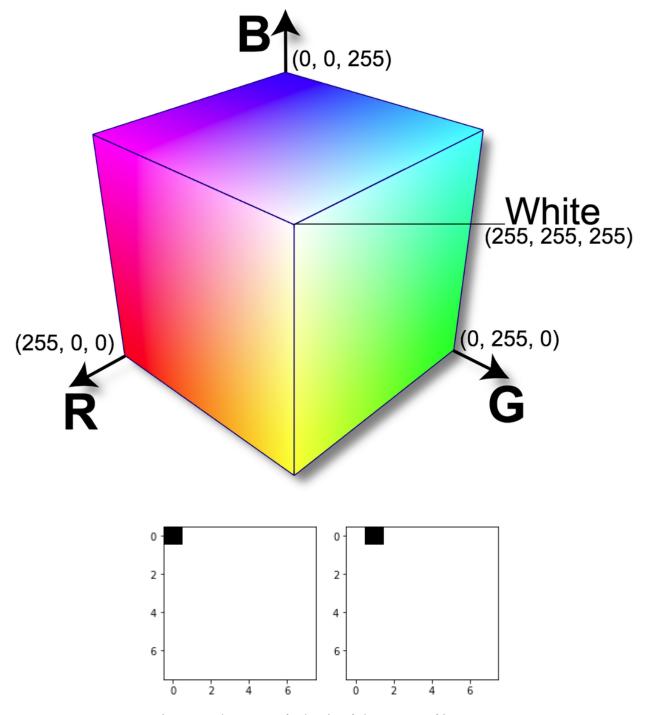
# 05 Linear Independence



First two elements of a basis of the space of images.

#### Unit 1: Vectors, Book ILA Ch. 1-5

- 01 Vectors
- 02 Linear Functions
- 03 Norms and Distances
- 04 Clustering
- 05 Linear Independence

Unit 2: Matrices, Book ILA Ch. 6-11 + Book IMC Ch. 2

Unit 3: Least Squares, Book ILA Ch. 12-14 + Book IMC Ch. 8

Unit 4: Eigen-decomposition, Book IMC Ch. 10, 12, 19

### Outline: 05 Linear Independence

- Linear Independence
- Basis
- Orthonormal Vectors

### **Linear Dependence**

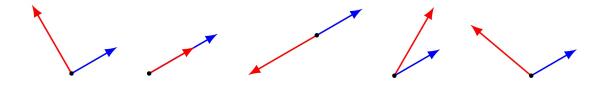
**Definition**: A set of *n*-vectors  $a_1, \ldots, a_k$  (with  $k \geq 1$ ) is linearly dependent if:

$$\beta_1 a_1 + \dots + \beta_k a_k = 0$$

holds for some  $\beta_1, \ldots, \beta_k$  that are not all zero. This statement is equivalent to: at least one  $a_i$  is a linear combination of the others.

- $a_1$  is linearly dependent only if  $a_1 = 0$ .
- ullet  $a_1,a_2$  is linearly dependent only if one  $a_i$  is multiple of the other.
- for k > 2, there is no simple way to state condition.

Exercise: Which sets of vectors are linearly dependent?



Example: The following vectors:

$$a_1 = \begin{pmatrix} 0.2 \\ -7 \\ 8.6 \end{pmatrix}, \quad a_2 = \begin{pmatrix} -0.1 \\ 2 \\ -1 \end{pmatrix} \quad a_3 = \begin{pmatrix} 0 \\ -1 \\ 2.2 \end{pmatrix}$$

are linearly dependent because:

- $a_1 + 2a_2 3a_3 = 0$
- we can express any of them as linear combination of the other two, e.g.,  $a_2=(-1/2)a_1+(3/2)a_3$

### Linear Independence

**Definition**: The set of n-vectors  $a_1, \ldots, a_k$  (with  $k \geq 1$ ) is linearly independent if it is not linearly dependent, i.e. if

$$\beta_1 a_1 + \cdots + \beta_k a_k = 0$$

**holds only when**  $\beta_1 = \cdots = \beta_k = 0$ . This statement is equivalent to: no  $a_i$  is a linear combination of the others.

Example: The one-hot n-vectors  $e_1, \ldots, e_n$  are linearly independent.

### Property of linear independence

Property: Take linearly independent vectors  $a_1, \ldots, a_k$ . Suppose x is linear combination of the  $a_1, \ldots, a_k$ :

$$x = \beta_1 a_1 + \dots + \beta_k a_k.$$

Then, the coefficients  $\beta_1, \ldots, \beta_k$  are unique.

Remark: This means that, in principle, we can compute the coefficients from x.

### Linear (in)dependence & dimension

#### Propositions:

- A linearly independent set of n-vectors  $a_1, \ldots, a_k$  can have at most n elements, i.e.  $k \leq n$ .
- ullet Any set of n+1 or more n-vectors is linearly dependent.

Exercise: Are the vectors (1,2),(2,3) and (3,0) linearly dependent or independent?

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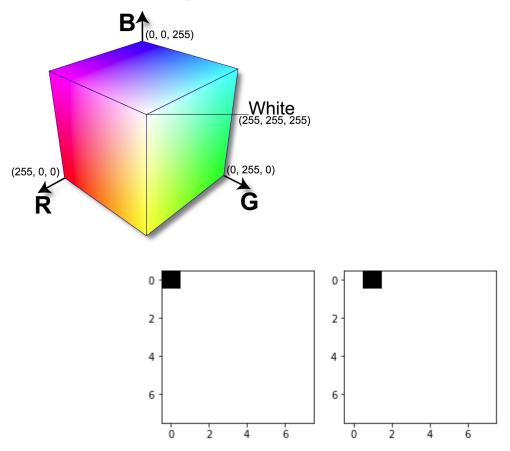
### **Basis**

**Definition**: A set of n linearly independent n-vectors  $a_1, \ldots, a_n$  is called a basis of the space of n-vectors.

Example: The set of n one-hot n-vectors is a basis of the space of n-vectors. This is why we can also call them "basis vectors".

Example: What is a possible basis:

- For the space of colors represented as vectors (r, g, b)?
- For the space of documents with dictionary *D*?
- For the space of  $8 \times 8$  images?
- Space of colors as 3-vectors: (r, g, b)
  - A basis: set of vectors representing red, green and blue.
- ullet Space of documents as n-vectors on a dictionary of n words
  - A basis: set of vectors representing on dictionary word each.
- Space of 8x8 images as 64-vectors
  - A basis: set of images with only one black pixel.



# Properties of a basis

Properties: If  $a_1, \ldots, a_n$  is a basis of the space of n-vectors, then:

- Any *n*-vector *b*:
  - $\blacksquare$  can be expressed as a linear combination of them:  $b=\beta_1a_1+\cdots+\beta_na_n$  for some  $\beta_1,\ldots,\beta_n.$
  - ${\color{black} \blacksquare}$  and the coefficients  $\beta_1,\ldots,\beta_n$  are unique.

Definition: The formula above is called expansion of b in the  $a_1,\ldots,a_n$  basis.

Example: Compute expansion of  $b=(b_1,\ldots,b_n)$  in basis  $e_1,\ldots,e_n$ 

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### Orthogonal Normalized, Orthonormal

Definitions: The *n*-vectors  $a_1, \ldots, a_k$  are:

- (mutually) orthogonal if  $a_i \perp a_j$  for all i,j
- ullet normalized if  $\|a_i\|=1$  for  $i=1,\ldots,k$
- orthonormal if they are orthogonal and normalized.

Example: Give examples of orthogonal, normalized and orthogonal vectors. Draw them.

### **Properties of Orthonormal Vectors**

Properties: If  $a_1, \ldots, a_k$  are orthonormal, then:

- $ullet \ a_i^Ta_j=0 ext{ if } i
  eq j ext{ and } a_i^Ta_i=1$  ,
- $k \leq n$
- $a_1, \ldots, a_k$  are linearly independent.

Definition: A set of *n* orthonormal *n*-vectors is called an orthonormal basis.

# **Examples of Orthonormal Basis**

- One-hot n-vectors:  $e_1, \ldots, e_n$
- The 3-vectors:

$$a_1=\left(egin{array}{c} 0 \ 0 \ -1 \end{array}
ight),\quad a_2=\left(egin{array}{c} 1/\sqrt{2} \ 1/\sqrt{2} \ 0 \end{array}
ight)\quad a_3=\left(egin{array}{c} 1/\sqrt{2} \ -1/\sqrt{2} \ 0 \end{array}
ight)$$

Exercise: Is the orthonormal basis of n-vectors unique?

### **Orthonormal Expansion**

Properties: If  $a_1, \ldots, a_n$  is an orthonormal basis of the n-vectors, then:

• Any *n*-vector *x* can be written:

$$x = (a_1^T x)a_1 + \dots + (a_n^T x)a_n.$$

Definition: The formula above is called orthonormal expansion of x in the orthonormal basis.

## **Gram-Schmidt Algorithm**

The Gram-Schmidt Algorithm:

- checks if a given set  $a_1, \ldots, a_k$  is linearly independent
- allows to get an orthonormal basis from a given set of linear independent vectors  $a_1, \ldots, a_k$ .

You will see it in the labs and the homeworks.

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Resources: Book ILA, Ch. 5