view_frames Result

Recorded at time: 4.802

trajectory/lower0

trajectory/lower1

trajectory/lower2

trajectory/lower3

map

Broadcaster: /trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /trajectory/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /rviz_interface
Average rate: 102.041 Hz
Most recent transform: 4.800 (0.002 sec old)
Buffer length: 0.490 sec

trajectory/toe0

trajectory/toe1

trajectory/toe2

trajectory/toe3

ground_truth/body

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

ground_truth/hip0

ground_truth/hip2

ground_truth/hip3

ground_truth/hip1

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

ground_truth/upper0

ground_truth/upper2

ground_truth/upper3

ground_truth/upper1

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 52.083 Hz
Most recent transform: 4.790 (0.012 sec old)
Buffer length: 0.480 sec

ground_truth/lower0

ground_truth/lower2

ground_truth/lower3

ground_truth/lower1

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

Broadcaster: /ground_truth/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4.802 sec old)
Buffer length: 0.000 sec

ground_truth/toe0

ground_truth/toe2

ground_truth/toe3

ground_truth/toe1