



- The process states in Linux and their mutual transitions
- Observe the process states



- TASK\_RUNNING (R)
  - A process that is running or waiting to run in the runnable process queue is in this state.
- TASK\_INTERRUPTIBLE (S)
  - The process in the state of waiting for resources will be woken up when the waiting resources are available. It can also be awakened by other processes or kernels with signals and interrupts and enter the ready state.
- TASK\_UNINTERRUPTIBLE (D)
  - The process in the state of waiting for resources will be woken up when the waiting resources are available. It cannot be woken up by other processes or kernels through signals and interrupts.

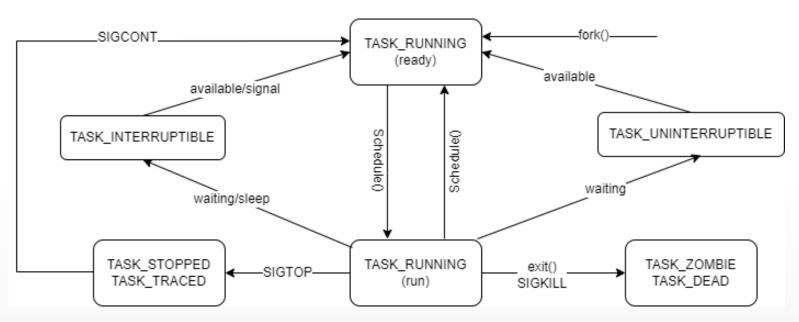


- TASK STOP/TASK TRACED (T)
  - When the process receives the signal SIGSTOP, SIGTSTP, SIGTTIN or SIGTTOU, it will enter the suspended state. A SIGCONT signal can be sent to it to make the process transition to a runnable state.
  - When a process is being traced, it is in this special state.
- TASK\_DEAD-EXIT\_ZOMBIE (Z)
  - The process is stopped but not yet dead. It is a transitional state before the process finishes running. Although resources such as memory and files have been released at this time, some data structures of this process (such as task\_struct) are still reserved in the kernel to wait for the parent process to recycle.



- TASK\_DEAD-EXIT\_DEAD (Z)
  - The last state before the process dies, indicating that the parent process has obtained the accounting information of the process, and the process can be destroyed. This state is very transient and almost impossible to capture with the ps command





Process state transition



### **Experiment 3—run\_status.c**

```
#include <stdio.h>
#include <unistd.h>
int main()
  int i=0, j=0, k=0;
  for(i=0;i<1000000;i++)
     for(j=0;j<10000000;j++)
       k++;
       k--;
```



- Observe the running state
  - gcc –o run\_status run\_status.c
  - ./run\_status &
  - ps -ax | grep run\_status
  - ps -ax | grep run\_status |grep -v grep





- Observe the "T" state
  - gcc –o run\_status run\_status.c
  - ./run\_status &
  - kill –SIGSTOP pid
  - kill -SIGCONT pid



```
[root@localhost code]# kill -SIGSTOP 6350

[1]+ Stopped ./run_status
[root@localhost code]# ps ax | grep run_status
6350 tty1 T 0:24 ./run_status
6356 tty1 S+ 0:00 grep run_status
```

```
[root@localhost code]# kill -SIGCONT 6350
[root@localhost code]# ps ax | grep run_status
6350 tty1 R 0:26 ./run_status
6358 tty1 S+ 0:00 grep run_status
```



# **Experiment 3—interruptible\_status.c**

```
#include <stdio.h>
#include <unistd.h>
int main()
{
    sleep(60);
    return 0;
}
```



Observe the "S" state



# **Experiment 3—uninter\_status.c**

```
#include <stdio.h>
#include <unistd.h>
int main()
      if(vfork()==0){
        sleep(60);
         return 0;
```



- Observe the "D" state
  - old kernel



- Observe the "D" state
  - newer kernel



# **Experiment 3—zombie\_status.c**

```
#include <stdio.h>
#include <unistd.h>
int main()
{
if(fork()){
sleep(60);
}
```



- Observe the "Z" state
- Run the ps command within 60s to check the running status.