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GRY ROBOT

ample | How to make Hungry Robot |
isor,3d printer project tutorial

EAT EVERYTHING!

nothing robots such as Drinky_(Drinking buddy robot). I
optional purpose not for functional. This is fun, makes

ess robot but, I'd like to make a funny robot! There are
ie). I'm going to make it by using 3d printer and an

ng modeling files are opensource. Feel free to make it by

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Hungry Robot | Servo,Sensor,3d printer Arm project tutorial e...

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Robot[ew/100happythings/18-Hungry-Robot/parts-list-for-](#)

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[fP_LfUiwdc](#)15.5 NEW Premiere
Pro Dial[.com/view/100happythings/18-Hungry-Robot](#)▼ 15 Premiere Pro Dial
DIY[.com/happythingsmaker/TrashEatingRobot](#)14 Bluetooth Pedal
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| Hungry Robot (Eat everything) using 3D printer project

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Main/Software

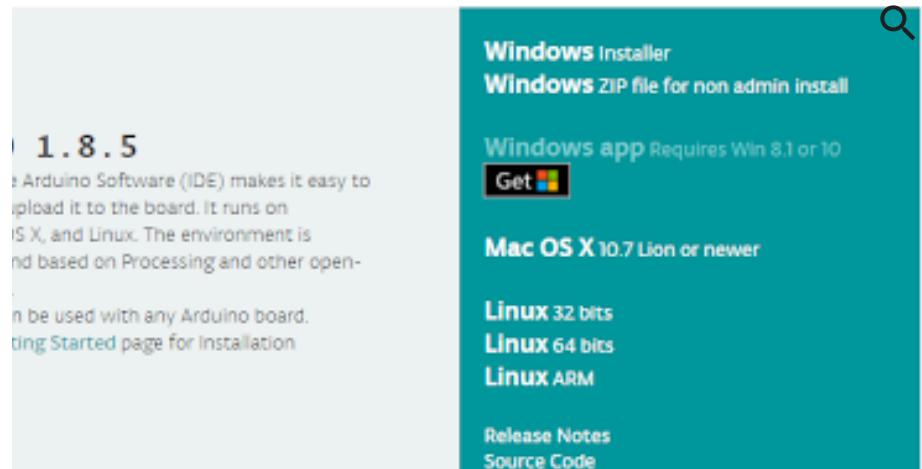
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or Chinese version)

[/CH341SER_ZIP.html](#)

DOWNS驱动程序和DLL动态库，内含非标准波特率的设置等使用说明，支持32/64位WIN7/8/10/XP，SERVER 2016/2012/2008/2003，2000/ME/98，通过微软数字签名认证串口。

340B, CH340E, CH340T, CH340R, CH341A, CH341T, CH341H

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[code](#)

[igsmaker/Trash Eating Robot](#)



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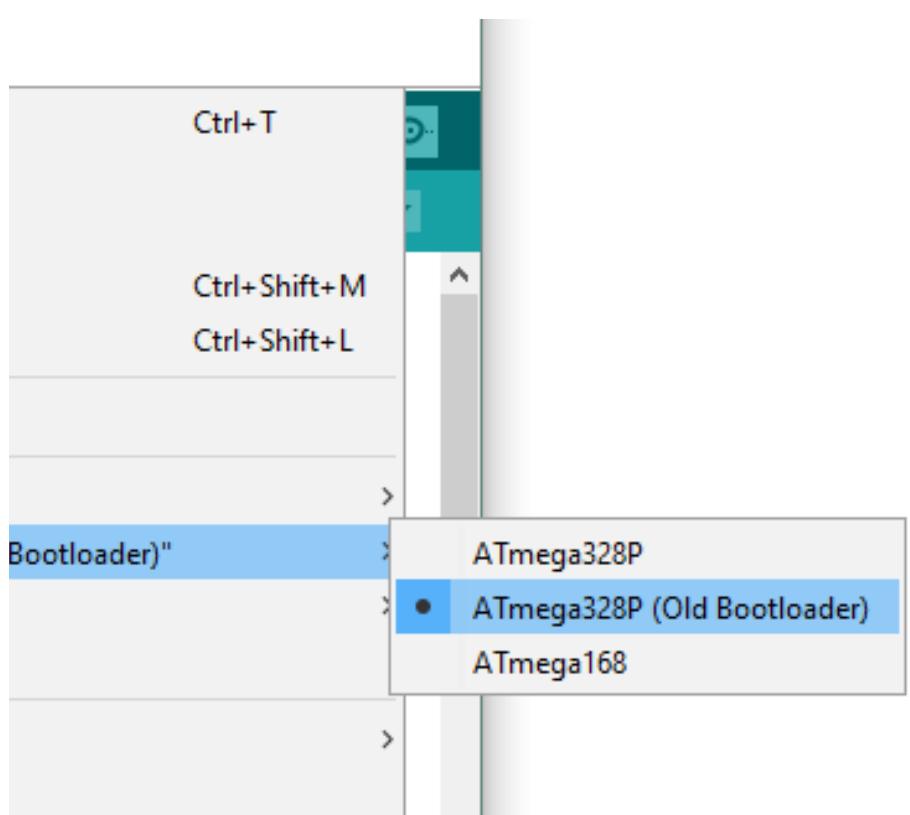
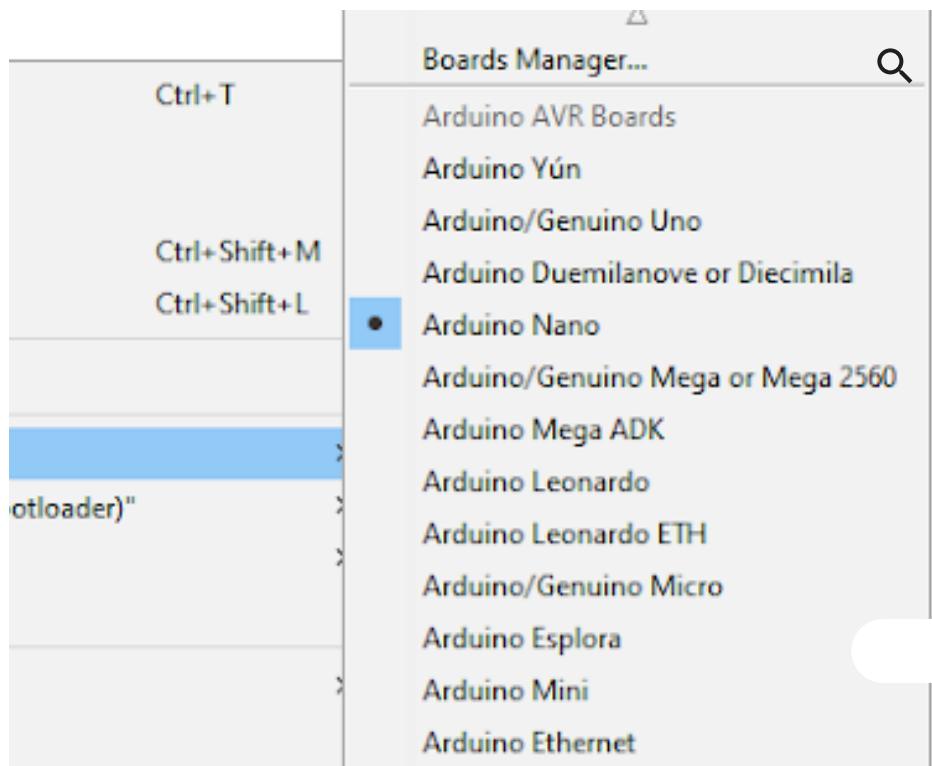
The first commit
Initial commit
Initial commit
Initial commit

Clone with HTTPS ⓘ Use SSH
Use Git or checkout with SVN using the web URL.
<https://github.com/happythingsmaker/tras>

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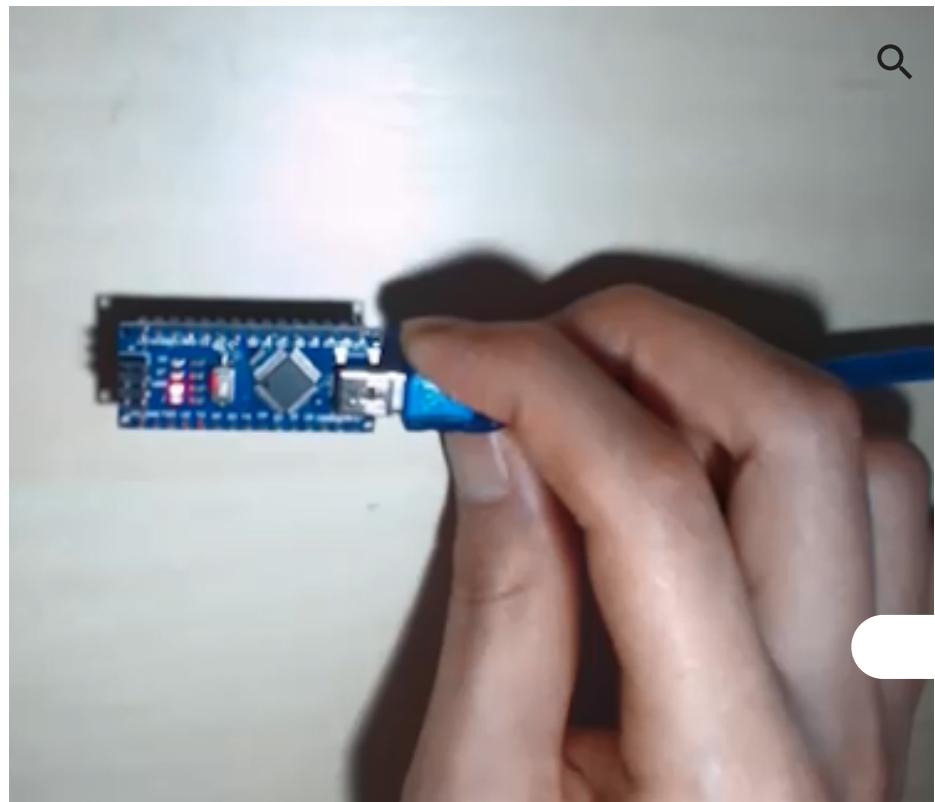
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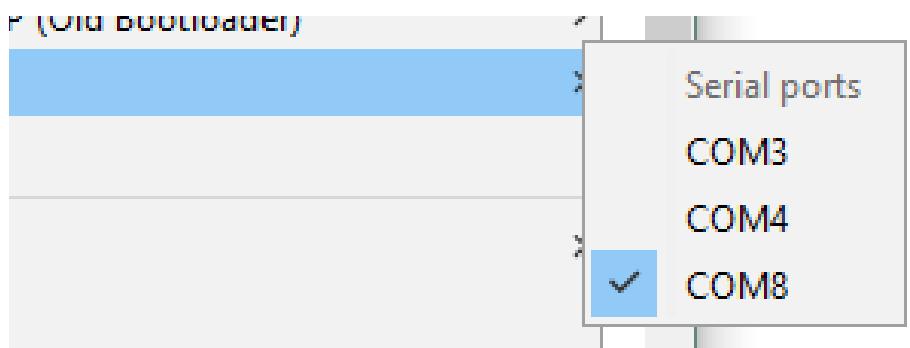
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com port



✓ com port will be appeared



TS



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g files



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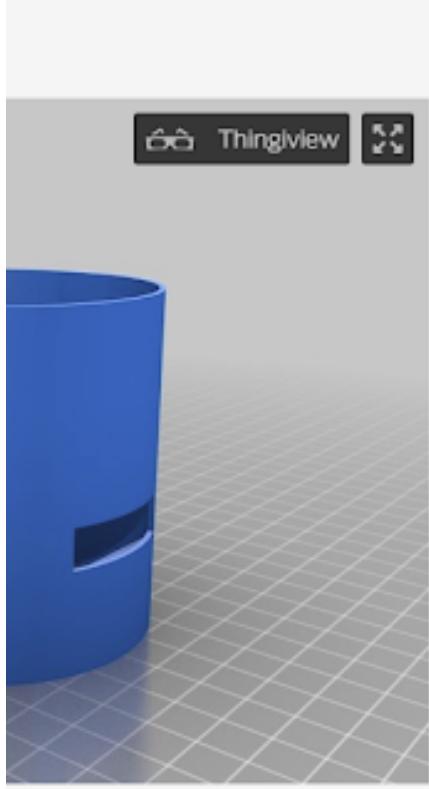
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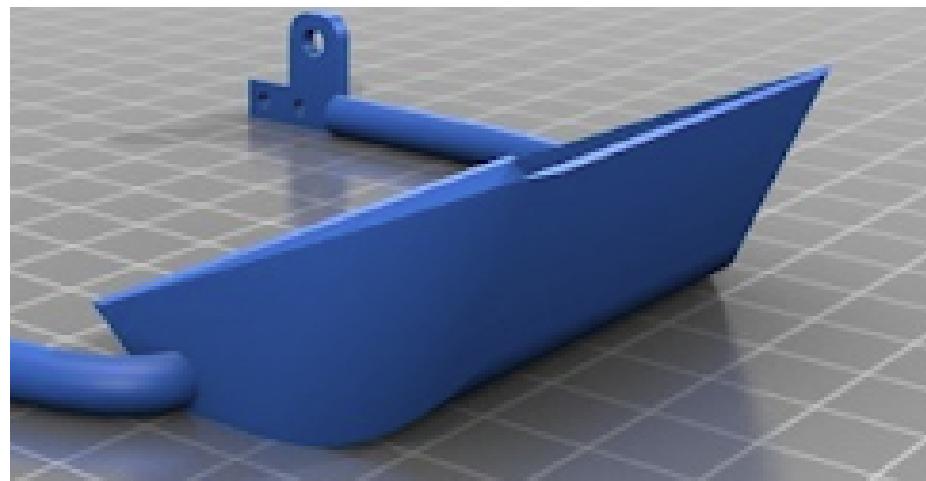
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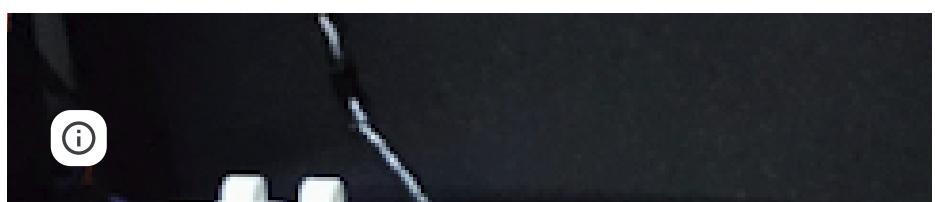
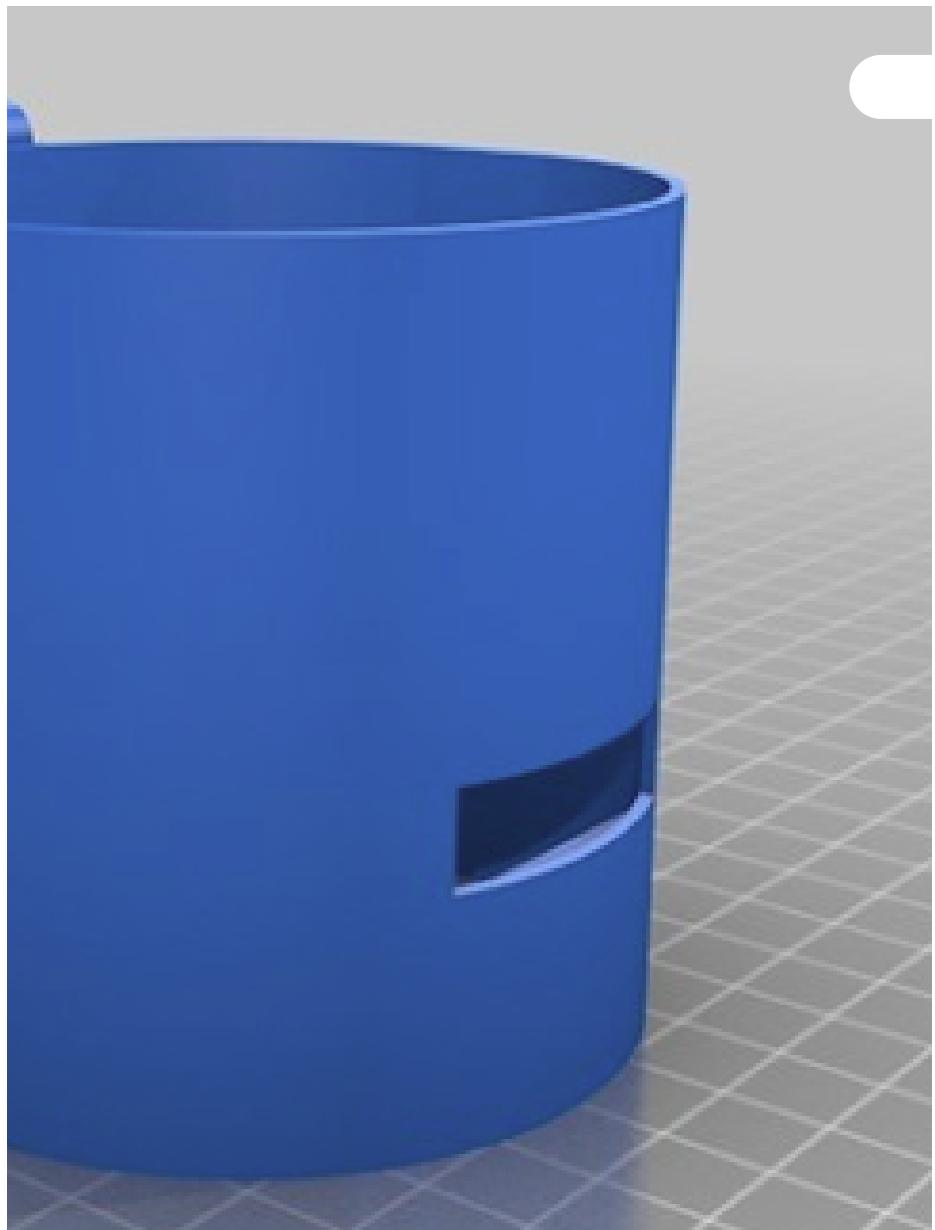
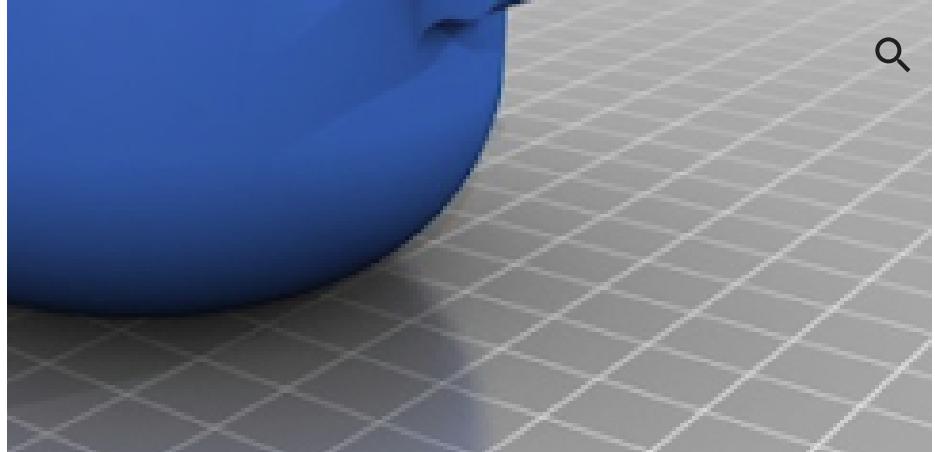
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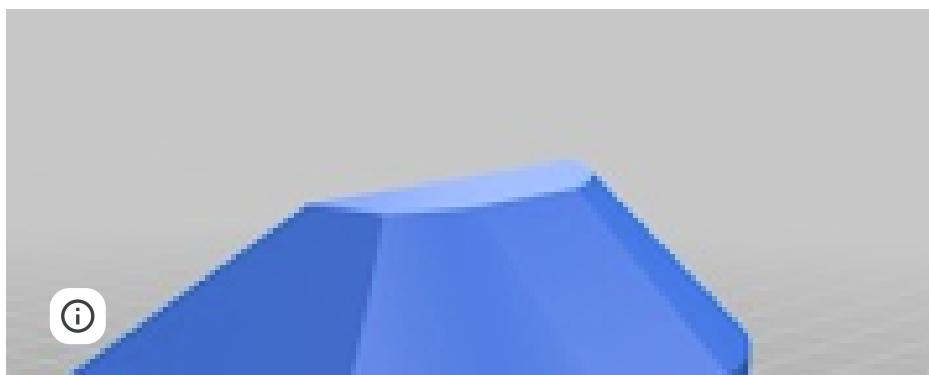
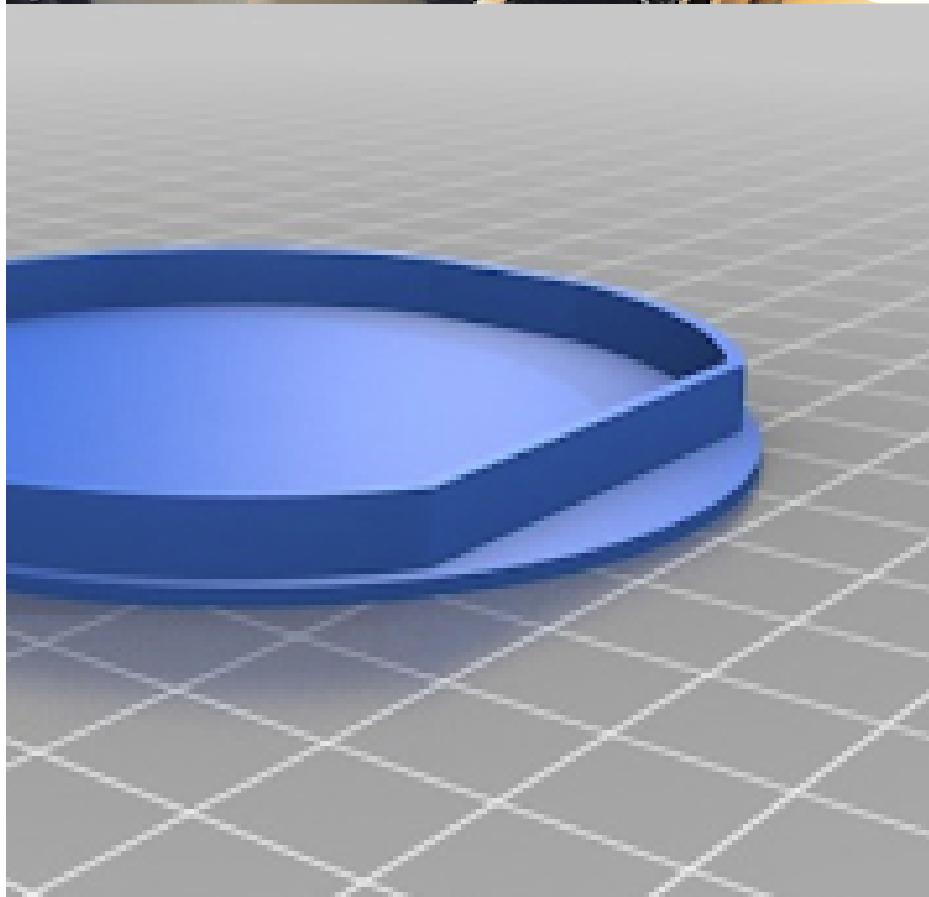
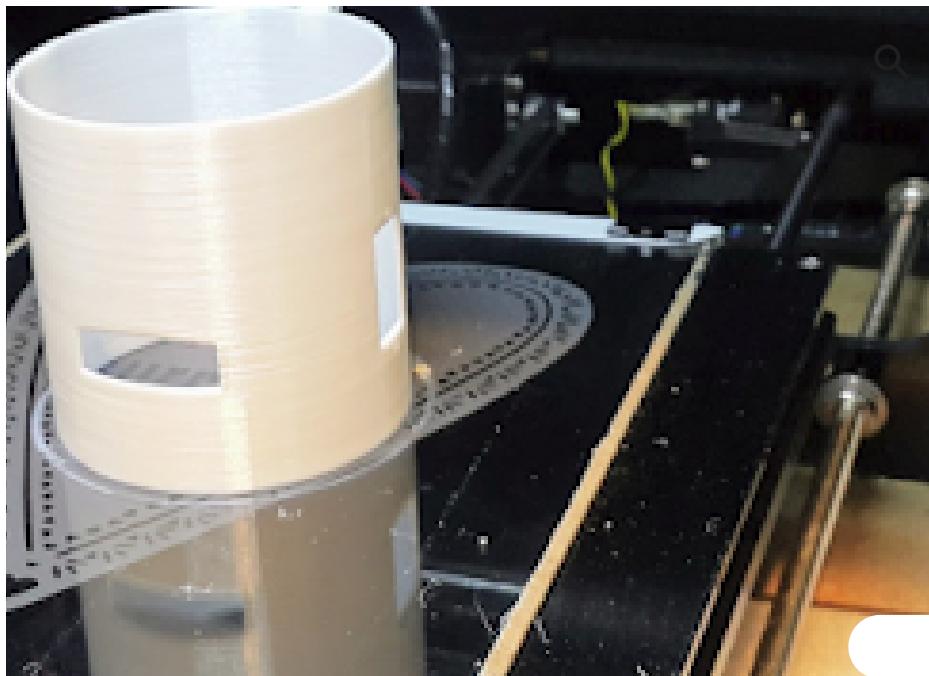
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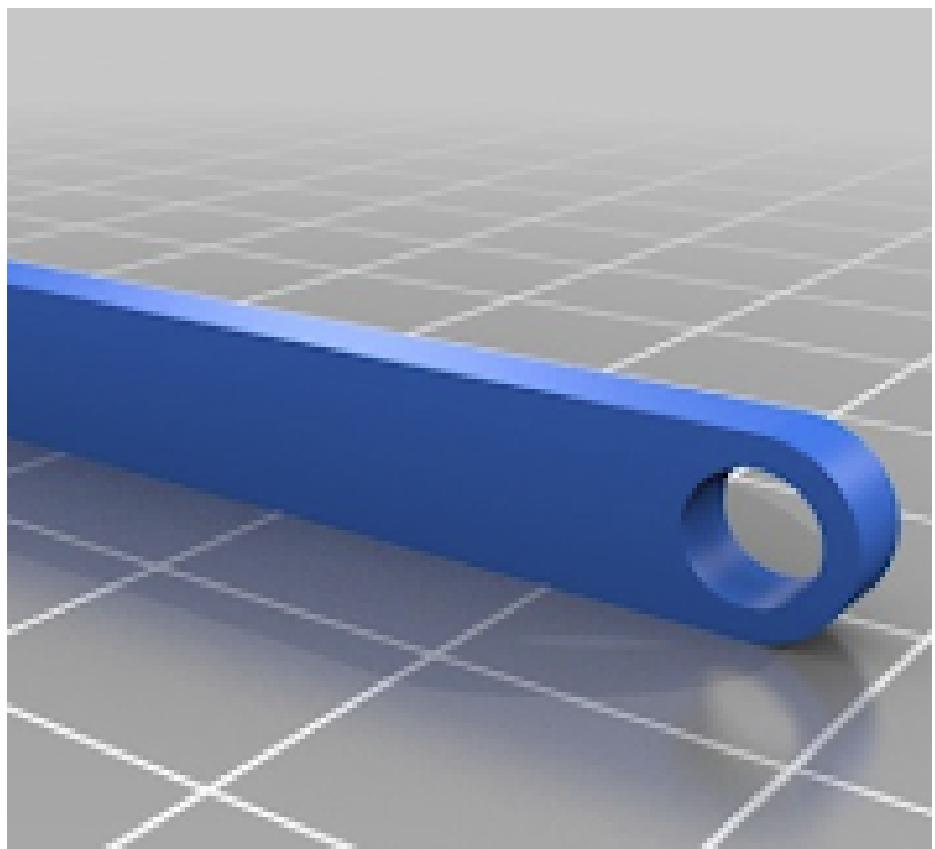
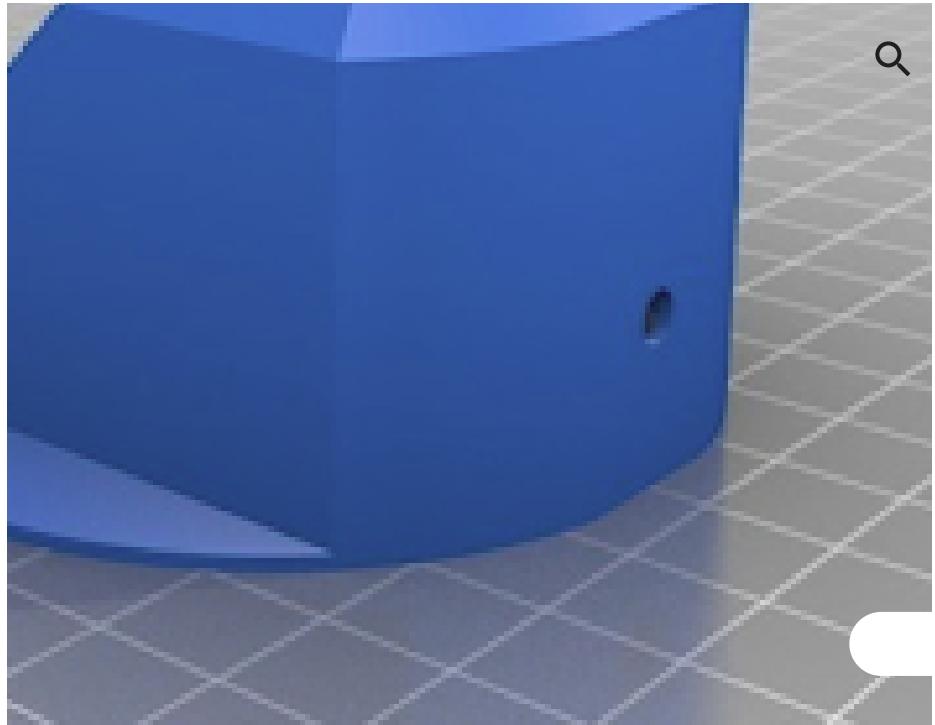
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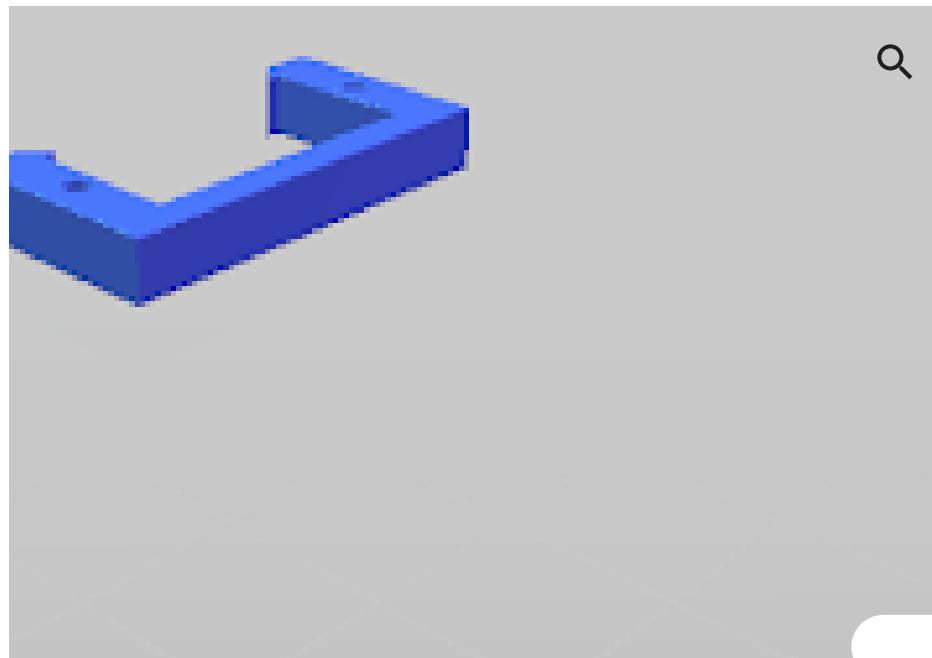


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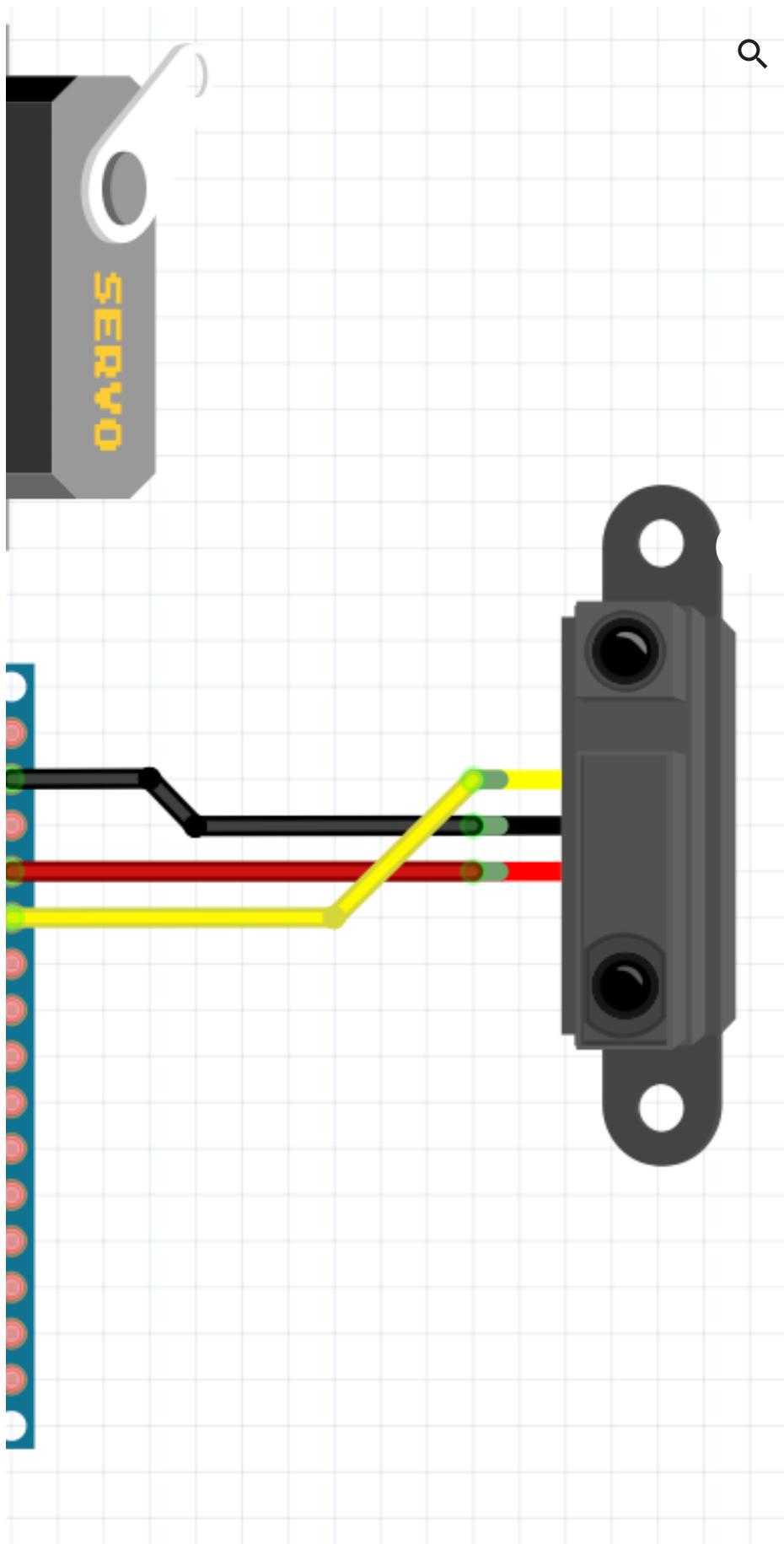
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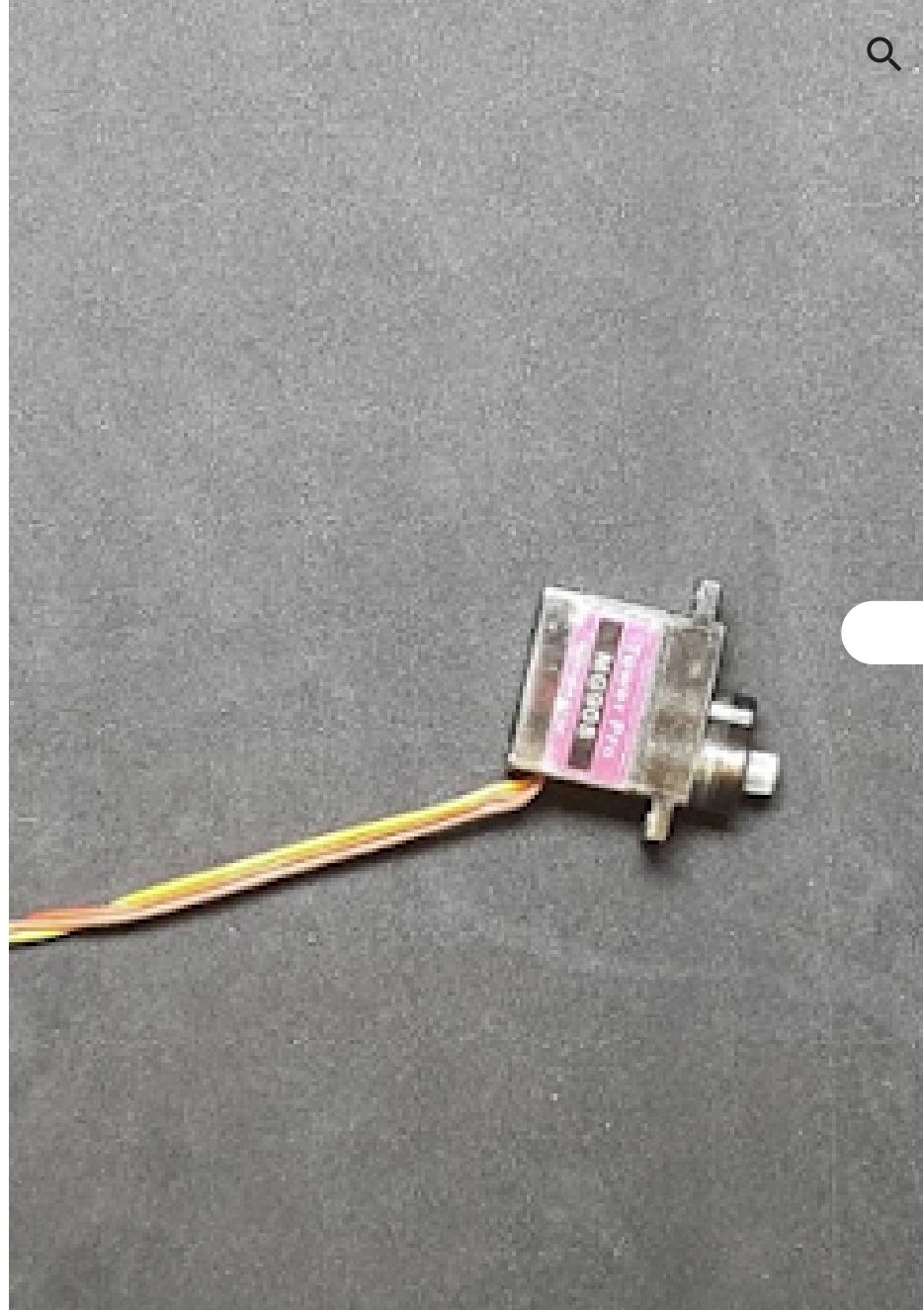
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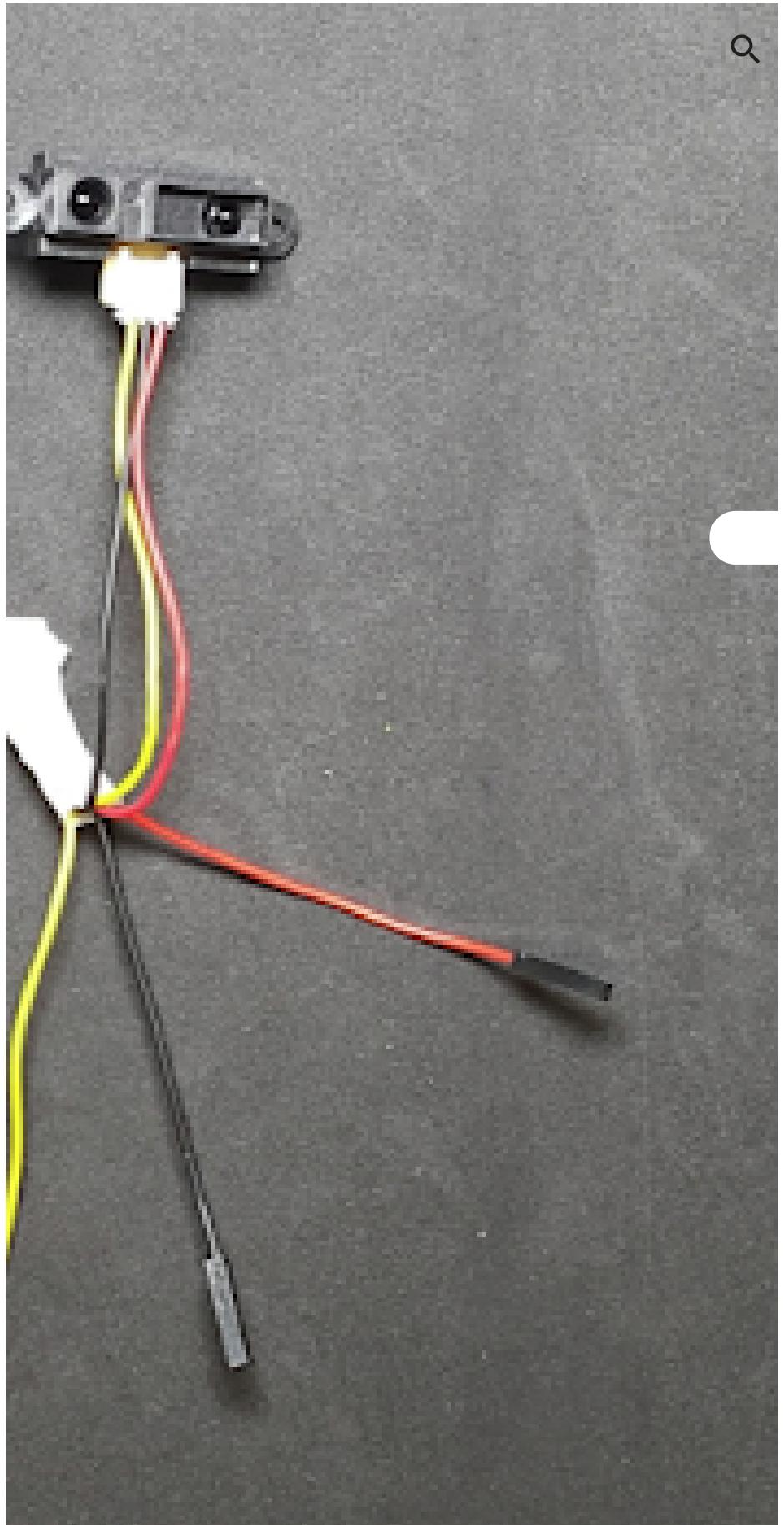
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the Sensor

connected with female-female Dupont cable.

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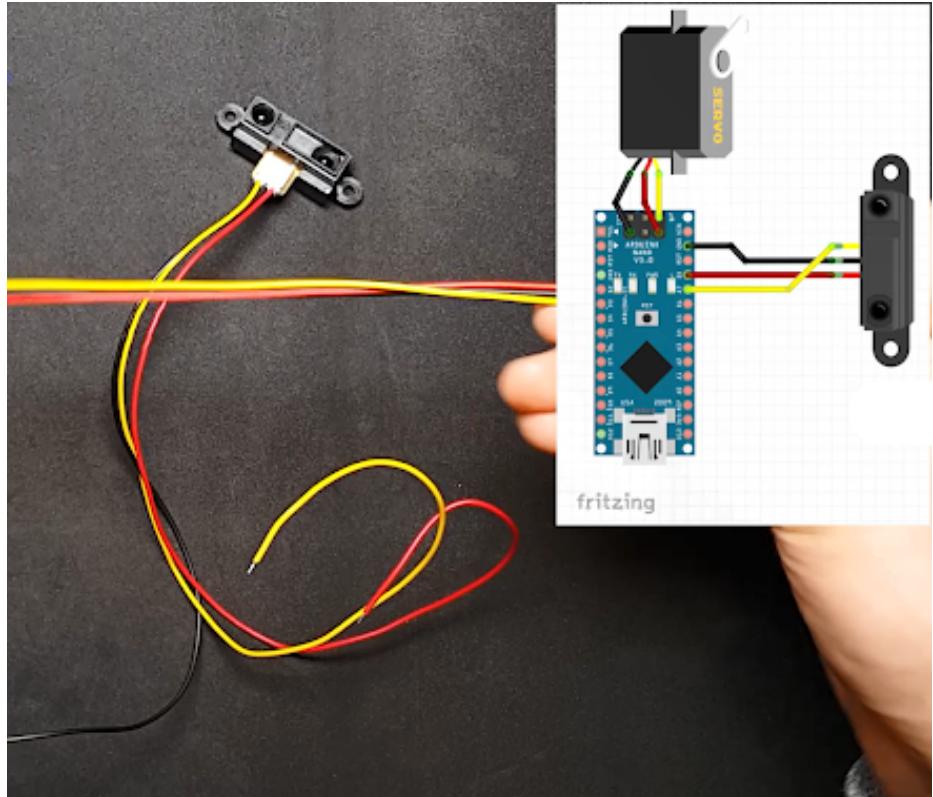
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robot we need to cut and rewire manually. This sensor uses three wires. in order to read distance from an read analog signal from this sensor. we are going to use or value



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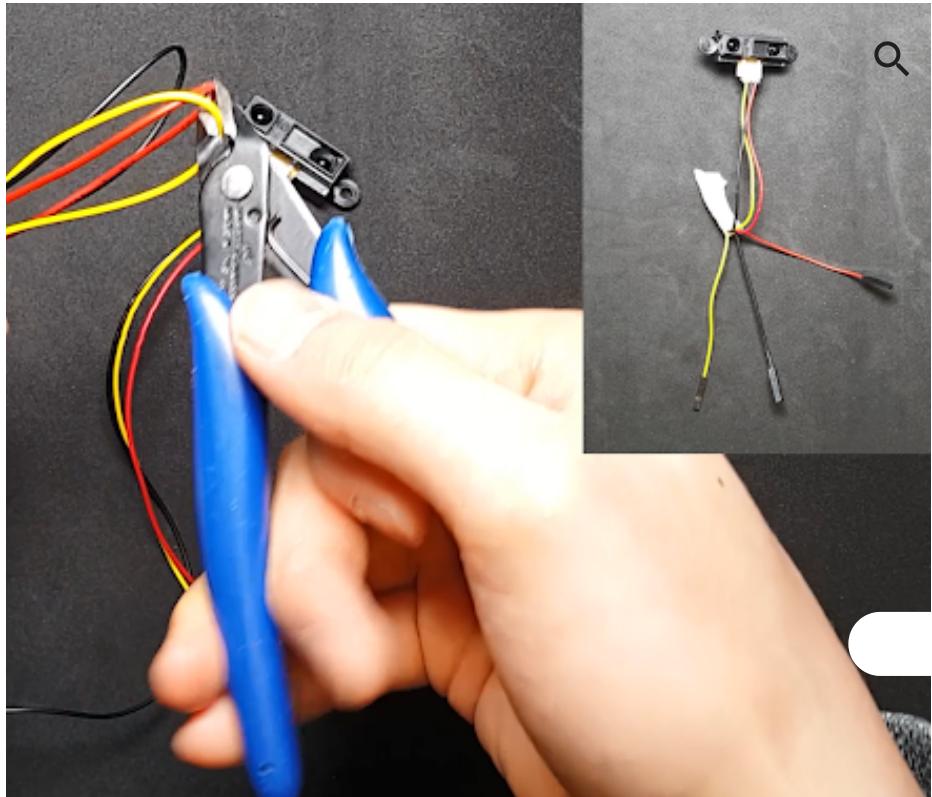
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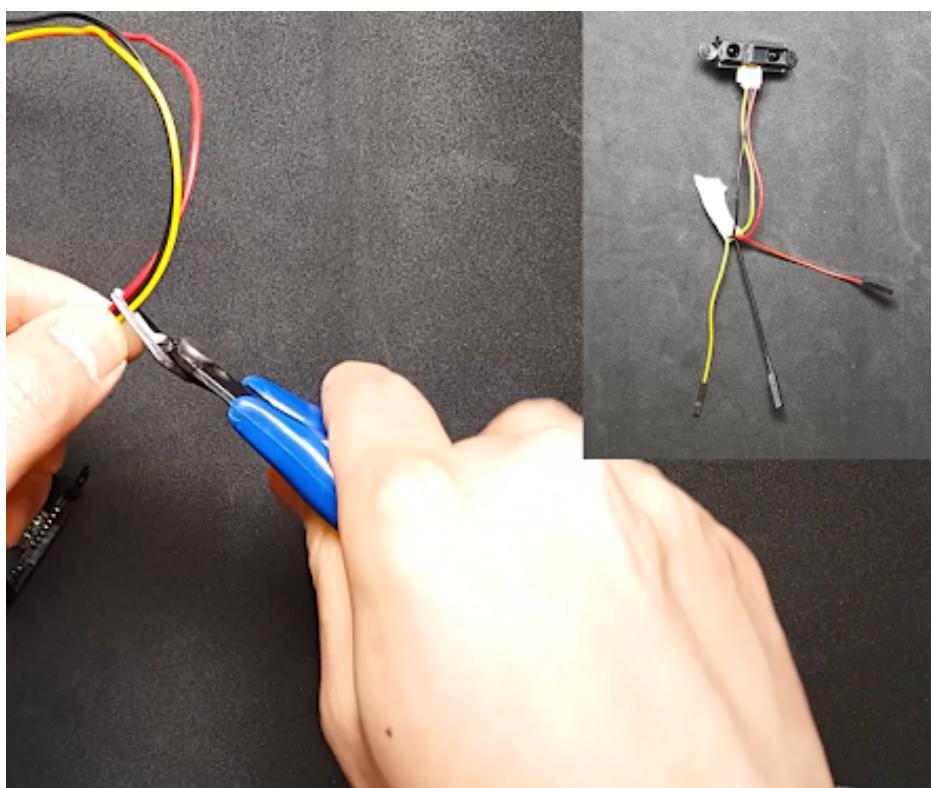


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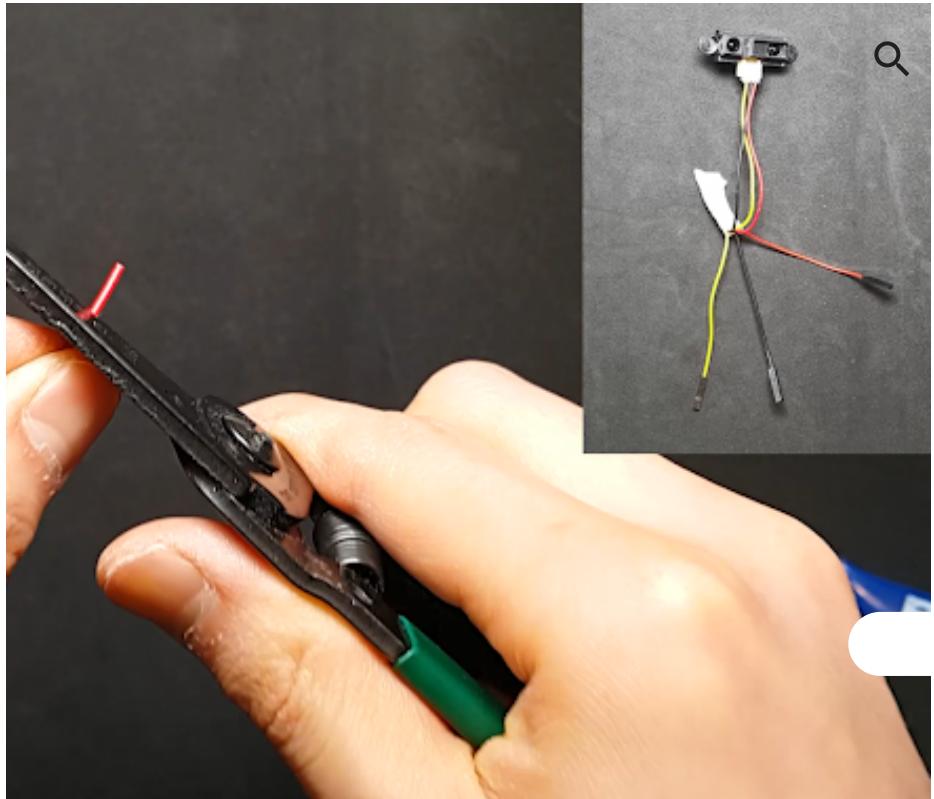
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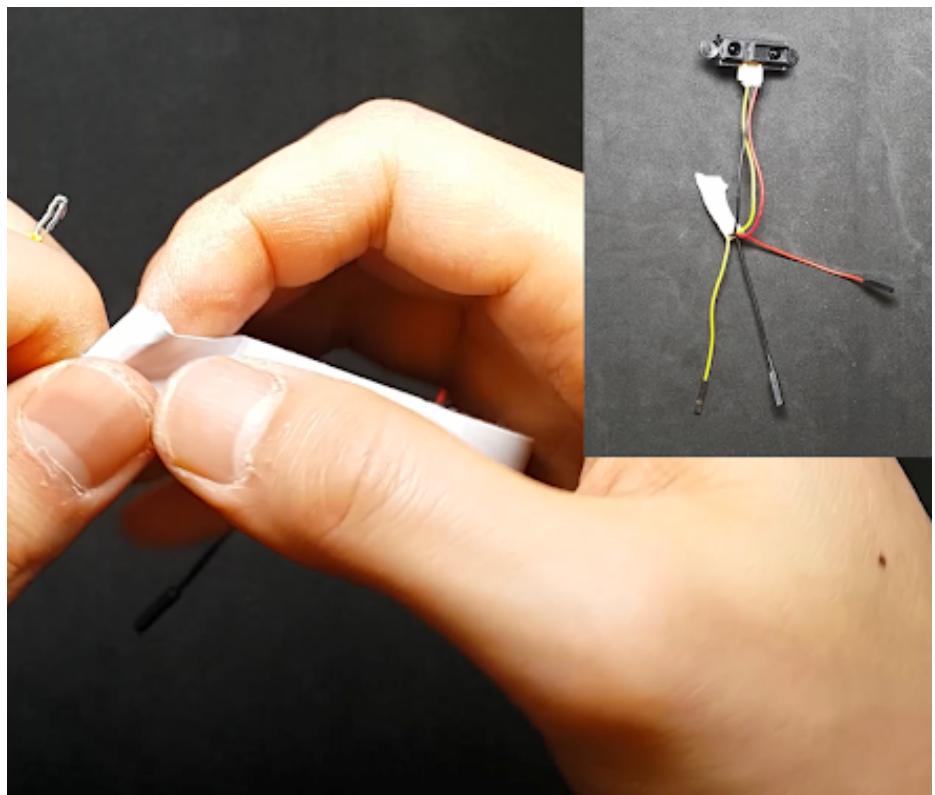
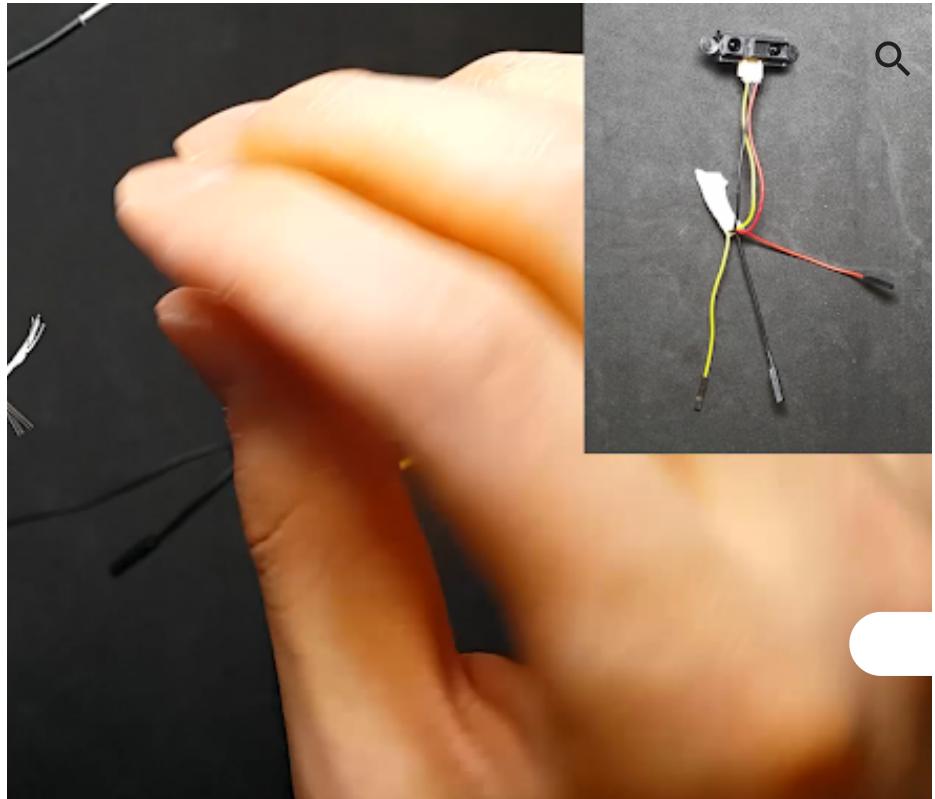
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r

s. VCC ground and PWM.

must be allocated with the servo motor. In this project



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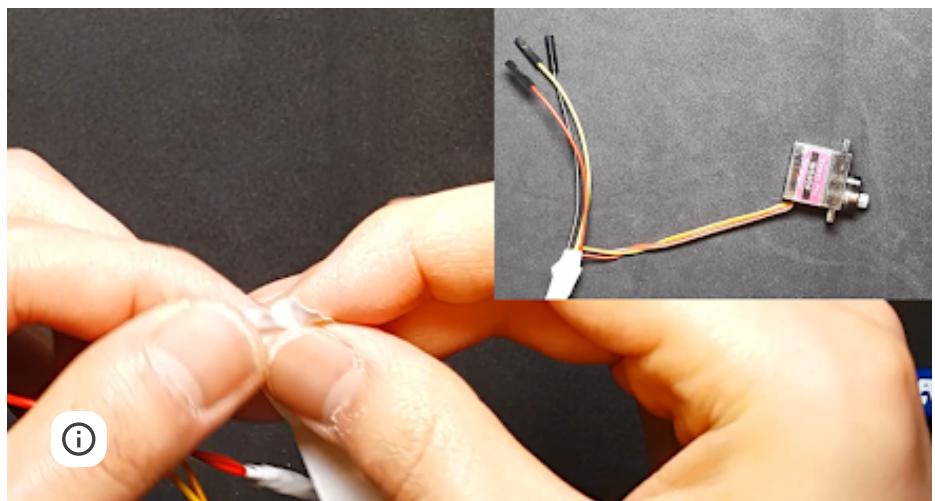
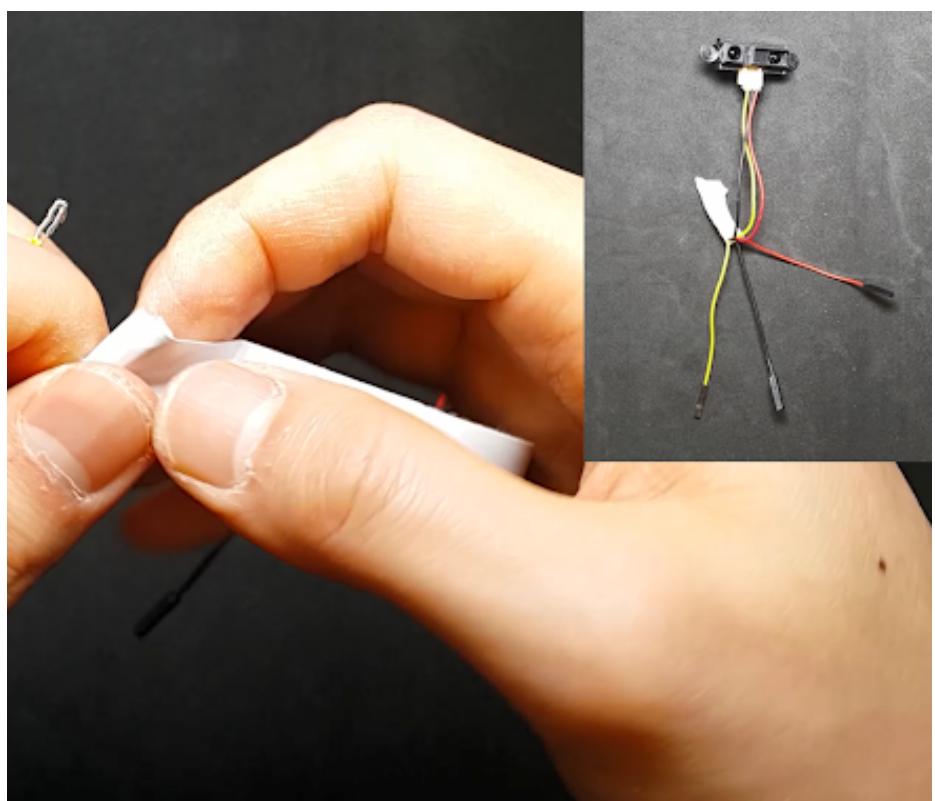
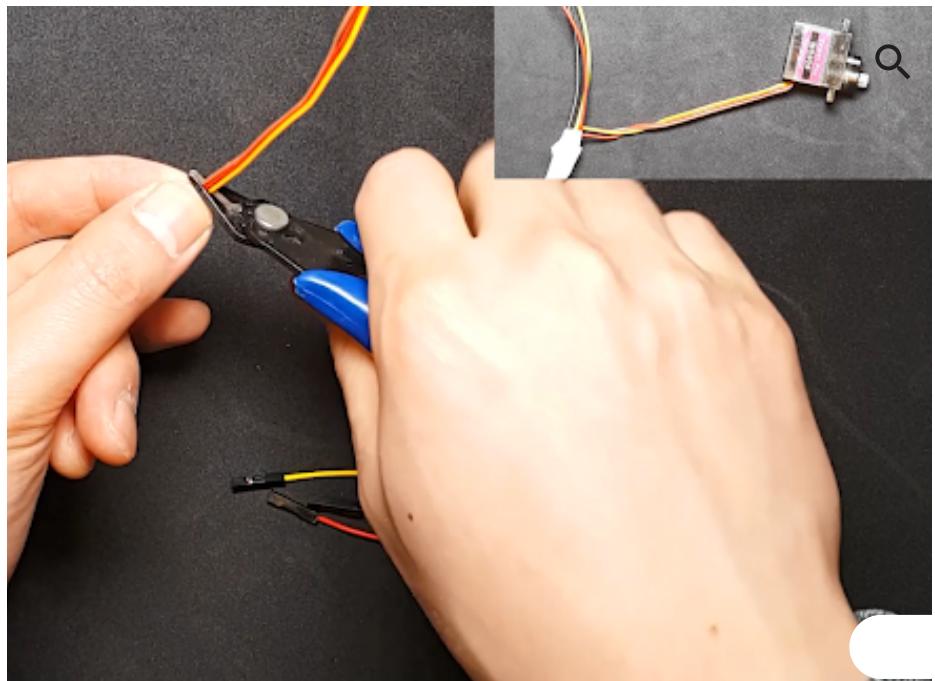
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servo motor. We need to use the screwdriver and screw

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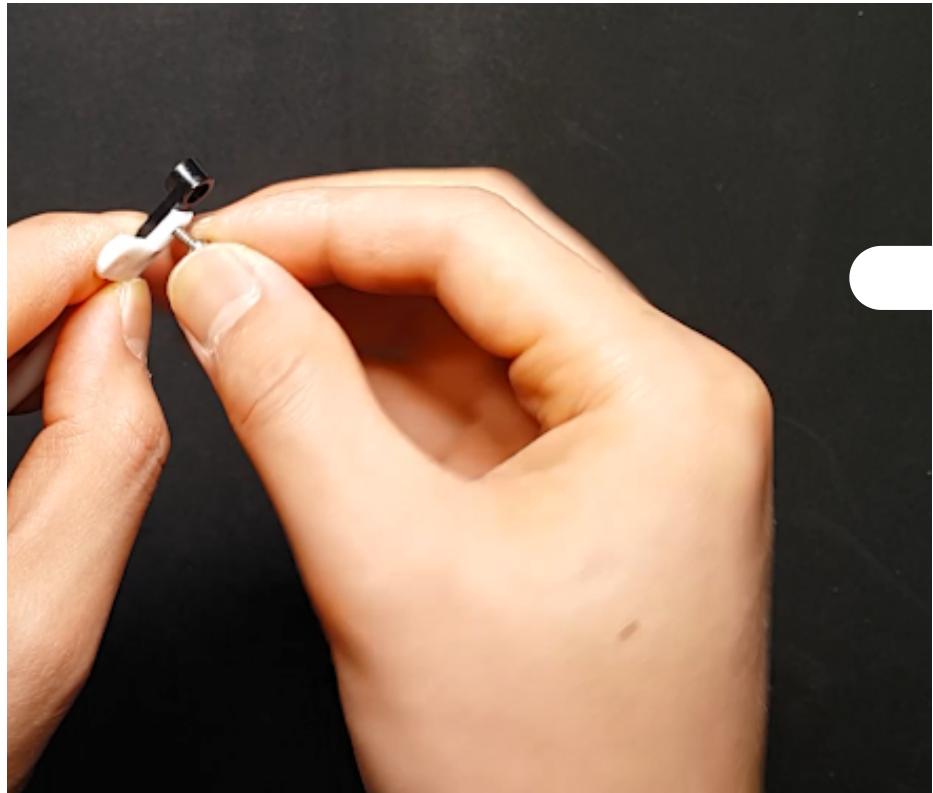
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Fit body and make sure the direction



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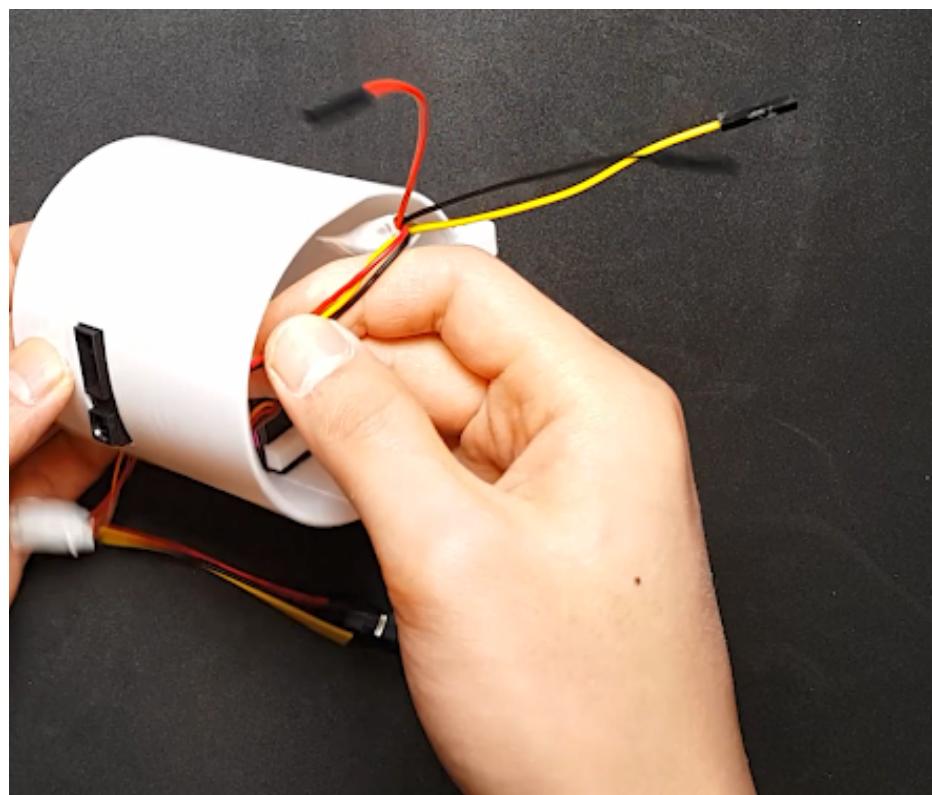
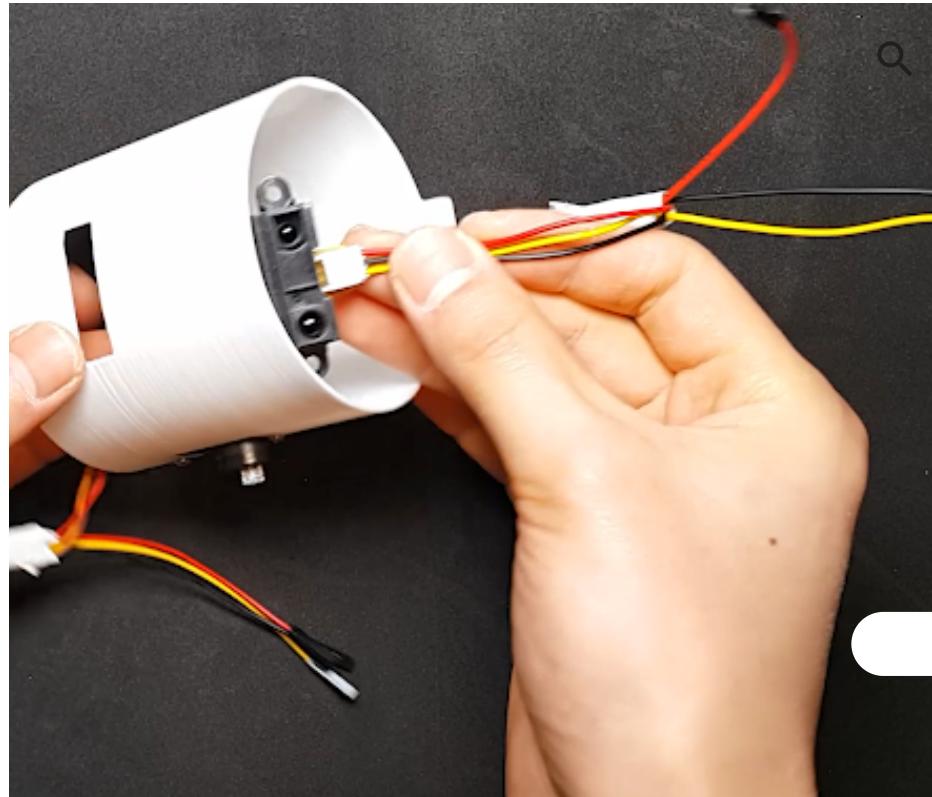
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Switch for Camera

13 Jibo Homage

12 HappyKeys

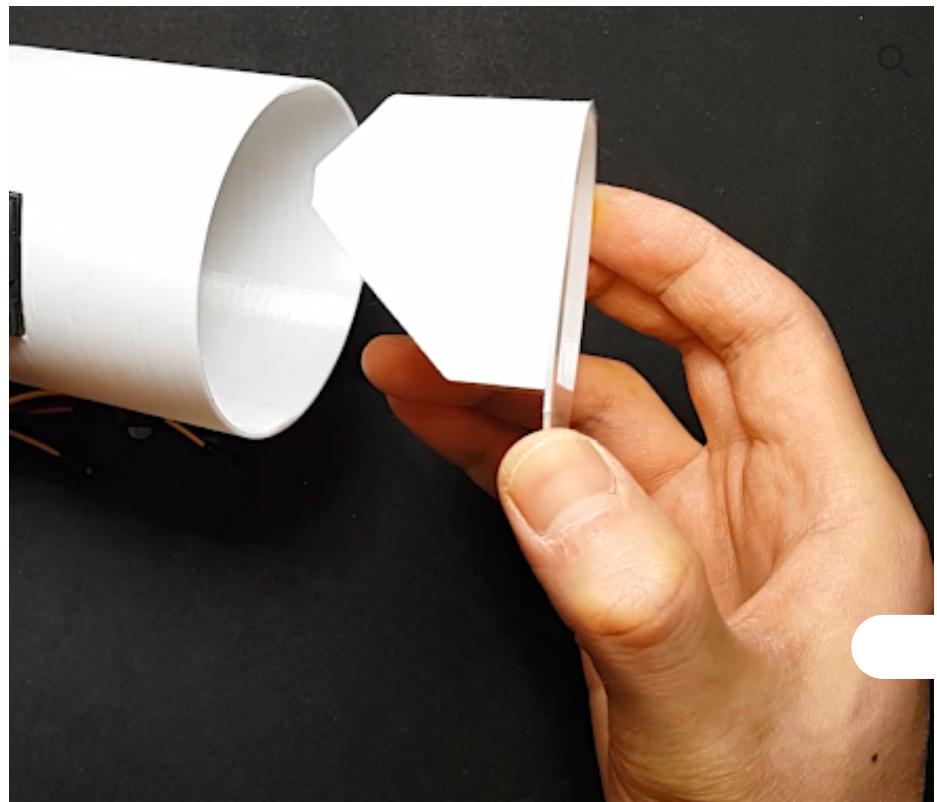
11 LED Ice Skate

10 igloo mold

05 BuskingBot

✓ Tools and Parts

✓ Tins



f the body

to outside.



igh the hole.



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✓ 20 Motion Capture Humanoid

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18 Hungry Robot(KOR)

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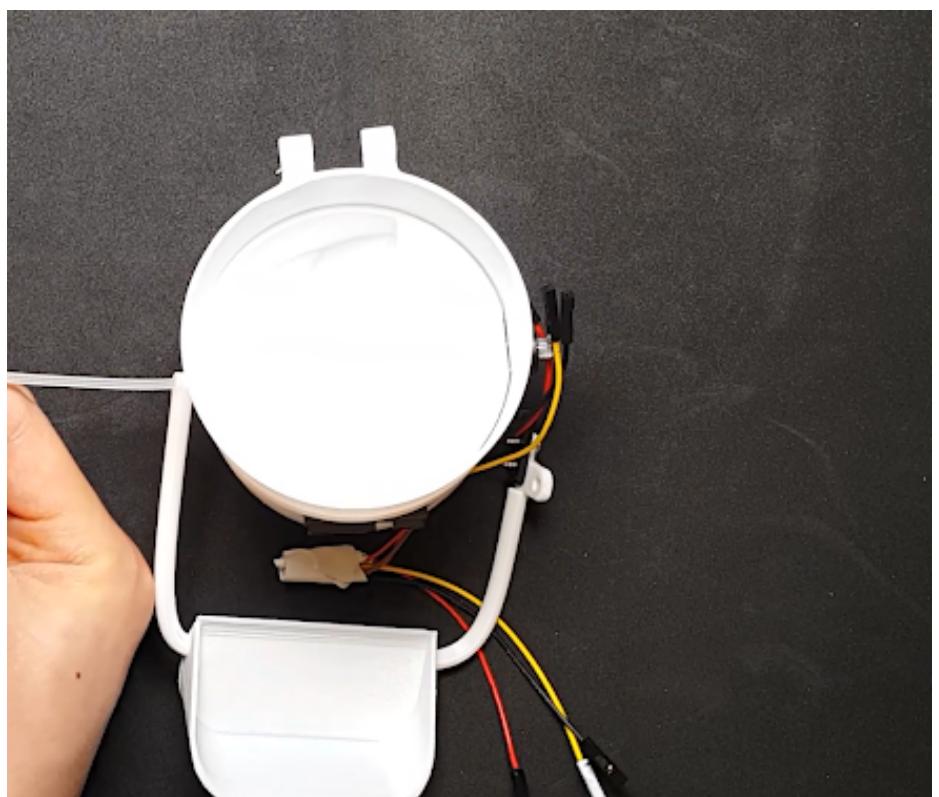
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2.

Very simple you don't need to use bolt anymore.



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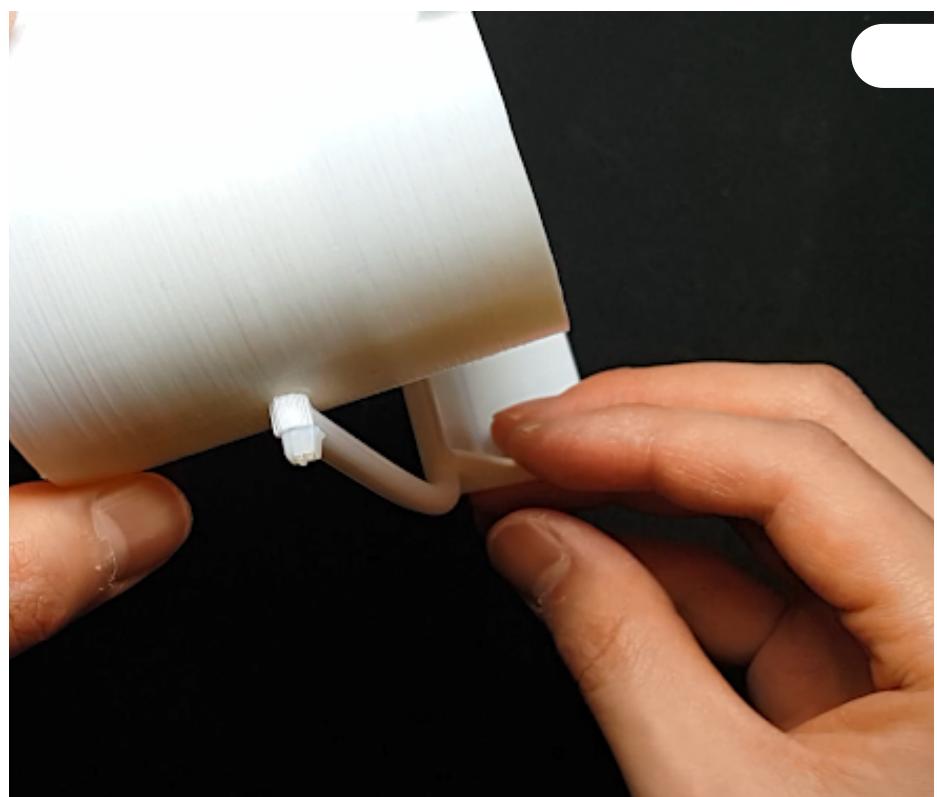


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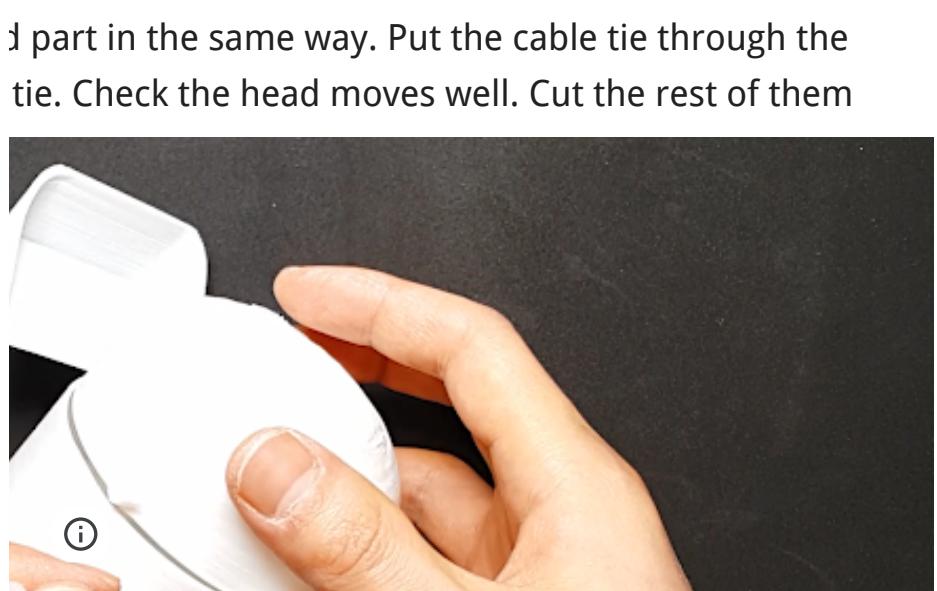
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↓ part in the same way. Put the cable tie through the tie. Check the head moves well. Cut the rest of them

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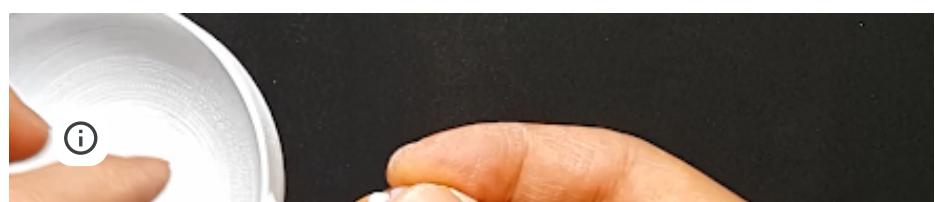
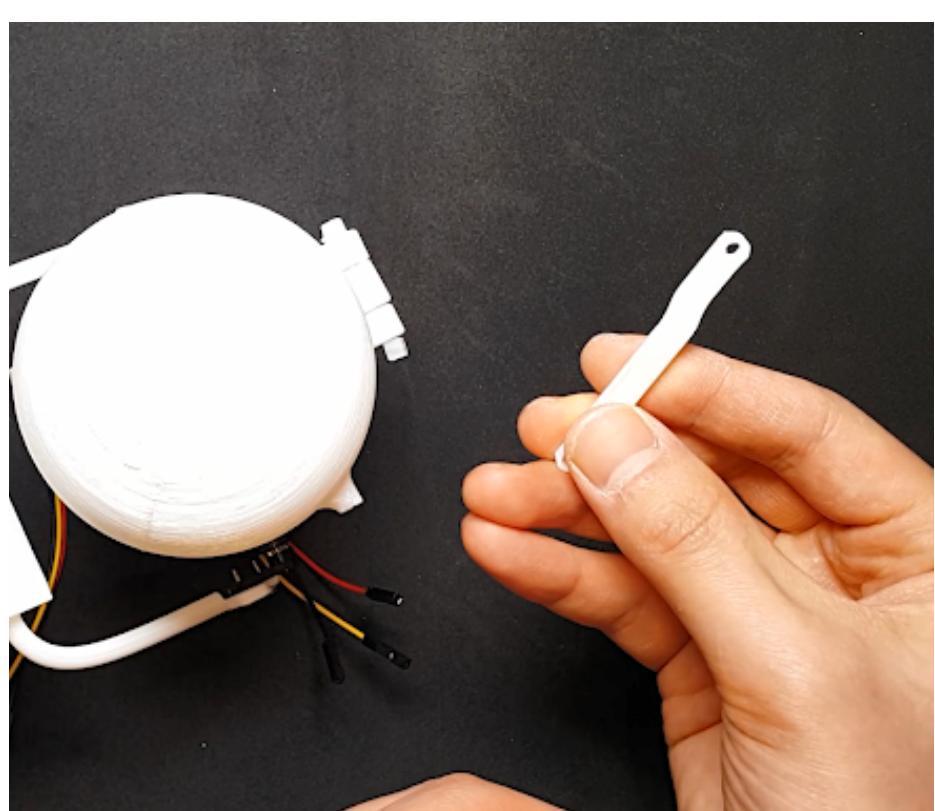
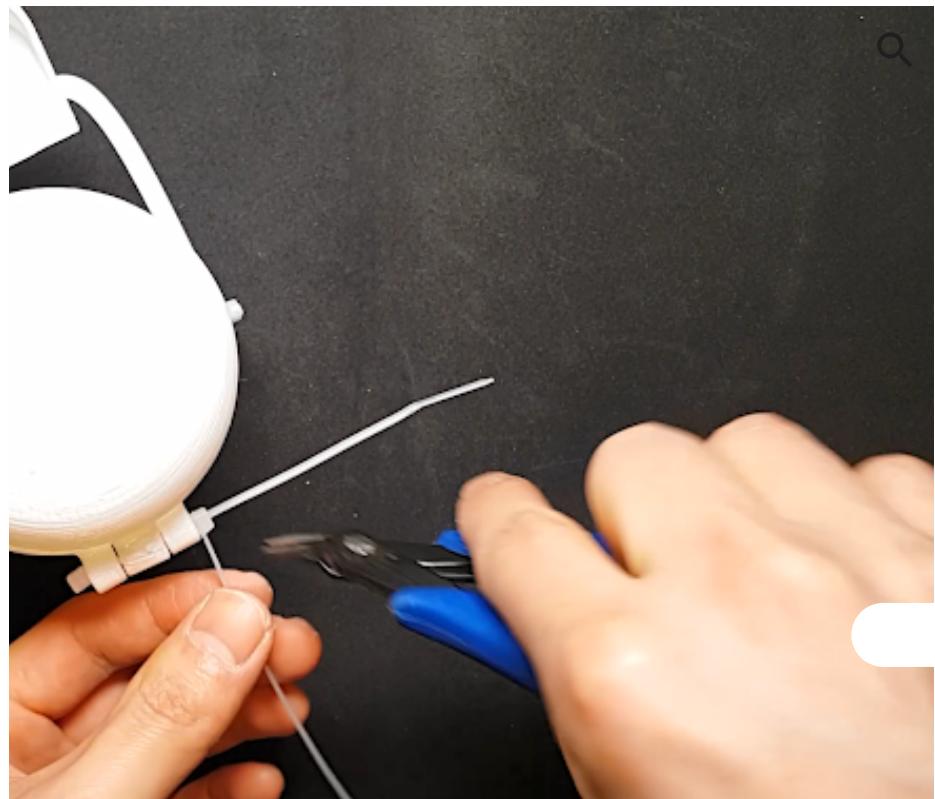
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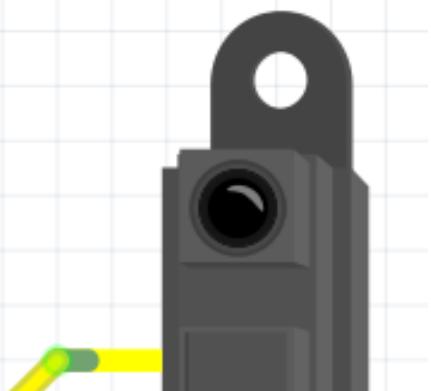
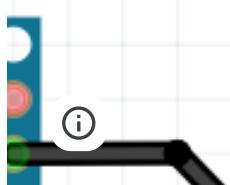
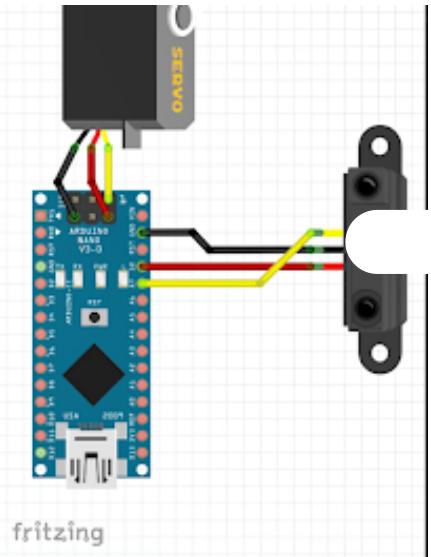
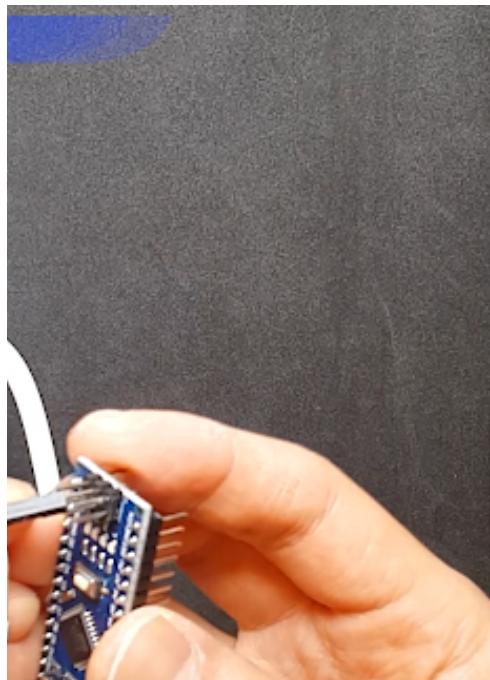
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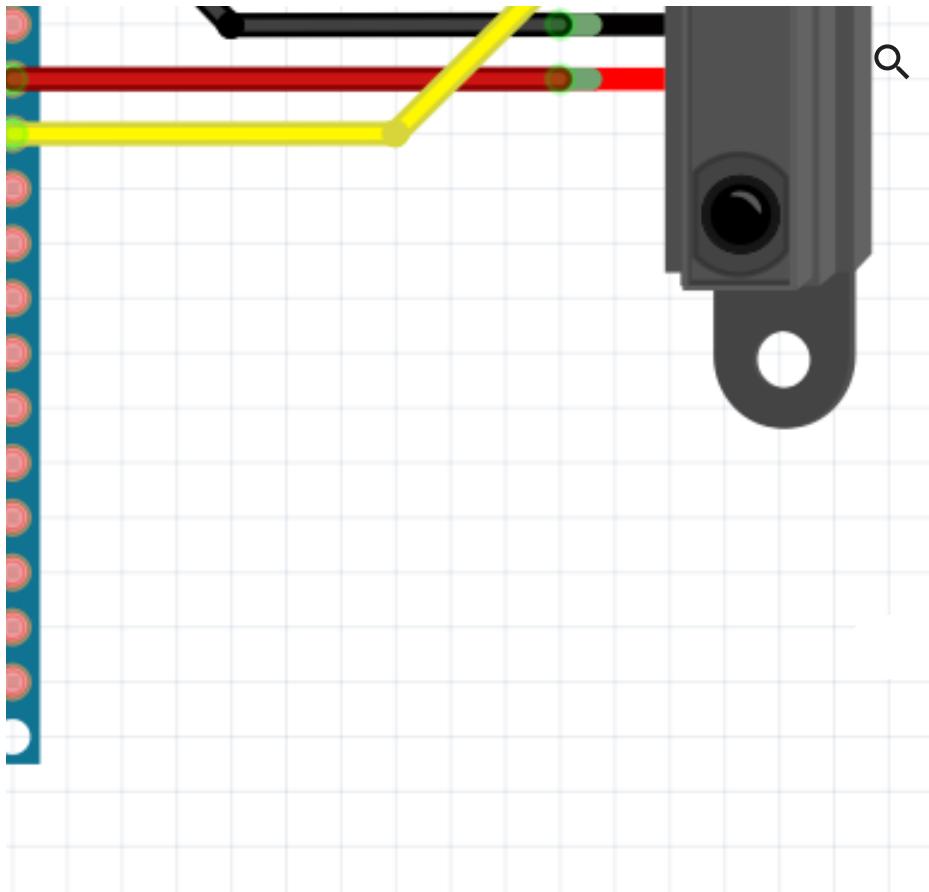


and pin numbers



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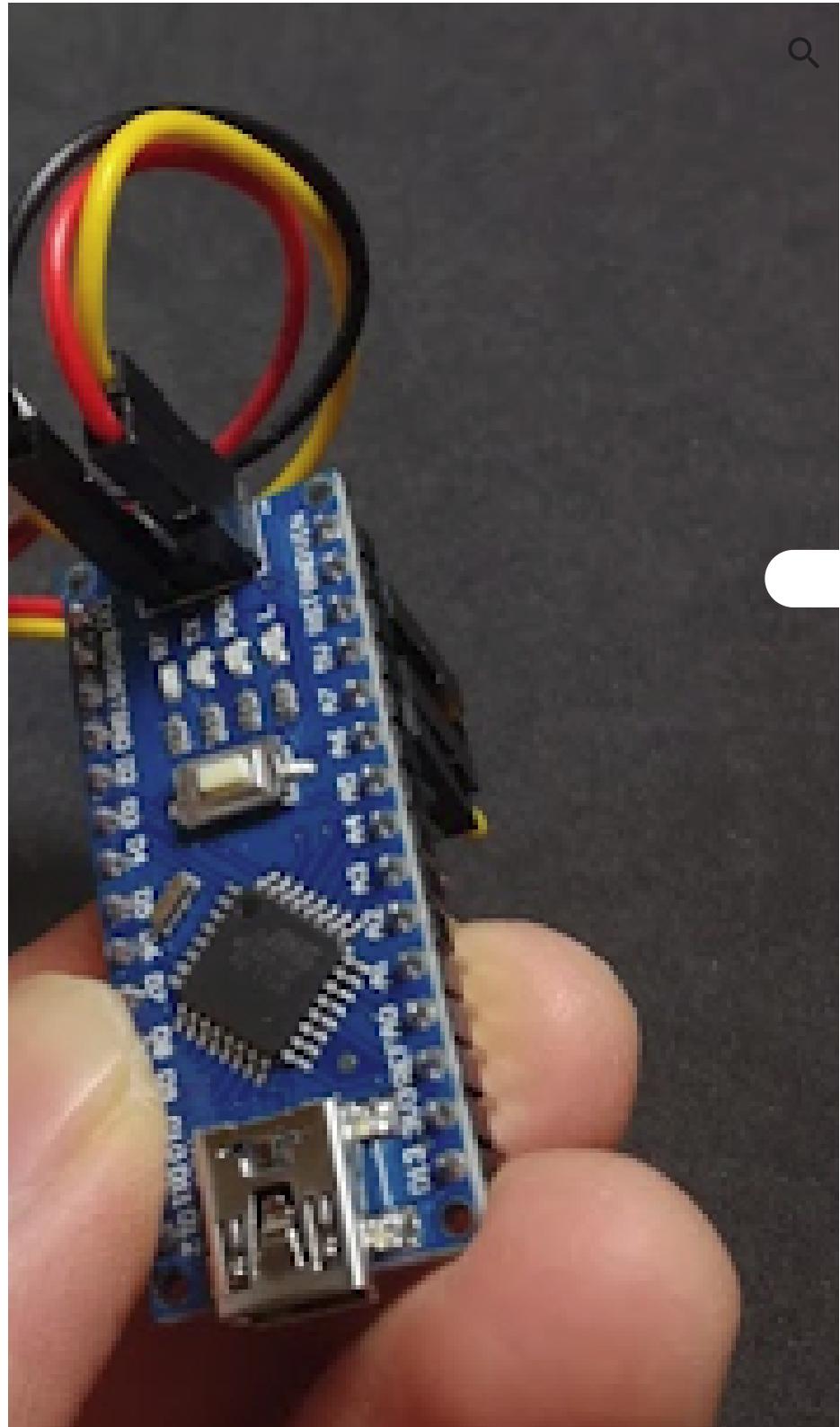
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<https://sites.google.com/view/100happythings/18-Hungry-Robot>



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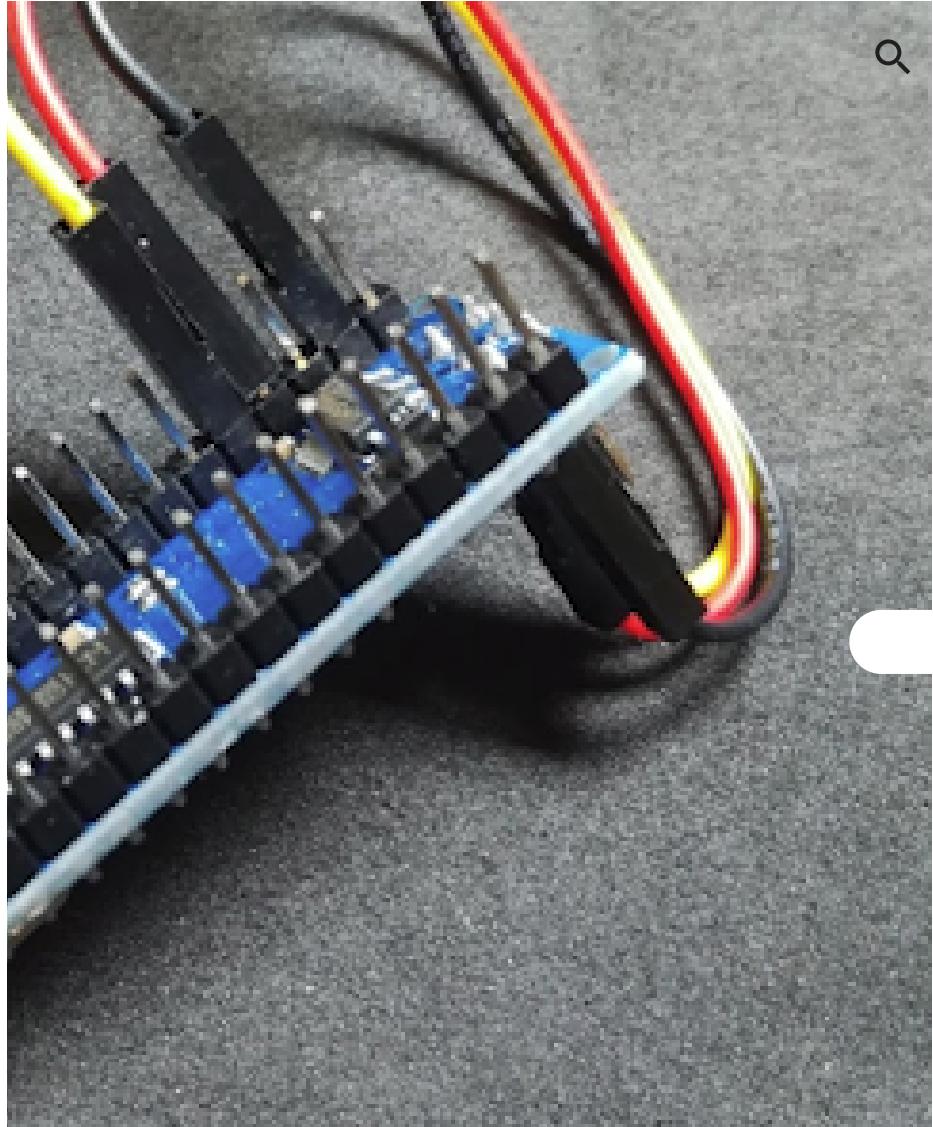
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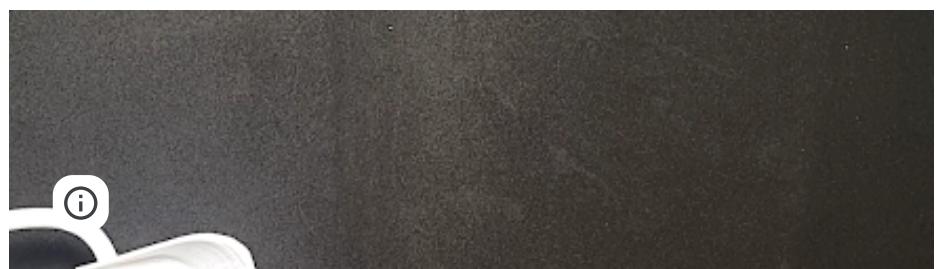
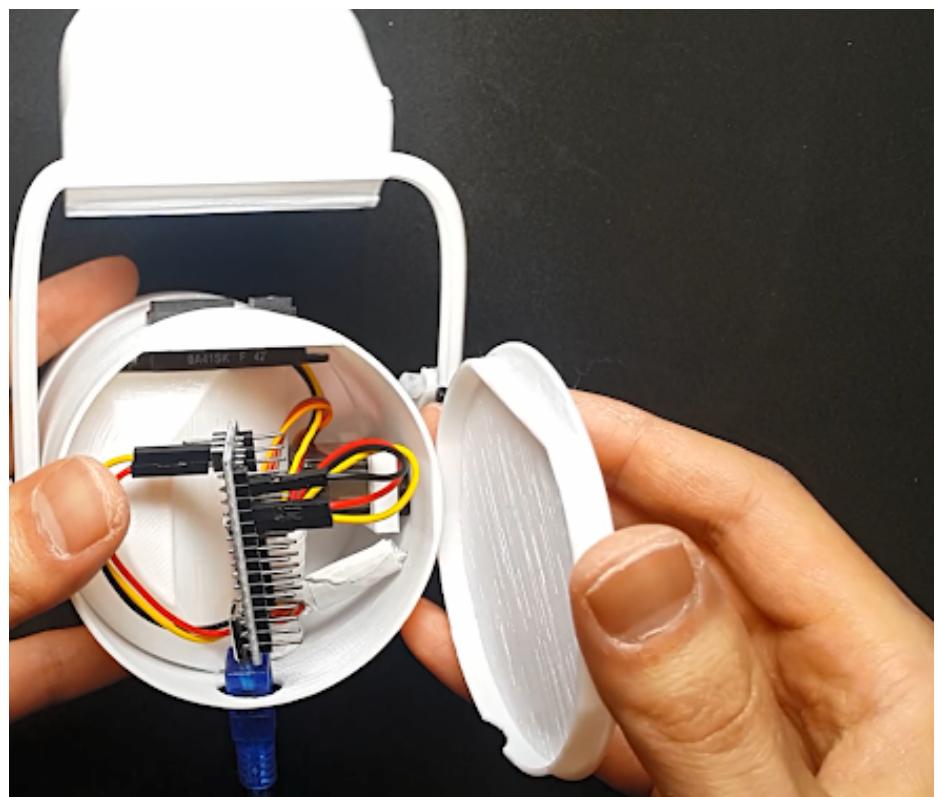
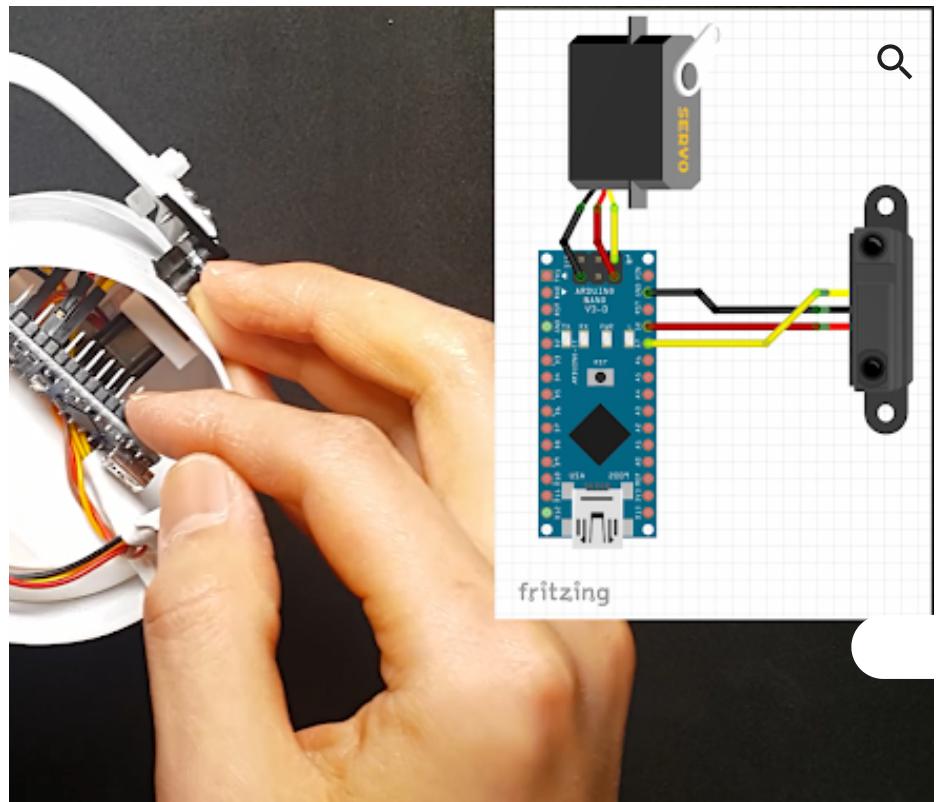
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body and plug the USB cable

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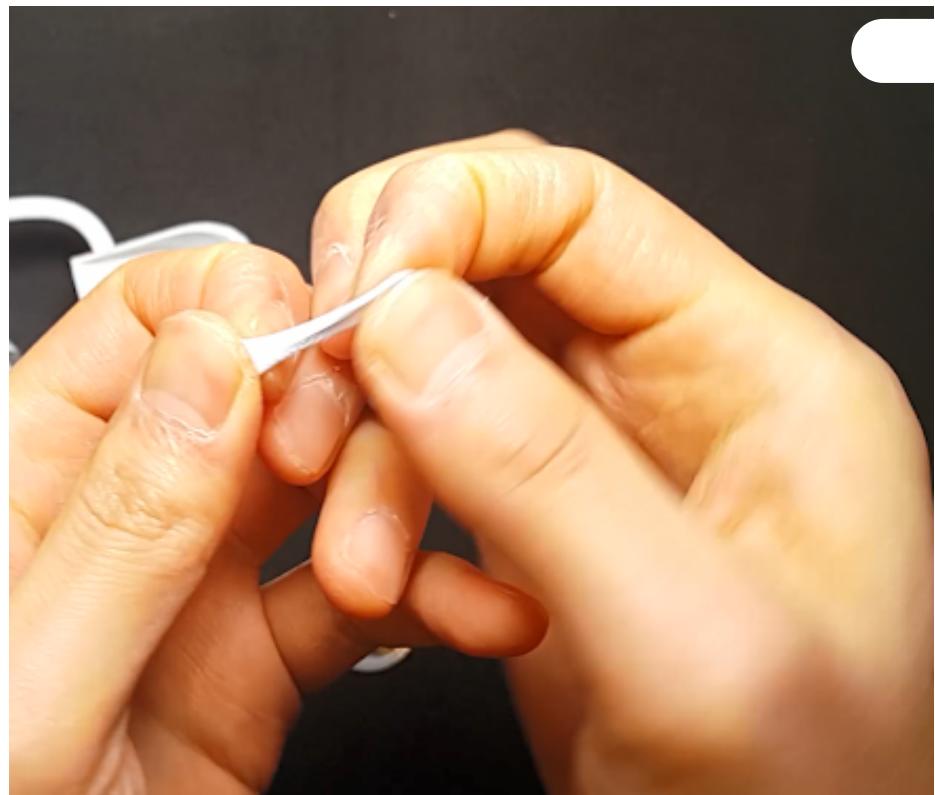


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DONE!!!



Question?

nel and Comment : <http://youtube.com/EunChanPark>

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