

# Andrew Kleinman

## Computer Scientist

### Contact



(714) 400-5903



andrewkleinman@gmail.com



github.com/Andrewkleinman



linkedin.com/in/andrew-kleinman

### Technical Profile

Java  
SQL  
Python  
JavaScript  
HTML  
Scala  
C++

### Competencies

AWS  
Embedded Software  
UAV  
Component integration  
Spring  
JSX  
Jira  
Docker  
LiDAR

### Education

December 2021

#### California Polytechnic University, Pomona

- M.S. Computer Science  
- GPA: 3.97

June 2020

#### San Jose State University

- B.S. Computer Science  
- Minor Mathematics  
- Minor Physics

## Work History

January 2024 – Present

### Software Engineer, Raytheon

- Designed and Implemented a full-stack airline website with features for booking and managing a user's flights using Java, Spring boot, HTML, and PostgreSQL.
- Collaborated with a team to develop an e-commerce application which includes advanced filtering, account management, and secure data manipulation

April 2022 – November 2023

### Cloud Support Engineer, Amazon Web Services

- Identified, analyzed and resolved infrastructure vulnerabilities and application deployment issues for over 300 businesses
- Modified and debugged implementations of AWS services in the areas of Serverless Development, Messaging, and Mobile Technologies
- Handled high urgency assignments with an SLA of 15 minutes

May 2021 – December 2021

### Full Stack Developer, Esdiac Global Systems

- Integrated Java, Scala, HTML, and Javascript code to create a real-time system to monitor active voice and video calls
- Managed and stored user data using a MySQL database, to control information displayed upon user login

## Projects

August 2020 - December 2021

### Embedded Software Engineer, UAV Fire Detection and Suppression

*Collaboration with Lockheed Martin Corporation*

- Led a team to produce a pair of drones that operate in tandem to navigate, detect and suppress fires, and map environment data
- Designed a variety of pathing and obstacle avoidance algorithms to allow automatic traversal through difficult terrain based on input from a VLP-16 LiDAR

## Publications

- Kleinman, A. (2022, January 28). Algorithms for automatic UAV pathing, detection, and traversal in an unknown environment. ScholarWorks. <http://hdl.handle.net/20.500.12680/4q77fx85d>
- Moffatt, A., Turcios, N., Edwards, C., Karnik, A., Kim, D., Kleinman, A., Nguyen, V., Ramos, V., Ranario, E., Sato, T., Uryeu, D., and Bhandari, S., "Collaboration between Multiple UAVs for Fire Detection and Suppression," *Proceedings of International Conference on Unmanned Aircraft Systems*, Hybrid Event, Athens, Greece, 15-18 June 2021.