

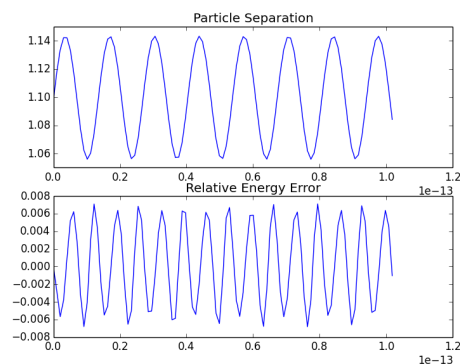
Computer Modelling Exercise 3 Group Report

Benjamin Cox, Ricardo Velasco

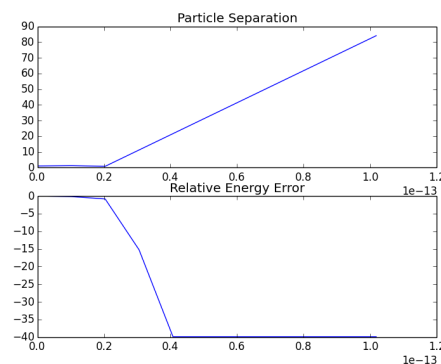
Due Thursday Week 11

In this exercise we were tasked with implementing a class in python to represent a particle in three dimensions. We were to use that class and implement two different time integration algorithms (Euler and Verlet) and use these to simulate vibrating oxygen and nitrogen molecules.

One weakness of discrete integrators is their susceptibility to large errors when the timestep is set too large. Below are two plots with timesteps $\Delta t = 0.1u$ and $\Delta t = 1u$. Each u unit of time (for the timestep) corresponds to 10.8fs.



$\Delta t = 0.1 \times (10.8\text{fs})$



$\Delta t = 1 \times (10.8\text{fs})$

The left figure is clearly showing signs of inaccuracy and is rather jagged. The right figure is wildly inaccurate.

To determine the dt_{max} we have to find the largest possible dt such that the relative energy error has magnitude less than 10^{-3} . This will be different for each integrator. For the velocity verlet implementation we find that dt_{max}