

# Complex eigenvalues and eigenvectors

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad 0 = \det(A - \lambda I)$$

$$\lambda = \pm i \quad = \det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix}$$

$$\lambda = i: A - iI = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \quad 0 = \cancel{i^2} + 1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} -i \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -d & c \\ b & a \end{bmatrix} \begin{bmatrix} 1 \\ -i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda = -i: A - (-i)I = \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} \begin{bmatrix} -i \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda = i, \vec{x} = \begin{bmatrix} i \\ 1 \end{bmatrix}, \lambda = -i, \vec{x} = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\lambda = \pm i, \vec{x} = \begin{bmatrix} \pm i \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} p^{-1}$$

$$C = \begin{bmatrix} a & -b \\ 1 & -b \end{bmatrix} \quad \begin{aligned} 0 &= (a-\gamma)^2 + b^2 \\ -b^2 &= (a-\gamma)^2 \end{aligned}$$

$$C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\begin{aligned}-b^2 &= (a-1)^2 \\ -b^2 &= (1-a)^2\end{aligned}$$

$$\lambda = a \pm ib$$

$$\operatorname{Re} \lambda = a$$

$$\operatorname{Im} \lambda = \pm b$$

$$\begin{bmatrix} a & -b \\ b & a \end{bmatrix} = \begin{bmatrix} r & 0 \\ 0 & r \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$a = r \cos \theta$$

$$b = r \sin \theta$$

$$r = \sqrt{a^2 + b^2}$$

$$\theta = \tan^{-1} \frac{b}{a}$$

contraction /  
dilation

counterclockwise  
rotation around  
origin of angle  $\theta$

$$A = \begin{bmatrix} -1 & -3 \\ 1 & 2 \end{bmatrix}$$

$$\begin{aligned}0 &= (-1-\lambda)(2-\lambda) + 3 \\ &= \lambda^2 + 1 - 2\lambda - 2 + 3\end{aligned}$$

$$\lambda = \frac{1 \pm \sqrt{1-4 \cdot 1}}{2}$$

$$= \frac{1 \pm \sqrt{3}i}{2} = \frac{1}{2} \pm \frac{\sqrt{3}}{2}i = a \pm ib$$

$$A = P C P^{-1} = \begin{bmatrix} \operatorname{Re} \vec{p} & \operatorname{Im} \vec{p} \end{bmatrix} \begin{bmatrix} a & -b \\ b & a \end{bmatrix} P^{-1}$$

$\vec{p}$  is the eigenvector corresponding  
to  $\lambda = a \pm ib$

$$\lambda = \frac{1}{2} - \frac{\sqrt{3}}{2}i$$

$$\lambda = \frac{1}{2} - \frac{\sqrt{3}}{2}i$$

$$A - \left(\frac{1}{2} - \frac{\sqrt{3}}{2}i\right)I = \begin{bmatrix} -1 - \left(\frac{1}{2} - \frac{\sqrt{3}}{2}i\right) & -3 \\ 1 & 2 - \left(\frac{1}{2} - \frac{\sqrt{3}}{2}i\right) \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{3}{2} + \frac{\sqrt{3}}{2}i & -3 \\ 1 & \frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix} \begin{bmatrix} 3 \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\frac{3}{2} - \frac{\sqrt{3}}{2}i\right) \begin{bmatrix} \frac{3}{2} + \frac{\sqrt{3}}{2}i \\ -1 \end{bmatrix} = \begin{bmatrix} \left(\frac{3}{2} - \frac{\sqrt{3}}{2}i\right)\left(\frac{3}{2} + \frac{\sqrt{3}}{2}i\right) \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix}$$

$$= \begin{bmatrix} \frac{9}{4} + \frac{3\sqrt{3}}{4}i & -\frac{3\sqrt{3}}{4}i & -\frac{3}{4}i^2 \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix} = \begin{bmatrix} \frac{9}{4} + \frac{3}{4} \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix} = \begin{bmatrix} 3 \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix}$$

$$a = \frac{1}{2}, b = \frac{\sqrt{3}}{2}$$

any real number

$$\rho = \begin{bmatrix} 3 \\ -\frac{3}{2} + \frac{\sqrt{3}}{2}i \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & -3 \\ 1 & 2 \end{bmatrix} = \rho C \rho^{-1} = \begin{bmatrix} 3 \\ -\frac{3}{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & 2 \end{bmatrix} \rho^{-1}$$

$$r = \sqrt{a^2 + b^2} = 1$$

$$\theta = \tan^{-1}(\sqrt{3}) = \frac{\pi}{3}$$

$$\begin{bmatrix} \sqrt{3} & 0 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$$

$$\begin{array}{c}
 \left[ \begin{array}{cc|cc|cc} 1 & 0 & \frac{1}{2} & -\frac{\sqrt{3}}{2} & \frac{2}{3\sqrt{3}} & \frac{1}{2} \\ -\frac{3}{2} & \frac{\sqrt{3}}{2} & \frac{1}{2} & \frac{1}{2} & \frac{3}{2} & 0 \end{array} \right] \\
 = \frac{2}{3\sqrt{3}} \left[ \begin{array}{cc|cc|cc} 3 & 0 & -\frac{\sqrt{3}}{2} & -\frac{3\sqrt{3}}{2} \\ -\frac{3}{2} & \frac{\sqrt{3}}{2} & \frac{3}{2} & \frac{3}{2} \end{array} \right] \\
 = \frac{2}{3\sqrt{3}} \left[ \begin{array}{cc|cc} -\frac{3\sqrt{3}}{2} & -\frac{9\sqrt{3}}{2} \\ \frac{3\sqrt{3}}{2} & 3\sqrt{3} \end{array} \right] = \begin{bmatrix} -1 & -3 \\ 1 & 2 \end{bmatrix}
 \end{array}$$

$$A = \begin{bmatrix} 1 & 2 \\ -4 & 5 \end{bmatrix}$$

$$A = P C P^{-1}$$

$$0 = (-1)(5-\lambda) + 8$$

$$0 = \lambda^2 - \lambda - 5\lambda + 5 + 8$$

$$0 = \lambda^2 - 6\lambda + 13$$

$$0 = \lambda^2 - 6\lambda + 9 + 4$$

$$-4 = (\lambda - 3)^2 \quad \lambda = 3 \pm 2i$$

$$\lambda = 3 - 2i$$

$$A - (3-2i)I = \begin{bmatrix} 1-(3-2i) & 2 \\ -4 & 5-(3-2i) \end{bmatrix}$$

$$\Gamma \rightsquigarrow \Gamma \cup \{ \lambda \}$$

$$= \begin{bmatrix} -2+2i & 2 \\ -4 & 2+2i \end{bmatrix} \begin{bmatrix} 1+i \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$A = P C P^{-1} = \begin{bmatrix} 1 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ 2 & 3 \end{bmatrix} P^{-1}$$

$C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

$$\vec{\phi} = \begin{bmatrix} 1+i \\ 2 \end{bmatrix} = \begin{bmatrix} 1+i \\ 2+0i \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} + i \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} \operatorname{Re}\phi & \operatorname{Im}\phi \end{bmatrix} \begin{bmatrix} 1 & -b \\ b & a \end{bmatrix} P^{-1}$$

$$\vec{\phi} \rightarrow A\vec{\phi} = (a - ib)\vec{\phi}$$

Discrete Dynamical Systems

$$\vec{x}_0, \vec{x}_1, \vec{x}_2, \vec{x}_3, \dots, \vec{x}_k, \dots$$

$$\vec{x}_{k+1} = A\vec{x}_k \quad , \quad A \text{ is diagonalizable}$$

w/e-vals  $\lambda_1, \lambda_2, \dots, \lambda_n$   
w/e-vecs  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$

$\vec{x}_0$  is known  
 $\hookrightarrow$

$\lambda_0$  is known

$$\vec{x}_1 = A\vec{x}_0$$

$$\vec{x}_2 = A\vec{x}_1 = A^2\vec{x}_0$$

$$\vec{x}_0 = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

$$\begin{aligned}\vec{x}_1 &= A\vec{x}_0 = A(c_1 \vec{v}_1 + \dots + c_n \vec{v}_n) \\ &= c_1 A\vec{v}_1 + \dots + c_n A\vec{v}_n\end{aligned}$$

$$= c_1 \lambda_1 \vec{v}_1 + \dots + c_n \lambda_n \vec{v}_n$$

$$\begin{aligned}\vec{x}_2 &= A\vec{x}_1 = A(c_1 \lambda_1 \vec{v}_1 + \dots + c_n \lambda_n \vec{v}_n) \\ &= c_1 \lambda_1^2 \vec{v}_1 + \dots + c_n \lambda_n^2 \vec{v}_n\end{aligned}$$

$$\boxed{\vec{x}_k = c_1 \lambda_1^k \vec{v}_1 + c_2 \lambda_2^k \vec{v}_2 + \dots + c_n \lambda_n^k \vec{v}_n}$$

$$\vec{x}_{k+1} = \begin{bmatrix} -0.2 & -0.2 \\ -1.8 & 0.3 \end{bmatrix} \vec{x}_k, \quad \vec{x}_0 = \begin{bmatrix} -5 \\ 3 \end{bmatrix}$$

$$0 = (-0.2 - \lambda)(0.3 - \lambda) - (-0.2)(-1.8)$$

$$= \lambda^2 + 0.2\lambda - 0.3\lambda - 0.06 - 0.36$$

$$0 = \lambda^2 - 0,1\lambda - 0,42$$

$$(\lambda - 0,7)(\lambda + 0,6) \quad \lambda = -0,6, 0,7$$

$$\lambda = -0,6: A - (-0,6)I = \begin{bmatrix} -0,2 + 0,6 & -0,2 \\ -1,8 & 0,3 + 0,6 \end{bmatrix}$$

$$= \begin{bmatrix} 0,4 & -0,2 \\ -1,8 & 0,9 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\lambda = 0,7: A - 0,7I = \begin{bmatrix} -0,9 & -0,2 \\ -1,8 & -0,4 \end{bmatrix} \begin{bmatrix} -2 \\ 9 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\vec{x}_k = c_1(-0,6)^k \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2(0,7)^k \begin{bmatrix} -2 \\ 9 \end{bmatrix}$$

$$\vec{x}_0 = \begin{bmatrix} -5 \\ 3 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} -2 \\ 9 \end{bmatrix}$$

$$B = B_{c_2}$$

$$1 = c_2$$

$$c_1 = -3$$

$$\vec{x}_k = -3(-0,6)^k \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 1(0,7)^k \begin{bmatrix} -2 \\ 9 \end{bmatrix}$$

$\mathbf{x}_k = \begin{pmatrix} 2 \\ 2 \end{pmatrix} + t \begin{pmatrix} 0,7 \\ 1 \end{pmatrix}$   
 $k \rightarrow \infty$   
  
 the origin is an attractor

$$\tilde{\mathbf{x}}_{k+1} = \begin{bmatrix} 0,2 & -0,3 \\ 1,8 & 1,7 \end{bmatrix} \tilde{\mathbf{x}}_k + \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$0 = (0,2 - \lambda)(1,7 - \lambda) + 0,3(1,8)$$

$$0 = \lambda^2 - 0,2\lambda - 1,71 + 0,34 + 0,54$$

$$0 = \lambda^2 - 1,9\lambda + 0,88$$

$$0 = (\lambda - 1,1)(\lambda - 0,8) \quad \lambda = 1,1, 0,8$$

$$\lambda = 1,1: A - 1,1I = \begin{bmatrix} -0,9 & -0,3 \\ 1,8 & 0,6 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

$$\lambda = 0,8: A - 0,8I = \begin{bmatrix} -0,6 & -0,3 \\ 1,8 & 0,9 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\tilde{\mathbf{x}}_k = c_1 (1,1)^k \begin{bmatrix} -1 \\ 3 \end{bmatrix} + c_2 (0,8)^k \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\vec{x}_k = \zeta_1 (1,1)^k \begin{bmatrix} -1 \\ 3 \end{bmatrix} + \zeta_2 (0,8)^k \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\vec{x}_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \zeta_1 \begin{bmatrix} -1 \\ 3 \end{bmatrix} + \zeta_2 \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$\zeta_1 = 3 \quad \zeta_2 = -4$$

$$\vec{x}_k = -4 (1,1)^k \begin{bmatrix} -1 \\ 3 \end{bmatrix} + 3 (0,8)^k \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

as  
 $k \rightarrow \infty$

$\downarrow$  do  
saddle point

$|z_1|, |z_2| < 1 \rightarrow$  attractor

$|z_1| < 1, |z_2| > 1 \rightarrow$  saddle point

$|z_1|, |z_2| > 1 \rightarrow$  repeller

