

ECE 101: Linear Systems Fundamentals

Spring 2025 - Lecture 1

Paul Siegel

University of California, San Diego

Today's topics

- Introduction to the course
- Signals
- Basic operations on signals

Signals and Systems (2nd Edition): sections 1.1.1 and 1.2.1

Introduction to the course

Introduction to the course: Instructor



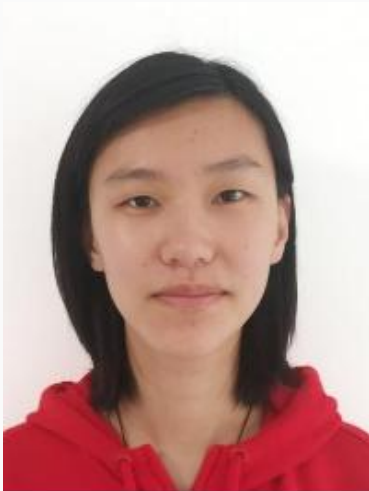
- Instructor: Paul Siegel
 - Email: psiegel@ucsd.edu
 - Zoom office hours:
Wednesdays, 1 pm - 2 pm
and by appointment at other times

Introduction to the course: TAs



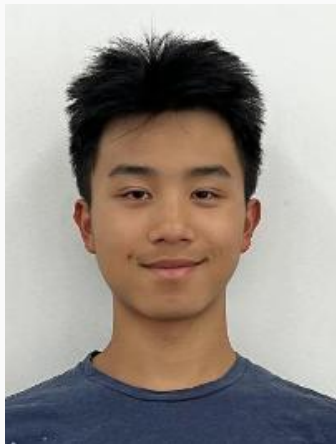
- TA: Deepak Sridhar
 - Email: desridha@ucsd.edu
 - Office hours:

Introduction to the course: TAs (cont.)



- TA: Qianyi Wu
 - Email: qiw010@ucsd.edu
 - Office hours:

Introduction to the course: Tutors/Readers



- Tutor/Reader: Kyle Lou
 - Email: kylou@ucsd.edu
 - Office hours:

Introduction to the course: Tutors/Readers (cont.)



- Tutor/Reader: Alex Simonyan
 - Email: asimonya@ucsd.edu
 - Office hours:

Introduction to the course: course structure

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- The lecture content is pre-recorded and will be delivered to you through the course website on Canvas.
- The lecture videos are the result of a collaborative work by three UC San Diego Professors (Baghdachi, Siegel, and Touri).
- You are asked to watch these videos **before** attending each lecture.

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- You will have a guided reading quiz for each lecture.
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- You will have opportunities to work on sample problems during the in-class activities.
- In-class “clicker questions” (using iClicker Cloud on your smartphones) will provide real-time feedback on your understanding of the material.

Introduction to the course: course structure

- Your assignments include 5 Problem Sets and 5 MATLAB labs.
- You may use MATLAB Online or MATLAB on your computer to complete the labs.
- Complete the MATLAB Onramp tutorial ASAP.
- We will demonstrate many concepts using in-class MATLAB demos throughout the course.
- MATLAB brings the course material to life!

Introduction to the course: course websites

- In this course, we will use Canvas, Gradescope and Piazza for delivering the course content, submitting/grading the assignments and discussions.
- Be sure you are enrolled at all websites - contact me with any problems.

Introduction to the course: textbooks and reference notes

- Textbook

Signals and Systems, 2nd Edition by A.V. Oppenheim and A.S. Willsky (with S.H. Nawab) Prentice Hall, 1997.

- Lab textbook

Computer Explorations in Signals and Systems (Using MATLAB), 2nd Edition, by J.R. Buck, M.M. Daniel, and A.C. Singer, Prentice Hall, 2002.

- Reference Notes for Signals and Systems (available on Canvas)

Introduction to the course: resources

- Resources (lecture videos, lecture notes, reading quizzes, assignments, etc.) are available on Canvas
- Submit assignments using Gradescope: Entry Code 42JVN7
- Piazza page:

https://piazza.com/ucsd/spring2025/ece101_sp25_a00

Introduction to the course: grade breakdown

- 10% Reading quizzes and clicker questions
- 10% Problem Sets
- 15% MATLAB Assignments
- 30% Midterm exam
- 35% Final exam

Introduction to the course: topics covered in this course

- Discrete-time (DT) and continuous-time (CT) signal properties
- DT and CT system properties
- Linear Time Invariant (LTI) systems and their properties
- Fourier Series and Fourier Transform of DT and CT signals
- Frequency analysis of DT and CT systems
- Amplitude Modulation (AM) for communication systems
- Sampling Theory, DT processing of CT signals
- Laplace transform of CT signals, Feedback control

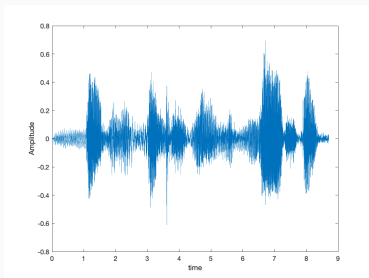
Today's topics

- Signals
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Signals

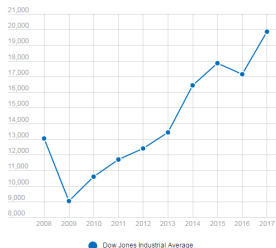
What is a signal?

- A signal is a quantitative description of a physical phenomenon, event or process that often has *time-dependency*.
- Examples:



Dow Jones Industrial Average, 2008-2017

After plunging as the Great Recession set in, the Dow Jones has recovered nicely. This chart shows the closing level on the day closest to January 1 of the year noted.



What is a signal?

- Signals:
 - Continuous-time (CT)
 - Discrete-time (DT)

Continuous-time Signals

- **Continuous-time Signals:** Signals that are functions of real-valued independent variables (time variable t).
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 - use parenthesis (\cdot)

Discrete-time Signals

- **Discrete-time Signals:** Signals that are defined only at discrete times (time variable n).
- For these signals, the independent variable takes on only a discrete set of values.
- We use notation: $x[n], y[n], z[n], \dots$:

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 - reserve time variable n for discrete-time signals' independent variable
 - use square bracket $[\cdot]$

Complex signals

Complex Signals - Notation

- A complex CT signal $x(t)$ is formed by the signal pair $\{x_r(t), x_j(t)\}$, where both $x_r(t)$ and $x_j(t)$ are real-valued signals.

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- A complex CT signal $x(t)$ is formed by the signal pair $\{x_r(t), x_j(t)\}$, where both $x_r(t)$ and $x_j(t)$ are real-valued signals.
- The relationship between these signals is given by:

$$x(t) = x_r(t) + j x_j(t)$$

where $j = \sqrt{-1}$

Complex Signals - Notation

- Similarly, a complex DT signal $x[n]$ can be represented as

$$x[n] = x_r[n] + j x_j[n]$$

where both $x_r[n]$ and $x_j[n]$ are real-valued DT signals.

Basic Notations

- \mathbb{Z} : the set of integers $\dots, -2, -1, 0, 1, 2, \dots$
- \mathbb{R} : the set of real numbers
- $\mathbb{C} := \{(a + bj) \mid a, b \in \mathbb{R}\}$ the set of complex numbers

Basic Notations

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- \mathbb{R} : the set of real numbers
- $\mathbb{C} := \{(a + bj) \mid a, b \in \mathbb{R}\}$ the set of complex numbers
 - $x = a + bj$ is Cartesian coordinate representation
 - $x = re^{j\theta}$, where $r = \sqrt{a^2 + b^2}$ and $\theta = \tan^{-1}(\frac{b}{a})$ is the polar coordinate representation
 - Euler's Formula:

$$e^{j\theta} = \cos(\theta) + j \sin(\theta)$$

Euler's Formula and Coordinate Transformation

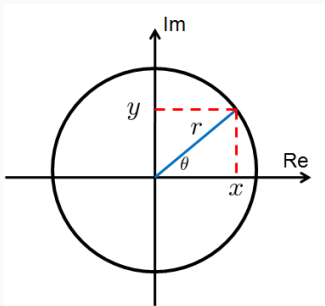
- Euler's Formula:

$$e^{j\theta} = \cos(\theta) + j \sin(\theta)$$

- Cartesian/polar coordinates:

$$z = x + j y$$

$$re^{j\theta} = r \cos(\theta) + j r \sin(\theta)$$



Basic Operations on Signals

Time Shift

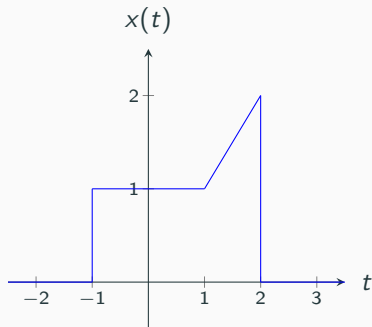
- For any $t_0 \in \mathbb{R}$ and $n_0 \in \mathbb{Z}$, **time shift** is defined as

$$\begin{array}{lll} x(t) & \longrightarrow & x(t - t_0) \quad \text{CT} \\ x[n] & \longrightarrow & x[n - n_0] \quad \text{DT} \end{array}$$

- For $t_0 > 0$ ($n_0 > 0$), it is called **delay** and for $t_0 < 0$ ($n_0 < 0$) it is called **advance**.

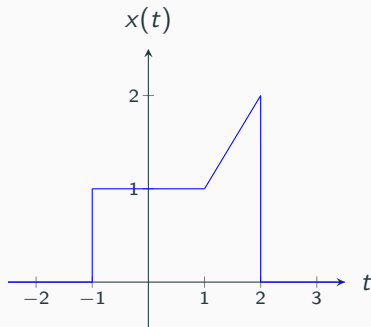
Time Shift: example

- Example: Suppose $x(t)$ is as shown below. Sketch $x(t - 1)$.



Time Reversal: example

- Example: Suppose $x(t)$ is as shown below. Sketch $x(-t)$.

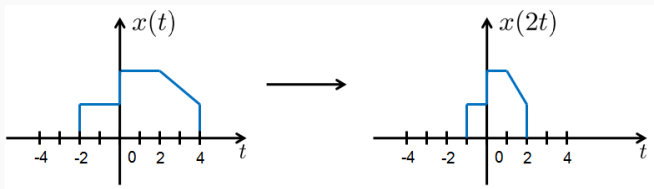


Time Scaling: Continuous Time

- For CT Signals, time-scaling by a factor $a > 0$ is defined as

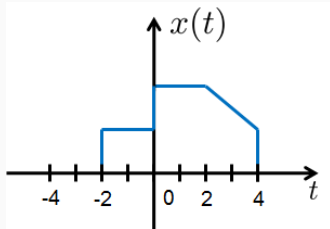
$$x(t) \longrightarrow x(at), \quad a > 0.$$

- If $a > 1$, it is called **Decimation** (squeezing)
- If $0 < a < 1$, it is called **Expansion** (enlarging)



Class activity:

- Sketch $x(\frac{t}{2})$ for the below signal.

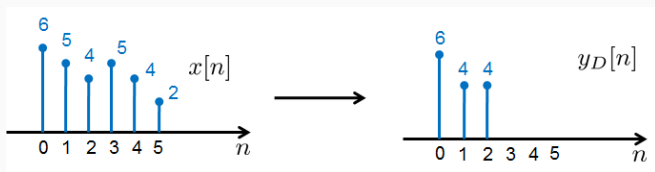


Time Scaling: Discrete Time

- **Decimation:** For a DT Signal, and an **integer** factor $M \geq 1$, the decimated signal is defined by:

$$y_D[n] = x[Mn].$$

- An example of decimation for $M = 2$:

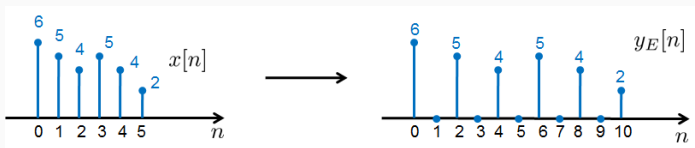


Time Scaling: Discrete Time

- **Expansion:** For an integer $L \geq 1$, the discrete-time expanded signal (by a factor L) is:

$$y_E[n] = \begin{cases} x\left[\frac{n}{L}\right], & n = \text{integer multiple of } L \\ 0, & \text{otherwise.} \end{cases}$$

- An example of expansion for $L = 2$:



Combination of Operations

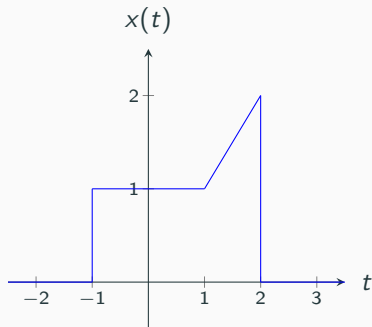
- Often we are interested in the transformation $x(t) \rightarrow x(at - b)$
- A combination of time shift and time scaling is needed (order matters):
- The recommended method is
 1. Define $v(t) = x(t - b)$,
 2. Define $y(t) = v(at) = x(at - b)$.
- So $x(t) \rightarrow x(at - b)$ is equivalent to time delay then scale!

Combination of Operations

- The second method is
 1. Define $v(t) = x(at)$,
 2. Define $y(t) = v(t - b/a) = x(at - b)$.
- This method will not always result in a correct answer for the discrete-time signals.

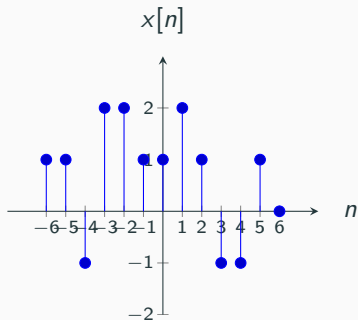
Combination of Operations: example

- Example: Plot the signal $x(-t + 2)$ for the signal $x(t)$ as bellow,

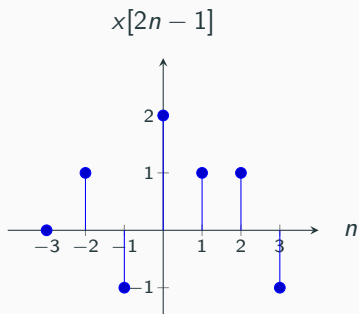
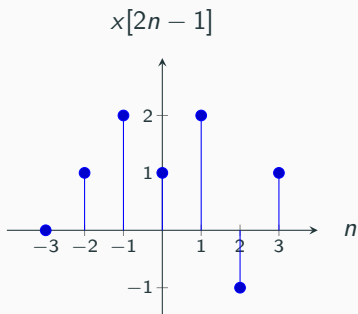


Lecture 1 reading quiz

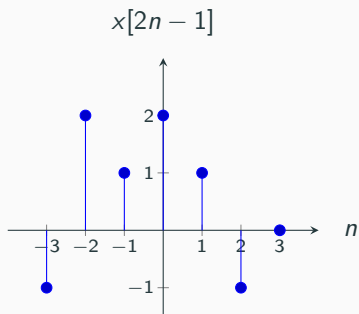
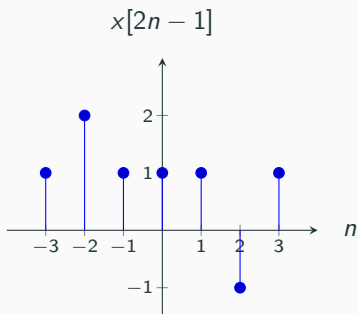
- A discrete-time signal $x[n]$ is shown below. Which option correctly represents $x[2n - 1]$?



Options for Quiz 1



More options for Quiz 1



Clicker question 1

- If $f(t) = x(t - 1)$ and $g(t) = f(-2t)$, which option correctly represents $g(t)$?

A. $g(t) = x(-2t + 2)$

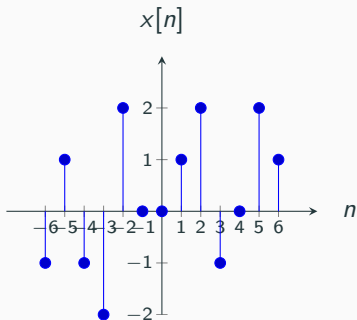
B. $g(t) = x(-2t - 2)$

C. $g(t) = x(-2t - 1)$

D. $g(t) = x(-2t + \frac{1}{2})$

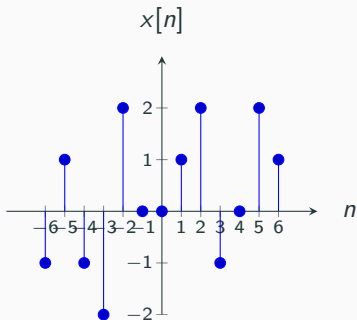
Class activity 1

- A discrete-time signal, $x[n]$, is shown below. Sketch and label $y[n] = x[2n] + x[-n]$.



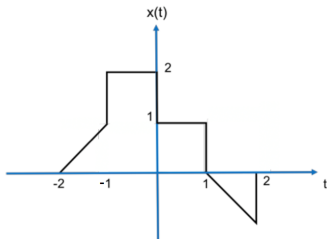
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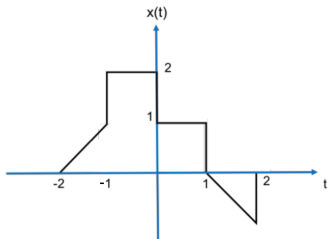
Class activity 2

- A continuous-time signal, $x(t)$, is shown below. Sketch and label $x(-\frac{1}{4}t - 1)$.



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Clicker question 2

- Consider the continuous-time signal, $x(t) = t - 1$.

If $y(t) = x(-3t + 5)$, the time for which $y(t_0) = 0$ is given by:

A. $t_0 = 0$

B. $t_0 = -\frac{4}{3}$

C. $t_0 = \frac{4}{3}$

D. $t_0 = \frac{5}{3}$

MATLAB Demo

- Lecture 1 Demo
 - Audio signals: loading, playing, plotting
 - Complex arithmetic
 - Complex signals: defining, plotting in 2D and 3D
- You will be able to download the MATLAB demo and its solution from the Canvas website.