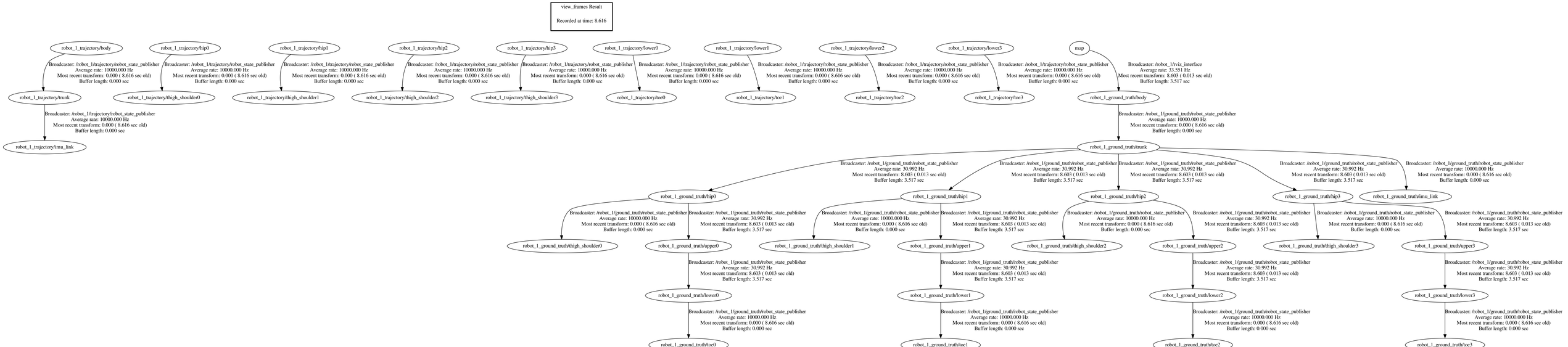
view_frames Result
Recorded at time: 8.616
robot_1_trajectory/body
robot_1_trajectory/hip0
robot_1_trajectory/hip1
robot_1_trajectory/hip2
robot_1_trajectory/hip3
robot_1_trajectory/lower0
robot_1_trajectory/lower1
robot_1_trajectory/lower2
robot_1_trajectory/lower3
map
Broadcaster: /robot_1/trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (8.616 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_1/rviz_interface
Average rate: 33.551 Hz
Most recent transform: 8.603 (0.013 sec old)
Buffer length: 3.517 sec
robot_1_trajectory/trunk
robot_1_trajectory/thigh_shoulder0
robot_1_trajectory/thigh_shoulder1
robot_1_trajectory/thigh_shoulder2
robot_1_trajectory/thigh_shoulder3
robot_1_trajectory/toe0
robot_1_trajectory/toe1
robot_1_trajectory/toe2
robot_1_trajectory/toe3
robot_1_ground_truth/body
robot_1_trajectory/imu_link
robot_1_ground_truth/trunk
Broadcaster: /robot_1/ground_truth/robot_state_publisher
Average rate: 30.992 Hz
Most recent transform: 8.603 (0.013 sec old)
Buffer length: 3.517 sec
Average rate: 10000.000 Hz
Most recent transform: 0.000 (8.616 sec old)
Buffer length: 0.000 sec
robot_1_ground_truth/hip0
robot_1_ground_truth/hip1
robot_1_ground_truth/hip2
robot_1_ground_truth/hip3
robot_1_ground_truth/imu_link
robot_1_ground_truth/thigh_shoulder0
robot_1_ground_truth/upper0
robot_1_ground_truth/thigh_shoulder1
robot_1_ground_truth/upper1
robot_1_ground_truth/thigh_shoulder2
robot_1_ground_truth/upper2
robot_1_ground_truth/thigh_shoulder3
robot_1_ground_truth/upper3
robot_1_ground_truth/lower0
robot_1_ground_truth/lower1
robot_1_ground_truth/lower2
robot_1_ground_truth/lower3
robot_1_ground_truth/toe0
robot_1_ground_truth/toe1
robot_1_ground_truth/toe2
robot_1_ground_truth/toe3