ECE 101: Linear Systems Fundamentals

Summer Session II 2020 - Lecture 10

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Today's topics

- Continuous-time Fourier series and LTI systems
- Discrete-time Fourier series and LTI systems

Signals and Systems (2th Edition): section 3.8

- Signals in the format of $x(t) = e^{st}$ are eigenfunctions of **LTI** systems
- That means if we apply the input signal

$$x(t) = e^{st}$$
, where $s = \alpha + j\omega$

to a CT LTI system, the output will be a scaled version of the input signal.

$$y(t) = H(s)e^{st}$$

$$H(s) = \int_{-\infty}^{\infty} h(\tau)e^{-s\tau}d\tau, \quad H(s) \in \mathbb{C}$$

 We found this using the convolution integral defined for LTI systems.

$$y(t) = \int_{-\infty}^{\infty} h(\tau)x(t-\tau)d\tau$$

Think about these eigenfunctions as a set of base functions

$$e^{(\alpha_1+j\omega_1)t} \qquad e^{(\alpha_1+j\omega_2)t} \qquad e^{(\alpha_1+j\omega_3)t} \qquad \dots \dots$$

$$e^{(\alpha_2+j\omega_1)t} \qquad e^{(\alpha_2+j\omega_2)t} \qquad e^{(\alpha_2+j\omega_3)t} \qquad \dots \dots$$

$$e^{(\alpha_3+j\omega_1)t} \qquad e^{(\alpha_3+j\omega_2)t} \qquad e^{(\alpha_3+j\omega_3)t} \qquad \dots \dots$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

 If we apply either one of them to an LTI system, the output will be the input signal multiplied by a scalar

$$\xrightarrow{e^{(\alpha_1+j\omega_1)t}} h(t) \qquad \xrightarrow{H(\alpha_1+j\omega_1)e^{(\alpha_1+j\omega_1)t}}$$

• Let's limit ourselves to a subset of the eigenfunctions e^{st} in which $s=jk\omega_0$, where $k\in\mathbb{Z}$

$$e^{0} = 1$$

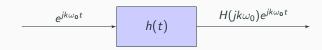
$$e^{-j\omega_{0}t} \qquad e^{j\omega_{0}t}$$

$$e^{-j2\omega_{0}t} \qquad e^{j2\omega_{0}t}$$

$$e^{-j3\omega_{0}t} \qquad e^{j3\omega_{0}t}$$

$$\vdots \qquad \vdots$$

$$e^{jk\omega_{0}t} , k \in \mathbf{Z}$$

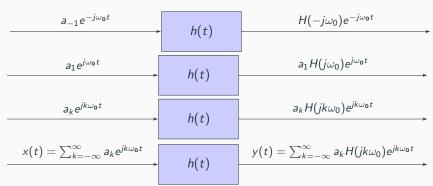


 Now, let's look at the Fourier series representation of periodic signals with period T, that have a finite energy in one period.

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$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} = \dots + a_{-1}e^{-j\omega_0 t} + a_0 e^0 + a_1 e^{j\omega_0 t} + \dots$$



$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

- The Fourier series representation of a continuous-time signal will tell us which frequency components (the $k\omega_0$ terms in $e^{jk\omega_0t}$) are present in the signal
- The Fourier series coefficients of a continuous-time signal will tell us the strength of each frequency component that is present in the signal
- $H(j\omega)$ evaluated at $\omega=k\omega_0$ will tell us the behavior of the LTI system at $k\omega_0$ frequency values

Continuous-time Fourier series

and LTI systems

- In the last lecture, we learned how to find the Fourier series coefficients of the CT periodic signals
- Let's look at how we can use the continuous-time Fourier series to find the output of an LTI system to a periodic input signal

Example. Consider an LTI system with the impulse response $h(t) = \delta(t-1)$. Use the continuous-time Fourier series to find the output of the system to input signal $x(t) = 1 + 2\cos(2\pi t) - \cos(3\pi t)$.

- 1. We will find the Fourier series coefficients of x(t) denoted by a_k
- 2. We will find the frequency response, $H(j\omega)$, of the system
- 3. We will find the output using $y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$
- 4. Since x(t) is a periodic signal with the period T and $\omega_0 = \frac{2\pi}{T}$, the output of the system y(t) will also be periodic with the period T.

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- 5. If we show the Fourier series coefficients of y(t) with b_k ,

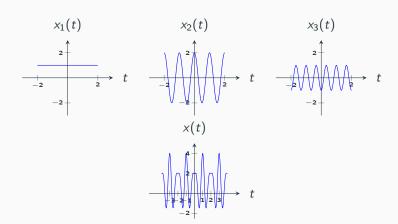
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$$b_k = a_k H(jk\omega_0)$$

Example. Consider an LTI system with the impulse response $h(t) = \delta(t-1)$. Use the continuous-time Fourier series to find the output of the system to input signal $x(t) = 1 + 2cos(2\pi t) - cos(3\pi t)$.

$$x(t) = 1 + 2\cos(2\pi t) - \cos(3\pi t) = x_1(t) + x_2(t) + x_3(t)$$



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1. We will find the Fourier series coefficients of x(t) denoted by a_k

x(t) is in the sinusoidal format, so we can write x(t) using complex exponentials and find its Fourier series coefficients directly

$$x(t) = 1 + 2\cos(2\pi t) - \cos(3\pi t)$$

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$$\begin{aligned} x(t) &= 1 + 2\cos(2\pi t) - \cos(3\pi t) \\ &= 1 \times e^{0} + 2 \times \left(\frac{e^{j2\pi t} + e^{-j2\pi t}}{2}\right) - 1 \times \left(\frac{e^{j3\pi t} + e^{-j3\pi t}}{2}\right) \\ &= 1 \times e^{0} + 2 \times \frac{e^{j2\pi t}}{2} + 2 \times \frac{e^{-j2\pi t}}{2} - 1 \times \frac{e^{j3\pi t}}{2} - 1 \times \frac{e^{-j3\pi t}}{2} \\ &= 1 \times e^{0} + 1 \times e^{j2\pi t} + 1 \times e^{-j2\pi t} - \frac{1}{2} \times e^{j3\pi t} - \frac{1}{2} \times e^{-j3\pi t} \end{aligned}$$

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$$= 1 \times e^{0} + 1 \times e^{j2\pi t} + 1 \times e^{-j2\pi t} - \frac{1}{2} \times e^{j3\pi t} - \frac{1}{2} \times e^{-j3\pi t}$$

Comparing the above expression with the Fourier series representation of x(t), we can find the Fourier series coefficients of x(t)

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\pi t}$$

$$a_0 = 1$$
, $a_{-2} = 1$, $a_2 = 1$, $a_{-3} = -0.5$, $a_3 = -0.5$

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2. Let's find the frequency response, $H(j\omega)$, of the system

$$H(j\omega) = \int_{-\infty}^{\infty} h(\tau)e^{-j\omega\tau}d\tau$$

$$= \int_{-\infty}^{\infty} \delta(\tau - 1)e^{-j\omega\tau}d\tau$$

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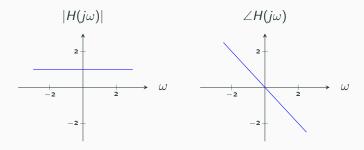
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The frequency response, $H(j\omega)$, of the LTI system will tell us the behavior of the system at different frequencies.

$$H(j\omega) = e^{-j\omega}$$



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- 3. We will find the output using $y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$
- 4. Since x(t) is a periodic signal with the period T and $\omega_0 = \frac{2\pi}{T}$, the output of the system y(t) will also be periodic with the period T.

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$$a_0=1, \quad a_{-2}=1, \quad a_2=1, \quad a_{-3}=-0.5, \quad a_3=-0.5$$
 $H(j\omega)=e^{-j\omega}, \quad so \quad H(jk\omega)=e^{-jk\omega}$

- $H(jk\omega)=e^{-jk\omega}$ is a complex number whose magnitude and angle depends on the value of k and ω
- Since x(t) has the fundamental frequency of $\omega_0 = \pi$, in the equation of $H(jk\omega) = e^{-jk\omega}$ we will replace ω with $\omega_0 = \pi$
- Since the Fourier series coefficients of x(t) a_k are non-zero for k=-3,-2,0,2,3, we only need to find calculate $H(jk\omega_0)=e^{-jk\omega_0}$ for these k values

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 $H(j\omega)=e^{-j\omega}, \quad so \quad H(jk\omega)=e^{-jk\omega}$

$$y(t) = \sum_{k=-\infty}^{\infty} a_k H(jk\omega_0) e^{jk\omega_0 t}$$
$$= \sum_{k=-\infty}^{\infty} a_k \times e^{-jk\pi} \times e^{jk\pi t}$$

$$y(t) = a_0 + a_{-3}e^{3j\pi}e^{-j3\pi t} + a_3e^{-3j\pi}e^{j3\pi t} + a_{-2}e^{2j\pi}e^{-j2\pi t} + a_2e^{-2j\pi}e^{j2\pi t}$$

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$$= 1 + \frac{-1}{2}e^{3j\pi}e^{-j3\pi t} + \frac{-1}{2}e^{-3j\pi}e^{j3\pi t} + e^{2j\pi}e^{-j2\pi t} + e^{-2j\pi}e^{j2\pi t}$$

$$= 1 + \frac{-1}{2}\left[e^{3j\pi}e^{-j3\pi t} + e^{-3j\pi}e^{j3\pi t}\right] + \left[e^{2j\pi}e^{-j2\pi t} + e^{-2j\pi}e^{j2\pi t}\right]$$

$$= 1 + \frac{-1}{2}\left[e^{-j(3\pi t - 3\pi)} + e^{j(3\pi t - 3\pi)}\right] + \left[e^{-j(2\pi t - 2\pi)} + e^{j(2\pi t - 2\pi)}\right]$$

$$= 1 - \cos(3\pi t - 3\pi) + 2\cos(2\pi t - 2\pi)$$

$$= 1 - \cos(3\pi t - \pi) + 2\cos(2\pi t)$$

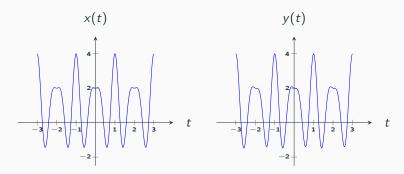
Note:
$$cos(\theta) = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

Example. Consider an LTI system with the impulse response $h(t) = \delta(t-1)$. Use the continuous-time Fourier series to find the output of the system to input signal $x(t) = 1 + 2\cos(2\pi t) - \cos(3\pi t)$. $y(t) = a_0 + a_{-3}e^{3j\pi}e^{-j3\pi t} + a_3e^{-3j\pi}e^{j3\pi t} + a_{-2}e^{2j\pi}e^{-j2\pi t} + a_2e^{-2j\pi}e^{j2\pi t}$ $=1+\frac{-1}{2}e^{3j\pi}e^{-j3\pi t}+\frac{-1}{2}e^{-3j\pi}e^{j3\pi t}+e^{2j\pi}e^{-j2\pi t}+e^{-2j\pi}e^{j2\pi t}$ $=1+\frac{-1}{2}\left[e^{3j\pi}e^{-j3\pi t}+e^{-3j\pi}e^{j3\pi t}\right]+\left[e^{2j\pi}e^{-j2\pi t}+e^{-2j\pi}e^{j2\pi t}\right]$ $=1+\frac{-1}{2}\left[e^{-j(3\pi t-3\pi)}+e^{j(3\pi t-3\pi)}\right]+\left[e^{-j(2\pi t-2\pi)}+e^{j(2\pi t-2\pi)}\right]$ $=1-\cos(3\pi t-3\pi)+2\cos(2\pi t-2\pi)$ $= 1 - \cos(3\pi t - \pi) + 2\cos(2\pi t)$

The system does not change the amplitude of x(t). It only adds a phase shift to the input signal. The value of phase shift depends on the frequency components of the input signal.

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$$y(t) = 1 + 2\cos(2\pi t) - \cos(3\pi t - \pi)$$



Discrete-time Fourier series and

LTI systems

Example. Consider a DT LTI system with the impulse response h[n]. Assume a periodic input signal, x[n], with period N and fundamental frequency $\omega_0 = \frac{2\pi}{N}$ is applied to the system. Find the output of the system, y[n].

- 1. We will find the Fourier series coefficients of x[n] denoted by a_k
- 2. We will find the frequency response, $H(e^{j\omega})$, of the system
- 3. We will find the output using $y[n] = \sum_{k=\langle N \rangle} a_k H(e^{jk\omega_0}) e^{jk\omega_0 n}$
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- 5. If we show the Fourier series coefficients of y[n] with b_k ,

$$y[n] = \sum_{k = \langle N \rangle} b_k e^{jk\omega_0 n}$$

$$y[n] = \sum_{k=-\langle N \rangle} a_k H(e^{jk\omega_0}) e^{jk\omega_0 n}$$

$$b_k = a_k H(e^{jk\omega_0})$$

Consider a discrete time LTI system whose frequency response is

$$H(e^{j\omega}) = egin{cases} 1, & |\omega| \leq rac{\pi}{8} \ 0, & rac{\pi}{8} < |\omega| < \pi \end{cases}$$

What is the output of this system to a periodic input signal with period of N=3 and Fourier series coefficients $a_0=1$, $a_1=j$, $a_{-1}=-j$.

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$$b_{k} = a_{k} H \begin{pmatrix} jk\omega_{0} \\ \ell \end{pmatrix}$$

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$$b_0 = a_0 \times 1 = a_0 = 1$$

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$$b_{1}=a_{1}H(e^{j \ln \frac{2\pi}{3}})=a_{1}H(e^{j k \omega_{0}})\Big|_{k\omega_{0}=\frac{2\pi}{3}}=a_{1}H(e^{j \omega})\Big|_{\omega=\frac{2\pi}{3}}$$

note: 7/2/3/7

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$$b_0 = 1$$
, $b_1 = 0$, $b_{-1} = 0$

$$y[n] = \sum_{k=1}^{l} b_k e^{jk con} = 1 \rightarrow y[n] = 1$$
 for all n

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