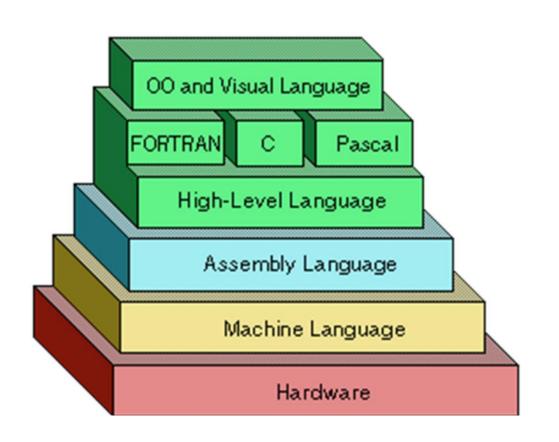
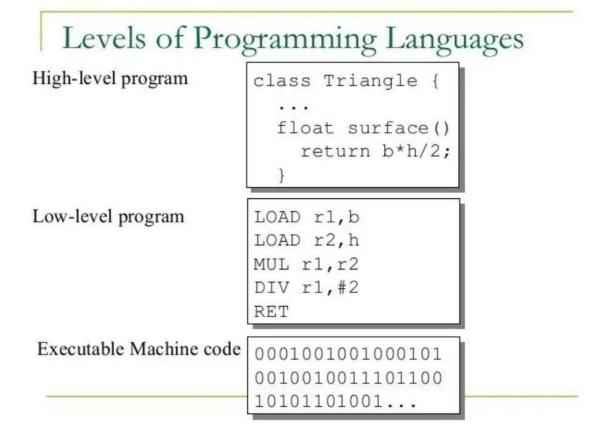


## 4. Machine-language programming







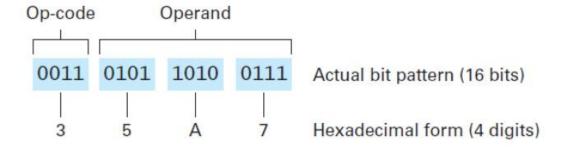
### Machine language

- Writing programs in microcode is very time-consuming:
  - Performing even simple tasks (e.g. multiplication) requires multiple microinstructions
- Machine language provides a (little) bit more user-friendly way
  - One step higher than microcode in abstraction level
  - Still quite far removed from higher level languages (C, Python)
  - No need to care about what happens in which clock cycle
- In order to understand machine language programs, microprogrammed computers need an interpreter
  - Interpreter reads the program and translates it "on the fly" to microcode
  - Interpreter program is written on microcode and stored in MPM



#### Symbolic machine language

- True machine code is raw binary data, that consists of an operation part and an operand part (as we learned before)
  - The binary code can be shortened to octal or hexadecimal form to improve readability

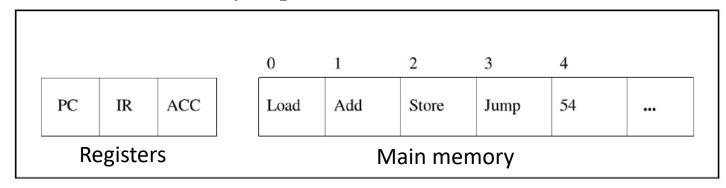


- The same code can be represented in symbolic machine language:
  - Operation codes are replaced by (more descriptive) operation names
  - Operands are given in decimal form
  - Further improved readability



#### Machine language example

- As the name implies, machine languages are "tied" to the machine: they are processor-specific (not necessarily in general, but at least in detail level)
- Let's investigate how machine language works via an example computer that has the following features:
- Special registers
  - PC (program counter; similar to MPC+MPM in microprogrammed computer)
  - IR (instruction register; similar to MIR in microprogrammed computer)
  - ACC (accumulator; includes the data that is currently in process)
- Main memory (RAM)
  - Machine language programs
  - Data to be handled





#### Machine language example: operations

- Our example computers machine language includes the following commands
- This language uses single operands: one is given, the other one (if needed) is always the accumulator (ACC)
  - Two- or even threeoperand languages exist, though

| Symbolic command | Action                                     |
|------------------|--|
| LOAD M           | ACC ← (M)                                  |
| STORE M          | $(M) \leftarrow ACC$                       |
| ADD M            | $ACC \leftarrow ACC + (M)$                 |
| SUBTRACT M       | $ACC \leftarrow ACC - (M)$                 |
| MULTIPLY M       | $ACC \leftarrow ACC * (M)$                 |
| DIVIDE M         | $ACC \leftarrow ACC / (M)$                 |
| JUMP M           | Jump to M                                  |
| JUMPZERO M       | Jump to M, if ACC = 0                      |
| JUMPNEG M        | Jump to M, if ACC < 0                      |
| JUMPSUB M        | Jump to subprogram that starts from M      |
| RETURN M         | Return from subprogram that started from M |



#### Machine language example: features

- Commands are stored in main memory as binary code
- Commands are executed one at a time in given order, unless the order is specifically changed (for example via JUMP commands)
- Word size 16 bits, memory address 12 bits (= 4096 different addresses)
  - 4 bits left for operation code, so 16 different operations possible (in theory)
- In our example language, constant numbers are not available
  - All numbers that we use in calculation must be stored in main memory
- Language can be expanded to cover also "immediate addressing" with an operation called LOADI
  - This way numbers can be given as operands

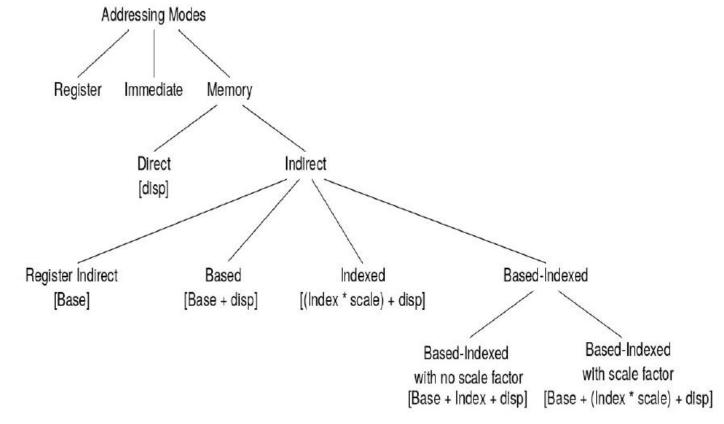
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#### Addressing modes

• Addressing mode means the way how the operand part of the command defines what the true operand is

- Possibilities:
  - Immediate
  - Direct
  - Indirect
    - Indirect indexed
    - Indirect based-indexed



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### Addressing modes

- Immediate addressing:
  - Operand specifies the data that will be loaded to ACC
  - LOADI  $M \Rightarrow ACC \leftarrow M$
- Direct addressing:
  - Operand specifies the memory address of the data that will be loaded to ACC
  - LOAD  $M \Rightarrow ACC \leftarrow (M)$
- Indirect addressing:
  - Operand specifies the memory address that contains the memory address of the data that will be loaded to ACC
  - LOADID  $M \Rightarrow ACC \leftarrow ((M))$



### Addressing modes

- In some cases, the data that we want to use may change depending on which stage of program execution we're in
- We can use indexed addressing to take this into account
- Indexed addressing:
  - The sum of operand and index register value gives the memory address of the data that will be loaded to ACC
  - LOADIX  $M \Rightarrow ACC \leftarrow (IR+M)$
- Indirect indexed addressing:
  - The sum of value found in memory address given by the operand and index register value gives the memory address of the data that will be loaded to ACC
  - LOADIDX  $M \Rightarrow ACC \leftarrow (IR+(M))$



### Addressing modes: example

• State of memory & IR are following:

|  | Index register value | 4 |
|--|----------------------|---|
|--|----------------------|---|

| Address | 280 | 281 | 282 | 283 | 284 | 285 | 286 | ••• |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|
| Content | 282 | 87  | 13  | 27  | 16  | 66  | 77  |     |

• What are the ACC values after following commands?

| Addressing mode  | Command     | ACC value after command |
|------------------|-------------|-------------------------|
| Immediate        | LOADI 280   |                         |
| Direct           | LOAD 280    |                         |
| Indirect         | LOADID 280  |                         |
| Indexed          | LOADIX 280  |                         |
| Indirect indexed | LOADIDX 280 |                         |

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### Addressing modes: example

• State of memory & IR are following:

| Address | 280 | 281 | 282 | 283 | 284 | 285 | 286 | ••• |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|
| Content | 282 | 87  | 13  | 27  | 16  | 66  | 77  |     |

• What are the ACC values after following commands?

| Addressing mode  | Command     | ACC value after command |  |
|------------------|-------------|-------------------------|--|
| Immediate        | LOADI 280   | 280                     |  |
| Direct           | LOAD 280    | 282                     | $(280) \rightarrow 282$                        |
| Indirect         | LOADID 280  | 13                      | $((280)) \rightarrow (282) \rightarrow 13$     |
| Indexed          | LOADIX 280  | 16                      | $(280+4) \rightarrow (284) \rightarrow 16$     |
| Indirect indexed | LOADIDX 280 | 77                      | $((280)+4) \rightarrow (282+4) \rightarrow 77$ |



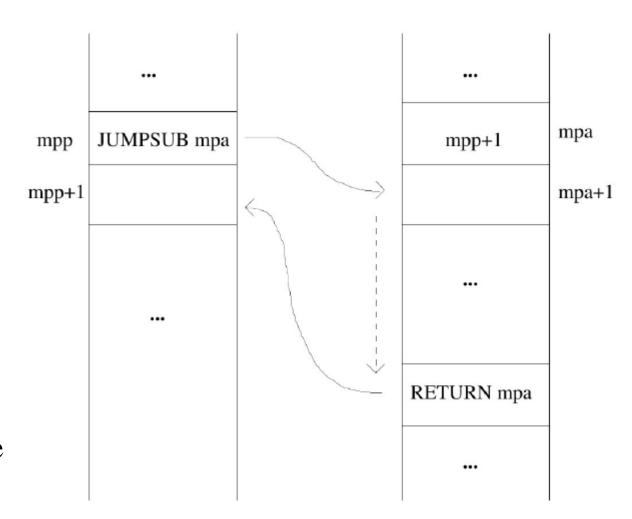
#### Execution order of commands

- Execution order of commands can be changed by jumps
- Unconditional jump: JUMP M
  - Jumps to memory address M, no matter what
- Conditional jumps:
  - JUMPZERO M jumps to memory address M, if ACC = 0
  - JUMPNEG M jumps to memory address M, if ACC < 0
- Jump to subprogram and back:
  - JUMPSUB M jumps to address M, where the subprogram begins
  - RETURN M returns from subprogram that started from memory address M



#### Jumps to subprograms

- When execution proceeds to mpp, we jump to subprogram that starts from mpa
- Execution continues from mpa+1
- After the subprogram has been executed, final RETURN tells where it started from (mpa)
- From this address we find the information, where we should return in the original program (mpp+1)
- Same subprogram can be called multiple times





#### Example: Two to the power of n

- Let's write a program that calculates the value of two to the power of n
- First, a pseudo-code:

```
MODULE exp(n) RETURNS 2^n Idea: output value starts from 1 and is doubled (= value + value) n times

WHILE n > 0 DO

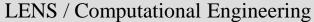
n := n - 1

value := value + value

ENDWHILE

RETURN value

ENDMODULE
```





#### Example: Two to the power of n

• Then the program in symbolic machine language:

MODULE exp(n) RETURNS 2^n
value := 1
WHILE n > 0 DO
n := n - 1
value := value + value
ENDWHILE
RETURN value
ENDMODULE

Now we see the reason for "strange" order; n was already in the ACC, so changing it now means not having to load it again later!

| Memory address | Command      | Explanation                       |
|----------------|--------------|-----------------------------------|
| 371            | LOAD 383     | Load 1 to ACC                     |
| 372            | STORE 382    | Store 1 as initial value of F     |
| 373            | LOAD 381     | Load n to ACC                     |
| 374            | JUMPZERO 384 | If n = 0, jump to 384 (aka. Stop) |
| 375            | SUBTRACT 383 | Subtract 1 from n                 |
| 376            | STORE 381    | Save new value of n               |
| 377            | LOAD 382     | Load function value F to ACC      |
| 378            | ADD 382      | ACC = F + F                       |
| 379            | STORE 382    | Save new value of F (F = ACC)     |
| 380            | JUMP 373     | Jump to beginning of iteration    |
| 381            | n            | Parameter                         |
| 382            | 0            | Function value F                  |
| 383            | 1            | Number constant                   |



### Example: $2^x + 2^y$ using subprogram

- If we want to calculate what is  $2^x + 2^y$ , a natural solution would be to use the previous program twice (1st as n = x and 2nd time as n = y)
- For educational purposes, let's see how this could be implemented using a subprogram!
- First the pseudo-code:

MODULE sum(x,y) RETURNS 2^x + 2^y RETURN exp(x)+exp(y) ENDMODULE

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### Example: $2^x + 2^y$ using subprogram

• Main program on the left, subprogram + data on the right

| Address | Command     | Explanation                                       |
|---------|-------------|---|
| 287     | LOAD 314    | Load x to ACC                                     |
| 288     | STORE 311   | Save x as subprogram input                        |
| 289     | JUMPSUB 299 | Execute subprogram (i.e. calc. 2^x)               |
| 290     | LOAD 312    | Load 2 <sup>x</sup> to ACC                        |
| 291     | STORE 316   | Save 2 <sup>x</sup> as end result value           |
| 292     | LOAD 315    | Load y to ACC                                     |
| 293     | STORE 311   | Save y as subprogram input                        |
| 294     | JUMPSUB 299 | Execute subprogram (i.e. calc. 2^y)               |
| 295     | LOAD 312    | Load 2^y to ACC                                   |
| 296     | ADD 316     | Add 2 <sup>x</sup> to ACC value (2 <sup>y</sup> ) |
| 297     | STORE 316   | Store the end result                              |
| 298     | JUMP 317    | Stop program execution                            |

| Address | Command       | Explanation                     |
|---------|---------------|---------------------------------|
| 299     | 0 / 290 / 295 | Begin / Return1 / Return2       |
| 300     | LOAD 313      | Load 1 to ACC                   |
| 301     | STORE 312     | Save 1 as subprogram result w   |
| 302     | LOAD 311      | Load subprogram input to ACC    |
| 303     | JUMPZERO 310  | If n = 0, jump to end of subpr. |
| 304     | SUBTRACT 313  | Subtract 1 from n               |
| 305     | STORE 311     | Save new n value                |
| 306     | LOAD 312      | Load subprogram result w        |
| 307     | ADD 312       | ACC = w + w                     |
| 308     | STORE 312     | w = ACC                         |
| 309     | JUMP 302      | Jump back to iteration start    |
| 310     | RETURN 299    | Return to main program          |
| 311     | 0             | Subprogram input n              |
| 312     | 0             | Subprogram result w             |
| 313     | 1             | Constant value                  |
| 314     | x             | Main program input x            |
| 315     | У             | Main program input y            |
| 316     | 0             | End result                      |



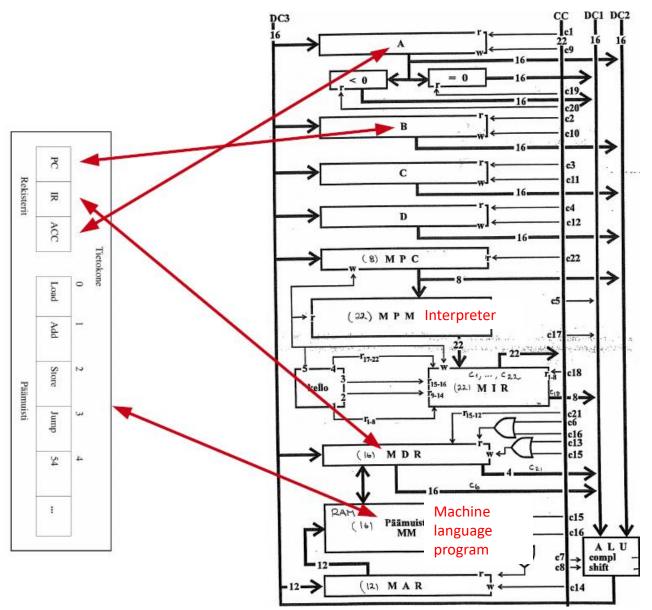
#### Machine language interpreter for our microprogrammed computer

- Interpreter is a microprogram, which understands and executes machine-language commands
- Operating principle:
  - Fetch the command from main memory
  - Find out the contents of the command
  - Execute the command
- In order to complete this task, the interpreter must remember the address of the next command
- From our example machine language to example microprogrammed computer:
  - ACC = Register A
  - IR = MDR as command register (4 most significant bits for the command)
  - PC = Register B as program counter (we could use C or D too, though)



# Machine language interpreter for our microprogrammed computer

• Graph illustrates the relationships between the registers





#### Summary

- Machine language is processor- or computer-specific programming language
  - Can be presented in either symbolic or numerical (binary, hexadecimal...) form
- Several symbolic machine languages can be implemented for the same processor
- The machine language of "real-world" computers is more complex than of our example computer
  - Larger word size, more operations
- The interpreter program has been stored in read-only memory (MPM) beginning from memory address 0
  - Interpreter program execution is started by setting MPC to zero
- Programs written on high-level languages will be converted to machine language via a compiler (or an interpreter) and the machine language program will be executed using the microcode interpreter



## Thank you for listening!

