

Module 3: Threads in Go

Topic 1.1: Goroutines

Creating a Goroutine

- One goroutine is created automatically to execute the `main()`
- Other goroutines are created using the **go** keyword

```
a = 1  
foo()  
a = 2
```

```
a = 1  
go foo()  
a = 2
```

- Main goroutine blocks on call to `foo()`
- New goroutine created for `foo()`
- Main goroutine does not block

Exiting a Goroutine

- A goroutine exits **when its code is complete**
- **When the main goroutine is complete**, all other goroutines exit
- A goroutine may not complete its execution because main completes early

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Topic 1.2: Exiting Goroutines

Early Exit

```
func main() {  
    go fmt.Printf("New routine")  
    fmt.Printf("Main routine")  
}
```

- Only “**Main routine**” is printed
- Main finished before the new goroutine started

Delayed Exit

```
func main() {  
    go fmt.Printf("New routine")  
    time.Sleep(100 * time.Millisecond)  
    fmt.Printf("Main routine")  
}
```

- Add a delay in the main routine to give the new routine a chance to complete
- **“New RoutineMain Routine”** is now printed

Timing with Goroutines

- Adding a delay to wait for a goroutine is **bad!**
- Timing assumptions may be wrong
 - Assumption: delay of 100 ms will ensure that goroutine has time to execute
 - Maybe the OS schedules another thread
 - Maybe the Go Runtime schedules another goroutine
- Timing is nondeterministic
- Need formal **synchronization** constructs

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Topic 2.1: Basic Synchronization

Synchronization

- Using **global events** whose execution is viewed by all threads, simultaneously

1: x = 1	
	1: print x
2: x = x + 1	

1: x = 1	
2: x = x + 1	
	1: print x

- Want print to occur after update of x

Synchronization Example

Task 1

```
x = 1  
x = x + 1  
GLOBAL EVENT
```

Task 2

```
if GLOBAL EVENT  
    print x
```

- **GLOBAL EVENT** is viewed by all tasks at the same time
- Print must occur after update of x
- Synchronization is used to restrict bad interleavings

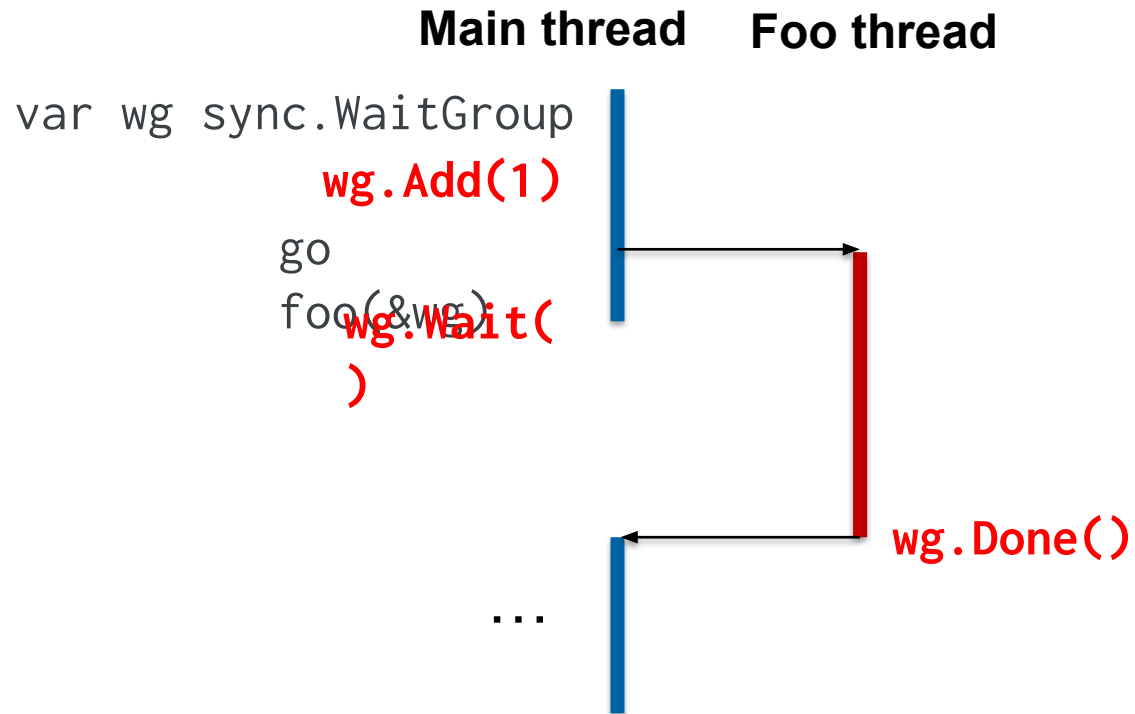
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Topic 2.2: Wait Groups

Sync WaitGroup

- Sync package contains functions to synchronize between goroutines
- **sync.WaitGroup** forces a goroutine to wait for other goroutines
- Contains an internal counter
 - Increment counter for each goroutine to wait for
 - Decrement counter when each goroutine completes
 - Waiting goroutine cannot continue until counter is 0

Using WaitGroup



- `Add()` increments the counter
- `Done()` decrements the counter
- `Wait()` blocks until counter == 0

WaitGroup Example

```
func foo(wg *sync.WaitGroup) {  
    fmt.Printf("New routine")  
    wg.Done()  
}  
  
func main() {  
    var wg sync.WaitGroup  
    wg.Add(1)  
    go foo(&wg)  
    wg.Wait()  
    fmt.Printf("Main routine")  
}
```

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Topic 3.1: Communication

Goroutine Communication

- Goroutines usually work together to perform a bigger task
- Often need to send data to collaborate
- Example: Find the product of 4 integers
 - Make 2 goroutines, each multiplies a pair
 - Main goroutine multiplies the 2 results
- Need to send ints from main routine to the two sub-routines
- Need to send results from sub-routines back to main routine

Channels

- Transfer data between goroutines
- Channels are typed
- Use `make()` to create a channel

```
c := make(chan int)
```

- Send and receive data using the `<-` operator
- Send data on a channel

```
c <- 3
```

- Receive data from a channel

```
x := <- c
```

Channel Example

```
func prod(v1 int, v2 int, c chan int) {  
    c <- v1 * v2}  
func main() {  
    c := make(chan int)  
    go prod(1, 2, c)  
    go prod(3, 4, c)  
    a := <- c  
    b := <- c  
    fmt.Println(a*b)  
}
```

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Topic 3.2: Blocking on Channels

Unbuffered Channel

- Unbuffered channels cannot hold data in transit
 - Default is unbuffered
- Sending blocks until data is received
- Receiving blocks until data is sent

Task 1

```
c <- 3
```

Task 2

One hour later ...

```
x := <- c
```

Blocking and Synchronization

- Channel communication is synchronous
- Blocking is the same as waiting for communication
- Receiving and ignoring the result is same as a Wait()

Task 1

```
c <- 3
```

Task 2

```
<- c
```

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Topic 3.3: Buffered Channels

Channel Capacity

- Channels can contain a limited number of objects
 - Default size 0 (unbuffered)
- **Capacity** is the number of objects it can hold in transit
- Optional argument to `make()` defines channel capacity

```
c := make(chan int, 3)
```

- Sending only blocks if **buffer is full**
- Receiving only blocks if **buffer is empty**

Channel Blocking, Receive

- Channel with capacity 1



```
c <- 3
```

```
a := <- c  
b := <- c
```

- First receive blocks until send occurs
- Second receive blocks forever

Channel Blocking, Send



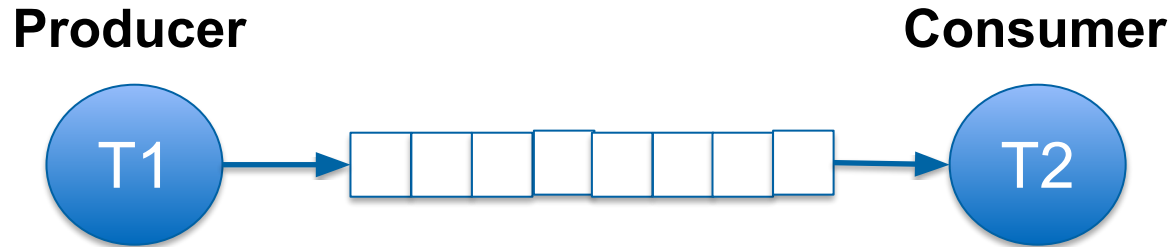
```
c <- 3  
c <- 4
```

```
a := <- c
```

- Second send blocks until receive is done
- Receive can block until first send is done

Use of Buffering

- Sender and receiver do not need to operate at exactly the same speed



- Speed mismatch is acceptable
- Average speeds must still match