

Lecture II

Frequency response and the Fourier transform

Preview of today's lecture

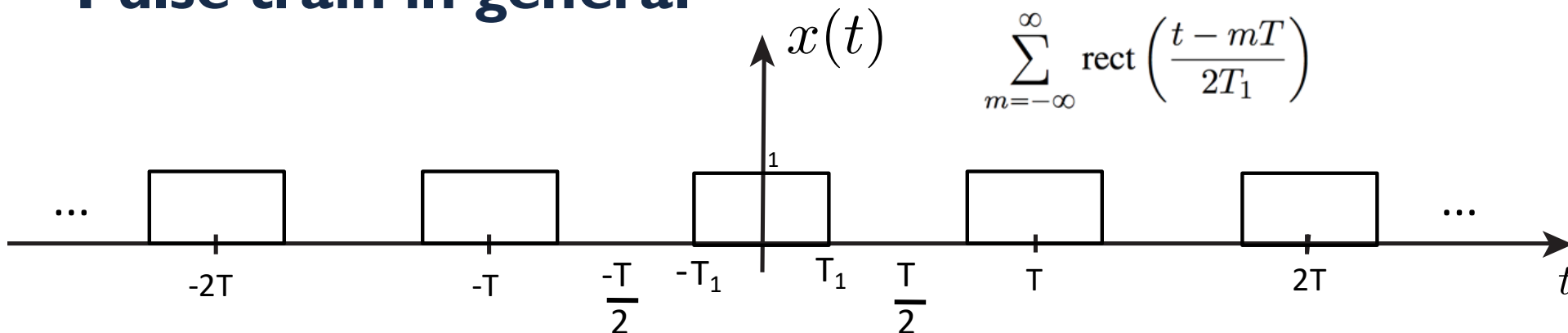
- ◆ Fourier series application examples
- ◆ Filtering a periodic signal
 - ★ Impact of filtering on the FS coefficients
 - ★ Types of common filters: lowpass, highpass, bandpass, bandstop
- ◆ Introduction to the Fourier transform

Basic signals

| | Time domain $x(t)$ | Fourier coefficients a_k |
|---|--|---|
| Constant (periodic for any T) | c | $c\delta[k]$ |
| Cosine | $\cos(\omega_0 t)$ | $\frac{1}{2}\delta[k-1] + \frac{1}{2}\delta[k+1]$ |
| Sine | $\sin(\omega_0 t)$ | $\frac{1}{2j}\delta[k-1] - \frac{1}{2j}\delta[k+1]$ |
| Impulse train | $\sum_{m=-\infty}^{\infty} \delta(t - mT)$ | $\frac{1}{T}$ |

Pulse train in general

From O&W Example 3.5



From the book

$$a_k = \frac{\sin\left(\pi k \frac{2T_1}{T}\right)}{k\pi} \quad k \neq 0$$

$$a_0 = \frac{2T_1}{T}$$

Rewritten using the sinc function $\text{sinc}(x) = \frac{\sin(\pi x)}{\pi x}$

$$a_k = \frac{\omega_0 T_1}{\pi} \text{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) \quad \text{with fundamental frequency}$$

$$a_k = \frac{2T_1}{T} \text{sinc}\left(\frac{k2T_1}{T}\right) \quad \text{simplified}$$

Fourier series properties

◆ Let $\mathbf{x}(t)$ and $\mathbf{y}(t)$ both have period $T = \frac{2\pi}{\omega_0}$, and

$$x(t) \xleftrightarrow{FS} a_k \qquad y(t) \xleftrightarrow{FS} b_k$$

| | Time domain | FS domain |
|---------------|-----------------|---------------------------|
| Linearity | $Ax(t) + By(t)$ | $Aa_k + Bb_k$ |
| Time shift | $x(t - t_0)$ | $a_k e^{-jk\omega_0 t_0}$ |
| Time reversal | $x(-t)$ | a_{-k} |

Fourier series properties (continued)

| | Time domain | FS domain |
|--------------------|--|---|
| Time scaling | $x(\alpha t)$ | a_k $T_{\text{new}} = \frac{T}{\alpha}$ period changes |
| Conjugate | $x^*(t)$ | a_{-k}^* |
| Multiplication | $x(t)y(t)$ | $\sum_{\ell=-\infty}^{\infty} a_{\ell} b_{k-\ell}$ |
| Derivative | $\frac{d}{dt}x(t)$ | $a_k(jk\omega_0)$ |
| Parseval's Theorem | $\frac{1}{T} \int_T x(t) ^2 dt = \sum_{k=-\infty}^{\infty} a_k ^2$ | |

Fourier series and symmetry

| | Time domain | FS domain |
|--------------------|----------------------|---------------------|
| Conjugate symmetry | $x(t)$ real | $a_k = a_{-k}^*$ |
| Real and even | $x(t)$ real and even | a_k real and even |
| Real and Odd | $x(t)$ real and odd | a_k imag. and odd |

Application Example 6

- ◆ Let $x(t)$ be a periodic signal whose FS coefficients are

$$a_k = \begin{cases} 2 & k = 0 \\ j(1/2)^{|k|} & \text{otherwise} \end{cases}$$

- ◆ Is $x(t)$ real?

★ Real signals must satisfy $x(t) = x^*(t)$ or $a_k = a_{-k}^*$ not satisfied here

- ◆ Is $x(t)$ even?

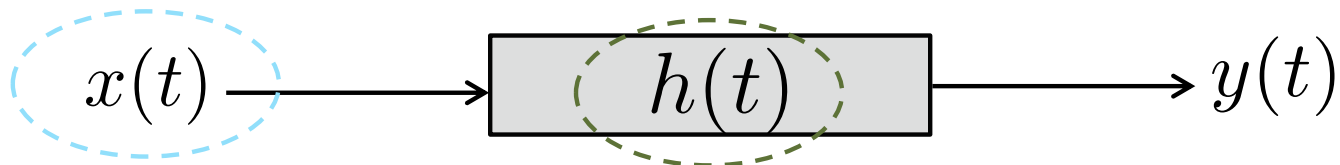
★ Even signals satisfy $x(t) = x(-t)$ or $a_k = a_{-k}$ yes is satisfied

- ◆ Is $\frac{dx(t)}{dt}$ even?

★ The FS coefficients of $\frac{dx(t)}{dt}$ are $(j\omega_0 k)a_k$ for which $(j\omega_0 k)a_k \neq -(j\omega_0 k)a_{-k}$

Connections back to ECE 45

Lectures 2 - 3 working with signals



Lectures 4 - 7 LTI systems in the time domain

Lectures 11-12 LTI systems in the frequency domain



Lectures 8 - 10 Fourier series

Lectures 13 - 17 Fourier transform

Fourier

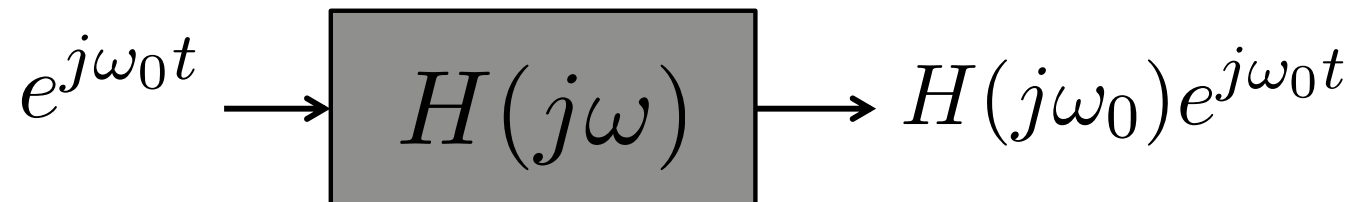
Filtering periodic signals

Key points

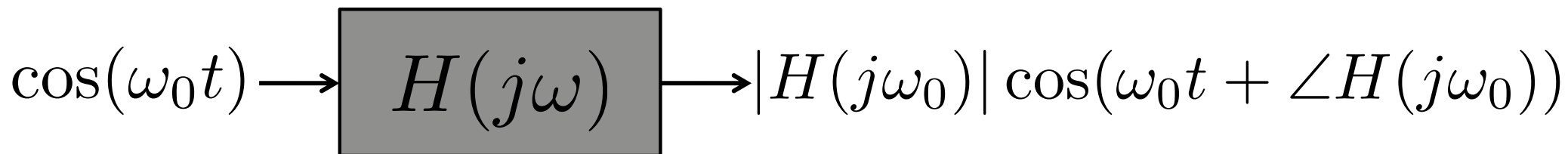
- Explain how LTI systems impact signals
- Distinguish between different kinds of frequency filters

Recall the implications of the eigenfunction property

◆ General case



◆ Special case for real impulse responses



How to find the frequency response?

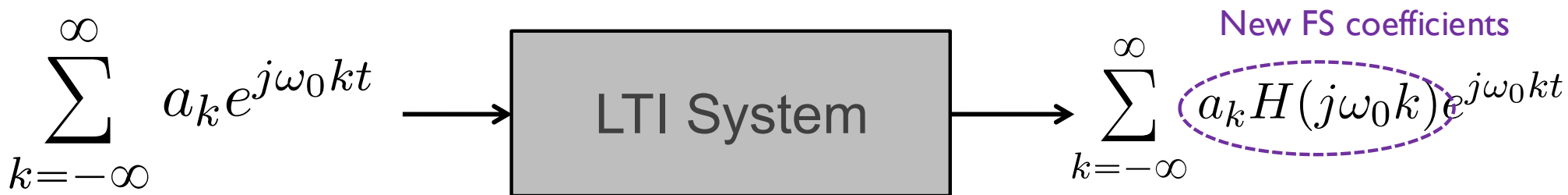
- ◆ If the system is described by a differential equation

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k} \quad \Rightarrow \quad H(j\omega) = \frac{\sum_{k=0}^M b_k (j\omega)^k}{\sum_{k=0}^N a_k (j\omega)^k}$$


- ◆ If you have the impulse response, compute the Fourier transform

$$H(j\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt$$

Impact of LTI systems on periodic signals

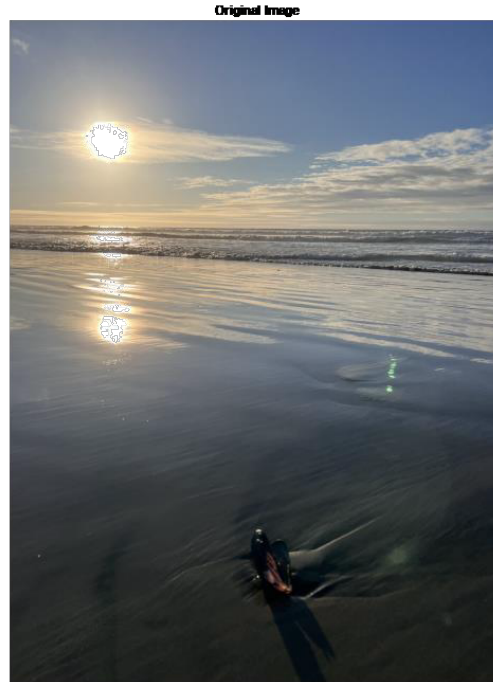


Fourier series coefficients are modified by the frequency response of the system

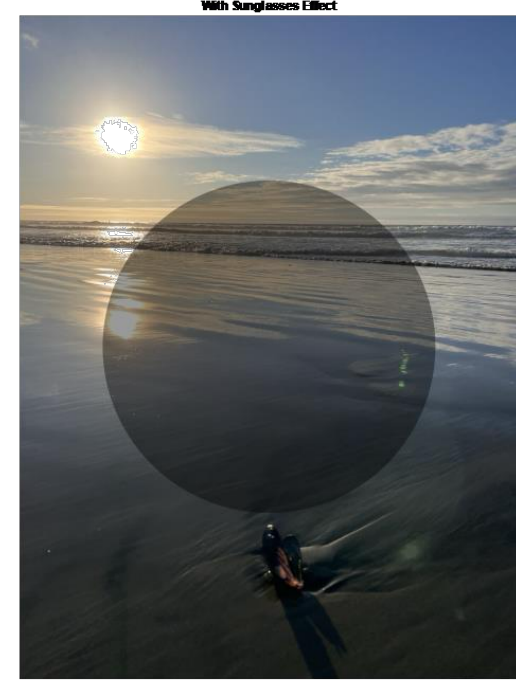
General concept of a filter



Coffee filter



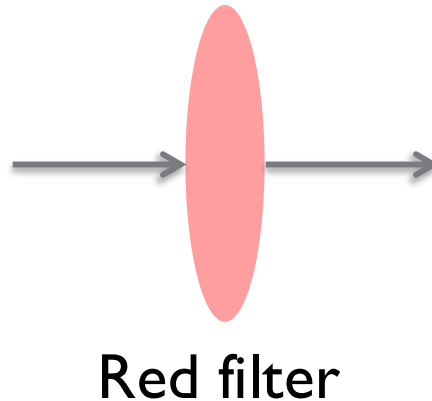
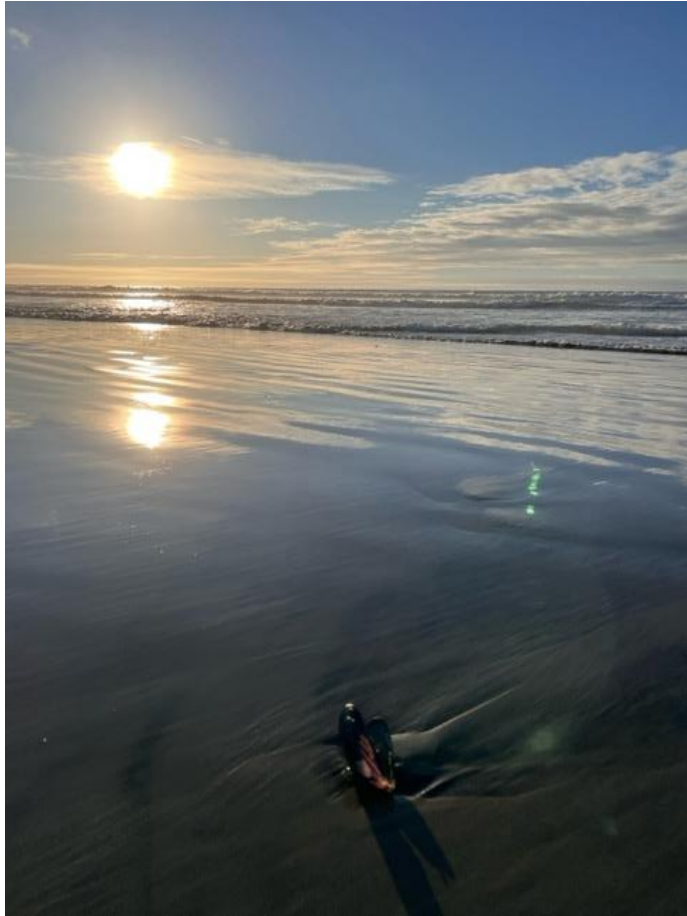
Original Image



With Sunglasses Effect

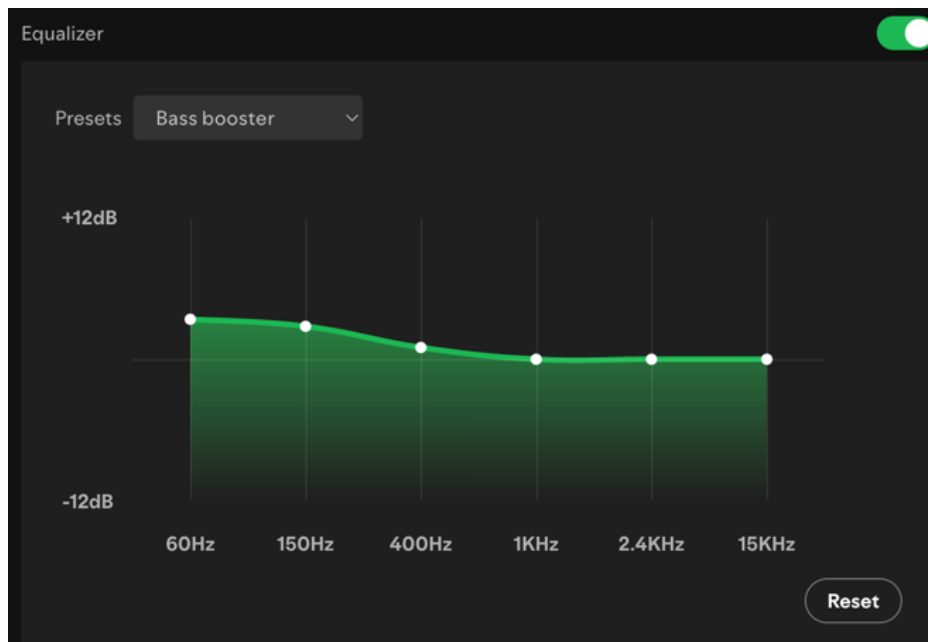
Sunglasses

Filtering an image to enhance the red



Modify the frequency content of the signal to create a sunset effect

Filtering a signal to enhance the bass

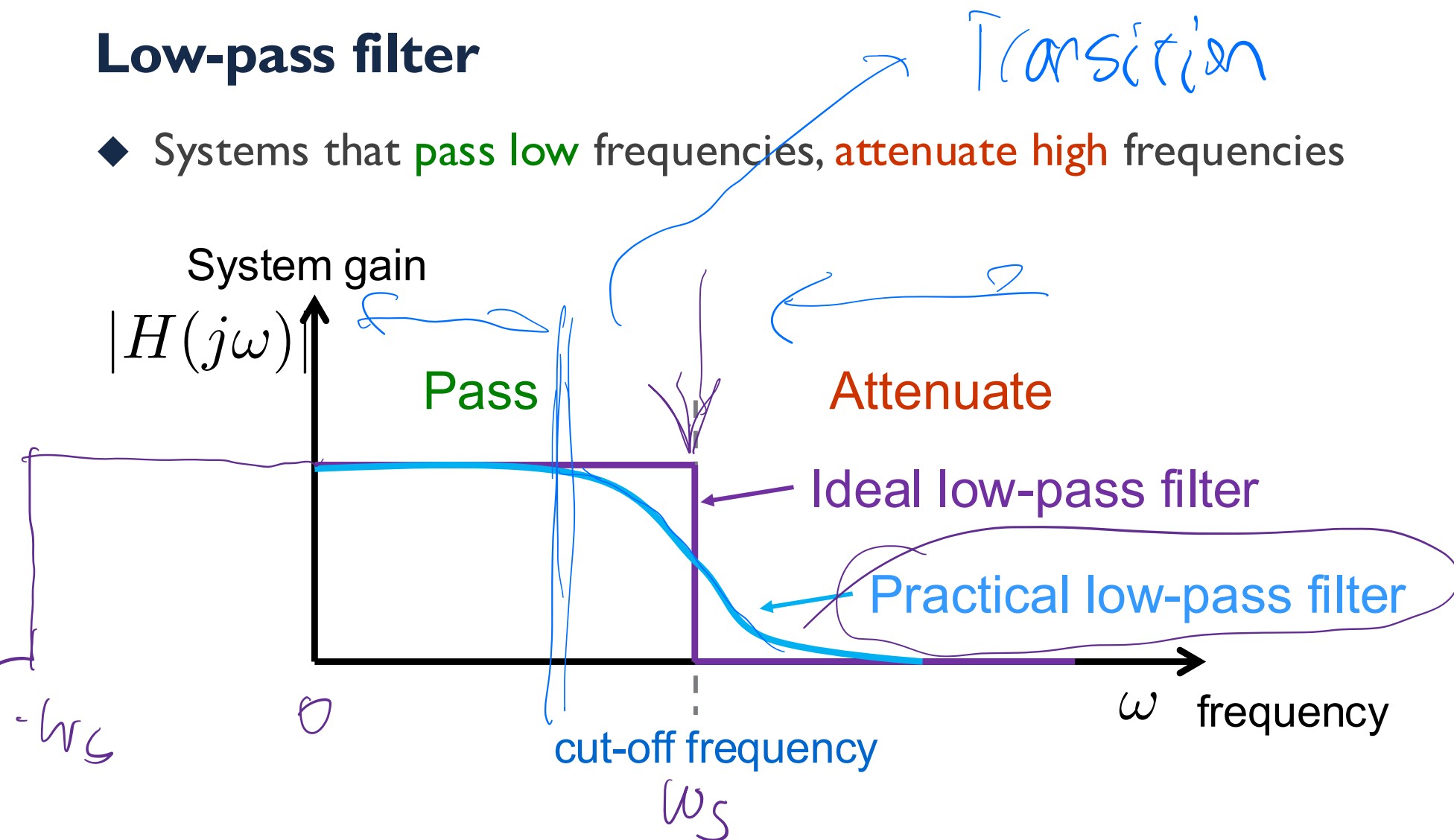


Change the frequency content of audio playback per personal preference

example of Spotify pre-set equalizer settings

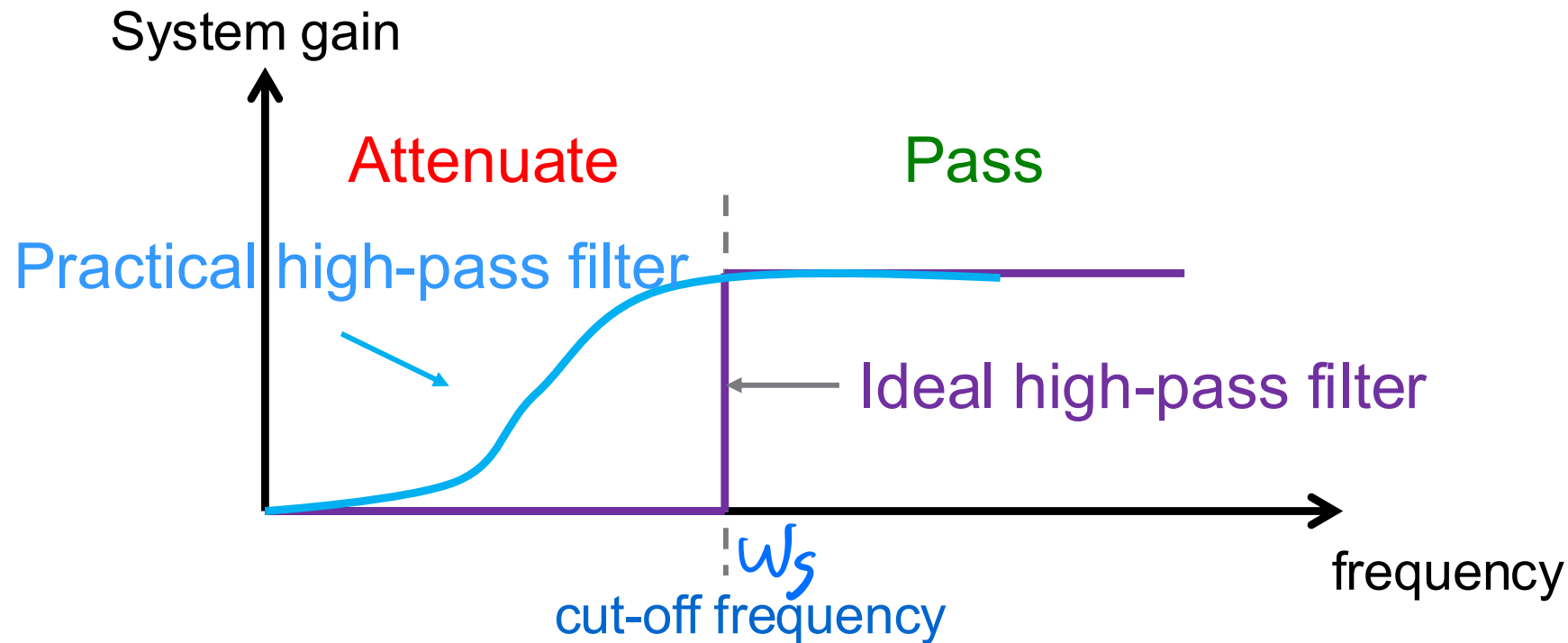
Low-pass filter

- ◆ Systems that **pass low** frequencies, **attenuate high** frequencies



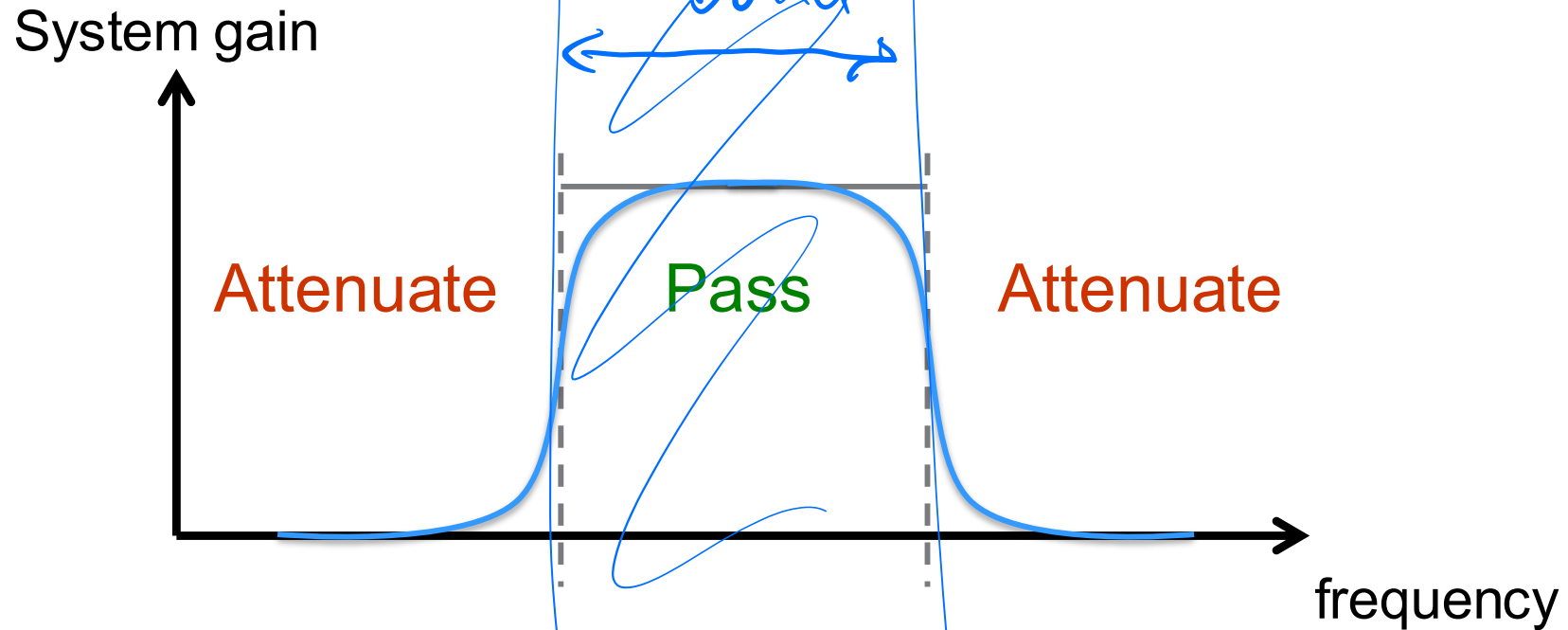
High-pass filters (HPFs)

- ◆ Systems that **pass high** frequencies, **attenuate low** frequencies



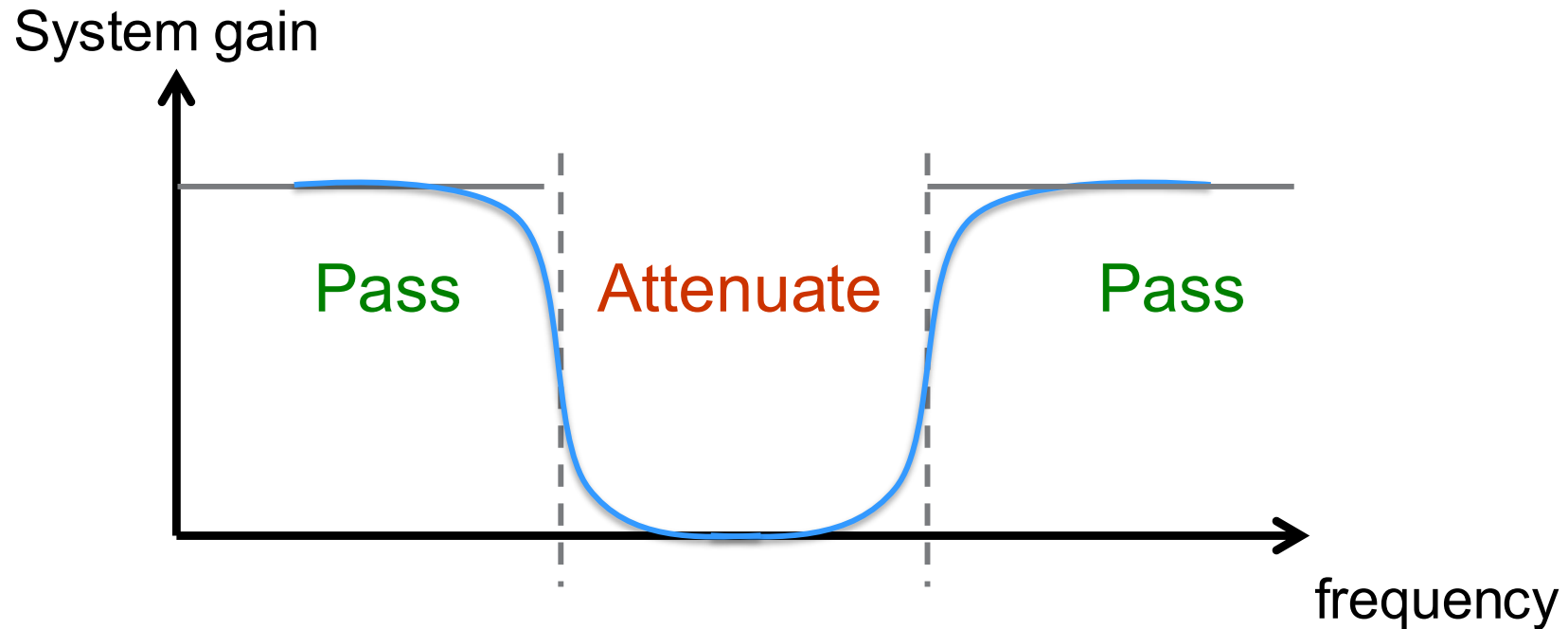
Band-pass filters

- ◆ A specific band is passed, and outside this band is attenuated



Band-stop (notch) filters

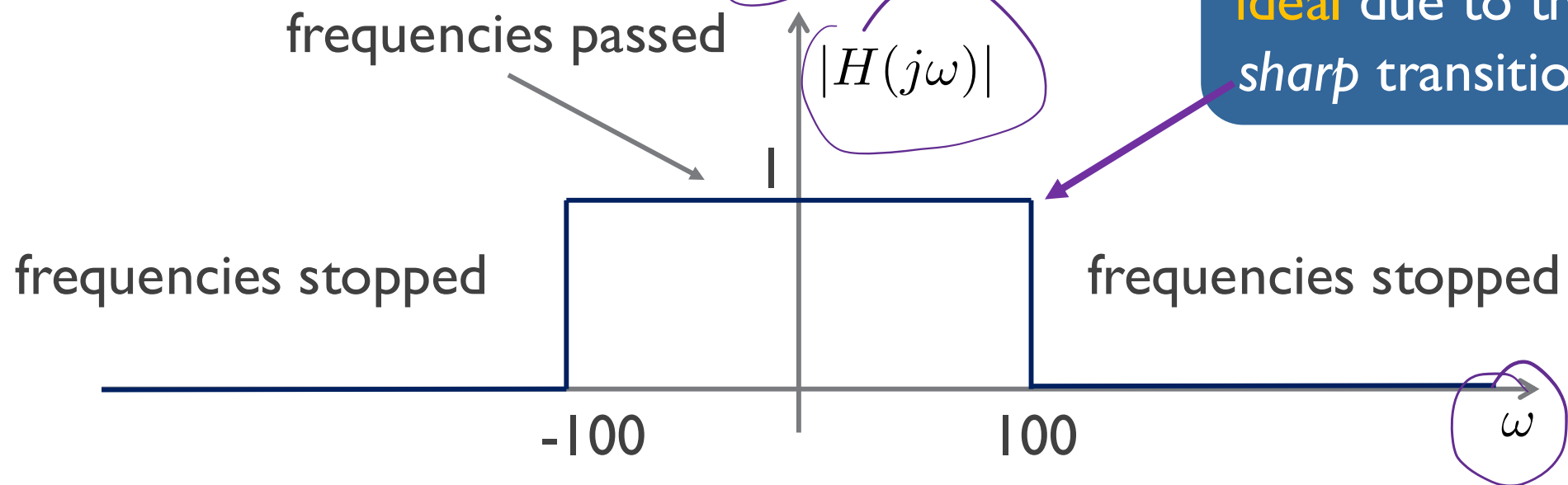
- ◆ **Stop** (attenuates) a **certain band**, and **passes the other frequencies**



Example: Low-pass filtering a periodic signal I

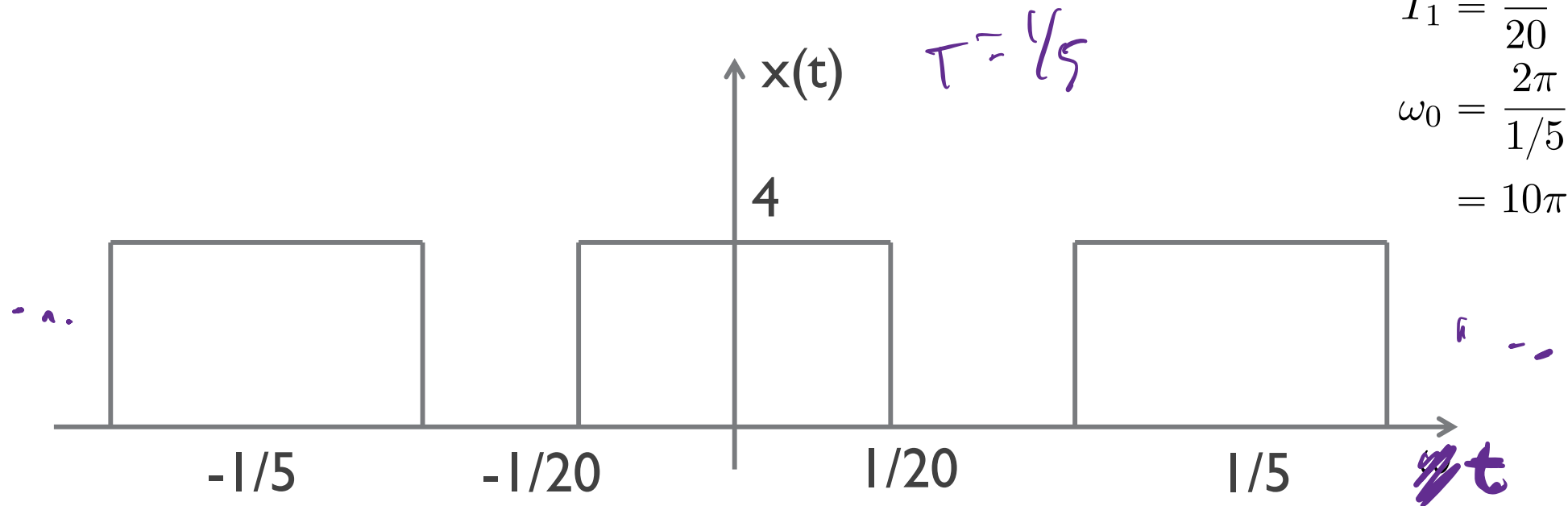
- ◆ Consider an **ideal low-pass filter** whose frequency response is

$$H(j\omega) = \begin{cases} 1, & |\omega| \leq 100 \\ 0, & |\omega| > 100 \end{cases}$$



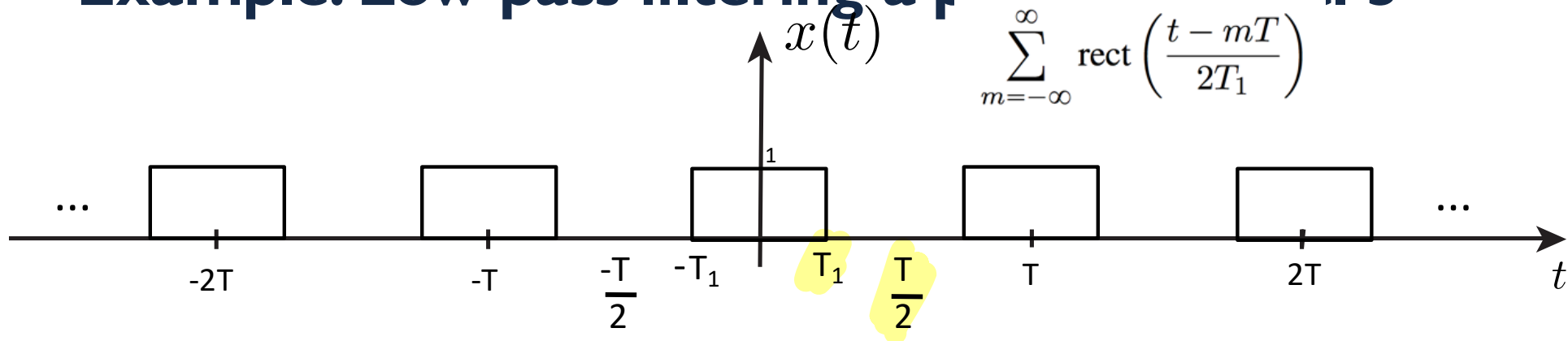
Example: Low-pass filtering a periodic signal 2

- ◆ Find the output if the input signal is



Square wave with period $T = 1/5$

Example: Low-pass filtering a periodic signal 3



From the book

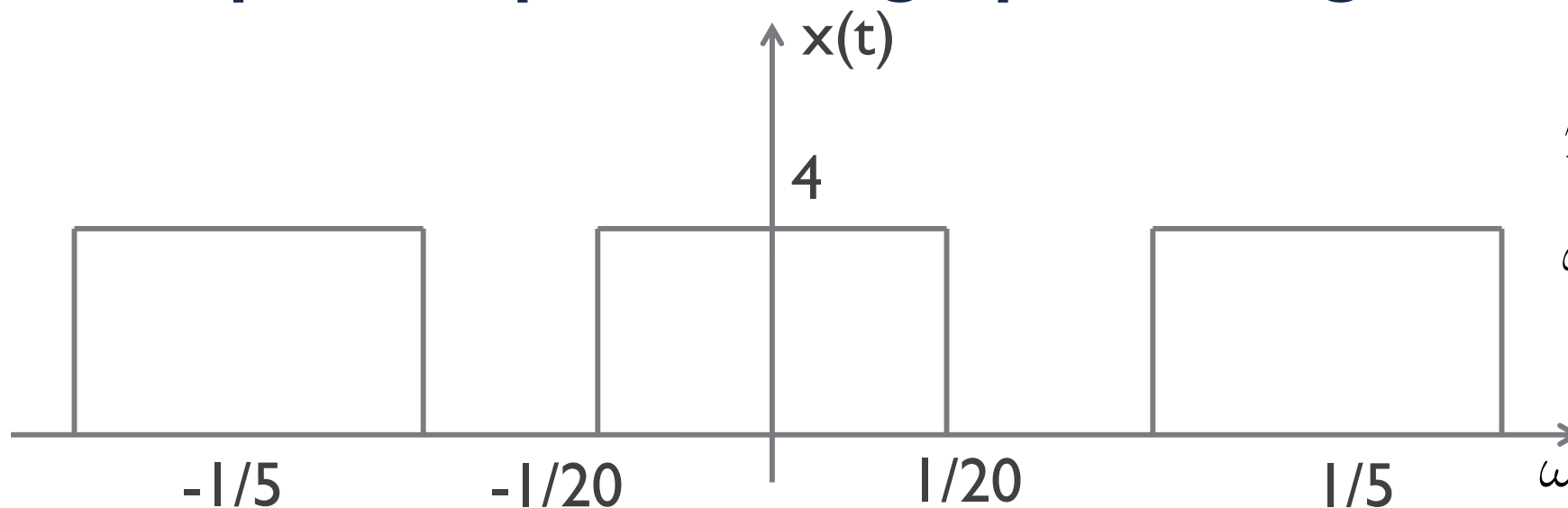
$$a_k = \frac{\sin\left(\pi k \frac{2T_1}{T}\right)}{k\pi} \quad k \neq 0$$

$$a_0 = \frac{2T_1}{T}$$

Rewritten using the sinc function $\text{sinc}(x) = \frac{\sin(\pi x)}{\pi x}$
(for connecting to results in later lectures)

$$a_k = \frac{2T_1}{T} \text{sinc}\left(\frac{k2T_1}{T}\right)$$

Example: Low-pass filtering a periodic signal 4



$$T = \frac{1}{5}$$

$$T_1 = \frac{1}{20}$$

$$\omega_0 = \frac{2\pi}{1/5}$$

$$= 10\pi$$

Period $T = \frac{1}{5}$

Rectangle size $T_1 = \frac{1}{20}$

Fundamental frequency $\omega_0 = \frac{2\pi}{1/5}$
 $= 10\pi$

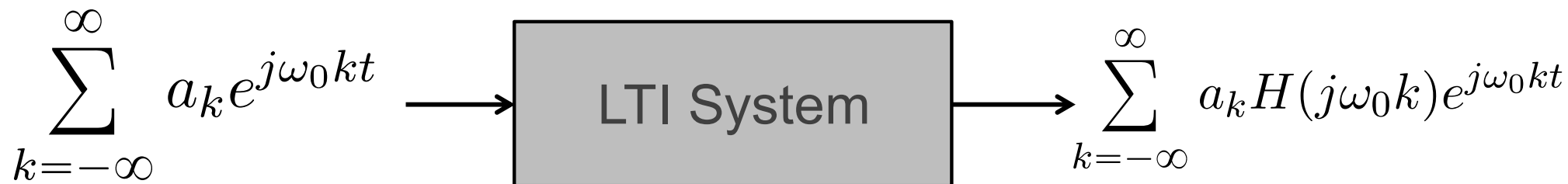
Fourier series coefficients

$$k \neq 0 \quad a_k = \frac{4}{\pi k} \sin\left(\pi k \frac{1}{2}\right)$$

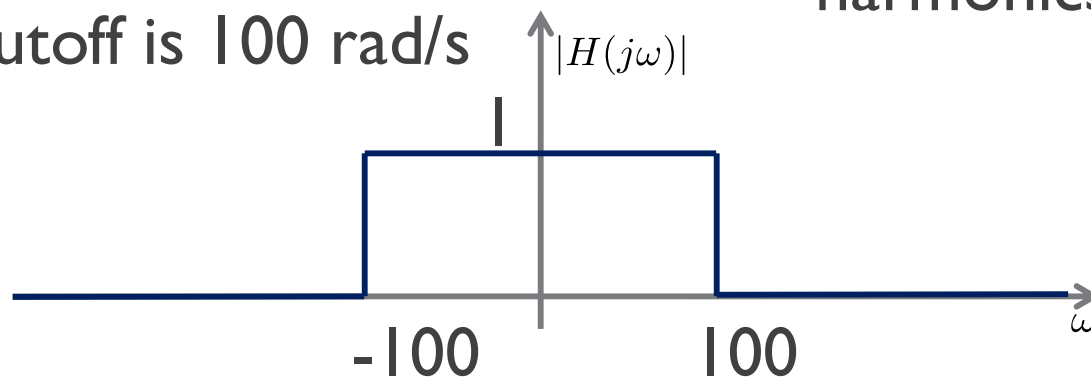
$$k = 0 \quad a_0 = 2$$

(note effect of scaling by 4)

Example: Low-pass filtering a periodic signal 5



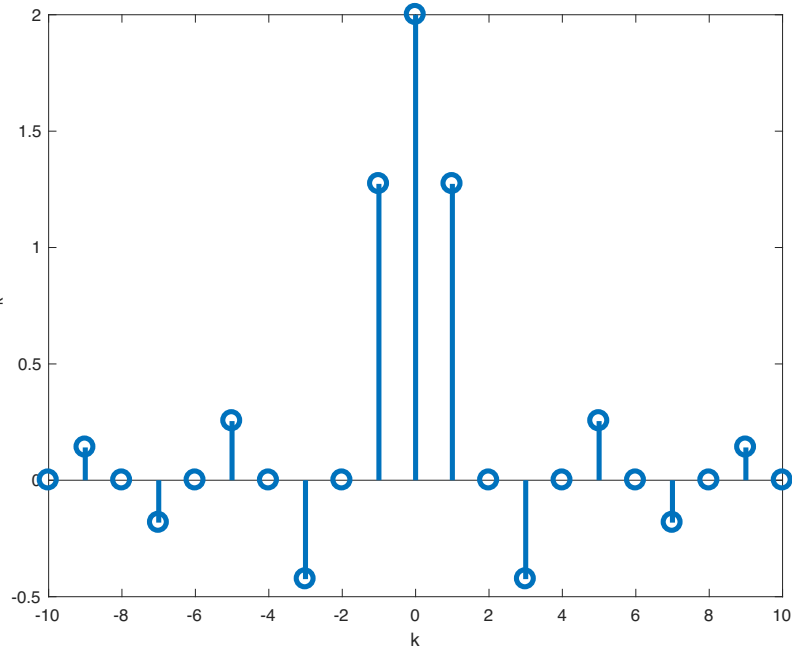
cutoff is 100 rad/s harmonics are at frequencies $k\omega_0$



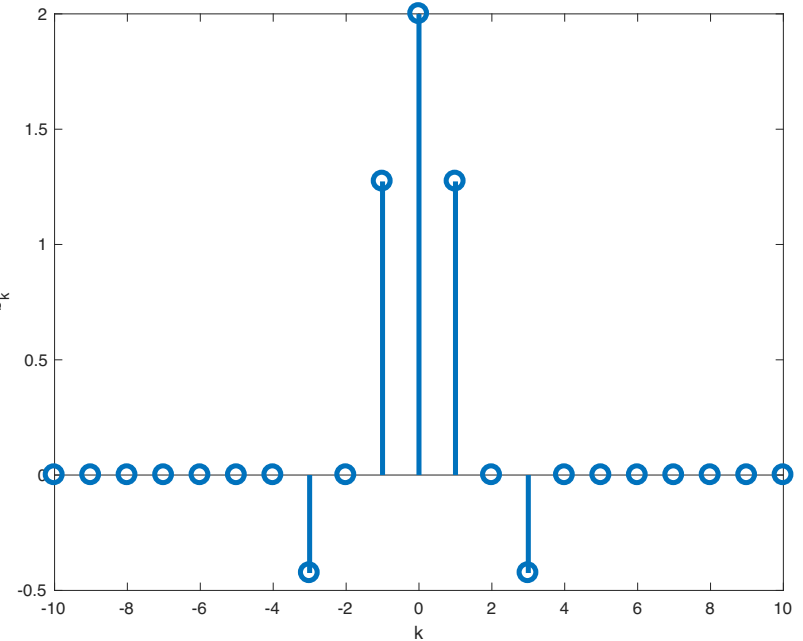
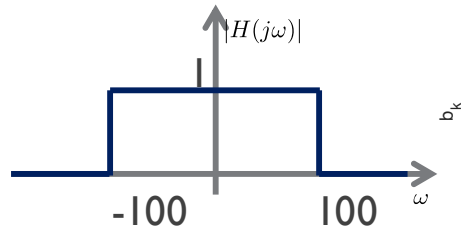
$$\begin{aligned}
 \omega_0 &= 10\pi \approx 31.4 \\
 2\omega_0 &= 2 \cdot 10\pi \approx 62.8 \\
 3\omega_0 &= 3 \cdot 10\pi \approx 94.2 \\
 4\omega_0 &= 4 \cdot 10\pi \approx 125.6
 \end{aligned}$$

Fourier series coefficients are modified by the frequency response of the system

Example: Low-pass filtering a periodic signal 6

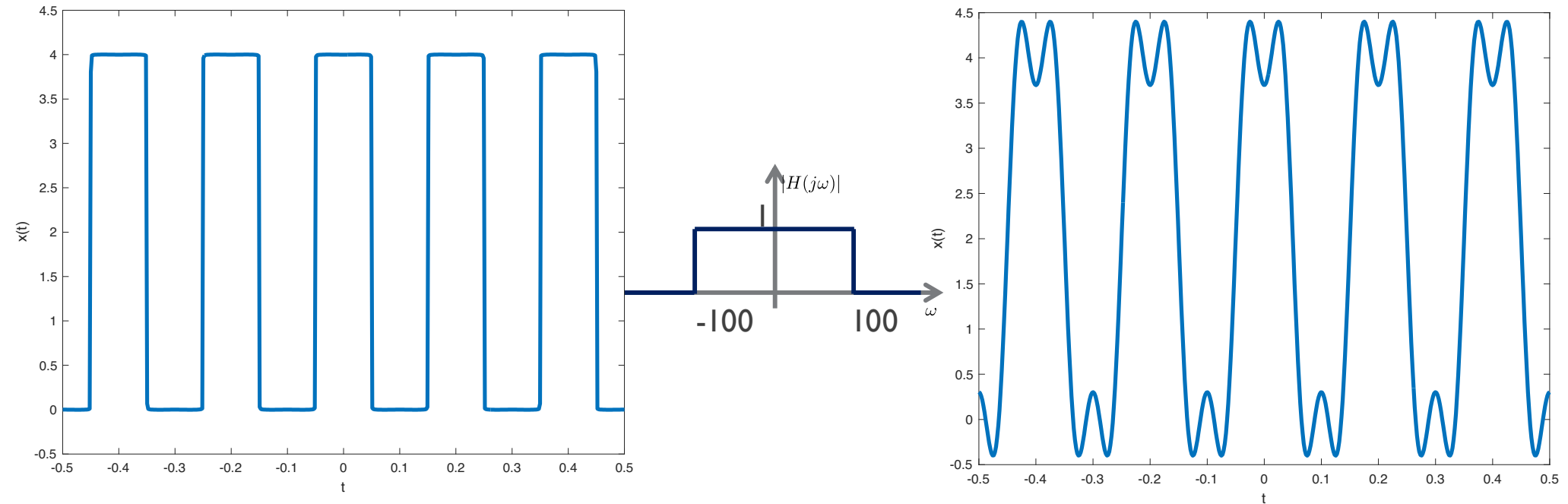


Fourier coefficients
before the LTI system



Fourier coefficients
after the LTI system

Example: Low-pass filtering a periodic signal 7



Time domain signal
before the LTI system

Time domain signal
after the LTI system

Frequency response summary

- ◆ If the input to an LTI system is periodic, then the output is also periodic with the same period
- ◆ LTI systems impact the amplitude and phase of the Fourier series coefficients as determined by the frequency response of the system
- ◆ To determine the effect of an LTI system on a periodic signal, compute the Fourier transform of the impulse response and evaluate it at multiples of the fundamental frequency $k\omega_0$

Fourier transform

Key points

- Define Fourier transform
- Determine the Fourier transforms of ~~CT and DT~~ signals

Fourier transform for all signals

- ◆ For a signal $\mathbf{x}(t)$, the **Fourier transform (FT)** $X(j\omega)$ is

$$\begin{aligned} X(j\omega) &= \mathcal{F}\{x(t)\} \\ &= \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \end{aligned}$$

- ◆ The notation $\mathcal{F}\{\cdot\}$ means to take the Fourier transform of the function inside the brackets
- ◆ In some books, $X(\omega)$ is used instead of $X(j\omega)$

No periodicity assumption in the signal

Fourier series for **periodic** signals

- ◆ Consider the periodic signal $x(t)$ with period T : $x(t + T) = x(t)$
- ◆ The Fourier series representation of the **periodic** signal $x(t)$ is

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

$k\omega_0$

where $\omega_0 = \frac{2\pi}{T}$ is the **fundamental frequency**

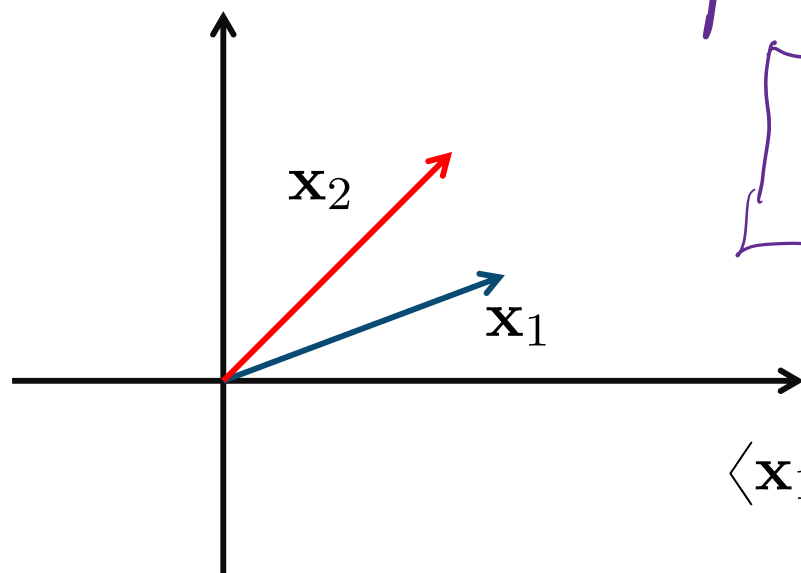
- ◆ The Fourier series coefficients of $x(t)$ are $\{a_k\}$ and a_0 is DC
- ◆ The **k-th harmonic components** of $x(t)$ are a_k and a_{-k}

Interpreting the Fourier transform

- ◆ The Fourier transform can be written

$$X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

$= \langle x(t), e^{j\omega t} \rangle$
Inner product



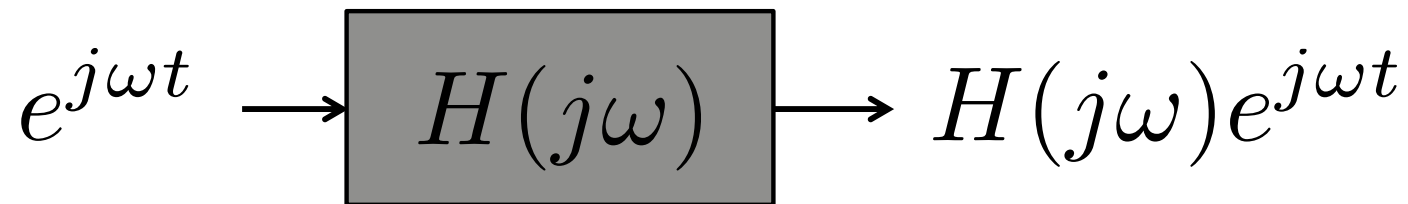
$$\langle \mathbf{x}_1, \mathbf{x}_2 \rangle$$

Measures how much the vectors
“line up” with each other

How much does $x(t)$ look like complex sinusoid $e^{j\omega t}$ with frequency ω ?

Why do we care about complex sinusoids anyways?

- ◆ For an LTI system, with input $e^{j\omega t}$ it is easy to compute the output



- ◆ If a signal can be represented as a sum of sinusoids, then it is possible to compute the output of an LTI system

without convolution

Fourier transform!!

- ◆ Further notice that

$$H(j\omega) = \int_{-\infty}^{\infty} h(t)e^{-j\omega t} dt$$

Example – Unit impulse

- ◆ Consider the signal

$$x(t) = \delta(t)$$

- ◆ Its FT is given by

$$X(j\omega) = \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt$$

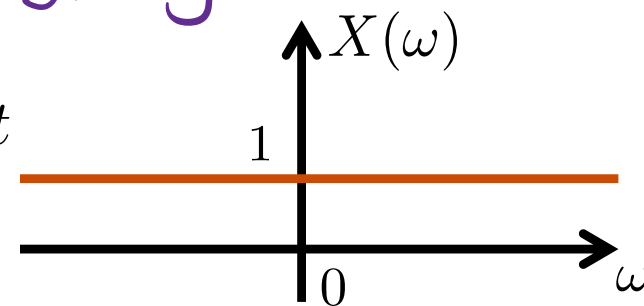
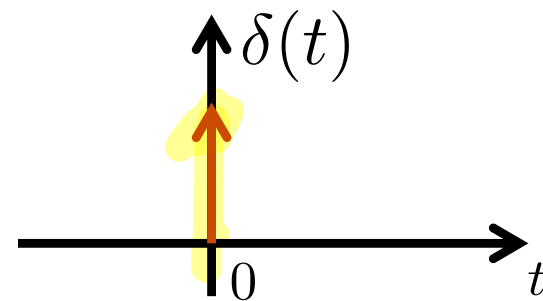
$$= \int_{-\infty}^{\infty} \delta(t) e^{-j\omega 0} dt$$

$$= \int_{-\infty}^{\infty} \delta(t) dt$$

$$= 1$$

① Plug in

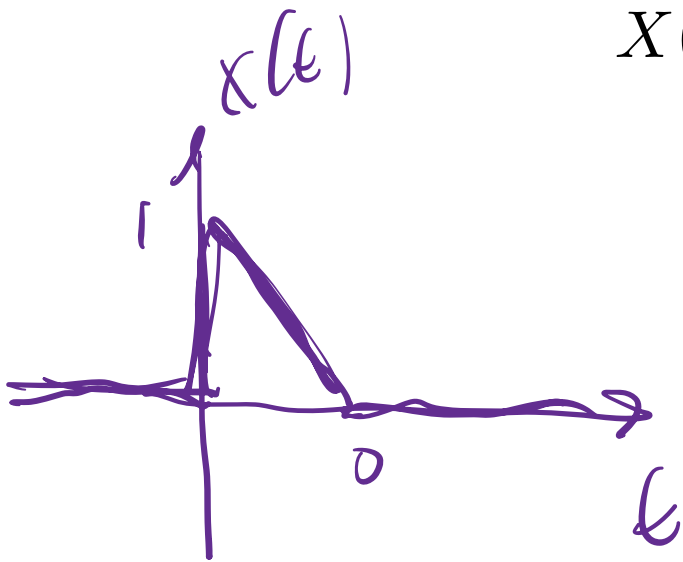
sitting



Example - Triangle

◆ Compute the Fourier transform of $x(t) = \begin{cases} 1 - t & t \in [0, 1] \\ 0 & \text{else} \end{cases}$

◆ Solution:



$$X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

$$= \int_0^1 (1 - t)e^{-j\omega t} dt$$

$$= \int_0^1 e^{-j\omega t} dt - \int_0^1 te^{-j\omega t} dt$$

plug in
+ simplify

Example - Triangle (continued)

- ◆ Compute the Fourier transform of $x(t) = \begin{cases} 1 - t & t \in [0, 1] \\ 0 & \text{else} \end{cases}$
- integrate by parts*

- ◆ Solution:

$$\begin{aligned}
 X(j\omega) &= \int_0^1 e^{-j\omega t} dt - t \frac{1}{-j\omega} e^{-j\omega t} \Big|_0^1 + \int_0^1 \frac{1}{-j\omega} e^{-j\omega t} dt \\
 &= \int_0^1 e^{-j\omega t} dt - t \frac{1}{-j\omega} e^{-j\omega t} \Big|_0^1 + \left(\frac{1}{j\omega} \right)^2 e^{-j\omega t} \Big|_0^1 \\
 &= \frac{1}{j\omega} - \frac{1}{j\omega} e^{-j\omega} + \frac{1}{j\omega} e^{-j\omega} - \frac{1}{\omega^2} e^{-j\omega} + \frac{1}{\omega^2} \\
 &= \frac{1}{j\omega} - \frac{1}{\omega^2} e^{-j\omega} + \frac{1}{\omega^2}
 \end{aligned}$$

Inverse Fourier transform ^{*j\omega*}

- ◆ Given the frequency response $X(j\omega)$, $x(t)$ is given by the **inverse Fourier transform**

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$= \mathcal{F}^{-1}\{X(j\omega)\}$$

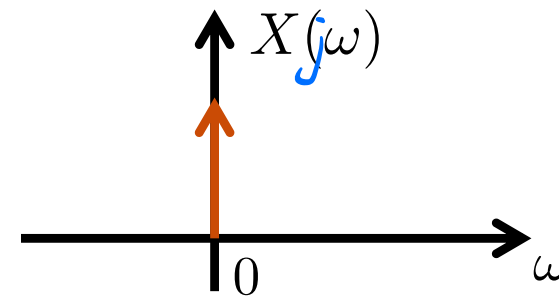
- ◆ Transform looks similar to direct transform except
- ★ Sign of the exponential is different
 - ★ Scaling factor in front (results from using radians and not Hertz)

Similarity will lead to the concept of **duality**

Example – Unit impulse in frequency

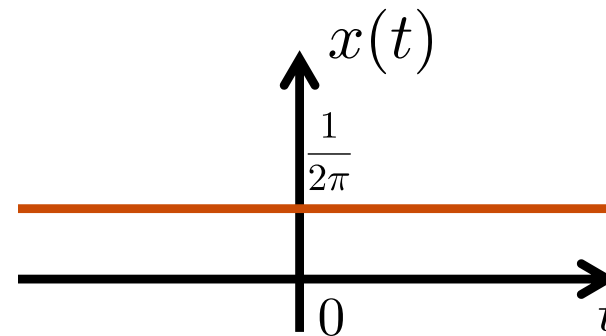
- ◆ Consider the signal

$$X(j\omega) = \delta(\omega)$$



- ◆ Its FT is given by

$$\begin{aligned} x(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \delta(\omega) e^{j\omega t} d\omega \\ &= \frac{1}{2\pi} \end{aligned}$$



Notice the **duality** here in each domain

Example – Shifted delta in frequency

- ◆ Consider an impulse in the frequency domain $X(j\omega) = \delta(\omega - \omega_0)$
- ◆ Its inverse FT is given by

$$\begin{aligned}
 x(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \delta(\omega - \omega_0) e^{j\omega t} d\omega \\
 &= \frac{e^{j\omega_0 t}}{2\pi} \underbrace{\int_{-\infty}^{\infty} \delta(\omega - \omega_0) d\omega}_1 \\
 &= \frac{e^{j\omega_0 t}}{2\pi}
 \end{aligned}$$

Example – A few deltas in frequency

- ◆ Use the Fourier transform synthesis equation to determine the inverse Fourier transform of

$$X(\omega) = 2\pi\delta(\omega) + \pi\delta(\omega - 4\pi) + \pi\delta(\omega + 4\pi)$$

- ◆ Solution

$$\begin{aligned}
 x(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} (2\pi\delta(\omega) + \pi\delta(\omega - 4\pi) + \pi\delta(\omega + 4\pi)) e^{j\omega t} d\omega \\
 &= \frac{1}{2\pi} (2\pi e^{j0t} + \pi e^{j4\pi t} + \pi e^{-j4\pi t}) \\
 &= 1 + \frac{1}{2} e^{j4\pi t} + \frac{1}{2} e^{-j4\pi t} \\
 &= 1 + \cos(4\pi t)
 \end{aligned}$$

\mathcal{Q}_1
 \mathcal{Q}_{-1}

Summarizing the Fourier transform and its inverse

Fourier transform (analysis)

$$X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

Inverse Fourier transform (synthesis)

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)e^{j\omega t} d\omega$$

$$x(t) \leftrightarrow X(j\omega)$$

Note: An alternative formulation that is common uses Hertz rather than radians/sec

Fourier transform in Hertz

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt \quad f \text{ in Hz}$$

Inverse Fourier transform from $X(f)$ (note lack of $1/2\pi$)

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi ft} df$$

In EE 45 we will use $X(j\omega)$