

UNIVERSITY OF CALIFORNIA, SAN DIEGO  
Electrical & Computer Engineering Department  
ECE 101 - Fall 2021

Linear Systems Fundamentals

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**FINAL EXAM**

**Preface**

- I recognize that final exams are stressful in the best of times, and this is an unusually hard time.
- Please remember that despite the stress, I am counting on you to uphold academic integrity while you complete your final exam.
- Posting or seeking exam questions or answers online, or by consulting unauthorized resources, is a gross violation of our principles of integrity and engineering ethics.
- To be fair to all students, any integrity violations discovered during the final exam will be reported to the Dean of Engineering and to the office of Academic Integrity.
- Please make sure you understand and follow the academic integrity guidelines for the exam. If you are not sure, ask me.
- An honest effort, no matter what the outcome, is something to be proud of, especially in these challenging times.
- I am very proud of the commitment and resilience you have displayed. You should feel proud, too.
- **Good luck on the exam!**

PRINT YOUR NAME \_\_\_\_\_

Student ID Number \_\_\_\_\_

Signature \_\_\_\_\_

**Your signature confirms that you have completed this exam on your own and in accordance with the Academic Integrity Agreement.**

## Instructions

- No electronics allowed for problem solving.
- Notes and Tables from Chapters 3 ,4, 5, 9 of the textbook are attached.
- Two 2-sided sheets of your own notes are allowed.
- Time allowed: 3 hours (including upload time).
- Write your solutions in the designated spaces in the exam.
- **Justify all of your answers.**
- If extra pages are needed to show all of your work, use the scratch pages at the end of the exam and submit them.
- **Upload your solutions by 6pm via Gradescope.**

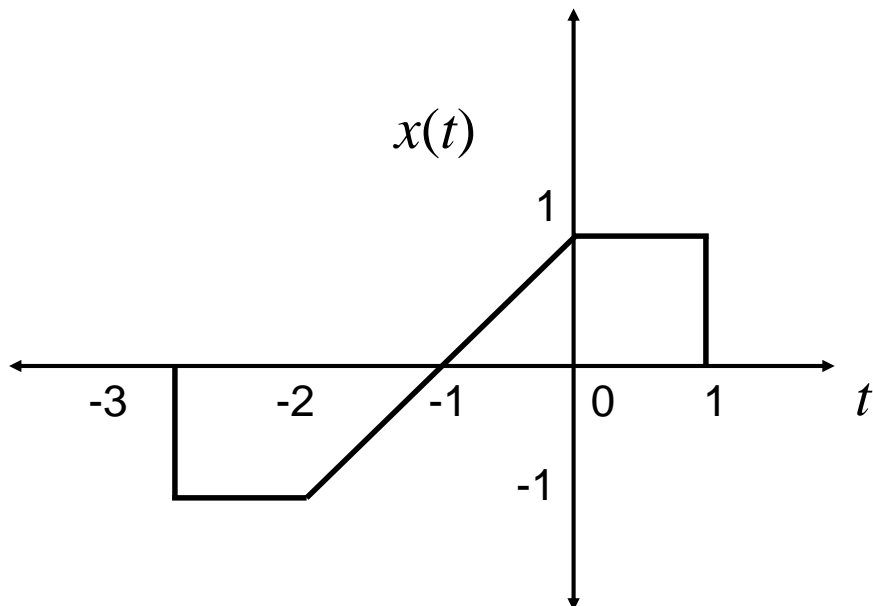
Problem	Weight	Score
1	30 pts	
2	30 pts	
3	30 pts	
4	30 pts	
5	30 pts	
6	30 pts	
Total	180 pts	

**Good luck!**

Name/Student ID: \_\_\_\_\_

**Problem 1 [CTFT Properties]** (30 points, 10 points each part)

Let  $x(t)$  be the CT signal below. Let  $X(j\omega)$  denote its Fourier transform.



(a) Determine  $\int_{-\infty}^{\infty} X(j\omega) d\omega$ .

(b) Determine  $X(j0)$ .

Let  $x_1(t) = x(t - 1)$ , with Fourier transform  $X_1(j\omega)$ .

(c) Determine  $\text{Re}\{X_1(j\omega)\}$ .

**Write answers to parts (a), (b), (c) on the following pages.**

**Justify your answers.**

Name/Student ID: \_\_\_\_\_

**Problem 1 (cont.)**

(a) (10 points)

Determine  $\int_{-\infty}^{\infty} X(j\omega) d\omega$ .

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**Problem 1 (cont.)**

(b) (10 points)

Determine  $X(j0)$ .

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**Problem 1 (cont.)**

Let  $x_1(t) = x(t - 1)$ , with Fourier transform  $X_1(j\omega)$ .

(c) (10 points)

Determine  $\operatorname{Re}\{X_1(j\omega)\}$ .

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**Problem 2 [DTFT]** (30 points; 10 points each part)

Let  $S$  be the DT LTI system obtained by concatenating the two DT LTI systems  $S_1$  and  $S_2$  defined by:

$$\begin{aligned} S_1 : \quad y[n] &= x[n] - \frac{1}{2}x[n-1] \\ S_2 : \quad y[n] &= x[n] + \frac{1}{4}x[n-1] \end{aligned}$$

- (a) Determine the frequency response  $H(e^{j\omega})$  of  $S$  and write it in the form

$$\frac{\sum_{k=0}^M b_k e^{-jk\omega}}{\sum_{k=0}^N a_k e^{-jk\omega}}.$$

- (b) Let  $S'$  be the inverse system to  $S$ . Determine the frequency response  $G(e^{j\omega})$  of  $S'$  and write it in the form

$$\frac{\sum_{k=0}^M b_k e^{-jk\omega}}{\sum_{k=0}^N a_k e^{-jk\omega}}.$$

- (c) Let  $x[n] = \delta[n] - \frac{1}{2}\delta[n-1]$  be the input signal to the system  $S'$ . Determine the output signal  $y[n]$ .

**Write answers to parts (a), (b), (c) on the following pages.**

**Justify your answers.**

Name/Student ID: \_\_\_\_\_

**Problem 2 (cont.)**

(a) (10 points)

Determine the frequency response  $H(e^{j\omega})$  of  $S$  and write it in the form

$$\frac{\sum_{k=0}^M b_k e^{-jk\omega}}{\sum_{k=0}^N a_k e^{-jk\omega}}.$$



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**Problem 2 (cont.)**

(b) (10 points)

Let  $S'$  be the inverse system to  $S$ . Determine the frequency response  $G(e^{j\omega})$  of  $S'$  and write it in the form  $\frac{\sum_{k=0}^M b_k e^{-jk\omega}}{\sum_{k=0}^N a_k e^{-jk\omega}}$ .

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**Problem 2 (cont.)**

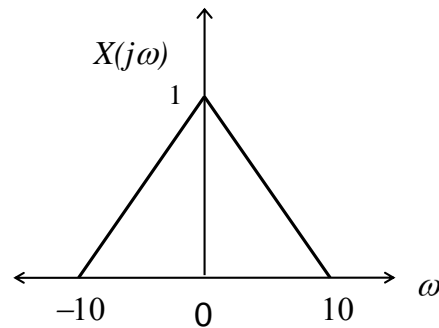
(c) (10 points)

Let  $x[n] = \delta[n] - \frac{1}{2}\delta[n-1]$  be the input signal to the system  $S'$ . Determine the output signal  $y[n]$ .

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**Problem 3 [Modulation]** (30 points, 10 points each part)

Let  $x(t)$  be the signal with Fourier transform  $X(j\omega)$  shown below.



- (a) Let  $x_1(t) = x(t) \cos(30t)$ . The signal  $x_1(t)$  is received and passed through a bandpass filter with frequency response

$$H_{BP}(j\omega) = \begin{cases} 2, & 20 < |\omega| < 30 \\ 0, & \text{otherwise.} \end{cases}$$

Write the CTFT  $X_1(j\omega)$  of  $x_1(t)$  in terms of  $X(j\omega)$ .

Let  $y_1(t)$  be the output of the bandpass filter. Sketch precisely the Fourier transform  $Y_1(j\omega)$  of the signal  $y_1(t)$  and write it in terms of  $X(j\omega)$ .

- (b) Using the signal  $y_1(t)$  from part (a), define  $x_2(t) = y_1(t) \cos(20t)$ . The signal  $x_2(t)$  is transmitted and then passed through the lowpass filter with frequency response

$$H_{LP}(j\omega) = \begin{cases} 2, & |\omega| < 20 \\ 0, & \text{otherwise.} \end{cases}$$

Let  $y_2(t)$  be the output of the lowpass filter. Sketch precisely its Fourier transform  $Y_2(j\omega)$  and write it in terms of  $X(j\omega)$ .

- (c) Can the original signal  $x(t)$  be recovered from the signal  $y_2(t)$  of part (c)? If not, explain why not. If so, describe a demodulation scheme to recover  $x(t)$ . Write the transform of any intermediate signal you generate from  $y_2(t)$  during the recovery process in terms of  $X(j\omega)$  and sketch it precisely.

**Write your answers to parts (a), (b), (c) on the following pages.**

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**Problem 3 (cont.)**

(a) (10 points)

Let  $x_1(t) = x(t) \cos(30t)$ . The signal  $x_1(t)$  is received and passed through a bandpass filter with frequency response

$$H_{BP}(j\omega) = \begin{cases} 2, & 20 < |\omega| < 30 \\ 0, & \text{otherwise.} \end{cases}$$

Write the CTFT  $X_1(j\omega)$  of  $x_1(t)$  in terms of  $X(j\omega)$ .

Let  $y_1(t)$  be the output of the bandpass filter. Sketch precisely the Fourier transform  $Y_1(j\omega)$  of the signal  $y_1(t)$  and write it in terms of  $X(j\omega)$ .

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**Problem 3 (cont.)**

(b) (10 points)

Using the signal  $y_1(t)$  from part (a), define  $x_2(t) = y_1(t) \cos(20t)$ . The signal  $x_2(t)$  is transmitted and then passed through the lowpass filter of with frequency response

$$H_{LP}(j\omega) = \begin{cases} 2, & |\omega| < 20 \\ 0, & \text{otherwise.} \end{cases}$$

Let  $y_2(t)$  be the output of the lowpass filter. Sketch precisely its Fourier transform  $Y_2(j\omega)$  and write it in terms of  $X(j\omega)$ .

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**Problem 3 (cont.)**

(c) (10 points)

Can the original signal  $x(t)$  be recovered from the signal  $y_2(t)$  of part (c)? If not, explain why not. If so, describe a demodulation scheme to recover  $x(t)$ . Write the transform of any intermediate signal you generate from  $y_2(t)$  during the recovery process in terms of  $X(j\omega)$  and sketch it precisely.

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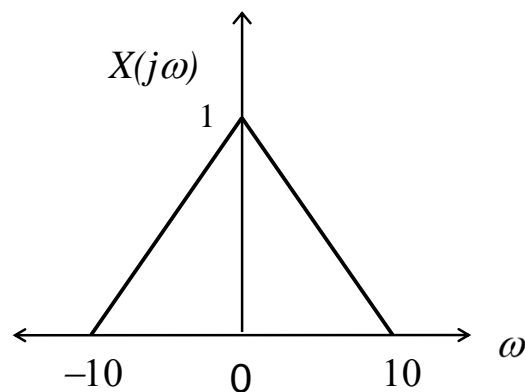
**Problem 4 [Sampling Theory] (30 points)**

- (a) For each of the following signals  $x(t)$ , determine if a sampling period of  $T = \frac{1}{4}$  sec is sufficiently small to avoid aliasing and allow reconstruction of the signal from its samples. **Justify your answers by determining the Fourier Transforms  $X(j\omega)$  of the signals.**

(i)  $x(t) = \frac{\sin(3\pi t)}{\pi t}$

(ii)  $x(t) = \begin{cases} 1, & |t| < 3\pi \\ 0, & |t| > 3\pi \end{cases}$

- (b) Let  $x(t)$  be the signal with Fourier transform  $X(j\omega)$  shown below.



Let  $x_p(t)$  be obtained from  $x(t)$  by impulse train sampling with sampling period  $T = \frac{\pi}{20}$ , with Fourier transform by  $X_p(j\omega)$ . Let  $x_d[n] = x(nT)$  be the DT sampled signal, with Fourier transform  $X_d(e^{j\Omega})$ .

- (i) Write  $X_p(j\omega)$  in terms of  $X(j\omega)$ . Write the formula relating  $X_d(e^{j\Omega})$  to  $X_p(j\omega)$ . Determine  $\omega_0$  such that  $X_d(e^{j2\pi}) = X_p(j\omega_0)$ .
- (ii) Sketch precisely  $X_p(j\omega)$  in the range  $|\omega| \leq \omega_0$  and  $X_d(e^{j\Omega})$  in the range  $|\Omega| \leq 2\pi$ .

**Justify your answers by referring to the formula for  $X_p(j\omega)$  and its relation to  $X_d(e^{j\Omega})$**

**Write your answers to parts (a), (b) on the following pages.**

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**Problem 4 (cont.)**

(a) (16 points)

For each of the following signals  $x(t)$ , determine if a sampling period of  $T = \frac{1}{4}$  sec is sufficiently small to avoid aliasing and allow reconstruction of the signal from its samples.

(i)  $x(t) = \frac{\sin(3\pi t)}{\pi t}$

(ii)  $x(t) = \begin{cases} 1, & |t| < 3\pi \\ 0, & |t| > 3\pi \end{cases}$



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**Problem 4 (cont.)**

(b) (14 points) Let  $x_p(t)$  be obtained from  $x(t)$  by impulse train sampling with sampling period  $T = \frac{\pi}{20}$ , with Fourier transform by  $X_p(j\omega)$ . Let  $x_d[n] = x(nT)$  be the DT sampled signal, with Fourier transform  $X_d(e^{j\Omega})$ .

(i) (4 points)

Write  $X_p(j\omega)$  in terms of  $X(j\omega)$ . Write the formula relating  $X_d(e^{j\Omega})$  to  $X_p(j\omega)$ . Determine  $\omega_0$  such that  $X_p(j\omega_0) = X_d(e^{j2\pi})$ .

(ii) (10 points)

Sketch precisely  $X_p(j\omega)$  in the range  $|\omega| \leq \omega_0$  and  $X_d(e^{j\Omega})$  in the range  $|\Omega| \leq 2\pi$ .

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**Problem 5 [Laplace Transform and LTI Systems]** (30 points)

Consider an LTI system  $S$  with transfer function

$$H(s) = \frac{s - 1}{(s^2 - 2s + 2)(s + 1)}.$$

- (a) Sketch precisely the pole-zero plot associated with  $H(s)$ . Indicate the order of all poles and zeros.
- (b) Suppose  $S$  is stable.
  - (i) Determine  $|H(j0)|$  and  $\angle H(j0)$ .
  - (ii) Determine  $|H(j\omega)|$  and  $\angle H(j\omega)$  in the limit of as  $\omega \rightarrow \pm\infty$ .
  - (iii) Is the system lowpass, highpass, bandpass, or allpass?
- (c) Suppose  $S$  is causal. If the impulse response is  $h(t)$ , does  $h(t)e^{-2t}$  have a Fourier transform?

**Write your answers to parts (a), (b), (c) on the following pages.**

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**Problem 5 (cont.)**

Consider the LTI system function  $H(s) = \frac{s-1}{(s^2-2s+2)(s+1)}$ .

(a) (10 points)

Sketch precisely the pole-zero plot associated with  $H(s)$ . Indicate the order of all poles and zeros.

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**Problem 5 (cont.)**

Consider the LTI system function  $H(s) = \frac{s-1}{(s^2-2s+2)(s+1)}$ .

(b) (12 points)

Suppose  $S$  is stable.

(i) Determine  $|H(j0)|$  and  $\angle H(j0)$ .

(ii) Determine  $|H(j\omega)|$  and  $\angle H(j\omega)$  in the limit of as  $\omega \rightarrow \pm\infty$ .

(iii) Is the system ~~have~~ lowpass, highpass, bandpass, or allpass?

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**Problem 5 (cont.)**

Consider the LTI system function  $H(s) = \frac{s-1}{(s^2-2s+2)(s+1)}$ .

(c) (8 points)

Suppose  $S$  is causal. If the impulse response is  $h(t)$ , does  $h(t)e^{-2t}$  have a Fourier transform?

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**Problem 6 [LT and Differential Equations]** (30 points, 10 points each)

Consider the causal LTI system whose input  $x(t)$  and output  $y(t)$  satisfy the differential equation

$$\frac{d^2y(t)}{dt^2} - 2\frac{dy(t)}{dt} - 3y(t) = \frac{dx(t)}{dt} - x(t).$$

- (a) Determine the transfer function  $H(s)$  and sketch precisely the pole-zero plot.
- (b) Determine the region of convergence (ROC). and determine the impulse response  $h(t)$ .
- (c) Draw a block diagram for the direct form (canonical) realization of the system using a cascade of integrators with feedforward and feedback components.

**Write your answers to parts (a), (b), (c), and (d) on the following pages.**

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**Problem 6 (cont.)**

Causal LTI system defined by  $\frac{d^2 y(t)}{dt^2} - 2\frac{dy(t)}{dt} - 3y(t) = \frac{dx(t)}{dt} - x(t)$ .

(a) (10 points)

Determine the transfer function  $H(s)$  and sketch precisely the pole-zero plot.

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**Problem 6 (cont.)**

Causal LTI system defined by  $\frac{d^2 y(t)}{dt^2} - 2\frac{dy(t)}{dt} - 3y(t) = \frac{dx(t)}{dt} - x(t)$ .

(b) (10 points)

Determine the region of convergence (ROC). and determine the impulse response  $h(t)$ .



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**Problem 6 (cont.)**

Causal LTI system defined by  $\frac{d^2 y(t)}{dt^2} - 2\frac{dy(t)}{dt} - 3y(t) = \frac{dx(t)}{dt} - x(t)$ .

(c) (10 points)

Draw a block diagram for the direct form (canonical) realization of the system using a cascade of integrators with feedforward and feedback components.

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