06 Matrices



Class Survey

Fill out the survey at this link!:)

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Unit 1: Vectors, Book ILA Ch. 1-5

Unit 2: Matrices, Book ILA Ch. 6-11 + Book IMC Ch. 2

- 06 Matrices
- 07 Linear Equations
- 08 Linear Dynamical Systems
- 09 Matrix Multiplication
- 10 Matrix Inverse

Unit 3: Least Squares, Book ILA Ch. 12-14 + Book IMC Ch. 8

Unit 4: Eigen-decomposition, Book IMC Ch. 10, 12, 19

Outline: 06 Matrices

- Matrices
- Matrix-vector multiplication
- Examples

Matrices

Definition: A matrix is a rectangular array of numbers, e.g.:

$$A = \begin{bmatrix} 0 & 1 & -2.3 \\ 1.3 & 4 & -0.1 \end{bmatrix}$$

- Its size, or shape, is: (row dimension) x (column dimension).
 - Example: Matrix above has size 2 x 3.
- Its elements are called: entries, coefficients.
- $A_{i,j}$ refers to element at ith row and jth column in matrix A.
 - i is the row index and j is the column index.

In Python, we use numpy and nplarray to build matrices. The shape of the matrix can be accessed via the function shape.

```
In [7]:
          import numpy as np
          A = np.array([
               [0, 1, -2.3],
               [1.3, 4, -0.1]
          ])
          print(np.shape(A)); print(A.shape)
          v = np.array([1, 2, 3, 4]); print(len(v))
          (2, 3)
          (2, 3)
         In Python, we can access the elements of the matrix.
In [18]:
```

```
v = [1.1, 2.2, 3.3, 4.3]; #print(len(v))
          for v index in range(len(v)):
              print(v[v index])
          for v value in v:
              print(v_value)
         1.1
         2.2
         3.3
         4.3
In [29]:
          print(A); print(A[0][2]); print(A[0, 2])
          # Implement code that prints all entries of the matrix A
          print("Begin for loop:")
          print(A.shape)
          n rows = A.shape[0]; n columns = A.shape[1]
          n_rows, n_columns = A.shape
          for i in range(n rows):
              for j in range(n_columns):
                  print(A[i, j])
                 1. -2.3]
         [[ 0.
          [1.3 4. -0.1]
         -2.3
         -2.3
         Begin for loop:
```

```
(2, 3)
0.0
1.0
-2.3
```

Sizes/Shapes of Matrices

Definitions: A m x n matrix A is:

- tall if m > n,
- wide if m < n,
- square if m = n.

In [15]:

A = ...

Matrices, Vectors and Scalars

Definitions:

- A 1 x 1 matrix is a number or scalar.
- A n x 1 matrix is an *n*-vector.
- A 1 x n matrix is a *n*-row-vector.

Starting now, we will distinguish vectors and row vectors.

Columns and rows of a matrix

Notations: Take A a $m \times n$ matrix with entries A_{ij} for $i=1,\ldots,m$ and j=1...,n.

• Its jth column is the *m*-vector:

$$\left[egin{array}{c} A_{1j} \ dots \ A_{mj} \end{array}
ight]$$

ullet Its ith row is the n-row-vector: $[A_{i1},\ldots,A_{in}].$

Slices of a matrix

Definition The slice of matrix $A_{p:q,r:s}$ is the matrix:

$$egin{bmatrix} A_{pr} & A_{p,r+1} & \dots & A_{ps} \ \dots & \dots & \dots \ A_{qr} & A_{q,r+1} & \dots & A_{qs} \end{bmatrix}$$

In Python, we can extract rows, columns and slices:

```
In [9]: """Extract rows, columns and slices from matrix A."""
```

Out[9]: 'Extract rows, columns and slices from matrix A.'

Block matrices

Definition: A matrix A composed from other matrices is called a block matrix:

$$A = \left[egin{array}{cc} B & C \ D & E \end{array}
ight]$$

where B, C, D, E are called submatrices or blocks of A.

Column/row representations

Notations: Take A a $m \times n$ matrix with entries A_{ij} for $i=1,\ldots,m$ and j=1...,n.

- A is the block matrix of its columns a_1, \ldots, a_n :
 - $\bullet \ \ A=[a_1\ldots a_n]$
- A is the block matrix of its rows b_1, \ldots, b_m :

$$\bullet \ \ A = \left[\begin{array}{c} b_1 \\ \vdots \\ b_m \end{array} \right].$$

Examples in ECE and beyond

• Images: A_{ij} is intensity value at i,j.

In Python, we can plot an image represented by a matrix.

```
In [20]: ...
Out[20]: Ellipsis
```

Examples in ECE and beyond

- Weather: A_{ij} is rainfall data at location i on day j.
- ullet Finances: A_{ij} is the return of asset i in period j.

Exercise: In each of these, what do the rows and columns mean?

Special Matrices

Definition: The $m \times n$ zero matrix (resp. ones-matrix) is the matrix with all entries equal to 0 (resp. to 1).

Definition: The identity matrix I is the square matrix with $I_{ii}=1$ and $I_{ij}=0$ if $i\neq j$, for example:

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

In Python:

```
In [11]: """Code zeroes matrices, ones matrices and the identity matrix"""

Out[11]: 'Code zeroes matrices, ones matrices and the identity matrix'
```

Diagonal Matrices

 $egin{aligned} extbf{Definition} ext{:} A ext{ diagonal matrix } A ext{ is a square matrix with } A_{ij} = 0 ext{ for } i
eq j. \end{aligned}$

• $\operatorname{diag}(a_1,\ldots,a_n)$ denotes the diagonal matrix with $A_{ii}=a_i$:

$$\operatorname{diag}(0.2,-3,1.2) = \left[egin{array}{ccc} 0.2 & 0 & 0 \ 0 & -3 & 0 \ 0 & 0 & 1.2 \end{array}
ight]$$

In Python:

Triangular Matrices

Definition: A lower triangular matrix A is a matrix such that $A_{ij} = 0$ for i < j. An upper triangular matrix A is a matrix such that $A_{ij} = 0$ for i > j.

Example:
$$\begin{bmatrix} 0.2 & 1.2 & 10 \\ 0 & -3 & 0 \\ 0 & 0 & 1.2 \end{bmatrix}$$
 (upper-triangular)

Transpose

 ${f Definition}$: The transpose of an m imes n matrix A is written A^T and is defined by:

$$(A^T)_{ij} = A_{ji}, \quad i = 1, \ldots, n \quad j = 1, \ldots, m$$

Example:
$$\begin{bmatrix} 0.2 & 1.2 & 10 \\ 0 & -3 & 0 \end{bmatrix}^T = \begin{bmatrix} 0.2 & 0 \\ 1.2 & -3 \\ 10 & 0 \end{bmatrix}$$

In Python:

```
In [10]: """Transpose a vector or a matrix."""
```

Out[10]: 'Transpose a vector or a matrix.'

Addition, Substraction and Scalar Multiplication

Just like vectors:

- · we can add or subtract matrices of the same size,
- we can multiply a matrix by a scalar.

Property: The transpose verifies:

- $(A^T)^T = A$.
- $\bullet \ (A+B)^T = A^T + B^T.$

Matrix norm

Definition: For a $m \times n$ matrix A, we define the matrix norm as:

$$||A|| = \sqrt{\sum_{i=1}^m \sum_{j=1}^n A_{ij}^2}.$$

 $\overline{\text{Remark}}$: This definition agrees with the definition of norm of vectors when n=1 or m=1.

Exercise: Compute the matrix norm of $A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix}$.

In Python, there are many ways to find the norm of a matrix.

```
In [14]:
Out[14]: Ellipsis
```

Remark: As opposed to vectors which had 1 axis, matrices have several axes. Observe below how numpy functions adapt to the case of several axes.

```
In [13]:
Out[13]: Ellipsis
```

Distance between two matrices

Definition: The distance between two matrices A and B is defined as:

$$dist(A, B) = ||A - B||.$$

Remark: This means that the clustering algorithm, which only needs a notion of "distance", works on the matrices.

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Matrix-vector multiplication

Definition: The matrix-vector multiplication y of $m \times n$ matrix A and n-vector x is denoted y = Ax and is defined as:

$$y_i = A_{i1}x_1 + \ldots + A_{in}x_n, \quad i = 1, \ldots, m$$

Exercise: Let A be the $n \times n$ identity matrix and x an n-vector. Compute Ax.

Exercise: Let A be the $n \times n$ zeroes matrix and x an n-vector. Compute Ax.

Exercise: Compute the matrix-vector multiplication of:

$$A = \left[egin{array}{ccc} 0 & 2 & -1 \ -2 & 1 & 1 \end{array}
ight]; \quad v = \left[egin{array}{ccc} 2 \ 1 \ -1 \end{array}
ight]$$

In Python:

In [5]: ...

Out[5]: Ellipsis

Exercise: Take $m \times n$ matrix A, and one-hot vector e_i for some i in $1, \ldots, m$. Compute Ae_i .

Exercise: Take $m \times n$ matrix A, and one-hot vector e_i for some i in $1, \ldots, n$. Compute $A1_n$.

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Math operations as matrices

Example: The $(n-1) \times n$ difference matrix:

$$D = egin{bmatrix} -1 & 1 & 0 & \dots & 0 & 0 \ 0 & -1 & 1 & \dots & 0 & 0 \ 0 & 0 & 0 & \dots & -1 & 1 \end{bmatrix}$$

allows us to compute the (n-1) vector of differences between consecutive entries of x:

$$Dx = \left[egin{array}{c} x_2 - x_1 \ x_3 - x_2 \ dots \ x_n - x_{n-1} \end{array}
ight]$$

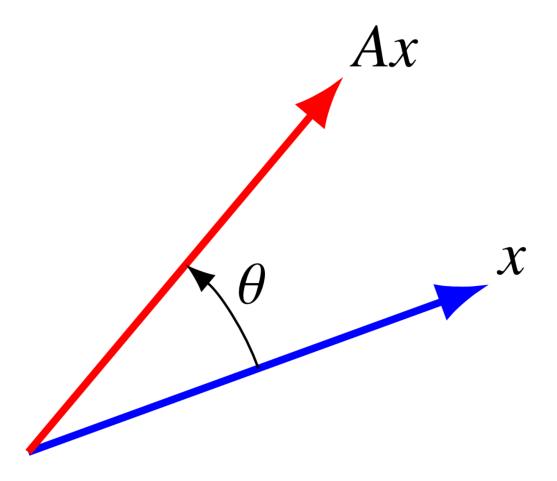
In Python, let be given a vector listing the days at which earthquakes have happened in California. Compute the vector giving the number of days in-between earthquakes.

Geometric transformations as matrices

Many geometric transformations and mappings of 2-D and 3-D vectors can be represented as matrices A. They can transform vectors x through matrix-vector multiplication y = Ax.

Example: For example, the rotation by angle θ can rotate the 2D-vector x through the rotation matrix R_{θ} :

$$R_{ heta} = egin{bmatrix} \cos(heta) & -\sin(heta) \ \sin(heta) & \cos(heta) \end{bmatrix}, \quad y = R_{ heta} x$$



In Python:

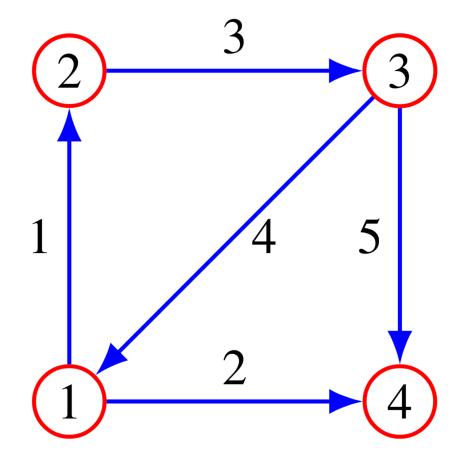
In [32]: ...

Out[32]: Ellipsis

(Social) graphs as matrices

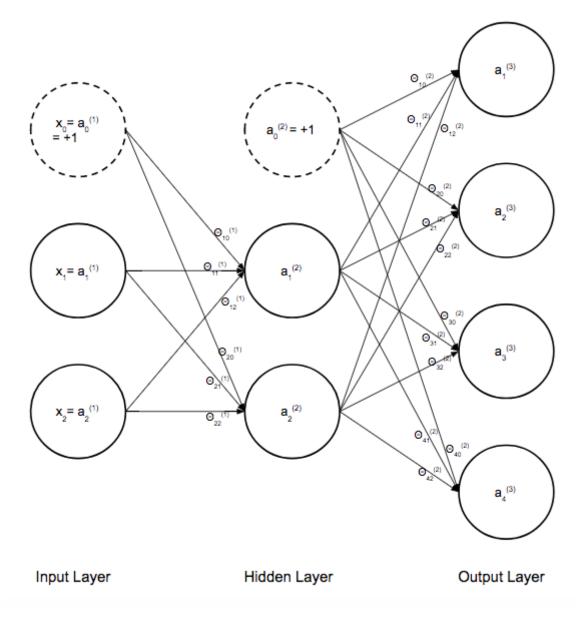
Any (social network) graph with n nodes and m edges can be represented by $n \times m$ matrix A defined defined as:

$$A_{ij} = \left\{ egin{array}{ll} 1 & ext{if edge } j ext{ points to node } i \ -1 & ext{if edge } i ext{ points to node } j \ 0 & ext{otherwise} \end{array}
ight.$$



Exercise: Compute the incidence matrix associated to this graph.

Deep Learning and Convolutions



By writing $a^{(1)}$ the vector of the first layer, and $a^{(2)}$ the vector of the second layer, we see that:

$$a^{(2)} = Wa^{(1)},$$

where W_{ij} is the weight on the edge going from the jth element of the first layer $a_j^{(1)}$ to the ith element of the second layer $a_i^{(2)}$.

In Python, we can implement the layer of a neural network.

```
In [33]:
def simple_nn(input_x):
...
```

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	Resources: ILA, Ch. 6, 7.
In []:	