

Discussion Week 7

Agenda

- Statistics Introduction/Review
 - Random Variables
 - Probability
 - Conditional Probability
 - Bayes Rule
- Vector embedding distances/similarity measures
 - Euclidean, Manhattan, Cosine
- HW3
 - Any questions?

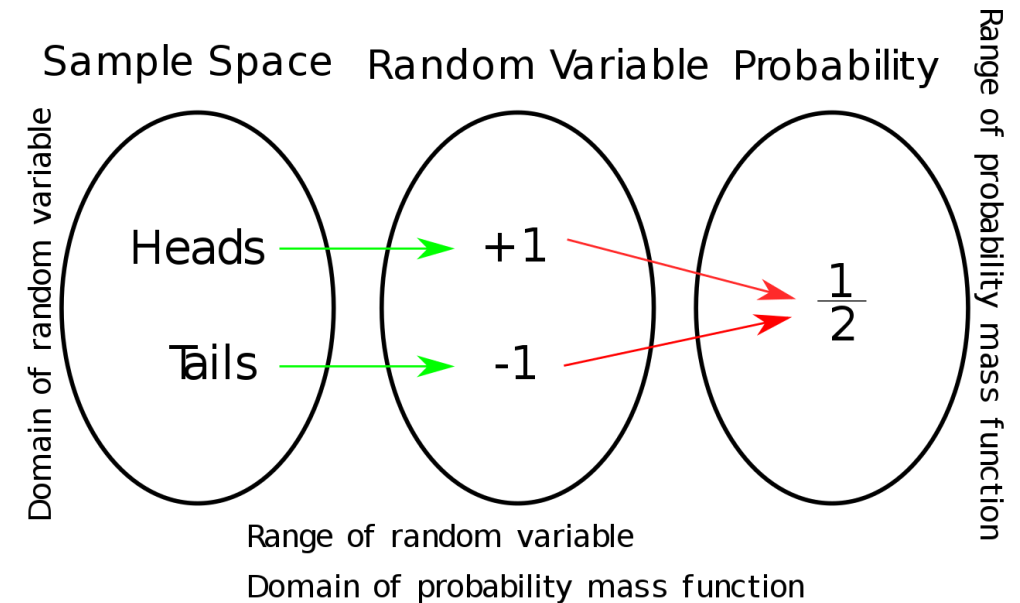
HW Submission and Other Reminders

- Please make sure that you select your pages when submitting the HW
 - There are ~150 students in the course and it makes grading difficult if we need to scan your PDF to find your answers
- Make sure you submit the PDF and .ipynb files into their respective submissions on Gradescope
 - We sometimes use the .ipynb files if there are large issues with your submission
 - If you still have troubles with this, please let me know and I would be happy to help you
- Congrats on completing the midterm!
 - **One piece of advice:** While showing each step of your calculations (such as eigenvalue calculation, etc), the work you show or explain, the more partial credit we can give as graders
 - If you don't show any work and give an incorrect answer, there is no way for us to see where you went wrong and give any partial credit!

Probability

Random Variables

- A random variable is a variable whose possible values are numerical outcomes of a random phenomenon
- A random variable X has a domain of possible values
 - For a discrete variable, it will have a domain of the form $\{x_1, x_2, \dots, x_m\}$
 - A continuous random variable could take on an infinite number of possible values.
- Discrete random variable example
 - Coin flip C with possible values
 - $\{c_1 = \text{Heads}, c_2 = \text{Tails}\}$



Unconditional Probability (prior)

- The unconditional probability $P(X = x_i)$ denotes our degree of belief that $X = x_i$ in the absence of all other knowledge
- e.g., What is the probability that we flip a heads? Flip a tails?
 - $P(C = \text{Heads}) = 0.5$
 - $P(C = \text{Tails}) = 0.5$ **or** $P(C = \text{Tails}) = 1 - P(C = \text{Heads})$

Axioms of Probability

- Probabilities are non-negative
 - $P(X = x_i) \geq 0$
- Probabilities are normalized or they sum to one:
 - $\sum_i P(X = x_i) = 1$
- Probabilities add for the union of mutually exclusive events
 - $P(X = x_i \text{ or } X = x_j) = P(X = x_i) + P(X = x_j)$
 - If $x_i \neq x_j$

Conditional Probability

- The conditional probability $P(X = x_i | Y = y_j)$ denotes our belief that $X = x_i$ given $Y = y_j$.
- Example: Drawing cards
 - Probability that the suit of the card is hearts
 - $P(S = \text{Hearts}) = \frac{13}{52} = 0.25$
 - Probability that the color of the card is red
 - $P(C = \text{Red}) = \frac{26}{52} = 0.5$
 - Probability that we draw a hearts given we know the color
 - $P(S = \text{Hearts} | C = \text{Red}) = \frac{13}{26} = 0.5$ (*higher*)
 - $P(S = \text{Hearts} | C = \text{Black}) = \frac{0}{26} = 0$ (*lower*)



Axioms of Probability Apply to Conditional Probability!

- Conditional probabilities are also non-negative
 - $P(X = x_i | Y = y_j) \geq 0$
- Conditional probabilities are normalized, or they sum to one:
 - $\sum_i P(X = x_i | Y = y_j) = 1$
- Probabilities add for the union of mutually exclusive events
 - $P(X = x_i \text{ or } X = x_j | Y = y_k) = P(X = x_i | Y = y_k) + P(X = x_j | Y = y_k)$
 - If $x_i \neq x_j$
- Notice, these axioms are the same!

Conditional Probability Check:

- We've seen that conditional probabilities sum to 1 when summed over the variables in the left side of the conditioning bar
 - $\sum_i P(X = x_i | Y = y_j) = 1$
- However, what about if we sum over the variable that we are conditioning on?
 - **True or False:** Does the following statement always hold?
 - $\sum_j P(X = x_i | Y = y_j) = 1$?

Conditional Probability Check:

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 - $\sum_i P(X = x_i | Y = y_j) = 1$
- However, what about if we sum over the variables we are conditioning on?
 - **True or False:** Does the following statement always hold?
 - $\sum_j P(X = x_i | Y = y_j) = 1$?
 - **False. This does not necessarily sum up to 1!**

More Rules

- The Product Rule:

- $P(X = x_i, Y = y_j) = P(X = x_i)P(Y = y_j|X = x_i)$
 - Similarly
- $P(X = x_i, Y = y_j) = P(Y = y_j)P(X = x_i|Y = y_j)$

- Marginalization:

- $P(X = x_i) = \sum_j P(X = x_i, Y = y_j)$

- Conditional Probability:

- $P(X = x_i|Y = y_j) = \frac{P(X=x_i, Y=y_j)}{P(Y=y_j)}$

- Bayes Rule:

- $P(X = x_i|Y = y_j) = \frac{P(Y = y_j|X = x_i)P(X = x_i)}{P(Y=y_j)}$

Bayes Rule

- So, when do we want to use Bayes rule?
 - We can utilize Bayes rule when we might need to express $P(X = x_i | Y = y_j)$ in terms of things that we already know or would be easier to calculate.

$$\boxed{P(A|B)}_{\text{posterior}} = \boxed{P(A)}_{\text{prior}} \times \frac{\boxed{P(B|A)}_{\text{likelihood}}}{\boxed{P(B)}_{\text{marginal}}}$$

<https://www.freecodecamp.org/news/bayes-rule-explained/>

Bayes Rule from Conditional Probability Formula

- From the definition of conditional probability on the slide previous:

$$P(X = x_i | Y = y_j) = \frac{P(Y = y_j | X = x_i)P(X = x_i)}{P(Y = y_j)}$$

Starting from the LHS:

$$\Rightarrow \frac{P(X=x_i, Y=y_j)}{P(Y=y_j)} \text{ (Conditional Probability)}$$

$$\Rightarrow \frac{P(X=x_i)P(Y=y_j|X=x_i)}{P(Y=y_j)} \text{ (product rule)}$$

Short Example:

- For a 6-sided dice, what's the probability that the outcome is at least 4, given that it is even?
 - Valid outcomes: 4 and 6
- Probability that the dice is at least 4?
 - $P(D \geq 4) = \frac{1}{6} + \frac{1}{6} + \frac{1}{6} = \frac{1}{2}$
- Probability that the dice is even?
 - $P(D \in \text{even}) = \frac{1}{6} + \frac{1}{6} + \frac{1}{6} = \frac{1}{2}$
- Probability that the dice is even and at least 4?
 - $P(D \in \text{even}, D \geq 4) = \frac{1}{6} + \frac{1}{6} = \frac{1}{3}$

Using the formula for conditional probability:

$$P(D \geq 4 | D \in \text{even}) = \frac{P(D \in \text{even}, D \geq 4)}{P(D \in \text{even})} \Rightarrow \frac{2/6}{3/6} = \frac{2}{3}$$

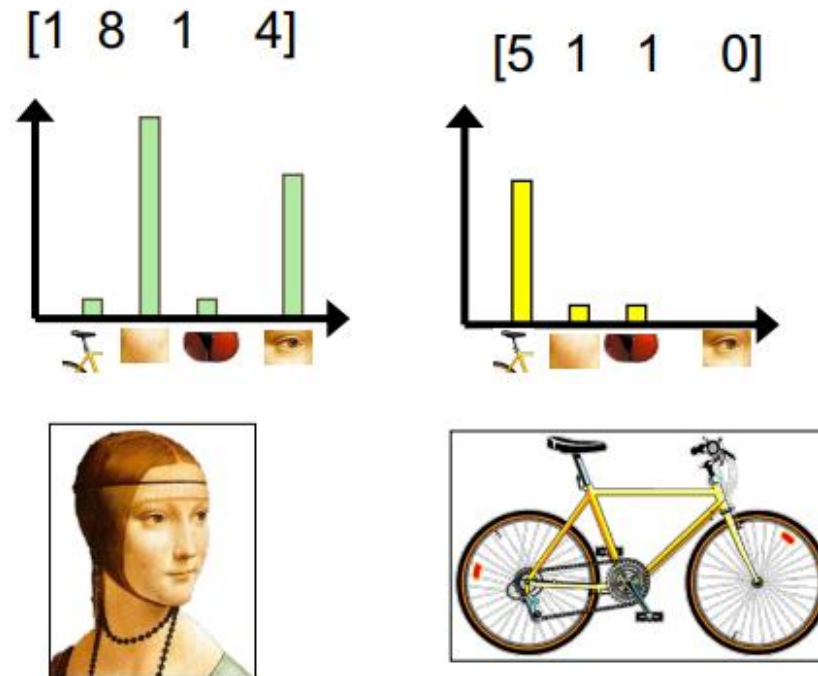
Using Bayes rule:

$$P(D \geq 4 | D \in \text{even}) = \frac{P(D \geq 4)P(D \in \text{even} | D \geq 4)}{P(D \in \text{even})} \Rightarrow \frac{\frac{3}{6} * \frac{2}{3}}{\frac{3}{6}} = \frac{2}{3}$$

Vector Distance/Similarity Measures

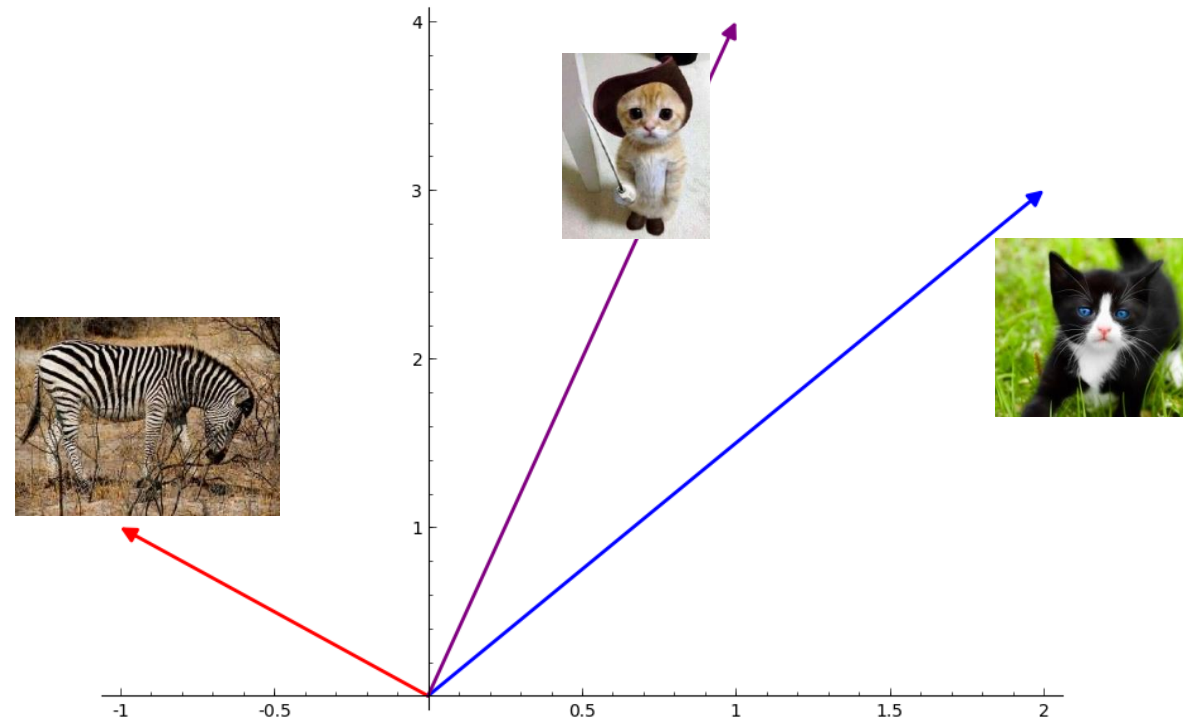
HW3 Question 1: Creating Vector Representations of Images using Visual Bag of Words

- In HW3, we create vector representations of our images using a histogram of our visual vocabulary



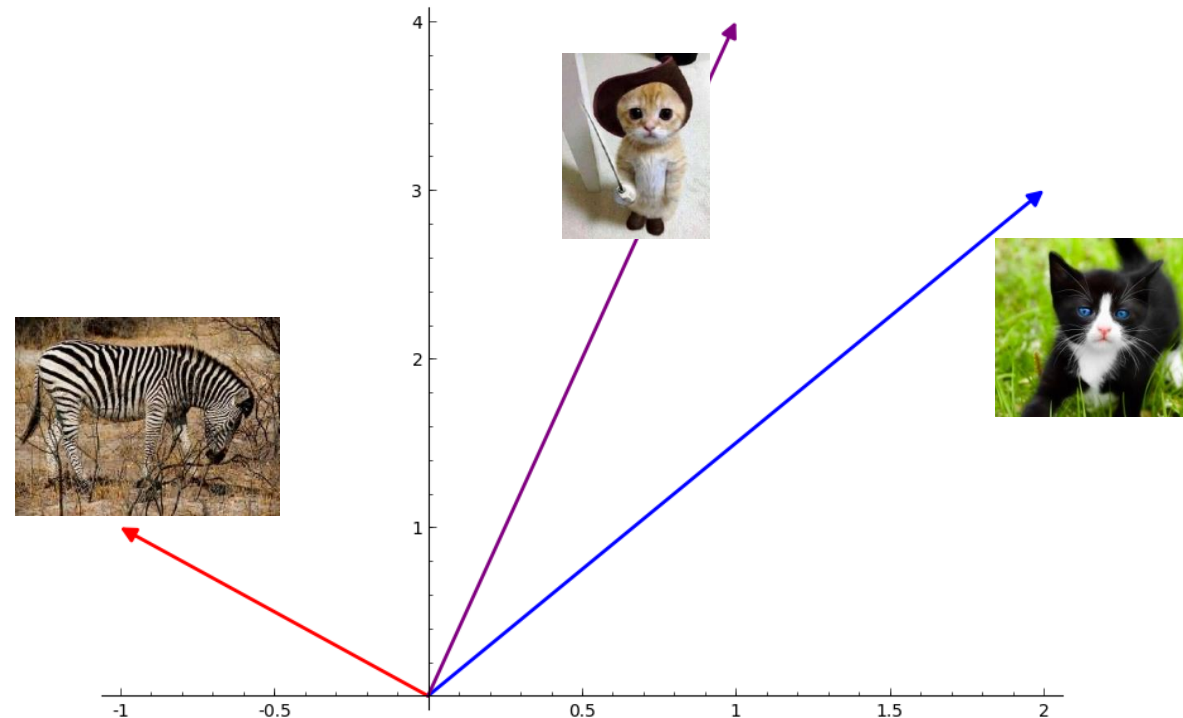
Plotting the Histograms of the Images as Vectors

- Once we have created the histograms of each of our images, we can treat the histograms as vectors (likely higher dimension than 2D or 3D).
- To simplify the visualization, imagine the histograms of the images plotted as 2D vectors like so:



Plotting the Histograms of the Images as Vectors

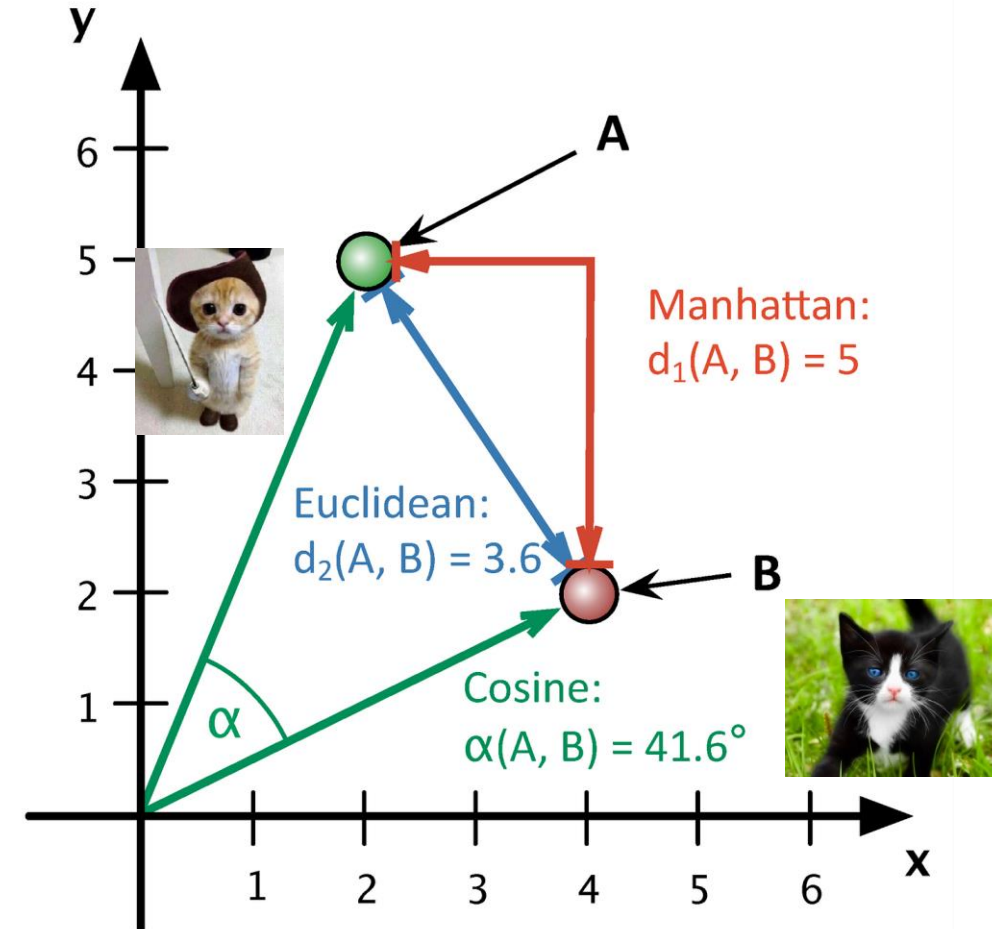
- Ideally, images that display similar objects would be “closer” to each other in our vector space than others
- Here, we can see that the vectors of the two cats are “closer” or “more similar” to each other than to the zebra.



Vector Distance Measures

- However, we want to quantify the “closeness” or similarity between the vectors
- The most obvious measure is the Euclidean distance

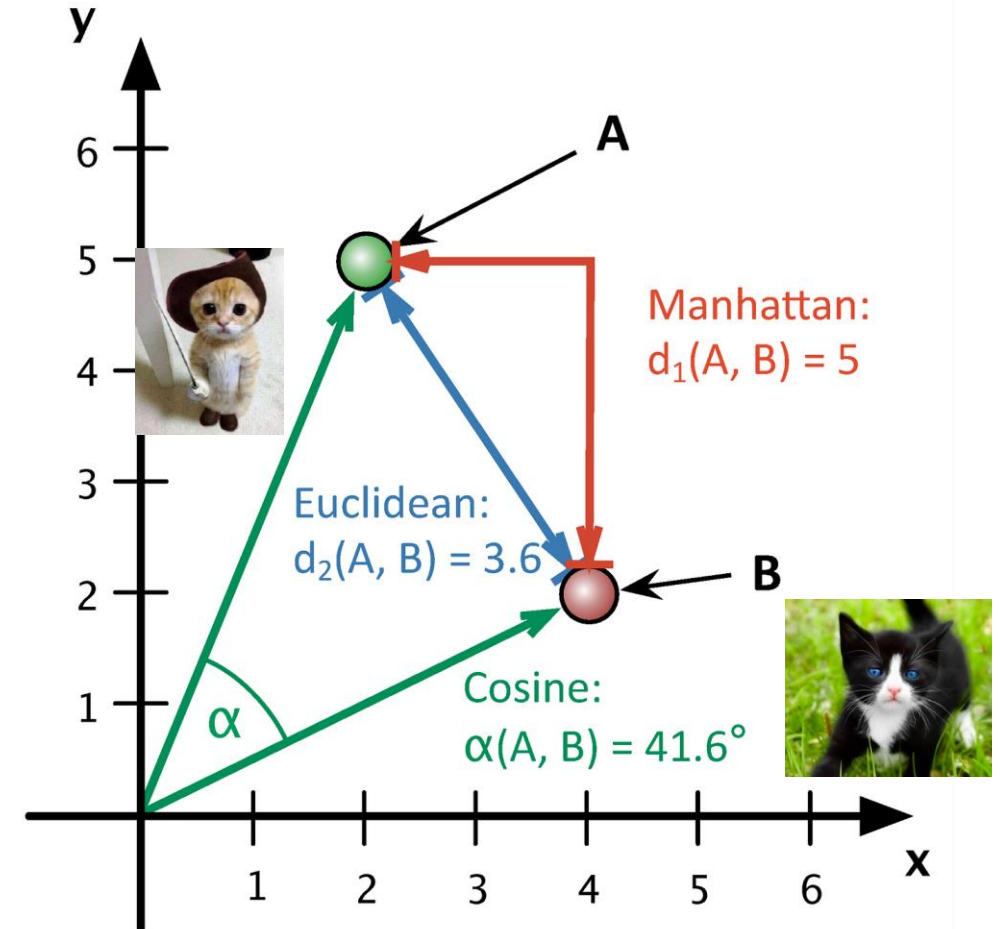
$$d(x, y) = \sqrt{\sum_{i=1}^n (y_i - x_i)^2}$$



Vector Distance Measures

- But there are others! As mentioned in lecture, we talked about the cosine similarity
- Here, we use the cosine of the angle between the vectors
 - Vector length here makes no difference!

$$\cos(\theta) = \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} = \frac{\sum_{i=1}^n A_i B_i}{\sqrt{\sum_{i=1}^n A_i^2} \sqrt{\sum_{i=1}^n B_i^2}}$$

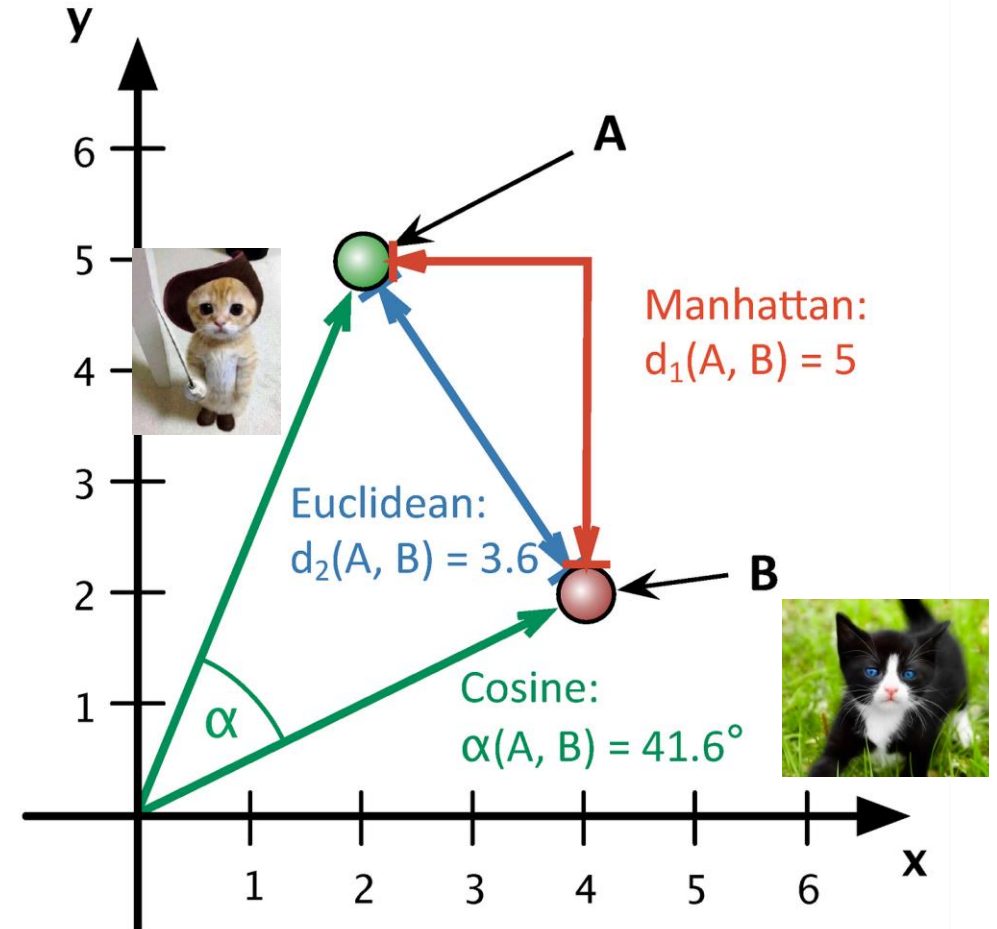


<https://medium.com/@prasoonthakur5/different-types-of-distances-used-in-machine-learning-7491128491b8>

Vector Distance Measures

- Another one is the Manhattan distance
 - Think walking around the streets of Manhattan!

$$\sum_{i=1}^n |p_i - q_i|$$



Vector Distance Measures

- There are infinitely many more measures we can use
 - Thinking back to discussion 1, both the Manhattan distance and the Euclidean distance are based on the L-p norm.
- Euclidean distance -> L-2 Norm
- Manhattan distance -> L-1 Norm
- The default distance used in Scipy's KNN is Euclidean distance
 - This is fine to use!

$$\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}$$

HW3 Question 1.6

- Main idea for Q1.6:
 1. Choose some combination of hyperparameters (e.g. uniform sampling, patch features, $K=3$)
 2. Build a visual vocabulary from the entire training set
 3. Populate the KNN with the histograms from the entire training set
 4. Calculate accuracy on the test sets:
 1. Classify the histograms from the images in the positive test set
 2. Calculate accuracy on the positive test set
 3. Classify the histograms from the images in the negative test set
 4. Calculate the accuracy on the negative test set
 5. Repeat for the rest of the combinations: the methods for interest points, feature descriptors, and number of neighbors in KNN

For each combination, you should only create 1 visual vocabulary!

- One way to put this into words is that we want our classifier to use the “same vocabulary” during training time and test time
- You should however make a new vocabulary and KNN once you complete calculating accuracy on both test sets and changing to a different combination of hyperparameters.

HW3 Question 1 Debugging Help

- Read the descriptions of the functions to determine how you should format the variables before returning them
- **For debugging only**, I would recommend shrinking the number of images in the training set. You can use this to make the test code run faster to debug basic syntax and runtime errors
 - Please make sure you set the reset back to the entire training set before running 1.6 and submitting!
- Accuracy for this assignment is poor. You can expect 40-60% accuracy on each test set with the implementation choices we've made. You will not be marked down for this.
 - Perhaps we can increase the performance with different implementation choices