

**UNIVERSITY OF CALIFORNIA, SAN DIEGO**  
**Electrical & Computer Engineering Department**  
**ECE 101 - Fall 2020**  
*Linear Systems Fundamentals*

**MIDTERM EXAM**

**Instructions**

- Open Canvas website, no electronics for problem solving.
- Tables 3.1 and 3.2 from the textbook are attached to the exam.
- No collaboration or external help of any kind, either in person or via web, phone, or any other device, is allowed. You may be asked to explain your answers over a Zoom call when the exam is graded.
- Time allowed: 2.5 consecutive hours (from 5pm PST Thursday to 11:59pm PST Friday)
- Write your solutions in the applicable space in the exam. **Justify your answers.** If extra pages are needed to show all of your work, use the scratch pages at the end of the exam and submit them.
- Upload your solutions via Gradescope

PRINT YOUR NAME \_\_\_\_\_

Student ID Number \_\_\_\_\_

Signature \_\_\_\_\_

**Your signature confirms that you have completed this exam on your own and in accordance with the Academic Integrity Agreement.**

Problem	Weight	Score
1	16 pts	
2	24 pts	
3	30 pts	
4	30 pts	
Total	100 pts	

**Good luck!**

Name/Student ID: \_\_\_\_\_

**Problem 1 (16 points: 2 parts, 8 points each)**

(a) (8 pts)

Let  $x(t) = t(u(t) - u(t - 1))$ . Define  $y(t) = x((-3t) - 2)$ .

Describe how to obtain  $y(t)$  from  $x(t)$  by the following rules:

**Approach 1:**

First shift  $x(t)$  by  $b = \underline{\hspace{2cm}}$

( $b > 0$  means shift right by  $b < 0$  means shift left by  $|b|$ )

Then (circle one) **stretch** or **compress** the signal by  $a = \underline{\hspace{2cm}}$   
( $a < 0$  means flip;  $|a| \geq 1$  is the stretch or compress factor)

or

**Approach 2:**

First (circle one) **stretch** or **compress** the signal by  $c = \underline{\hspace{2cm}}$   
( $c < 0$  means flip;  $|c| \geq 1$  is the stretch or compress factor)

Then shift  $x(t)$  by  $d = \underline{\hspace{2cm}}$

( $d > 0$  means shift right by  $d < 0$  means shift left by  $|d|$ )

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**Problem 1 (cont.)**

(b) (8 pts) Let  $x(t) = t(u(t) - u(t - 1))$ . Define  $y(t) = x((-3t) - 2)$ .

Sketch precisely  $y(t)$ .

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**Problem 2 (24 points: 3 parts, 8 points each)**

Let  $x[n] = e^{j\frac{\pi}{3}(n-1)} + \sum_{k=-\infty}^{\infty} \delta[n - 6k]$ .

(a) (8 pts)

Determine the fundamental period of  $x[n]$ .

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**Problem 2 (cont.)**

Let  $x[n] = e^{j\frac{\pi}{3}(n-1)} + \sum_{k=-\infty}^{\infty} \delta[n - 6k]$ .

(b) (8 pts)

Determine if  $x[n]$  is even, odd, or neither.

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**Problem 2 (cont.)**

Let  $x[n] = e^{j\frac{\pi}{3}(n-1)} + \sum_{k=-\infty}^{\infty} \delta[n - 6k]$ .

(c) (8 pts)

Determine the discrete-time Fourier series (DTFS) coefficients of  $x[n]$ .

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**Problem 3 (30 points: 3 parts, 10 points each)**

Consider the discrete-time linear time-invariant (LTI) system  $S$  with impulse response

$$h[n] = \left(\frac{1}{2}\right)^{n-1} u[n-1].$$

(a) (10 pts)

Determine the step response  $s[n]$  of the system  $S$ , and sketch  $s[n]$  precisely in the interval  $-3 \leq n \leq 3$ .

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**Problem 3 (cont.)**

Consider the discrete-time linear time-invariant (LTI) system  $S$  with impulse response

$$h[n] = \left(\frac{1}{2}\right)^{n-1} u[n-1].$$

(b) (10 pts)

Indicate whether the system  $S$  satisfies each listed property.

**Justify your answers with *specific* reference to the system  $S$ .**

**True    False**

       Memoryless

       Causal

       Stable

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**Problem 3 (cont.)**

Consider the discrete-time linear time-invariant (LTI) system  $S$  with impulse response

$$h[n] = \left(\frac{1}{2}\right)^{n-1} u[n-1].$$

(c) (10 pts)

The system  $S$  is invertible. Determine the impulse response  $g[n]$  of the inverse system.

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**Problem 4 (30 points: 3 parts, 10 points each)**

The signal  $x[n] = 1 + \cos(\frac{\pi}{2}n) \sin(\frac{\pi}{3}n)$  is passed through the discrete-time filter whose frequency response is given by:

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| \leq \frac{2\pi}{3} \\ 0, & \text{otherwise.} \end{cases}$$

(a) (10 pts)

Determine the discrete-time Fourier series (DTFS) of the signal  $x[n]$ .

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**Problem 4 (cont.)**

The signal  $x[n] = 1 + \cos(\frac{\pi}{2}n) \sin(\frac{\pi}{3}n)$  is passed through the discrete-time filter whose frequency response is given by:

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| \leq \frac{2\pi}{3} \\ 0, & \text{otherwise.} \end{cases}$$

(b) (10 pts)

Determine the output signal  $y[n]$  produced by the input signal  $x[n]$ . Write it in a form that does not involve complex exponential signals.

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**Problem 4 (cont.)**

The signal  $x[n] = 1 + \cos(\frac{\pi}{2}n) \sin(\frac{\pi}{3}n)$  is passed through the discrete-time filter whose frequency response is given by:

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| \leq \frac{2\pi}{3} \\ 0, & \text{otherwise.} \end{cases}$$

(c) (10 pts)

Let  $b_k$  denote the DTFS of the output signal  $y[n]$ . Determine the value of  $b_{11}$ ,  $b_{18}$ , and  $b_{52}$  (not the rock band). Express your answers numerically, as well as in terms of  $b_0, b_1, \dots, b_N$  where  $N$  is the fundamental period of  $y[n]$ .

**TABLE 3.1 PROPERTIES OF CONTINUOUS-TIME FOURIER SERIES**

Property	Section	Periodic Signal	Fourier Series Coefficients
		$x(t) \left\{ \begin{array}{l} \text{Periodic with period } T \text{ and} \\ y(t) \end{array} \right. \begin{array}{l} \text{fundamental frequency } \omega_0 = 2\pi/T \end{array}$	$a_k$ $b_k$
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} = e^{jM(2\pi/T)t} x(t)$	$a_{k-M}$
Conjugation	3.5.6	$x^*(t)$	$a_{-k}^*$
Time Reversal	3.5.3	$x(-t)$	$a_{-k}$
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period $T/\alpha$ )	$a_k$
Periodic Convolution		$\int_T x(\tau)y(t - \tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk \frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^t x(t) dt$ (finite valued and periodic only if $a_0 = 0$ )	$\left(\frac{1}{jk\omega_0}\right) a_k = \left(\frac{1}{jk(2\pi/T)}\right) a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a_{-k}^* \\ \Re\{a_k\} = \Re\{a_{-k}\} \\ \Im\{a_k\} = -\Im\{a_{-k}\} \\  a_k  =  a_{-k}  \\ \angle a_k = -\angle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	$a_k$ real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	$a_k$ purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \Re\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \Im\{x(t)\} & [x(t) \text{ real}] \end{cases}$	$\Re\{a_k\}$ $j\Im\{a_k\}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

**TABLE 3.2 PROPERTIES OF DISCRETE-TIME FOURIER SERIES**

Property	Periodic Signal	Fourier Series Coefficients
	$x[n]$ } Periodic with period $N$ and $y[n]$ } fundamental frequency $\omega_0 = 2\pi/N$	$a_k$ } Periodic with $b_k$ } period $N$
Linearity	$Ax[n] + By[n]$	$Aa_k + Bb_k$
Time Shifting	$x[n - n_0]$	$a_k e^{-jk(2\pi/N)n_0}$
Frequency Shifting	$e^{jM(2\pi/N)n} x[n]$	$a_{k-M}$
Conjugation	$x^*[n]$	$a_k^*$
Time Reversal	$x[-n]$	$a_{-k}$
Time Scaling	$x_{(m)}[n] = \begin{cases} x[n/m], & \text{if } n \text{ is a multiple of } m \\ 0, & \text{if } n \text{ is not a multiple of } m \end{cases}$ (periodic with period $mN$ )	$\frac{1}{m} a_k$ (viewed as periodic) (with period $mN$ )
Periodic Convolution	$\sum_{r=0}^{N-1} x[r]y[n-r]$	$Na_k b_k$
Multiplication	$x[n]y[n]$	$\sum_{l=0}^{N-1} a_l b_{k-l}$
First Difference	$x[n] - x[n - 1]$	$(1 - e^{-jk(2\pi/N)})a_k$
Running Sum	$\sum_{k=-\infty}^n x[k]$ (finite valued and periodic only)	$\left(\frac{1}{(1 - e^{-jk(2\pi/N)})}\right)a_k$
Conjugate Symmetry for Real Signals	$x[n]$ real	$\begin{cases} a_k = a_{-k}^* \\ \Re\{a_k\} = \Re\{a_{-k}\} \\ \Im\{a_k\} = -\Im\{a_{-k}\} \\  a_k  =  a_{-k}  \\ \angle a_k = -\angle a_{-k} \end{cases}$
Real and Even Signals	$x[n]$ real and even	$a_k$ real and even
Real and Odd Signals	$x[n]$ real and odd	$a_k$ purely imaginary and odd
Even-Odd Decomposition of Real Signals	$\begin{cases} x_e[n] = \Re\{x[n]\} & [x[n] \text{ real}] \\ x_o[n] = \Im\{x[n]\} & [x[n] \text{ real}] \end{cases}$	$\Re\{a_k\}$ $j\Im\{a_k\}$
Parseval's Relation for Periodic Signals		
$\frac{1}{N} \sum_{n=0}^{N-1}  x[n] ^2 = \sum_{k=0}^{N-1}  a_k ^2$		