

Learning Query-dependent Propagation for Knowledge Graph Reasoning

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Outline

- Background
- A unified framework of propagation path
- Learning to propagate for KG reasoning
- Summary

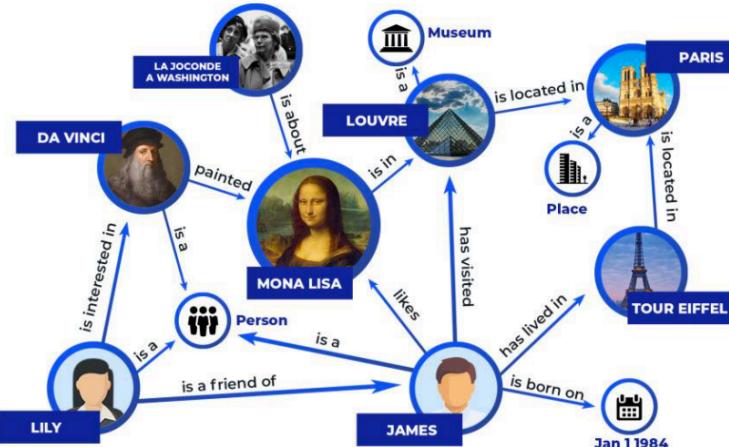
Background

A knowledge graph

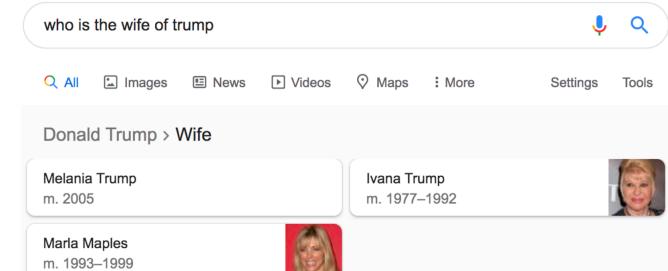
- Mainly describe real world entities and relations, organized in a graph
- Allows potentially interacting arbitrary entities with each other

Preliminaries

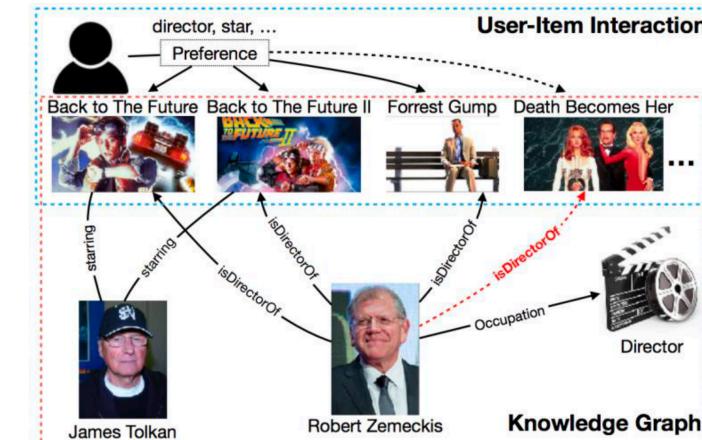
- Graph representation: $\mathcal{G} = (\mathcal{E}, \mathcal{R}, \mathcal{F})$
- Entities \mathcal{E}
 - real world objects or concepts
- Relations \mathcal{R}
 - interactions between entities
- Facts \mathcal{F}
 - the basic unit in form of (s, r, o)
 - (subject entity, relation, object entity)



Applications KGQA:

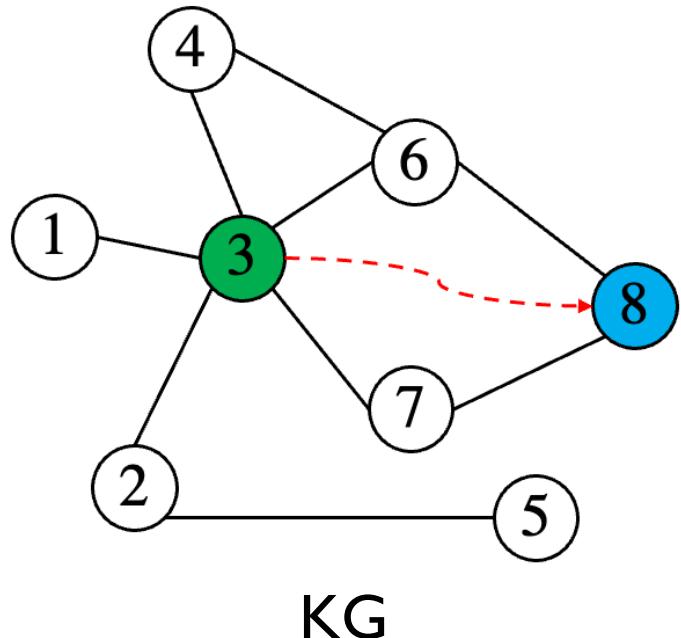


Recommendation:



Background

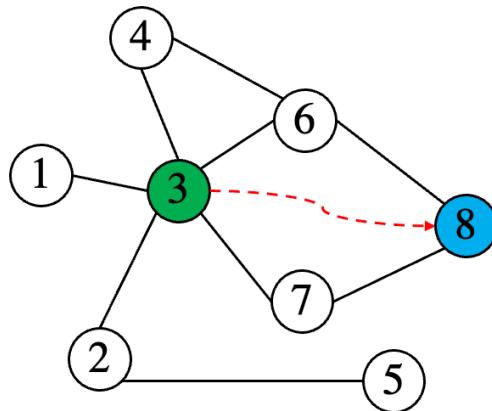
- Link prediction task in knowledge graph
 - give a query $(e_q, r_q, ?)$, to find the target entity e_a
 - based on observed (known) edges, to predict the latent (unknown) edges



query = $(e_q, r_q, ?)$
 $e_q \leftarrow 3, r_q \leftarrow r_1, e_a \leftarrow 8$

Background

- Three classes of existing works
 - **triple-based**
 - $p(e_q, r_q, e_a)$ is measured by a scoring function, utilizing the representations e_q, r_q, e_a
 - **path-based**
 - learn the sequential order of structures by leveraging the relational paths between e_q and e_a
 - **graph-based**
 - directly use the (sub-)graph structure for reasoning, capturing more complex semantics



triple-based
(3, 8)
(3, 7)
(3, 5)
(3, 4)

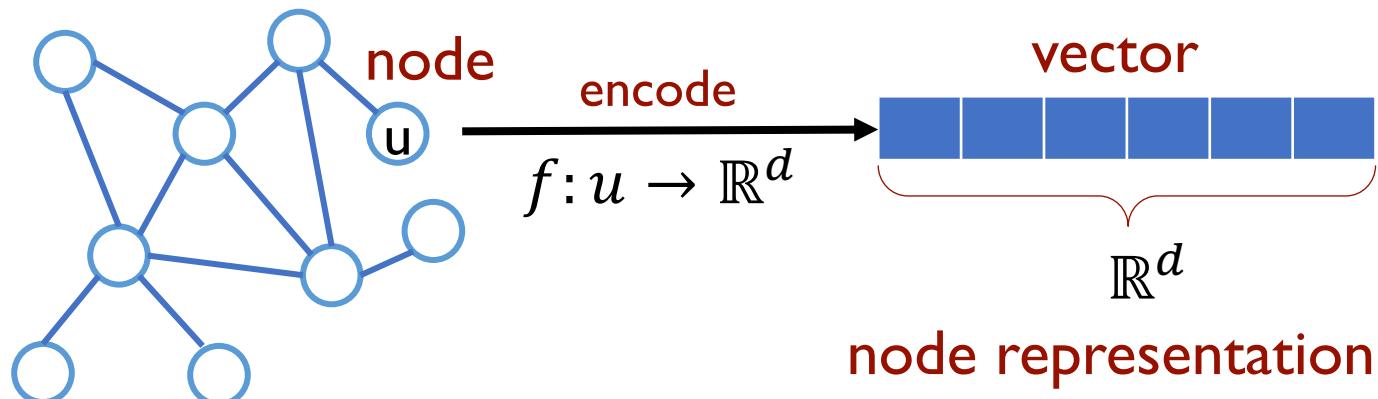
path-based
(3, 6, 8)
(3, 7, 8)

graph-based
(1, 3, 4, 6, 7, 8) → [0, 1]

Background

- Graph-based method for link prediction

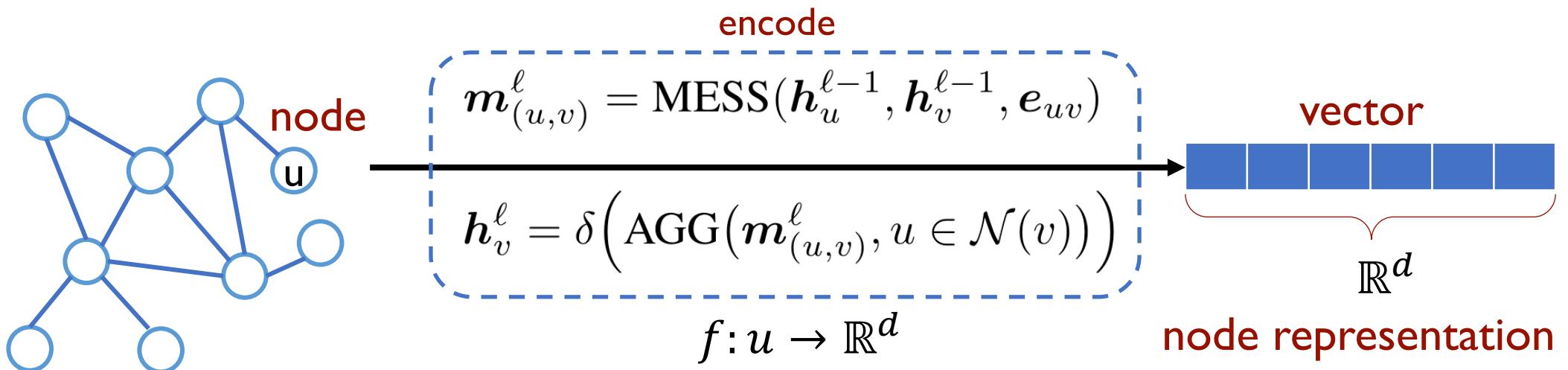
Goal: efficient task-independent representations for reasoning on KG.



Background

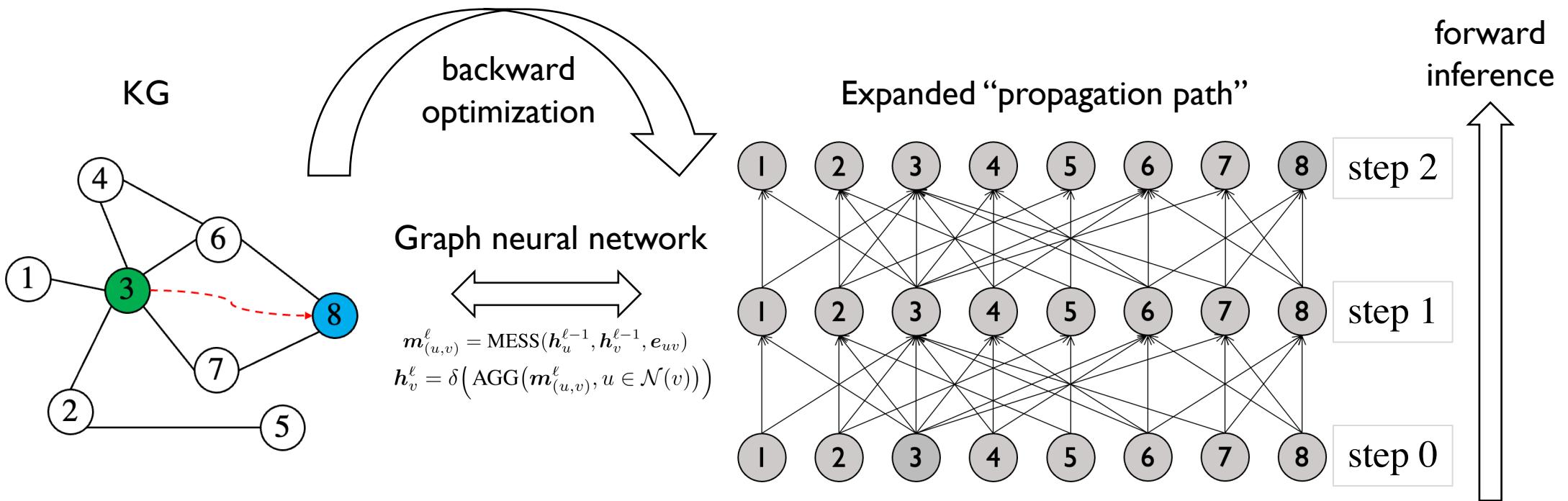
- Graph-based method for link prediction

Goal: efficient task-independent representations for reasoning on KG.



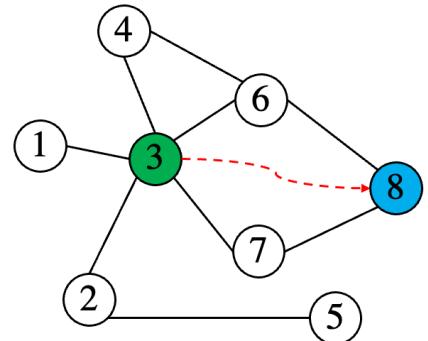
Background

- Graph-based method for link prediction
 - **propagate** the message with the KG structure
 - **update** entity representation at each propagation step

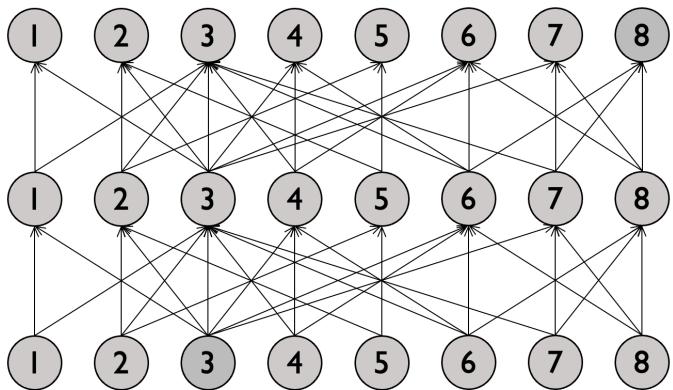


Background

- Different GNNs and their “propagation paths”

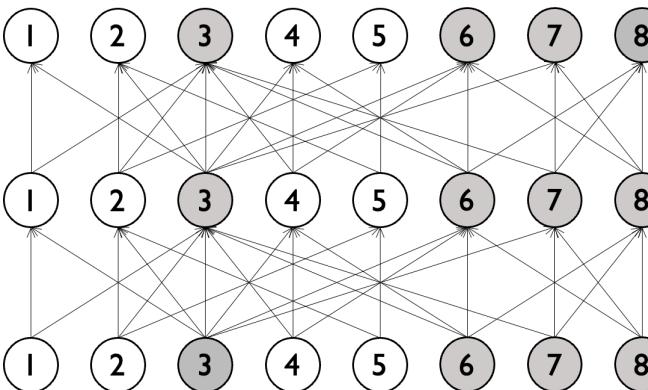


Standard

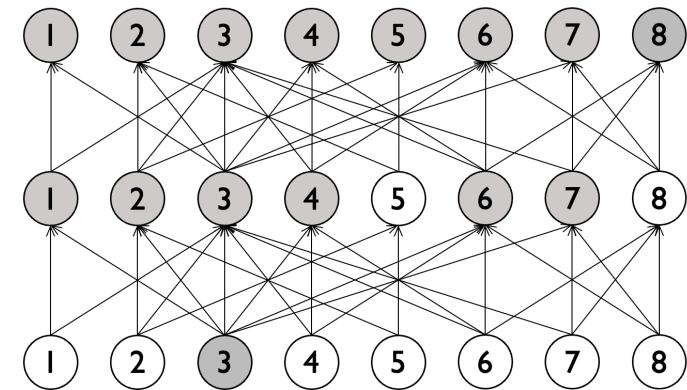


CompGCN / R-GCN

Variants

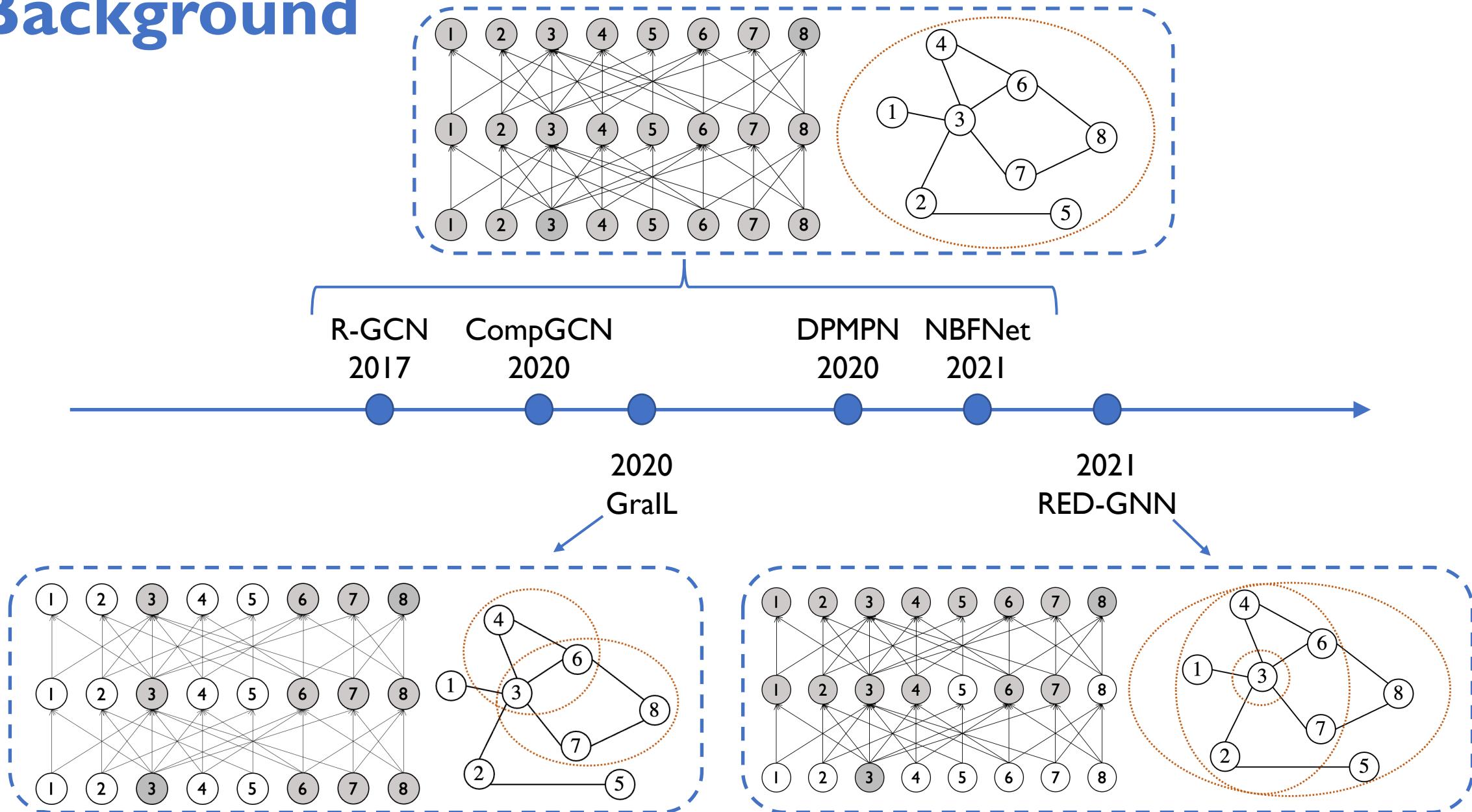


GrailL

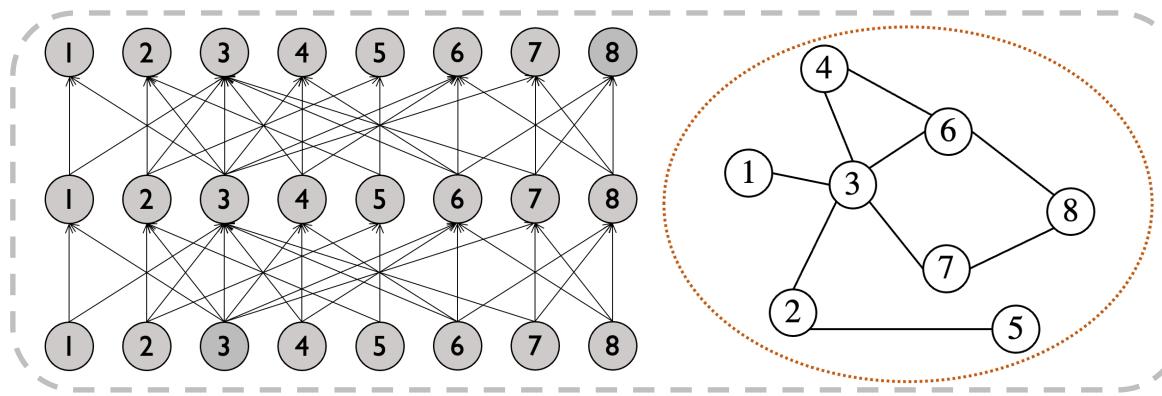


RED-GNN

Background



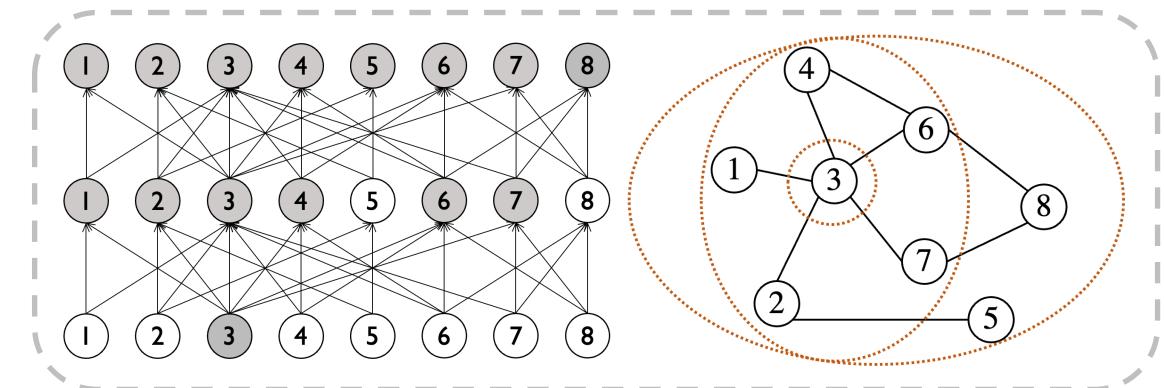
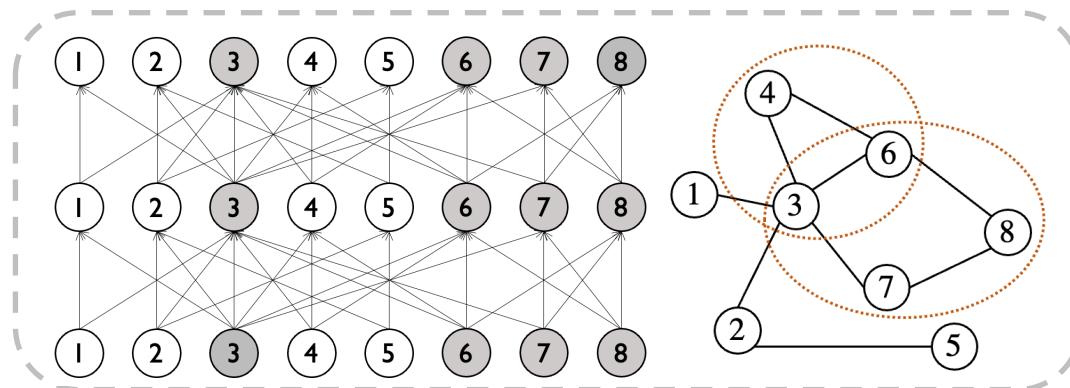
Background



Existing work designed various propagation schemes.

We make formal definition and detailed analysis

to better disentangle the factors of the “**propagation path**”.

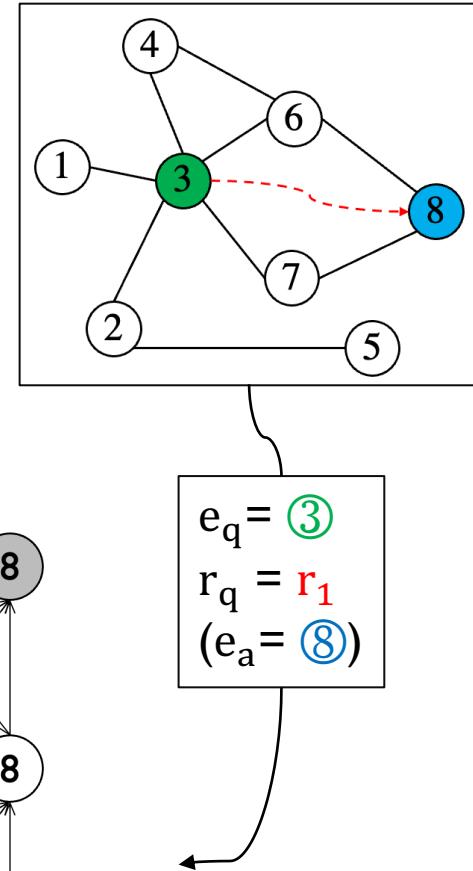
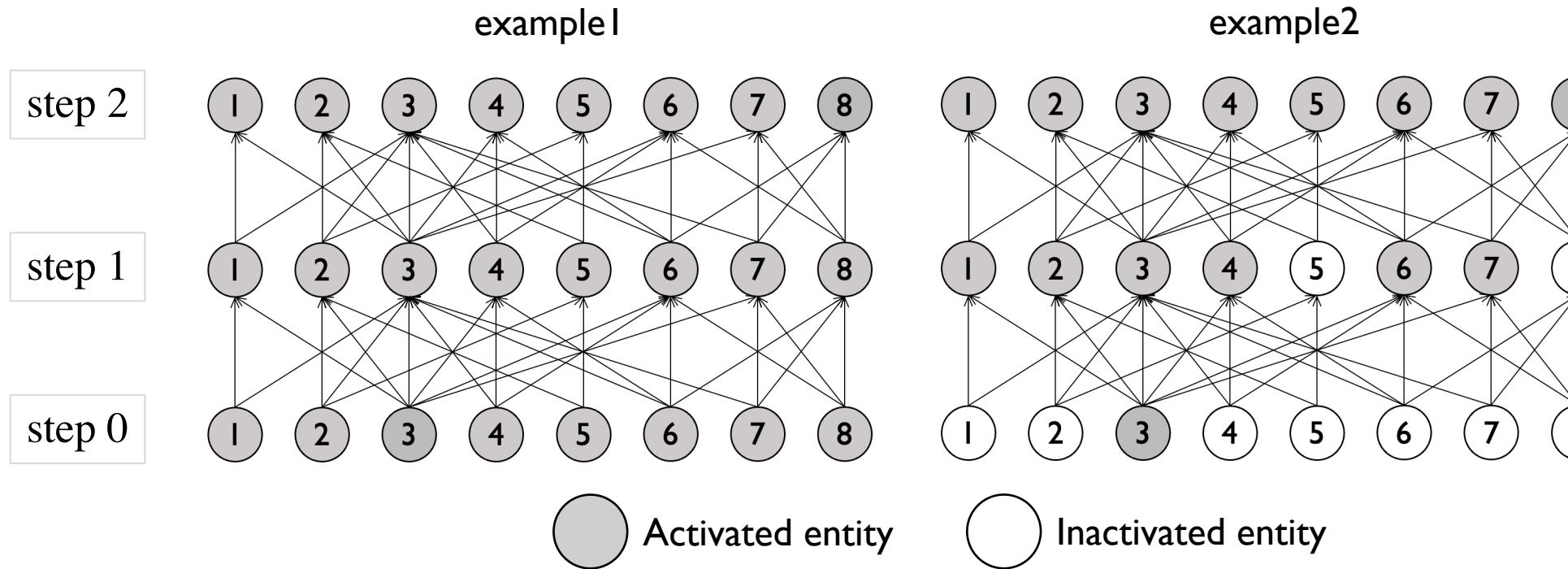


Outline

- Background
- A unified framework of propagation path
 - $\rightarrow Q_1$ What is the propagation path?
- Learning to propagate for KG reasoning
- Summary

Definition of propagation path

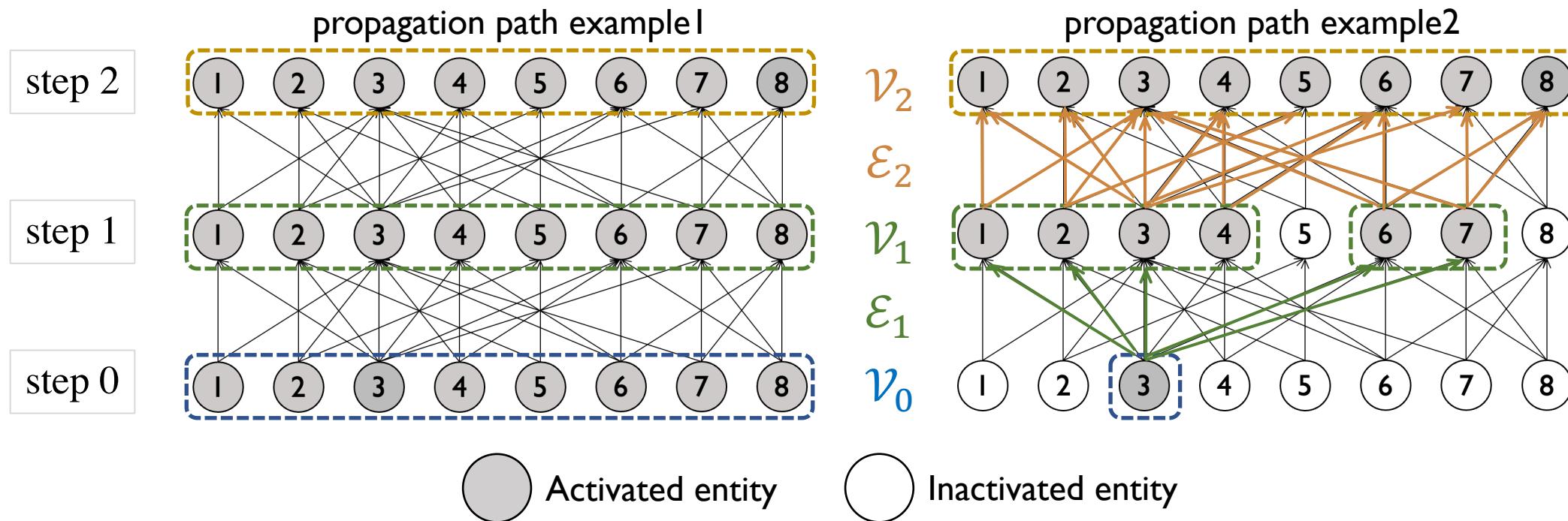
We define the ***propagation path*** for a query $(e_q, r_q, ?)$ as the layered and directed graph containing the activated entities and edges at each step, that is induced from the graph neural network by propagating the message of ***activated entities*** to their neighbors up to ***L steps***.



Definition of propagation path

A propagation path with L layers $\widehat{\mathcal{G}}^L = \{\mathcal{G}^0, \mathcal{G}^1, \mathcal{G}^2, \dots, \mathcal{G}^l\}$

- with propagation path at l -th layer $\mathcal{G}^l = (\mathcal{V}^l, \mathcal{E}^l)$



A unified learning framework based on the propagation path

Algorithm 1 General propagation algorithm for KG reasoning.

Require: propagation path $\hat{\mathcal{G}}^L = \{\mathcal{G}^0, \mathcal{G}^1, \dots, \mathcal{G}^L\}$ with $\mathcal{G}^\ell = \{\mathcal{V}^\ell, \mathcal{E}^\ell\}$.

What we focus on

1: **for** $\ell = 1 \dots L$ **do**

2: **for** $(e_s, r, e_o) \in \mathcal{E}^\ell$ **do**

3: message: $\mathbf{m}_{(e_s, r, e_o)}^\ell := \text{MESS}(\mathbf{h}_{e_s}^{\ell-1}, \mathbf{h}_r^\ell);$

4: **end for**

5: **for** $e_o \in \mathcal{V}^\ell$ **do**

6: aggregate: $\mathbf{h}_{e_o}^\ell := \delta(\text{AGG}(\mathbf{m}_{(e_s, r, e_o)}^\ell, (e_s, r, e_o) \in \hat{\mathcal{E}}^\ell));$

7: **end for**

8: **end for**

9: **return** $\mathbf{w}^\top \mathbf{h}_{e_a}^L$ for all $e_a \in \mathcal{V}^L$.

message passing

message aggregation

readout

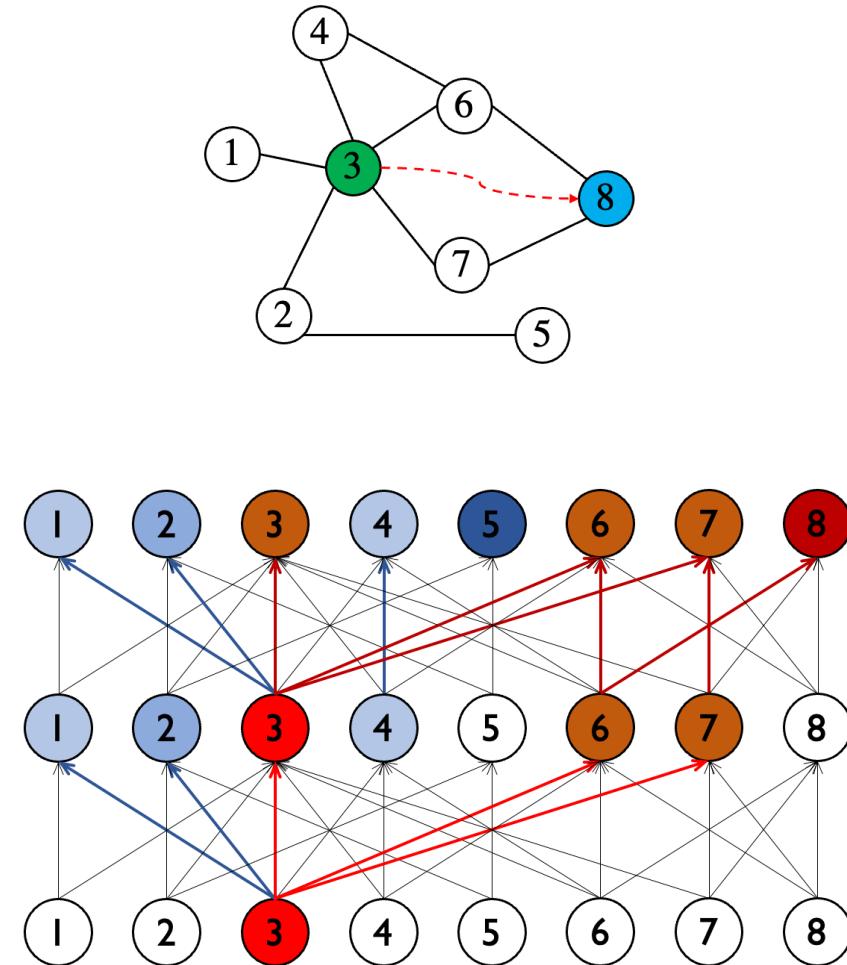
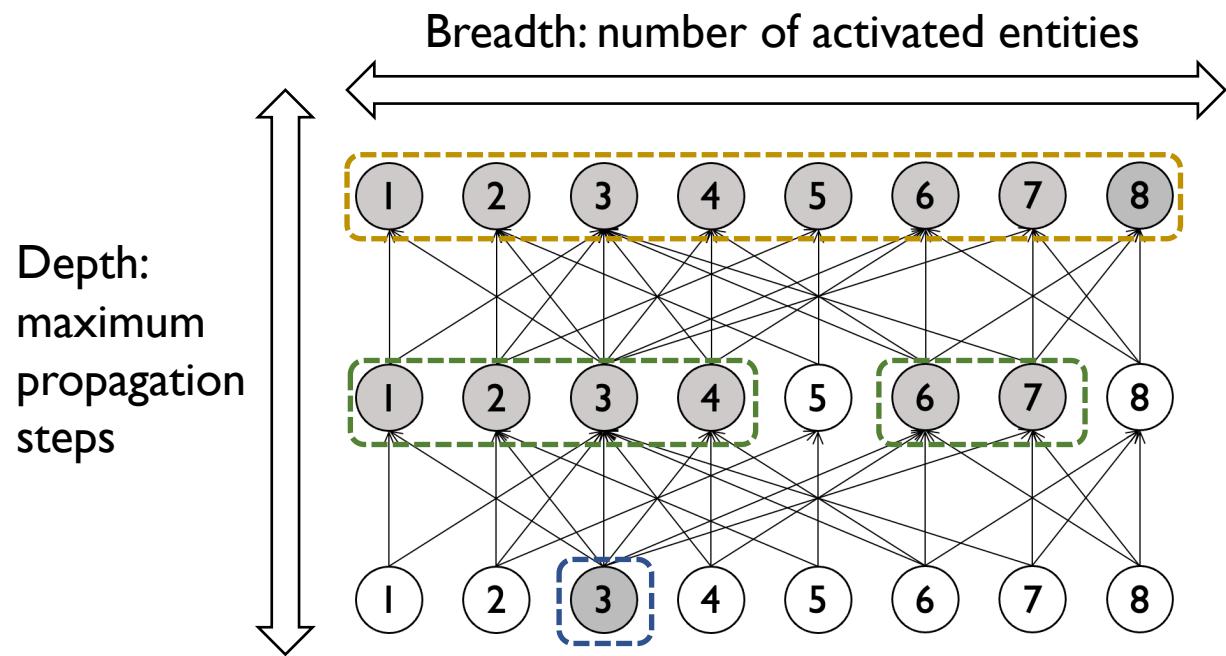
Properties of propagation path

Range (structural property)

- breadth / depth / size

Relevance w.r.t. the query (semantic property)

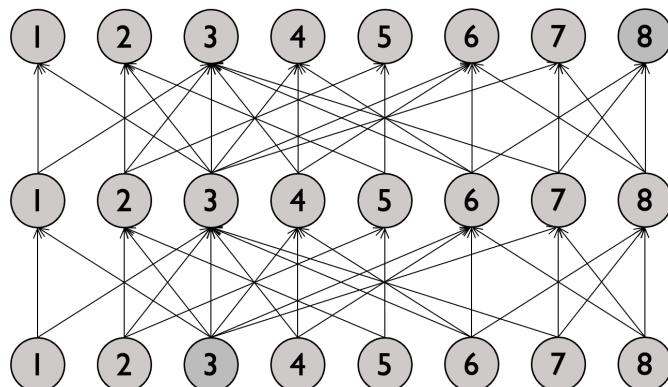
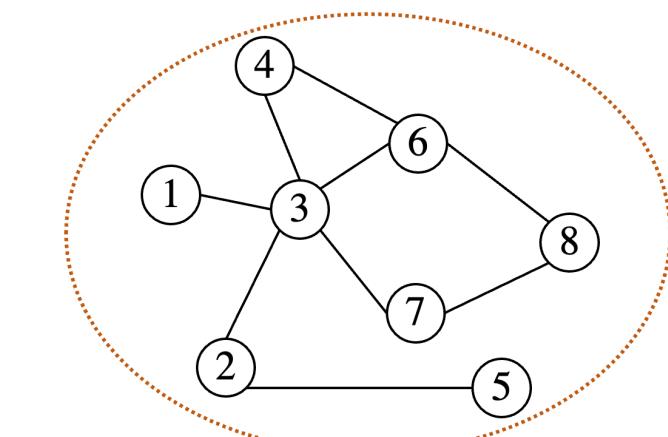
- weights of entities and edges



Taxonomy | w.r.t. Range

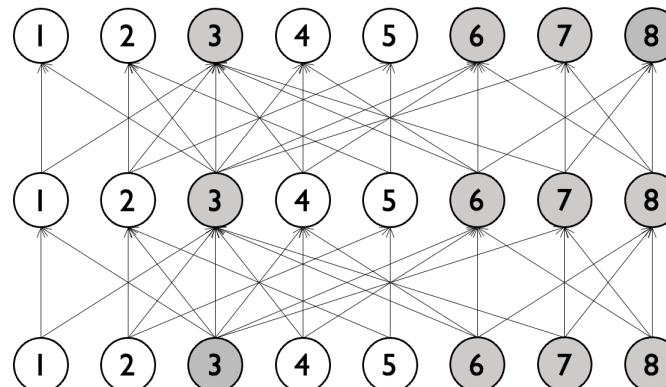
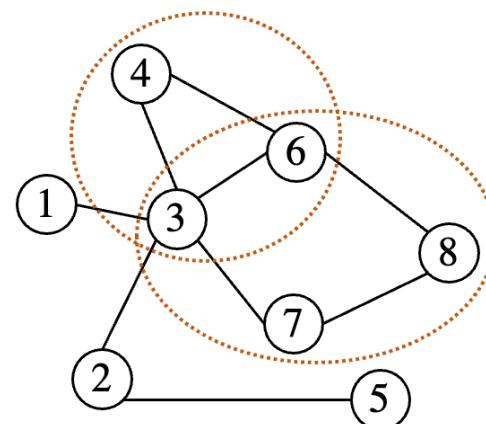
Full propagation

- CompGCN / R-GCN
- NBFNet / DPMPN



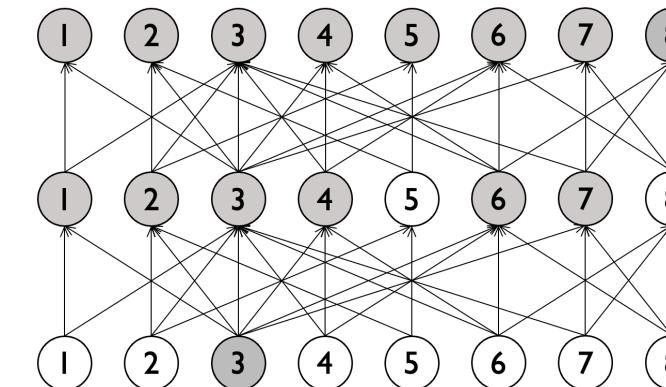
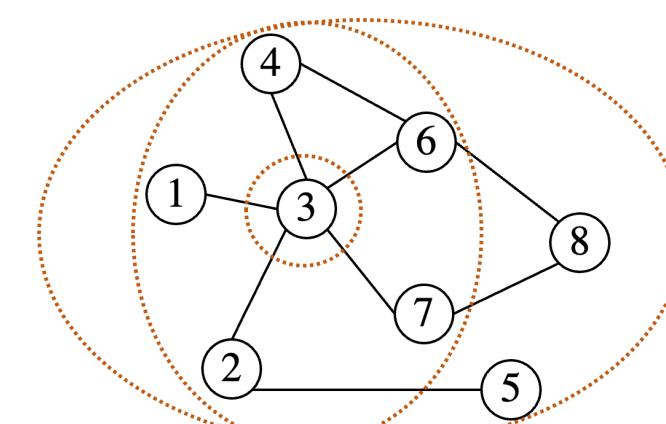
Limited propagation

- Grall



Progressive propagation

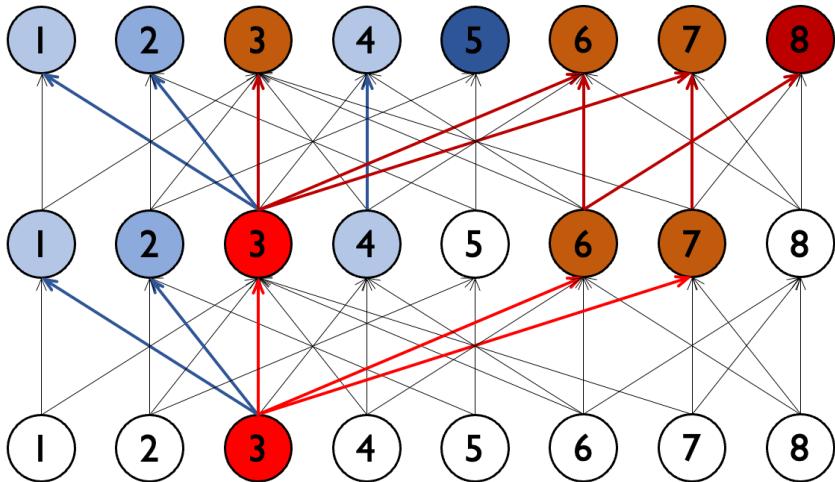
- RED-GNN



Taxonomy | w.r.t. Relevance

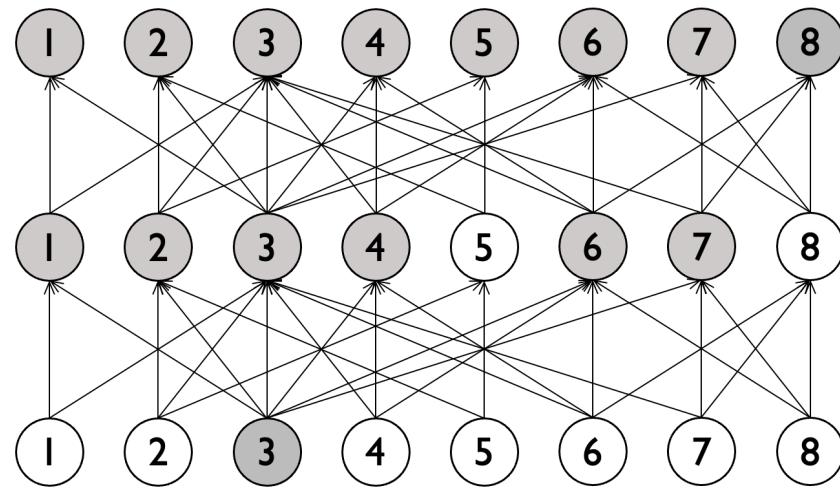
Query-dependent

- RED-GNN / NBFNet
- DPMPN / GrailL



Not query-dependent

- R-GCN / CompGCN



Comparison of existing works

		<i>Semantic</i>	
		Query-dependent	Not query-dependent
<i>Structural</i>	Full propagation	NBFNet DPMPN	R-GCN CompGCN
	Limited propagation	Grall	NA
	Progressive propagation	RED-GNN	NA

Comparison of existing works

		<i>Semantic</i>	
		Query-dependent is better than not query-dependent	
		NBFNet DPMPN	R-GCN CompGCN
<i>Structural</i>	Full propagation		
	Limited propagation	Grall	NA
	Progressive propagation	RED-GNN	NA

Comparison of existing works

Structural

Full propagation

NBFNet
DPMPN

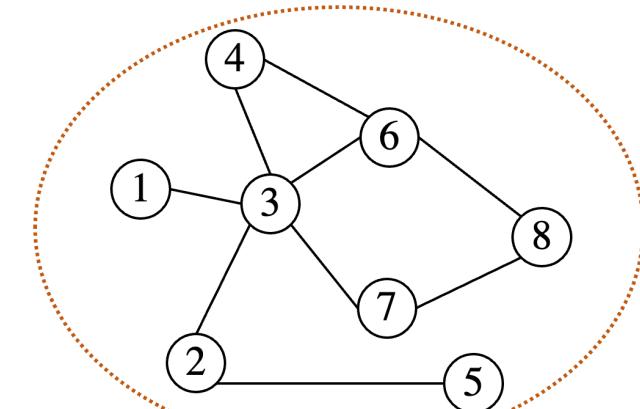
Limited propagation

GraIL

Progressive propagation

RED-GNN

- Too expensive.
- Hard to propagate deeper.



Comparison of existing works

Structural

Full propagation

NBFNet
DPMPN

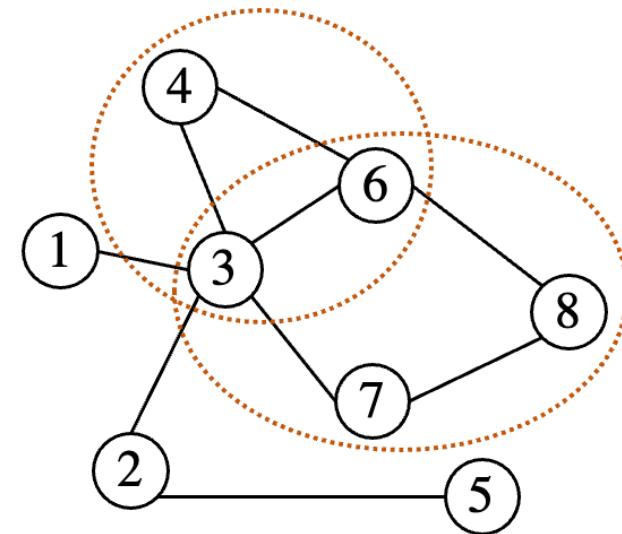
Limited propagation

GraIL

Progressive propagation

RED-GNN

- Requires query entity and answer entity.
- Extracting enclosing subgraphs is inefficient.



Comparison of existing works

Structural

Full propagation

NBFNet
DPMPN

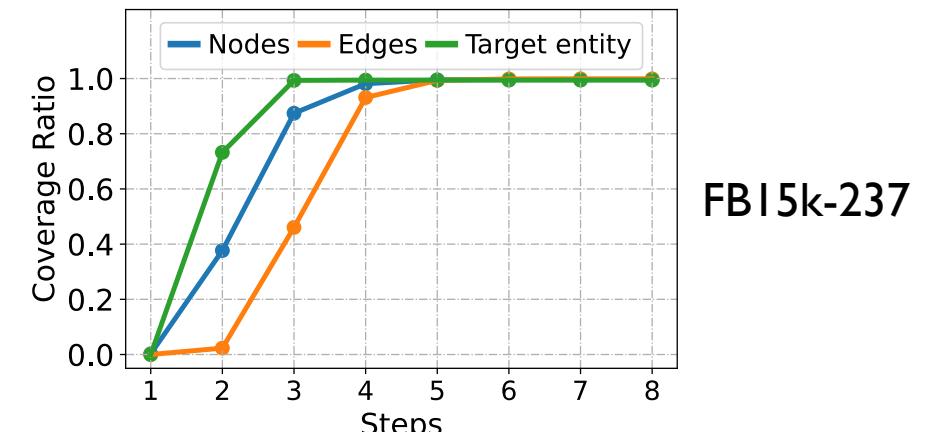
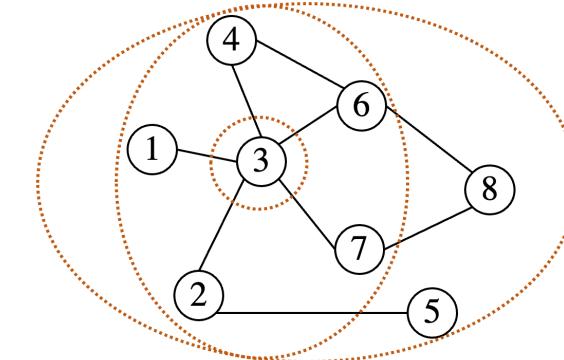
Limited propagation

Grail

Progressive propagation

RED-GNN

- Will degenerate to the full propagation.
- Suffer in a dense graph.



Comparison of existing works

	Query-dependent	Not query-dependent
Full propagation	Too expensive. Hard to propagate deeper.	
Limited propagation	Requires query entity and answer entity. Extracting enclosing subgraphs is inefficient. Inapplicable for large graph.	
Progressive propagation	Will degenerate to the full propagation. Suffer in a dense graph.	

Large size but shallow step.

Expensive and inefficient.

Outline

- Background
- A unified framework of propagation path
 - → Q_1 What is the propagation path?
 - → Q_2 What kinds of propagation paths do we need?
- Learning to propagate for KG reasoning
- Summary

Motivations

Q₂: what kinds of propagation paths do we need? 🤔

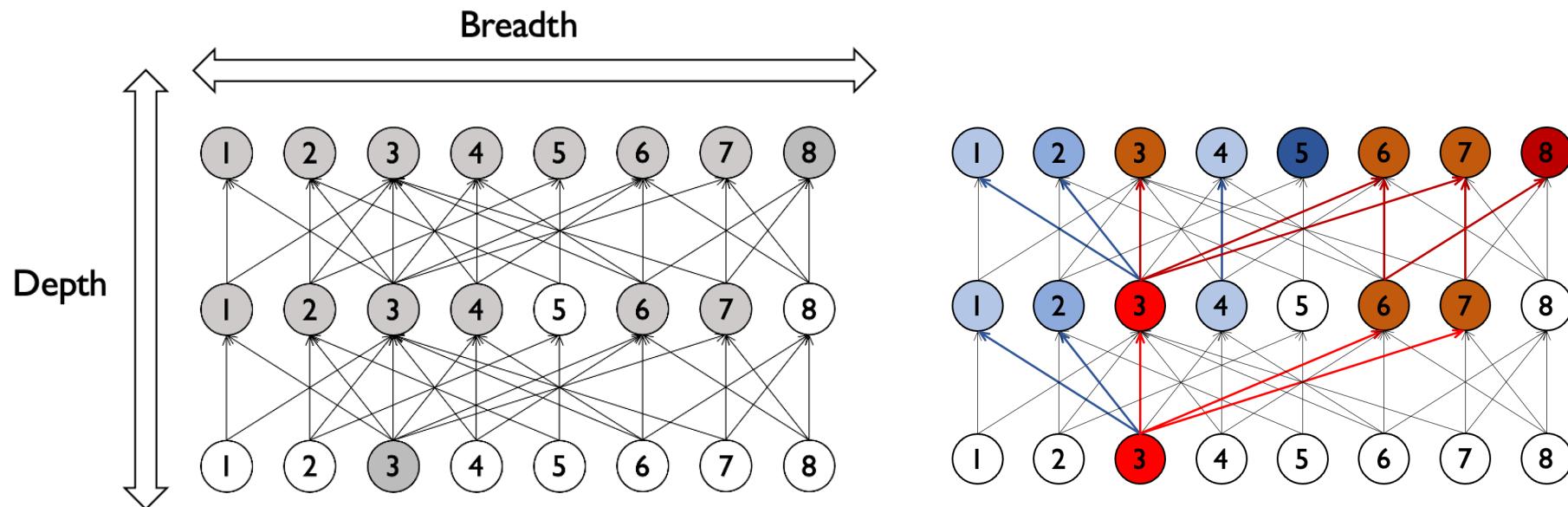
Structural

Deeper step → to capture longer-range semantics

Semantic

Smaller size → to decrease complexity and cost

Query-dependent → to distinguish different entities and edges



Motivations

Q₂: what kinds of propagation paths do we need? 🤔

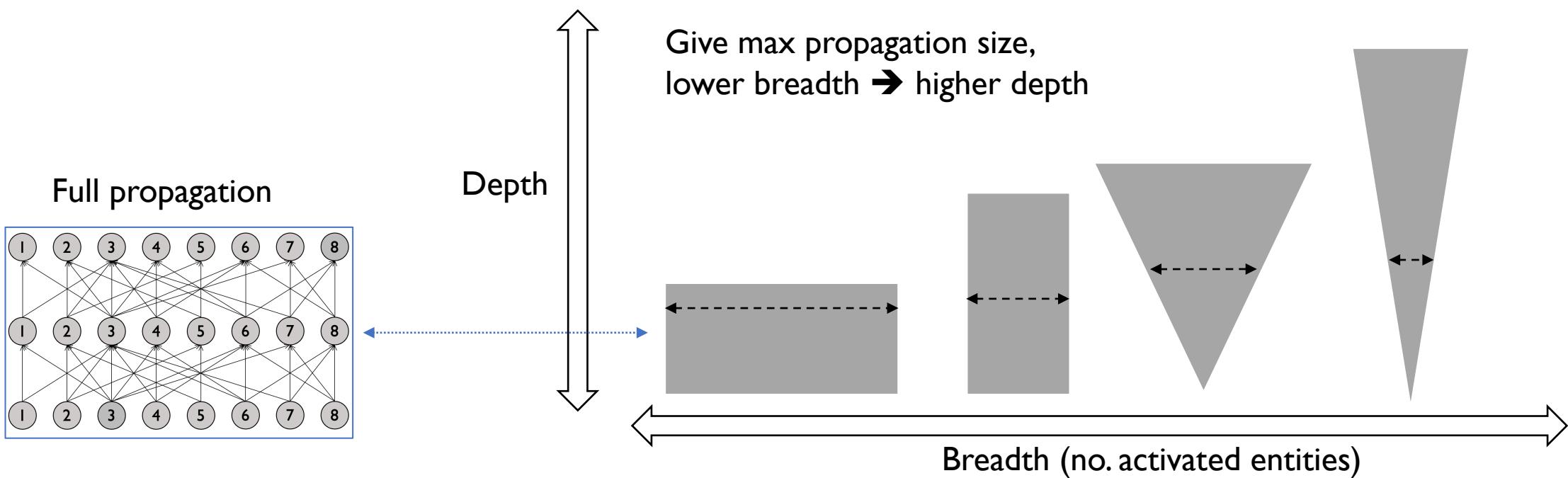
Structural

Deeper step → to capture longer-range semantics

Semantic

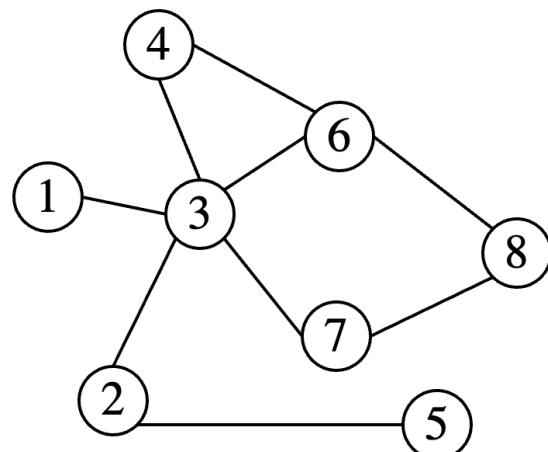
Smaller size → to decrease complexity and cost

Query-dependent → to distinguish different entities and edges



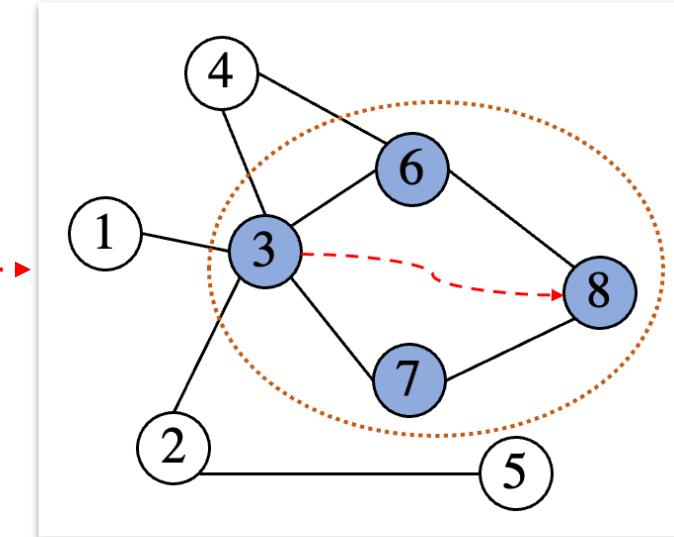
Motivations

Q₂: what kinds of propagation paths do we need?



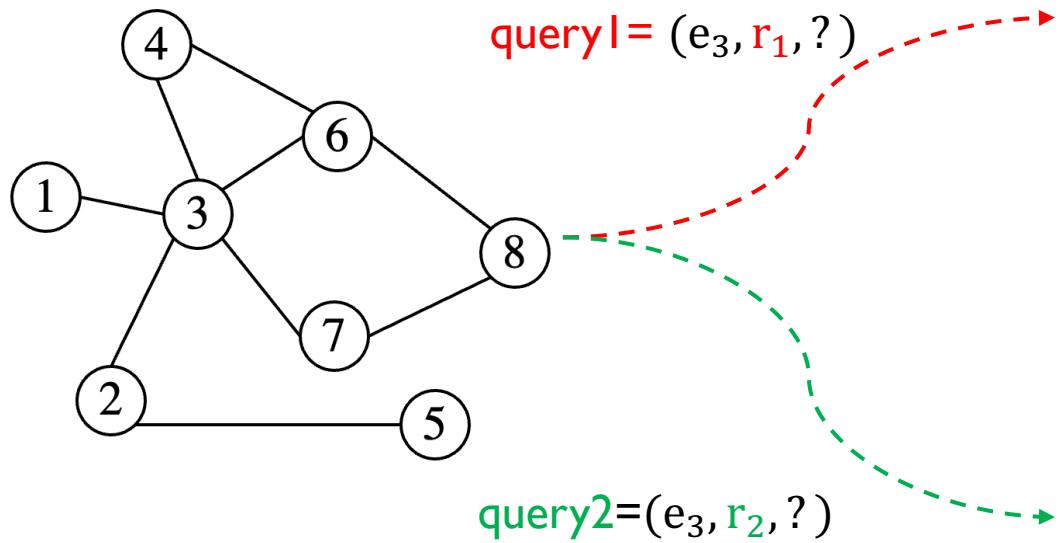
query= $(e_3, r_1, ?)$

The expected breadth

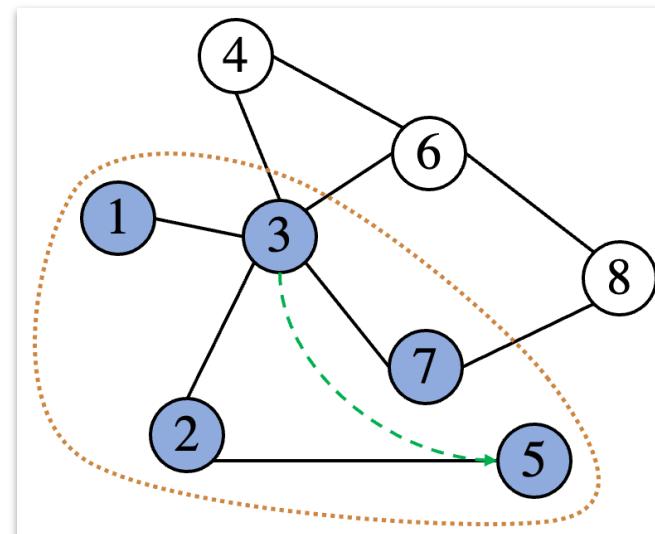
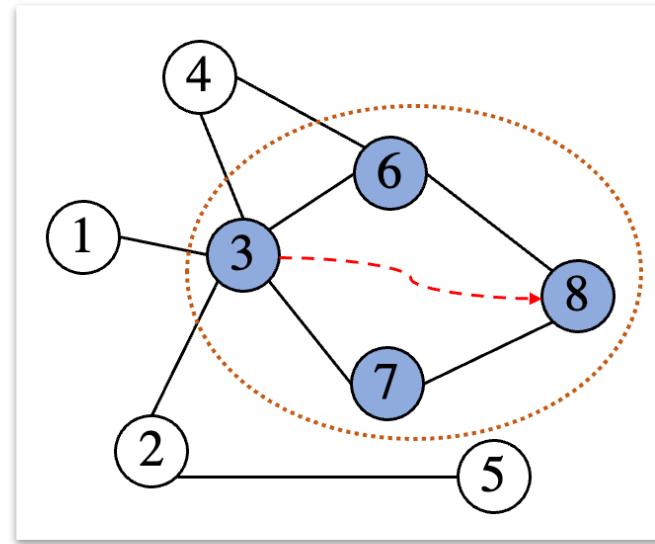


Motivations

Q₂: what kinds of propagation paths do we need?



The expected breadth

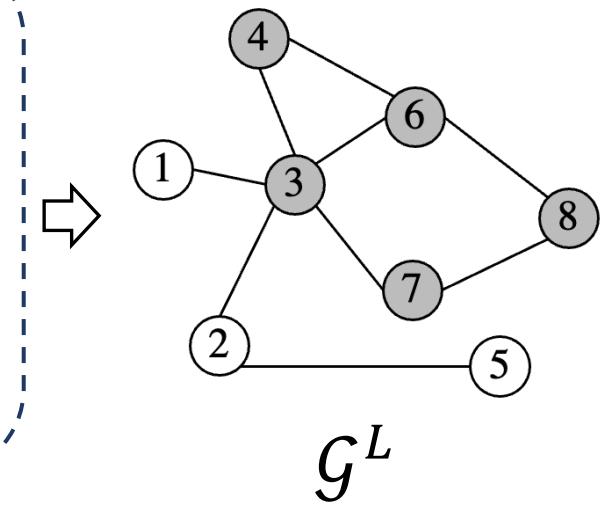
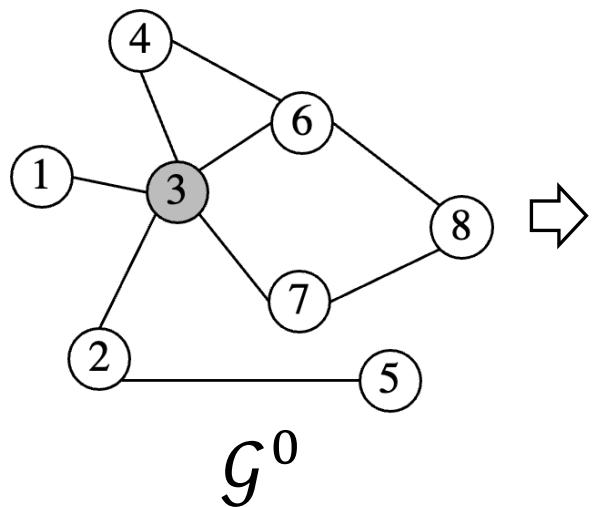


Outline

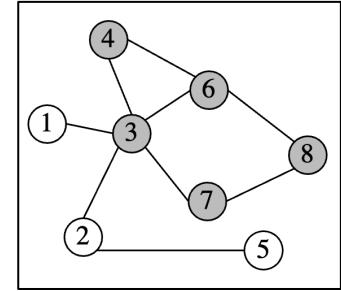
- Background
- A unified framework of propagation path
 - → Q₁ What is the propagation path?
 - → Q₂ What kinds of propagation paths do we need?
- Learning to propagate for KG reasoning
 - → Q₃ How to learn the expected propagation paths?
- Summary

Overview

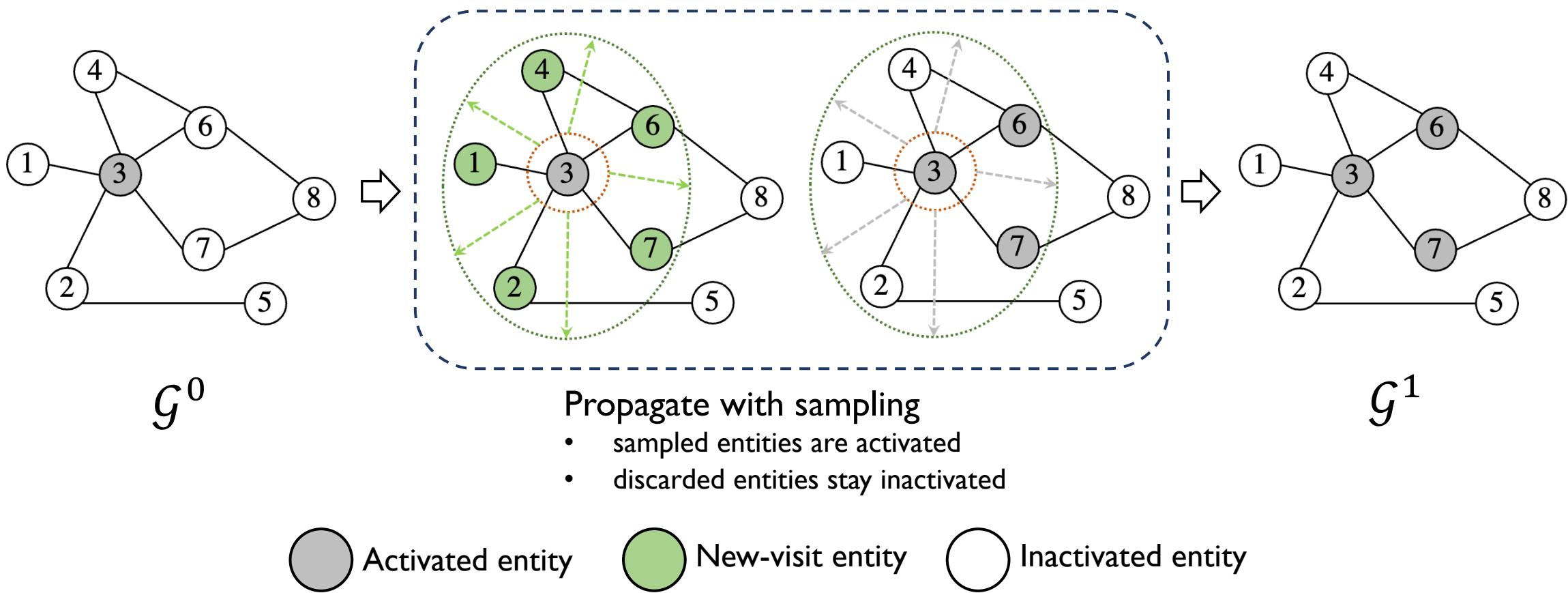
Q₃. How to learn the expected propagation paths?



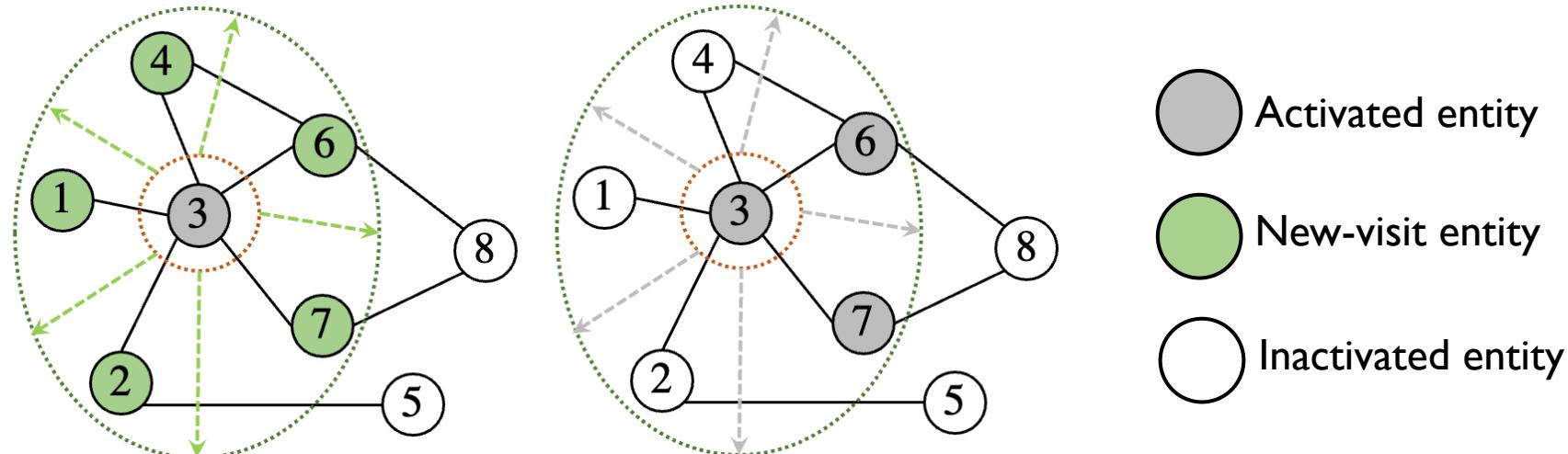
Overview



To sample the “good” entities and discard the “bad” ones **in each propagation step**.



Sampling scheme



The sampling problem: $\text{SAMP}(\text{CAND}(\mathcal{V}^{l-1})) \rightarrow \mathcal{V}^l$

- (**CAND**) determine the candidate entities for sampling.
- (**SAMP**) give the sampling probabilistic distribution.

Sampling scheme | CAND

SAMP(CAND(\mathcal{V}^{l-1})) $\rightarrow \mathcal{V}^l$

- (CAND) determine the candidate entities for sampling.
- (SAMP) give the sampling probabilistic distribution.

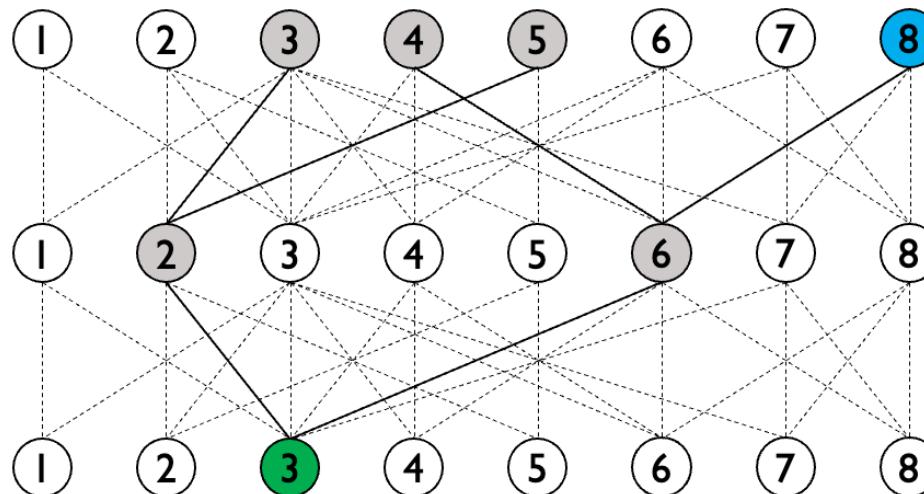
Node-wise sampling

- sample K neighbors for each entity in \mathcal{V}^{l-1}
- $\text{CAND}(\mathcal{V}^{l-1}) = \{\mathcal{N}(e) \mid e \in \mathcal{V}^{l-1}\}$
- $|\mathcal{V}^l| = K|\mathcal{V}^{l-1}| = K^2|\mathcal{V}^{l-2}|$ (max number)
- **exponential explosion in no. entity**

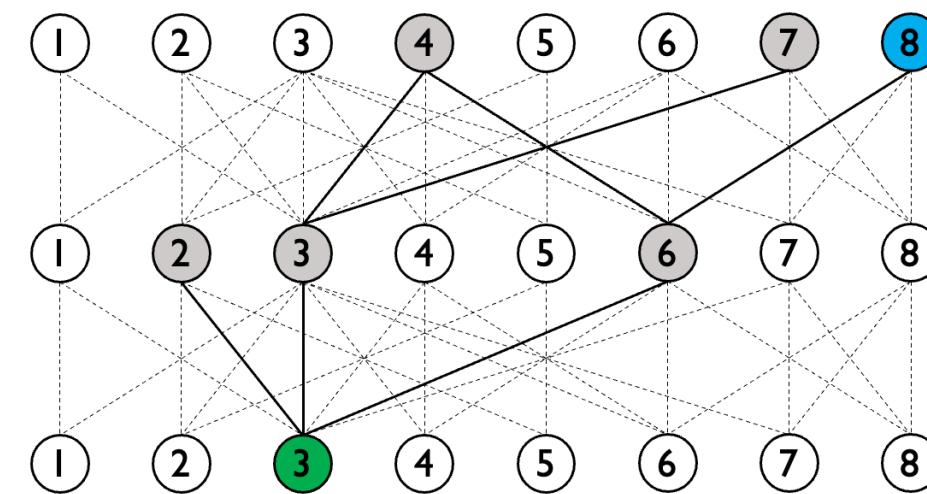
Layer-wise sampling

- sample K entities in each layer
- $\text{CAND}(\mathcal{V}^{l-1}) = \mathcal{V}$
- **sparse connection**
- **low node usage**

Node-wise, K=2



Layer-wise, K=3



Sampling scheme | CAND

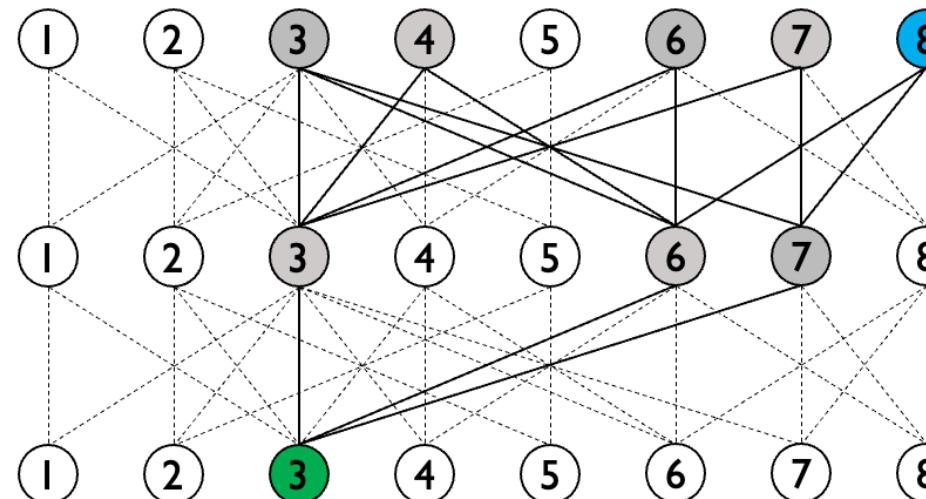
$\text{SAMP}(\text{CAND}(\mathcal{V}^{l-1})) \rightarrow \mathcal{V}^l$

- (CAND) determine the candidate entities for sampling.
- (SAMP) give the sampling probabilistic distribution.

Incremental sampling

- keep all the activated entities in the last layer
- sample K new-visit entities in the current layer
- $\ddot{\mathcal{V}}_l = \text{CAND}(\mathcal{V}^{l-1}) = \{e_n \mid e_n \in \mathcal{N}(e), e_n \notin \mathcal{V}^{l-1}, e \in \mathcal{V}^{l-1}\}$
- $\text{SAMP}(\ddot{\mathcal{V}}^l) \cup \mathcal{V}^{l-1} \rightarrow \mathcal{V}^l$

Incremental, $K=2$



Sampling scheme | CAND

$\text{SAMP}(\text{CAND}(\mathcal{V}^{l-1})) \rightarrow \mathcal{V}^l$

- (CAND) determine the candidate entities for sampling.
- (SAMP) give the sampling probabilistic distribution.

Node-wise sampling

- sample K neighbors for each entity in \mathcal{V}^{l-1}
 - exponential explosion in no. entity



Increase speed can be directly controlled by K

Layer-wise sampling

- sample K entities in each layer
 - sparse connection, low entity usage



Every entity in \mathcal{V}^{l-1} is connected to \mathcal{V}^l

Incremental sampling

- keep all the activated entities in the last layer
- sample K new-visit entities in the current layer

Sampling scheme | SAMP

SAMP(CAND(\mathcal{V}^{l-1})) $\rightarrow \mathcal{V}^l$

- (CAND) determine the candidate entities for sampling.
- (SAMP) give the sampling probabilistic distribution.

Definition 2 (The sampling problem).¹⁰ Given a set of entities $\bar{\mathcal{V}}^\ell$ and their learned representations $h_{e_o}^\ell$, we define the sampling distribution

$$p^\ell(e_o) = \frac{\exp(g^\ell(e_o)/\tau)}{\sum_{e' \in \bar{\mathcal{V}}^\ell} \exp(g^\ell(e')/\tau)}, \quad (4)$$

where τ is the temperature value and $g^\ell(e_o)$ is the logit of entity e_o that can be obtained by its local structure or representation. Based on this distribution, the sampling problem is to sample $K \leq |\bar{\mathcal{V}}^\ell|$ entities without replacement from $\bar{\mathcal{V}}^\ell$.

→ How to sample K entities from the candidate set $\bar{\mathcal{V}}_l$

Sampling scheme | SAMP

SAMP(CAND(\mathcal{V}^{l-1})) $\rightarrow \mathcal{V}^l$

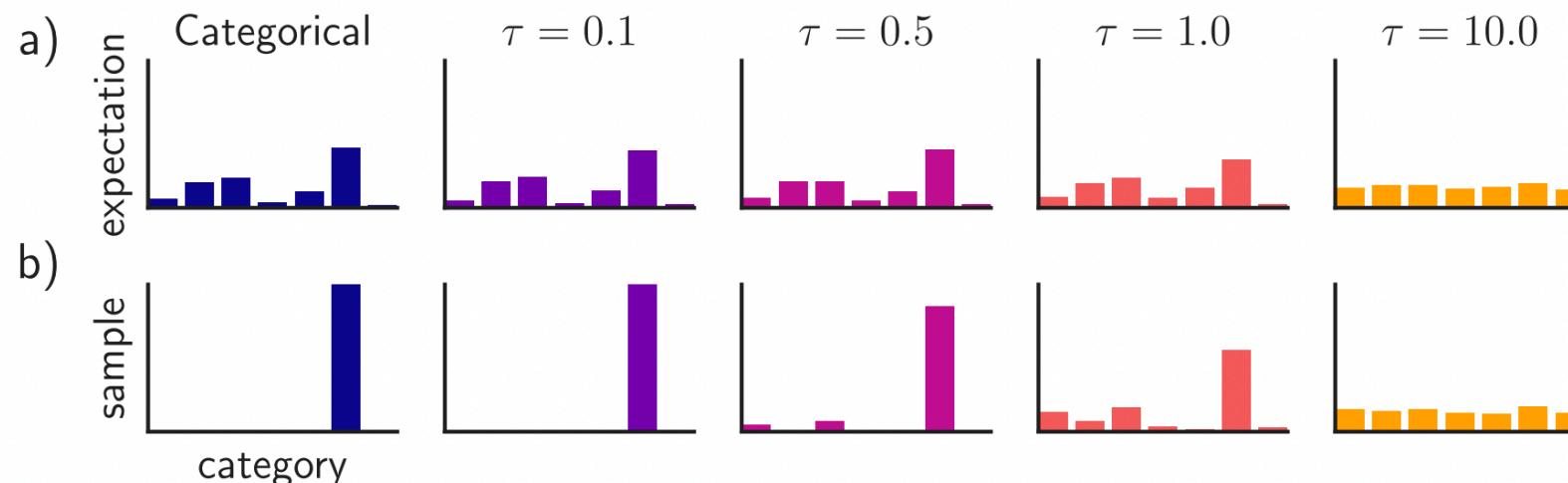
- (CAND) determine the candidate entities for sampling.
- (SAMP) give the sampling probabilistic distribution.

Standard categorical distribution:

- Given n logits $[\phi_1, \phi_2, \dots, \phi_n]$, and a sampling distribution $p_i = \frac{\exp(\phi_i)}{\sum_{j=1}^n \exp(\phi_j)}$

The Gumbel softmax trick:

- add the noise $u_i \sim U(0,1)$ to the logits with $\phi'_i = \phi_i - \log(-\log u_i)$
- get top-k ϕ'_i is an approximation of sampling from $p'_i = \frac{\exp(\phi'_i/\tau)}{\sum_{j=1}^n \exp(\phi'_j/\tau)}$



Sampling scheme | Optimization

Straight through gradient estimator

→ multiply the sampling **logits** to the corresponding entity **representations**

$$\boldsymbol{\phi}_{e_i} \leftarrow \sigma(\mathbf{W}_{samp}^l \mathbf{h}_{e_i}^l)$$

$$\mathbf{p}^l(e_i) \leftarrow \text{Gumbel_softmax}(\boldsymbol{\phi}_{e_i} \mid \{\boldsymbol{\phi}_{e_j}, e_j \in \ddot{\mathcal{V}}_l\})$$

$$\mathbf{h}_{e_i}^l \leftarrow \mathbf{h}_{e_i}^l * (1 - \text{no_grad}(\mathbf{p}^l(e_i)) + \mathbf{p}^l(e_i))$$

Full algorithm

Algorithm 3 PRINCE: propagation with incremental sampling.

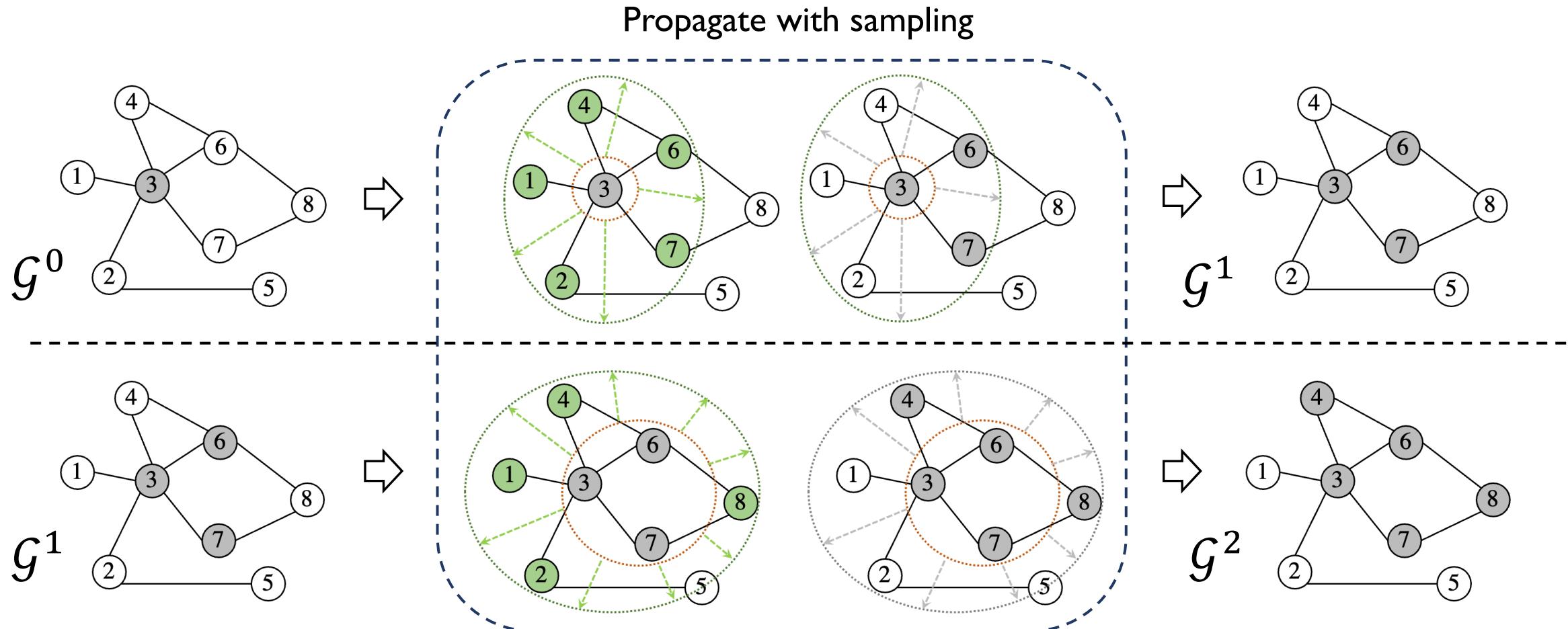
Require: a knowledge graph $\mathcal{K} = \{\mathcal{V}, \mathcal{R}, \mathcal{E}, \mathcal{Q}\}$, query $(e_q, r_q, ?)$, number of steps L and K_I entities each incremental step.

```

1: initialize  $\mathbf{h}_{e_q}^0(e_q, r_q) = \text{IND}(e_q, r_q, e_a)$  and the entity set  $\tilde{\mathcal{V}}_{e_q}^0 = \{e_q\}$ ;
2: for  $\ell = 1 \dots L$  do
3:   collect the  $\ell$ -step edges  $\bar{\mathcal{E}}_{e_q}^\ell = \{(e_s, r, e_o) \in \mathcal{F} | e_s \in \tilde{\mathcal{V}}_{e_q}^{\ell-1}\}$  CAND
   and entities  $\bar{\mathcal{V}}_{e_o}^\ell = \{e_o | (e_s, r, e_o) \in \bar{\mathcal{E}}_{e_o}^\ell\}$ ;
4:   for  $(e_s, r, e_o) \in \bar{\mathcal{E}}_{e_q}^\ell$  do
5:     message:  $\mathbf{m}_{(e_s, r, e_o)}^\ell := \text{MESS}(\mathbf{h}_{e_s}^{\ell-1}, \mathbf{h}_{e_o}^{\ell-1}, \mathbf{w}_q(e_s, r, e_o, e_q, r_q))$ ;
6:   end for
7:   for  $e_o \in \bar{\mathcal{V}}_{e_q}^\ell$  do Message propagation
8:     aggregate:  $\mathbf{h}_{e_o}^\ell(e_q, r_q) := \text{AGG}(\mathbf{m}_{(e_s, r, e_o)}^\ell, (e_s, r, e_o) \in \bar{\mathcal{E}}_{e_q}^\ell)$ ;
9:     logits:  $g^\ell(e_o) := g(\mathbf{h}_{e_o}^\ell(e_q, r_q); \boldsymbol{\theta}^\ell)$ ;
10:    end for
11:    obtain the new entities  $\ddot{\mathcal{V}}_{e_q}^\ell = \bar{\mathcal{V}}_{e_q}^\ell - \tilde{\mathcal{V}}_{e_q}^{\ell-1}$ ; SAMP
12:    for  $e_o \in \ddot{\mathcal{V}}_{e_q}^\ell$  do
13:      Gumbel logits:  $G_{e_o} = g^\ell(e_o) - \log(-\log U_{e_o})$  with  $U_{e_o} \sim \text{Uniform}(0, 1)$ ;
14:    end for
15:    sample  $\tilde{\mathcal{V}}_{e_q}^\ell = \{\arg \max_{e_o \in \ddot{\mathcal{V}}_{e_q}^\ell} G_{e_o}\}$ ; Optimization
16:    for  $e_o \in \tilde{\mathcal{V}}_{e_q}^\ell$  do
17:      Approximated probability:  $p^\ell(e_o \in \tilde{\mathcal{V}}_{e_q}^\ell) = \frac{K_I \cdot \exp(g^\ell(e_o)/\tau)}{\sum_{e' \in \tilde{\mathcal{V}}_{e_q}^\ell} \exp(g^\ell(e')/\tau)}$ ;
18:      ST:  $\mathbf{h}_{e_o}^\ell(e_q, r_q) = (\text{no\_grad}(1 - p^\ell(e_o \in \tilde{\mathcal{V}}_{e_q}^\ell)) + p^\ell(e_o \in \tilde{\mathcal{V}}_{e_q}^\ell)) \cdot \mathbf{h}_{e_o}^\ell(e_q, r_q)$ ;
19:    end for
20:    update  $\tilde{\mathcal{V}}_{e_q}^\ell = \tilde{\mathcal{V}}_{e_q}^{\ell-1} \cup \ddot{\mathcal{V}}_{e_q}^\ell$ ;
21:  end for
22: return  $\mathbf{w}^\top \mathbf{h}_{e_a}^L(e_q, r_q)$  for all  $e_a \in \tilde{\mathcal{V}}_{e_q}^L$ .

```

Full algorithm



Outline

- Background
 - → Q₁ What is the propagation path?
- A unified framework of propagation path
 - → Q₂ What kinds of propagation paths do we need?
- Learning to propagate for KG reasoning
 - → Q₃ How to learn the expected propagation paths?
- **Summary**

Summary

Three problems to study

- Q_1 What is the propagation path.
- Q_2 What kinds of propagation paths do we need.
- Q_3 How to learn the expected propagation paths.

Three major contributions

- A **unified framework** of propagation path of GNN models for KG reasoning.
- A novel GNN with **incremental sampling strategy** that can learn query-dependent propagation path.
- The **state-of-the-arts** performance in both transductive and inductive reasoning settings.

Q&A

Thanks for your attention!

Appendix

A unified learning framework based on the propagation path

Model	Year	\mathcal{V}_0	\mathcal{V}_l	\mathcal{E}_1	\mathcal{E}_l
R-GCN	2017	\mathcal{V}	\mathcal{V}	\mathcal{E}	\mathcal{E}
CompGCN	2020	\mathcal{V}	\mathcal{V}	\mathcal{E}	\mathcal{E}
GrailL	2020	$\mathcal{V}_s \subseteq \mathcal{V}$	$\mathcal{V}_s \subseteq \mathcal{V}$	$\mathcal{E}_s \subseteq \mathcal{E}$	$\mathcal{E}_s \subseteq \mathcal{E}$
NBFNet	2021	\mathcal{V}	\mathcal{V}	\mathcal{E}	\mathcal{E}
RED-GNN	2021	$\{e_q\}$	$\{e_o (e_s, r, e_o) \in \mathcal{E}_l\}$	$\{(e_q, r, e_o) \in \mathcal{E}\}$	$\{(e_s, r, e_o) \in \mathcal{E} e_s \in \mathcal{V}_{l-1}\}$

Model	MESS() $\rightarrow m^l$	AGG() $\rightarrow h_{e_o}^l$	Complexity
R-GCN	$W^l h_{e_s}^{l-1}$	$\sigma(\sum m_{e_o}^l + W_0^l h_{e_o}^{l-1})$	$L \mathcal{V} $
CompGCN	$W^l \phi(h_{e_s}^{l-1}, h_r^l)$	$\sigma(\sum m_{e_o}^l + W_0^l h_{e_o}^{l-1})$	$L \mathcal{V} $
GrailL	$W^l \phi(h_{e_s}^{l-1}, h_r^l, h_{r_q}^l)$	$\sigma(\sum m_{e_o}^l + W_0^l h_{e_o}^{l-1})$	$L \mathcal{V}_s $
NBFNet	$W_{r_q} \phi(h_{e_s}^{l-1}, h_r^l)$	$\sigma(W^l (\sum m_{e_o}^l, h_{e_o}^0))$	$L \mathcal{V} $
RED-GNN	$W^l \phi(h_{e_s}^{l-1}, h_r^l, h_{r_q}^l)$	$\sigma(W^l \sum m_{e_o}^l)$	$\sum_{i=1}^L \mathcal{V}_i $

Background – Knowledge Graph Embedding (KGE)

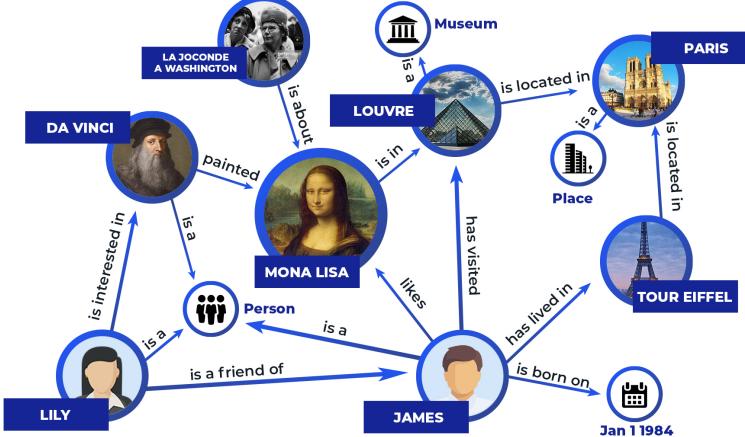
- Knowledge Graph Embedding
 - Encode **entities** and **relations** in KG into **low-dimensional vectors** space
 - while capturing nodes' and edges' connection properties



- Most KGE models based on embeddings define a **scoring function F** to estimate the **plausibility** of any fact (s, r, o) using their embeddings:

$$F(s, r, o) = p(o|s, r) \text{ or } p(s|o, r) \text{ or } p(r|s, o)$$

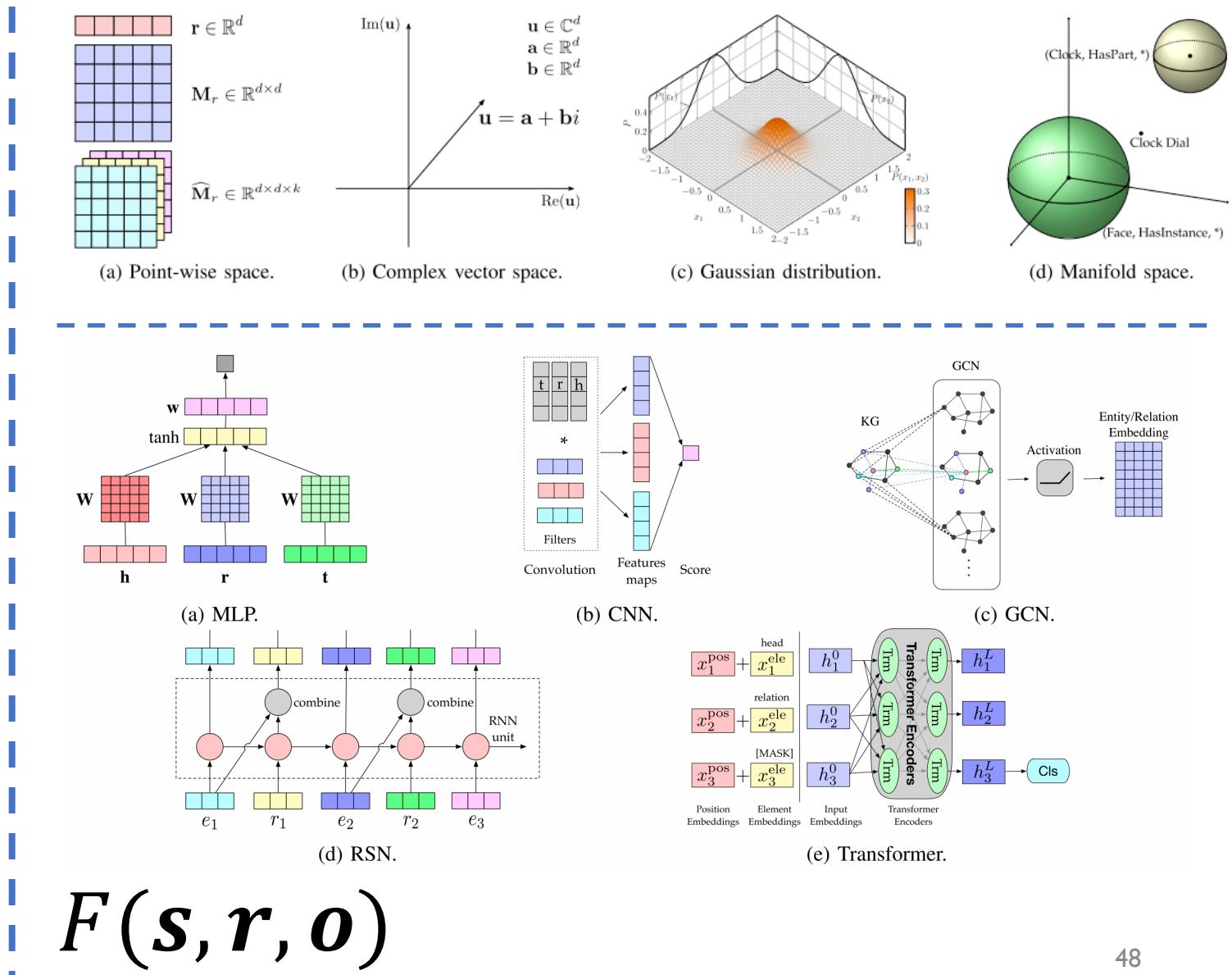
Background – review of KGE models



Simple Taxonomy

- Embedding models
 - tensor decomposition models
 - geometric models
 - deep learning models
- Structure-based models
 - rule-mining
 - path/graph-based

$$F(s, r, o)$$



KGE training and testing

- Training
 - S^+ : positive samples S^- : negative samples
 - Objectives: $\max \phi^+(S^+) + \phi^-(S^-)$
- Prediction
 - For link prediction, given an incomplete triple $(h, r, ?)$
 - the missing tail is inferred as the entity that results in the highest score:

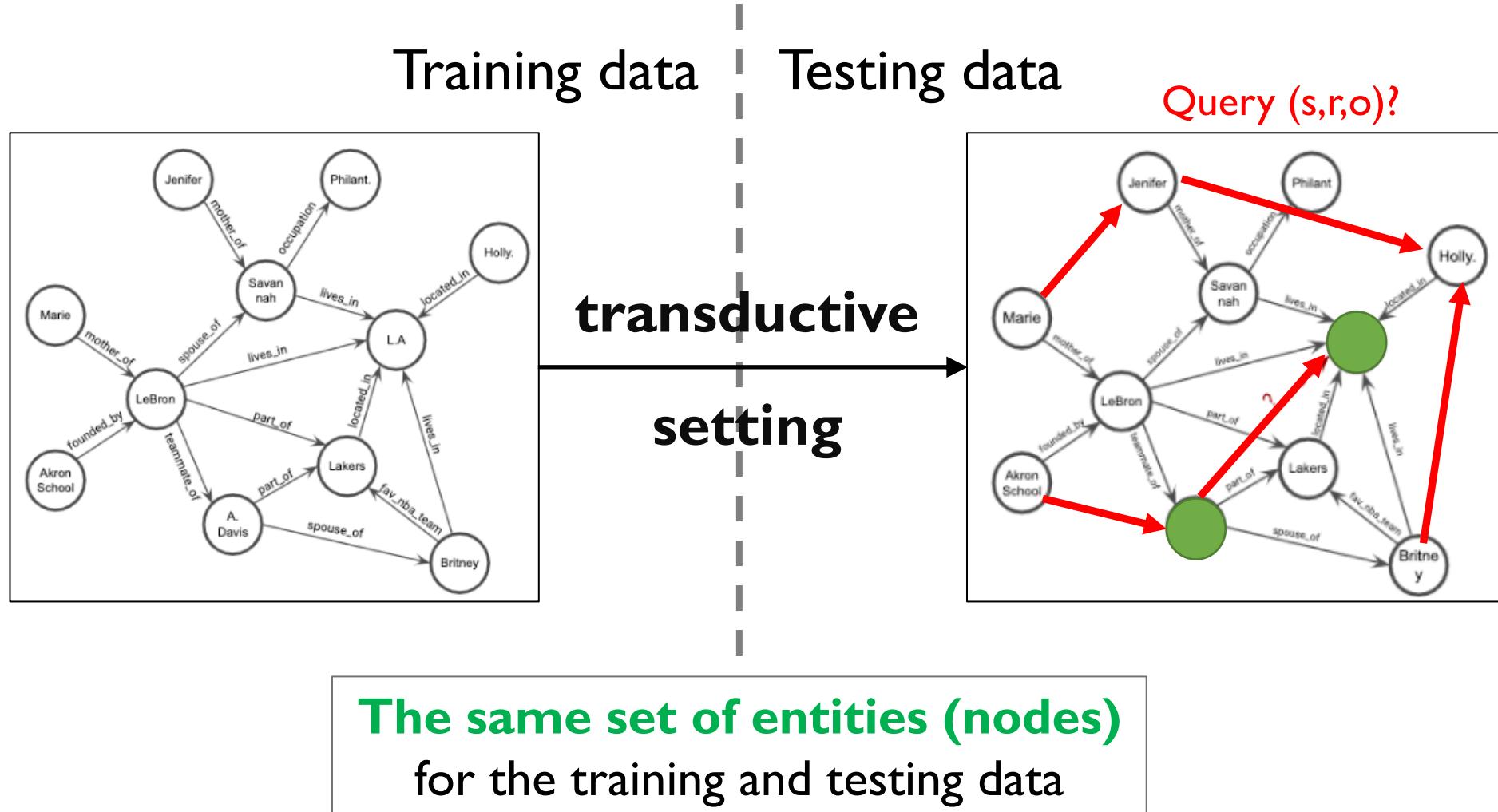
$$t = \operatorname{argmax}_{e \in \mathcal{E}} \phi(\mathbf{h}, \mathbf{r}, e)$$

- Evaluation
 - Three common metrics
 - q : the rank of correct entity

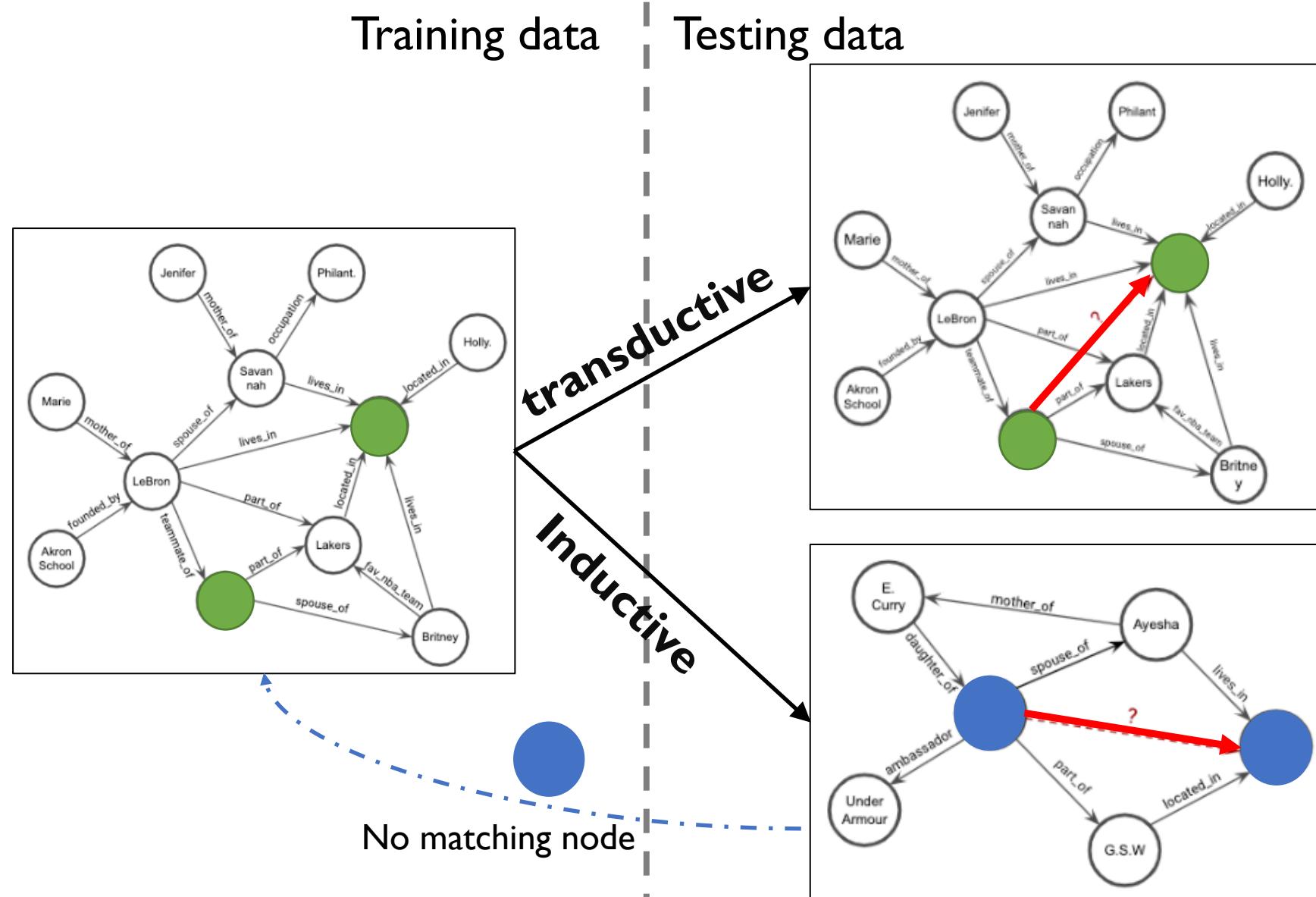
$$MR = \frac{1}{|Q|} \sum_{q \in Q} q \quad MRR = \frac{1}{|Q|} \sum_{q \in Q} \frac{1}{q} \quad H@K = \frac{|\{q \in Q : q \leq K\}|}{|Q|}$$

Background – Knowledge Graph Embedding (KGE)

Transductive learning | Popular learning paradigm in KGE



Two learning paradigms: Inductive and transductive



The same set of entities (nodes) as the training data

Different set of entities to the training data

e.g.,

- new users and products on e-commerce platforms
- new molecules in biomedical KG