

ДОДАТОК 3

Код мікроконтролера блоку обробки інформації

```
#include <SPI.h>
#include <Ethernet.h>
#include <RF24.h>
#include <SoftwareSerial.h>

// define SPI pins for arduino uno
#define useSoftSPI true
#define CE 5
#define CSN 6
#define SCK 7
#define MOSI 8
#define MISO 9

// define recieve structures
struct SensorData
{
    int id;
    float value;
};

// init ethernet module
byte mac[] = {0xDE, 0xAD, 0xBE, 0xEF, 0xFE, 0xED};
IPAddress ip(192, 168, 1, 177);
EthernetServer server(80);

// init other modules
RF24 radio(CE, CSN);
SoftwareSerial SIM800(A1, A0);

/**
 * Method for setup arduino
 */
void setup()
{
    // open serial port
    Serial.begin(9600);
    delay(500);

    // setup modules
    setupServer();
    setupRadio();
}

/**
 * Method for setup radio module
 */
void setupRadio()
```

```

{
    // set default props
    const int channel = 12;
    const uint64_t pipe = 0xFFFFFFFFFLL;

    // setup radio
    radio.begin();
    radio.setChannel(channel);
    radio.setDataRate(RF24_250KBPS);
    radio.setPALevel(RF24_PA_MIN);
    radio.openReadingPipe(0, pipe);
    radio.startListening();
}

/**
 * Method for looping arduino proccess
 */
void loop()
{
    // define need to send flag
    bool needToSend = false;

    // handle radio data receiving
    SensorData light = {0, 0};
    SensorData temperature = {0, 0};
    SensorData recievePackage[] = {light, temperature};
    if (radio.available())
    {
        // read received data
        radio.read(&recievePackage, sizeof(recievePackage));

        // handle light
        light = recievePackage[0];
        Serial.print("Light: ");
        Serial.print(light.value);
        Serial.println(" lx");

        // handle temperature
        temperature = recievePackage[1];
        Serial.print("Temperature: ");
        Serial.print(temperature.value);
        Serial.println(" C");
        Serial.println("Radio data was completely received.\n");

        // set need to send flag
        needToSend = true;
    }

    if (needToSend)
    {
        String sensorsDataJSON = converSensorsDataToJSON(recievePackage);
        makeRequest(sensorsDataJSON);
    }
}

```

```

    }
}

/**
 * Helper for waiting GSM-module response
 */
void waitResponse()
{
    while (SIM800.available())
    {
        Serial.write(SIM800.read());
    }
}

/**
 * Helper for making POST request via GSM-module
 */
void makeRequest(String data)
{
    SIM800.begin(9600);
    SIM800.println("AT");
    waitResponse();
    delay(1000);

    SIM800.println("AT+CSTT=\"internet\",\"\",\"\"");
    delay(1000);
    waitResponse();
    SIM800.println("AT+CIICR");
    delay(3000);
    waitResponse();
    SIM800.println("AT+CIFSR");
    delay(2000);
    waitResponse();
    SIM800.println("AT+CIPSPRT=0");
    delay(3000);
    waitResponse();
    SIM800.println("AT+CIPSTART=\"tcp\",\"solar-monitor.herokuapp.com\",\"80\"");
    delay(3000);
    waitResponse();
    SIM800.println("AT+CIPSEND");
    delay(3000);
    waitResponse();

    SIM800.println("POST /sensors/data HTTP/1.1");
    delay(100);
    waitResponse();
    SIM800.println("Content-Type: application/json");
    delay(100);
    waitResponse();
    SIM800.print("Content-Length: ");
    SIM800.println(data.length());
    delay(100);
}

```

```

        waitResponse();
        SIM800.println("Connection: close");
        delay(100);
        waitResponse();
        SIM800.println("Host: solar-monitor.herokuapp.com");
        delay(100);
        waitResponse();
        SIM800.println();
        delay(100);
        waitResponse();
        SIM800.println(data);
        delay(100);
        waitResponse();
        SIM800.println();
        delay(100);
        waitResponse();
        SIM800.println((char)26);
        delay(10000);

        SIM800.println("AT+CIPCLOSE");
        delay(200);
        waitResponse();
    }

/**
 * Helper for converting sensors data to JSON
 */
String converSensorsDataToJson(SensorData sensorsData[2])
{
    int sensorsDataLength = 2;
    String data = "{ \"data\": [";
    for (int i = 0; i < sensorsDataLength; i++)
    {
        SensorData sensorData = sensorsData[i];
        data += "{ \"id\": ";
        data += sensorData.id;
        data += ", \"value\": ";
        data += sensorData.value;
        data += " }";
        if (i != sensorsDataLength - 1)
        {
            data += ", ";
        }
    }
    data += "] ]";
    return data;
}

```