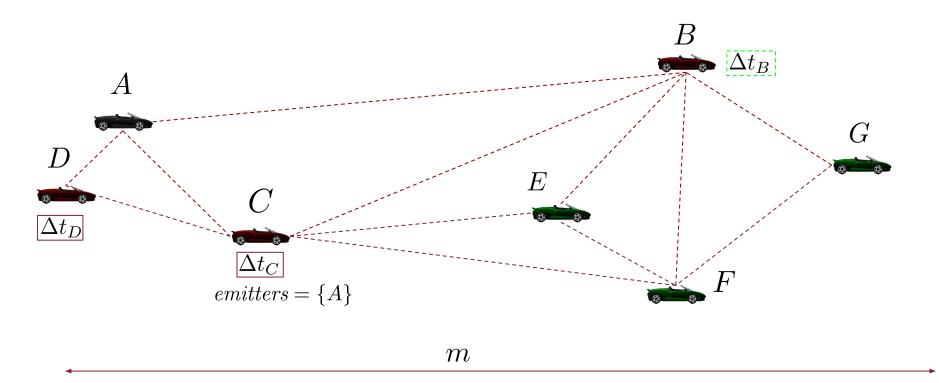
$$\min_{e} dist(n, e) \le R_{min}$$

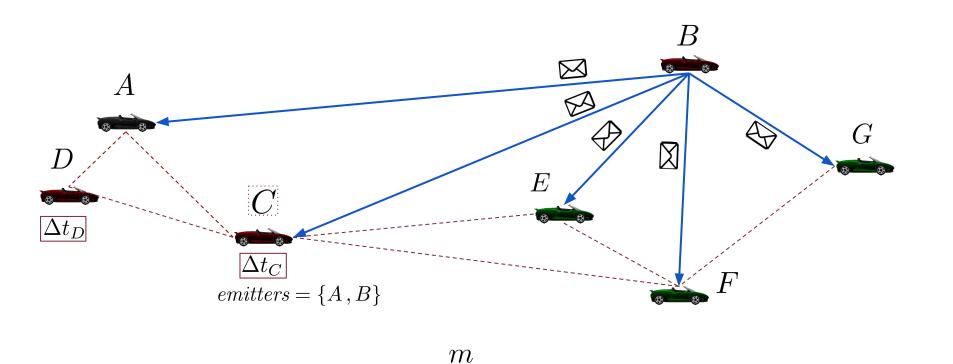
Broadcast phase rule: Let N be the number of neighbors and  $N_r$  the ones not covered by any emitter. If  $\frac{N_r}{N} > \alpha$  relay the message.

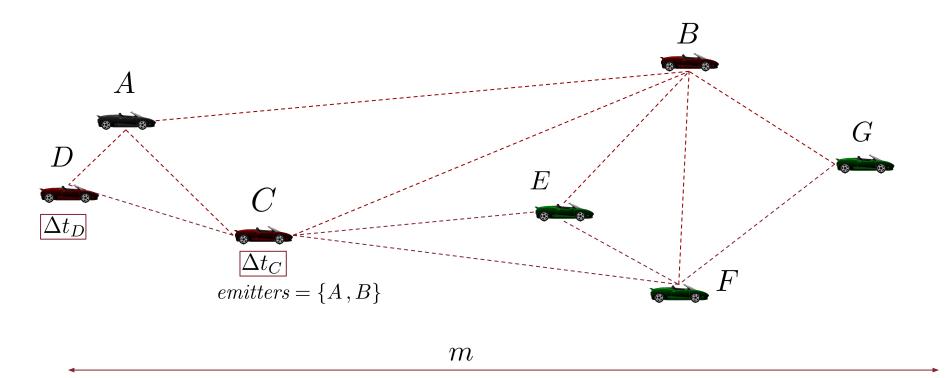


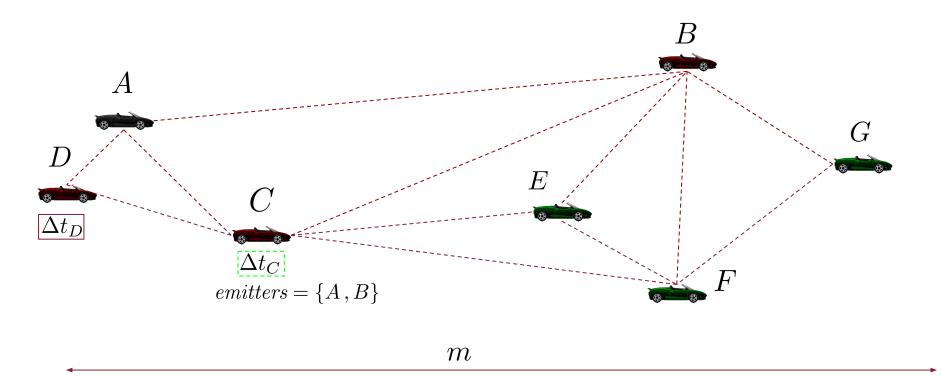


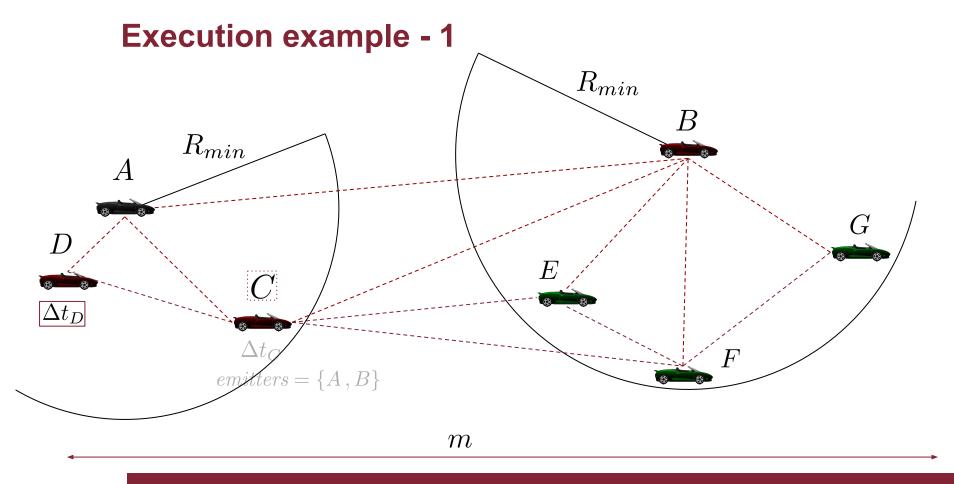


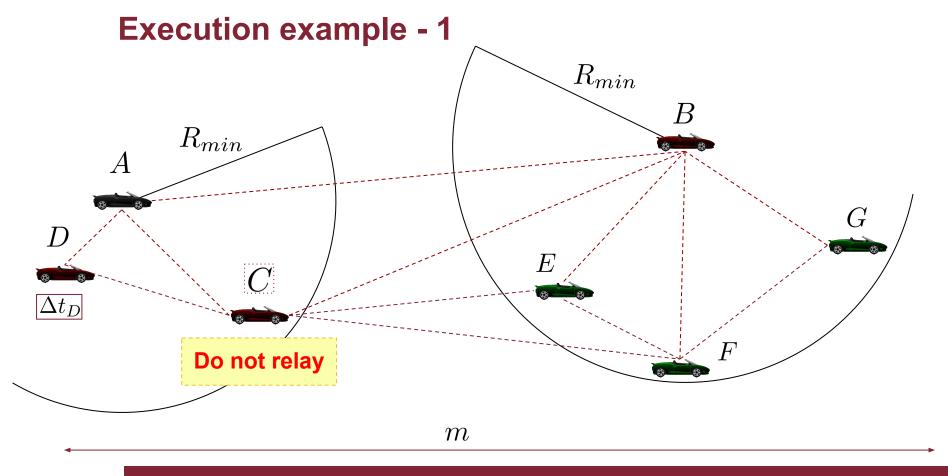


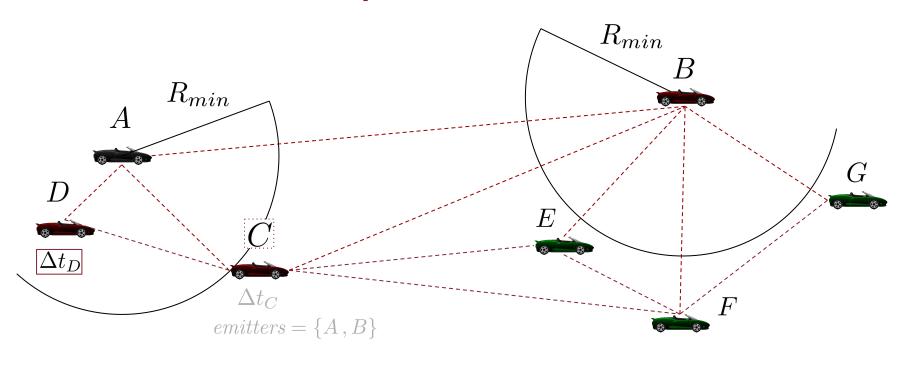




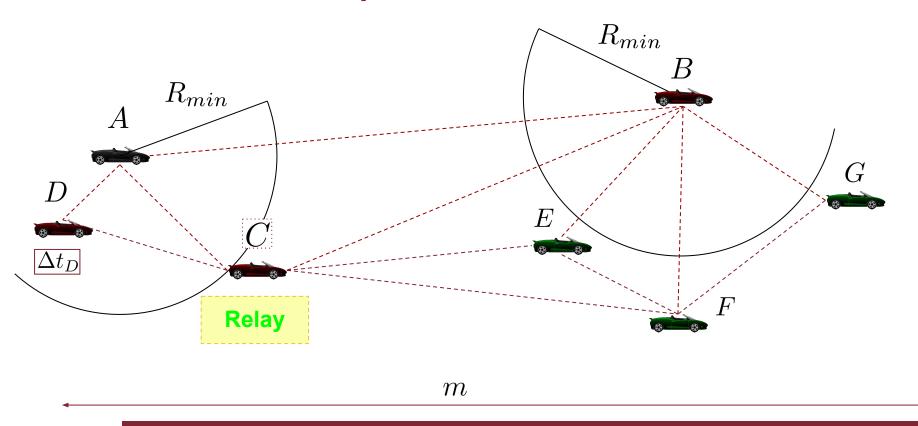






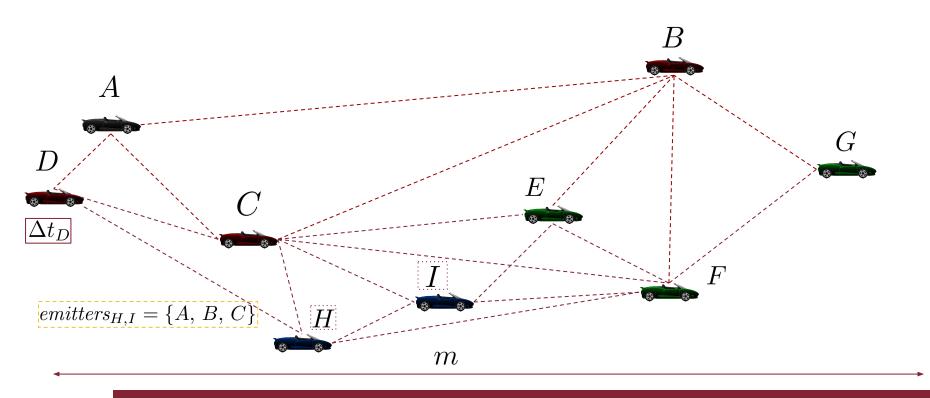


m

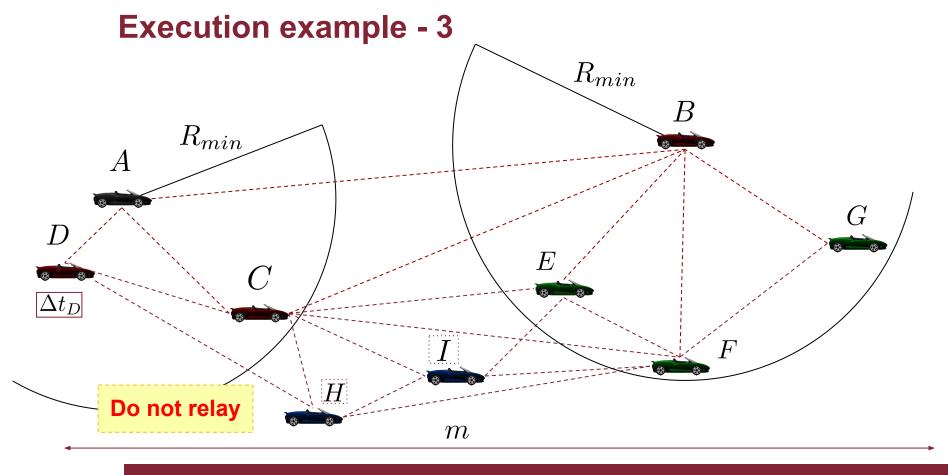


**Execution example - 3**  $R_{min}$  $R_{min}$ m

**Execution example - 3**  $R_{min}$  $R_{min}$ ERelay m

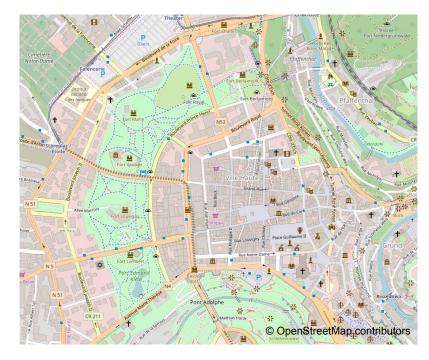


**Execution example - 3**  $R_{min}$  $R_{min}$ EH $emitters_{H,I}$ m



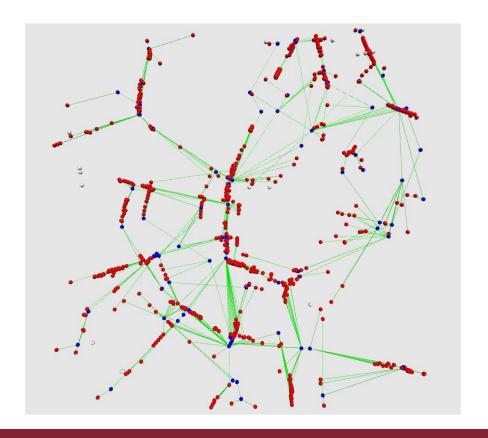
#### **Simulation scenario**

Parameter	Value
Number of vehicles	790
Road length (km)	28.19
Dissemination area (km²)	3.9
Avg. vehicle density (veh/km)	28.02
Avg. c $\delta$ nectivity degree (veh)	11.6 - 43.8
R <sub>min</sub> (m)	85 - 170
R <sub>max</sub> (m)	500
T <sub>max</sub> (ms)	200
$\alpha$	0.05
Packet loss	0.01



Luxembourg

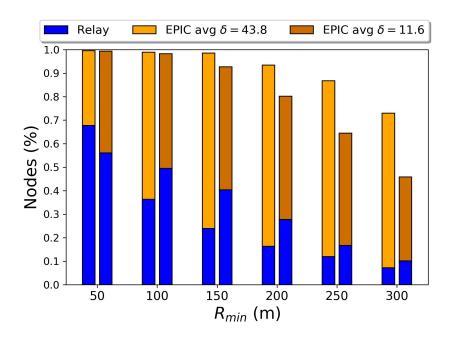
#### **Simulation scenario**

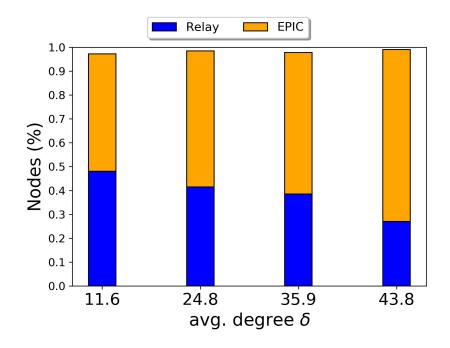


#### **Simulation scenario**

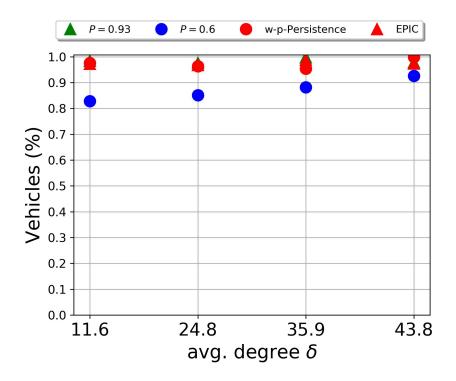


#### Reached and Relay Vehicles

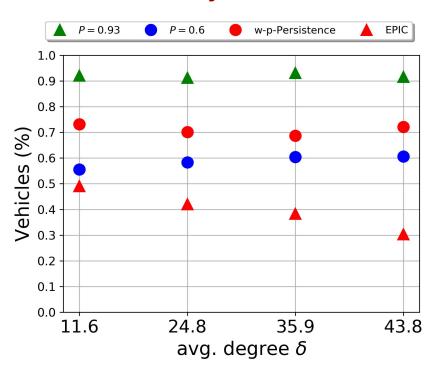




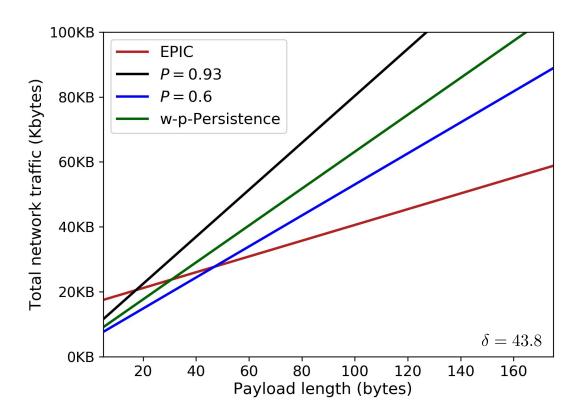
#### **Reached Vehicles**



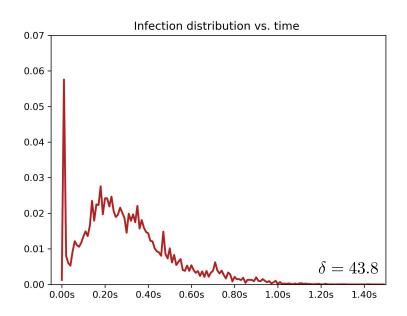
#### **Relay Vehicles**



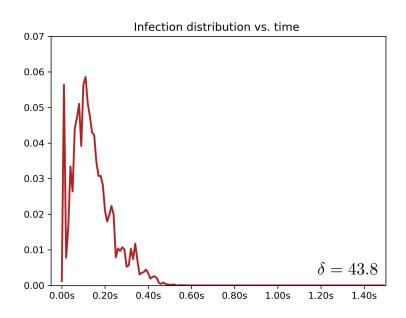
#### **Network Traffic**



#### Receivers distribution over time



$$T_{\rm max}$$
 = 300ms



$$T_{\text{max}} = 150 \text{ms}$$

#### Conclusions

- We designed a new protocol for VANETs, named EPIC, which disseminates messages on the basis of an epidemic approach
- We analyzed the down-stream dissemination by evaluating performance metrics like the fraction of reached vehicles, the fraction of relay nodes and the overhead needed for the correct behavior of the protocol
- We provided the simulation of the protocol execution in real urban scenarios, where obstacles are considered for the radio propagation

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