

ECE 101 - Spring 2025
Linear Systems Fundamentals
Midterm Exam Review Topics

1 Useful Identities

Complex numbers and trigonometry

- Complex arithmetic, magnitude, phase, triangle inequality
- Euler's formula: $e^{j\theta} = \cos \theta + j \sin \theta$
- Evaluation of complex exponential $e^{j\theta}$ at standard angles (e.g., $\pi, \frac{\pi}{2}, \frac{\pi}{3}, \frac{\pi}{4}, \frac{\pi}{6}$)
- Basic trigonometric identities:

$$\cos \theta = \frac{1}{2} (e^{j\theta} + e^{-j\theta}) ; \sin \theta = \frac{1}{2j} (e^{j\theta} - e^{-j\theta})$$

$$e^{j(A+B)} = \cos(A+B) + j \sin(A+B)$$

$$\begin{aligned} e^{jA} e^{jB} &= (\cos(A) + j \sin(A))(\cos(B) + j \sin(B)) \\ &= (\cos(A) \cos(B) - \sin(A) \sin(B)) + j(\sin(A) \cos(B) + \cos(A) \sin(B)) \end{aligned}$$

$$\cos(A+B) = \cos(A) \cos(B) - \sin(A) \sin(B) ; \sin(A+B) = \sin(A) \cos(B) + \cos(A) \sin(B)$$

$$\cos(A-B) = \cos(A) \cos(B) + \sin(A) \sin(B) ; \sin(A-B) = \sin(A) \cos(B) - \cos(A) \sin(B)$$

$$\sin(A) \cos(B) = \frac{1}{2} (\sin(A+B) + \sin(A-B))$$

$$\cos(A) \cos(B) = \frac{1}{2} (\cos(A+B) + \cos(A-B)) ; \sin(A) \sin(B) = \frac{1}{2} (\cos(A-B) - \cos(A+B))$$

- Infinite geometric series:
$$\sum_{n=0}^{\infty} z^n = \frac{1}{1-z}, \text{ for } |z| < 1.$$
$$\sum_{n=0}^{\infty} n z^n = \frac{z}{(1-z)^2}, \text{ for } |z| < 1.$$

- Finite geometric series:

$$\sum_{n=0}^{N-1} z^n = \begin{cases} N & z = 1 \\ \frac{1-z^N}{1-z} & \text{for any complex } z \neq 1. \end{cases}$$

- Useful identities involving complex exponentials:

$$1 + e^{-jM} = e^{-j\frac{M}{2}} \left(e^{j\frac{M}{2}} + e^{-j\frac{M}{2}} \right) = 2e^{-j\frac{M}{2}} \cos\left(\frac{M}{2}\right)$$

$$1 - e^{-jM} = e^{-j\frac{M}{2}} \left(e^{j\frac{M}{2}} - e^{-j\frac{M}{2}} \right) = 2je^{-j\frac{M}{2}} \sin\left(\frac{M}{2}\right)$$

2 Signals - Chapter 1

- Signal energy and power

Total energy (CT): $E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dt$

Total energy (DT): $E_{\infty} = \sum_{n=-\infty}^{\infty} |x[n]|^2$

Average power (CT): $P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$

Average power (DT): $P_{\infty} = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$

For periodic signals:

Average power in one period (CT): $\frac{1}{T} \int_T |x(t)|^2 dt$

Average power in one period (DT): $\frac{1}{N} \sum_{n=\langle N \rangle} |x[n]|^2$

- Transformations of independent variable
 - Time shifting, time reversal, time scaling
 - Interpretations of $x(at - b)$
 - * Shift by b , then scale by a
 - * Scale by a , then shift by b/a
 - Interpretations of $x[an - b]$, a, b integers
 - * Shift by b , then scale (decimate) by a
- Periodic signals
 - Periodicity conditions
 - Fundamental period and frequency
 - Finding fund. period/frequency of the sum of periodic signals
 - Periodicity and scaling
- Even and Odd signals
 - Definitions of even and odd signals,
 - Even-odd decomposition theorem: $x(t) = \mathcal{E}v\{x(t)\} + \mathcal{O}d\{x(t)\}$
where $\mathcal{E}v\{x(t)\} = \frac{x(t)+x(-t)}{2}$ and $\mathcal{O}d\{x(t)\} = \frac{x(t)-x(-t)}{2}$
- CT and DT impulse and unit step signals
 - Relationships
$$\sum_{n=-\infty}^{\infty} \delta[n] = 1$$
$$\delta[n] = u[n] - u[n-1]$$
$$\delta[n] = u[n] - u[n-1]$$
$$u[n] = \sum_{k=0}^{\infty} \delta[n-k] = \sum_{k=-\infty}^n \delta[k]$$

- $$\int_{-\infty}^{\infty} \delta(t) dt = 1$$
- $$\delta(t) = \frac{d}{dt} u(t)$$
- $$u(t) = \int_0^{\infty} \delta(t - \tau) d\tau = \int_{-\infty}^t \delta(\tau) d\tau$$
- Sampling and sifting properties

$$x[n] \delta[n - n_0] = x[n_0] \delta[n - n_0]$$

$$\sum_{n=-\infty}^{\infty} x[n] \delta[n - n_0] = x[n_0]$$

$$x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0)$$

$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)$$
 - Representation property

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - k]$$

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$
 - Complex exponential signals

CT: $x(t) = ce^{at}$, $c, a \in \mathbb{C}$

DT: $x[n] = c\alpha^n$, $c, \alpha \in \mathbb{C}$

$x(t) = e^{j\omega_0 t}$ periodic, fund. frequency ω_0 , fund. period $T = 2\pi/\omega_0$

$x[n] = e^{j\Omega_0 n}$ periodic in n if and only if $\Omega_0 = 2\pi m/N$, for $m, N \in \mathbb{Z}, N > 0$

If $\gcd(m, N) = 1$, fund. period N , fund. frequency $2\pi/N$

$x[n] = e^{j\Omega_0 n}$ periodic in Ω , period 2π .

3 Systems - Chapters 1 and 2

- **Basic system properties**

Memoryless: output at time n does not depend on inputs before or after time n

Invertible: distinct input signals produce distinct output signals

Causal: output at time n does not depend on inputs after time n

Stable: bounded input signals produces bounded output signals

Time-invariant: $x(t)$ produces $y(t) \Rightarrow x(t - t_0)$ produces $y(t - t_0)$

Linear: additive and scalable
- **System impulse response and step response (for any system)**

Input $\delta(t)$ produces impulse response $h(t)$

Input $u(t)$ produces step response $s(t)$

- **LTI systems**

Linear (additive and scalable) and time-invariant.

The impulse response $h(t)$ or $h[n]$ characterizes the system

$$\text{CT: } y(t) = x(t) * h(t) \quad \text{DT: } y[n] = x[n] * h[n]$$

- **Relationship between impulse response and step response**

$$s(t) = \int_{-\infty}^t h(\tau) d\tau \quad h(t) = \frac{ds(t)}{dt}$$

$$s[n] = \sum_{k=-\infty}^n h[k] \quad h[n] = s[n] - s[n-1]$$

- **Convolution formulas (DT and CT)**

$$\text{Convolution sum formula: } y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k] = x[n] * h[n]$$

$$\text{Convolution integral formula } y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau = x(t) * h(t)$$

- **Properties of convolution**

Commutativity, associativity, distributivity over addition

Convolution with shifted impulse:

$$\text{CT: } x(t) * \delta(t - t_0) = x(t - t_0); \quad \text{DT: } x[n] * \delta[n - n_0] = x[n - n_0]$$

Convolution with unit step:

$$\text{CT: } x(t) * u(t) = \int_{-\infty}^t x(\tau) d\tau; \quad \text{DT: } x[n] * u[n] = \sum_{k=-\infty}^n x[k]$$

- **Impulse response of serial and parallel concatenations of LTI systems.**

(shown here for CT systems; similar for DT systems)

$$\text{Serial: } h(t) = h_1(t) * h_2(t)$$

$$\text{Parallel: } h(t) = h_1(t) + h_2(t)$$

- **Impulse response and properties of LTI systems**

(shown here for CT systems; similar for DT systems)

$$\text{Memoryless: } h(t) = a\delta(t)$$

$$\text{Invertible: There exists } g(t) \text{ such that } h(t) * g(t) = \delta(t)$$

(necessary condition, also sufficient for inputs $x(t)$ with $x(t) * h(t)$ and $x(t) * g(t)$ both well defined and finite)

$$\text{Causal: } h(t) = 0 \text{ for } t < 0$$

$$\text{Stable: } h(t) \text{ is absolutely integrable}$$

- **Differentiation property of CT LTI systems**

$$x(t) \rightarrow y(t) \Rightarrow \frac{dx(t)}{dt} \rightarrow \frac{dy(t)}{dt}$$

- **LTI systems defined by differential/difference equations**

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k} \quad \sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k]$$

- **Non-recursive filters**

Non-recursive filters: no feedback of the output

$$y[n] = \sum_{k=0}^M b_k x[n-k]$$

DT blur filters with rectangular impulse response

$$h[n] = \frac{1}{N} \sum_{k=0}^{N-1} \delta[n-k] = \frac{1}{N} (u[n] - u[n-N])$$

- **Recursive filters**

Recursive filters: feedback of output

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k]$$

DT first order filters: $y[n] - ay[n-1] = x[n]$, a a real, $|a| < 1$

a positive: low-pass filter; $h[n] = a^n u[n]$ right-sided decaying exponential

a negative: high-pass filter; $h[n] = a^n u[n]$ right-sided alternating-polarity decaying exponential

4 CT and DT Fourier Series - Chapter 3

- **Key equations**

CTFS equations for periodic signal, fund. period T , fund. frequency $\omega_0 = 2\pi/T$

Synthesis: $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$

Analysis: $a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt$

DTFS equations for periodic signal, fund. period N , fund. frequency $\omega_0 = 2\pi/N$

Synthesis: $x[n] = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 n}$

Analysis: $a_k = \frac{1}{N} \sum_{n=-\infty}^{\infty} x[n] e^{-jk\omega_0 n}$

- **Response of LTI system to complex exponential**

System Functions $H(s)$ and $H(z)$

e^{st} (resp. z^n) is an *eigenfunction*

$H(s)$ (resp. $H(z)$) is the corresponding *eigenvalue*. It is called the *system function*

$H(j\omega)$ (resp. $H(e^{j\omega})$) is called the *system frequency response*

$$e^{st} \rightarrow H(s)e^{st} \qquad H(s) = \int_{-\infty}^{\infty} h(t)e^{-st} dt$$

$$z^n \rightarrow H(z)z^n \qquad H(z) = \sum_{k=-\infty}^{\infty} h[k]z^{-k}$$

- **How to determine if system may be LTI by action on complex exponential signals**

Check if eigenfunction property is satisfied. If violated, system is not LTI.

- **Filtering of periodic signal through an LTI system**

Assume frequency response $H(j\omega)$ (resp. $H(e^{j\omega})$)

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \rightarrow y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$$

$$x[n] = \sum_{k=\langle N \rangle} a_k e^{jk\omega_0 n} \rightarrow y[n] = \sum_{k=\langle N \rangle} a_k H(e^{jk\omega_0}) e^{jk\omega_0 n}$$

- **Key examples**

Periodic complex exponentials, sinusoidal signals, rectangular waves, impulse train

- **Properties of CTFS/DTFS (Tables 3.1 and 3.2 - provided with exam)**

Periodicity of DTFS: $x[n]$ fund. period $N \Rightarrow a_k$ period N

Linearity

Time shifting, frequency shifting

Time reversal, time scaling

Periodic convolution, multiplication

Differentiation, integration (CT) / First difference, running sum (DT)

Parseval's relation

FS and signal properties: real (conjugate symmetry), real & even, imaginary & odd

- **Finding system function and frequency response of causal LTI system from differential/difference equations**

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k} \quad H(s) = \frac{\sum_{k=0}^M b_k s^k}{\sum_{k=0}^N a_k s^k} \quad H(j\omega) - \text{plug in } s = j\omega$$

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k] \quad H(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}} \quad H(e^{j\omega}) - \text{plug in } z = e^{j\omega}$$

- **Effect of LTI system with *real* impulse response on sinusoids**

$$\cos(\omega_0 t) \rightarrow |H(j\omega_0)| \cdot \cos(\omega_0 t + \angle H(j\omega_0))$$

$$\cos(\omega_0 n) \rightarrow |H(e^{j\omega_0})| \cdot \cos(\omega_0 n + \angle H(e^{j\omega_0}))$$