ДОДАТОК 1

Код мікроконтролера блоку метеоспостережень

```
// include modules
#include <SPI.h>
#include < Digital IO.h >
#include <RF24.h>
#include <OneWire.h>
#include <BH1750.h>
#include <DallasTemperature.h>
// define SPI pins for arduino nano
#define CE 9
#define CSN 10
#define SCK 13
#define MOSI 11
#define MISO 12
// define sensors constants
#define LIGHT_SENSOR_ID 0
#define TEMPERATURE_SENSOR_ID 1
// define sending structures
struct SensorData
  int id;
  float value;
};
// init global modules
RF24 radio(CE, CSN);
BH1750 lightSensor;
OneWire temperatureSensorLink(2);
DallasTemperature temperatureSensor(&temperatureSensorLink);
void setup()
  // open serial port
  Serial.begin(9600);
  // setup modules
  setupRadio();
  setupSensors();
}
void setupRadio()
  // set default props
  const int channel = 12;
  const uint64_t pipe = 0xFFFFFFFFFLL;
```

```
// setup radio
  radio.begin();
  radio.setChannel(channel);
  radio.setDataRate(RF24_250KBPS);
  radio.setPALevel(RF24_PA_MIN);
  radio.openWritingPipe(pipe);
void setupSensors()
  // setup light sensors
  Wire.begin();
  lightSensor.begin(BH1750::ONE_TIME_HIGH_RES_MODE);
  // setup temperature sensor
  temperatureSensor.begin();
void loop()
  // read light data
  float lightValue = (float)lightSensor.readLightLevel();
  SensorData light = { LIGHT_SENSOR_ID, lightValue };
  Serial.print("Light: ");
  Serial.print(lightValue);
  Serial.println(" lx");
  // read temperature data
  temperatureSensor.requestTemperatures();
  float temperatureValue = (float)temperatureSensor.getTempCByIndex(0);
  SensorData temperature = { TEMPERATURE_SENSOR_ID, temperatureValue };
  Serial.print("Temperature: ");
  Serial.print(temperatureValue);
  Serial.println(" C");
  // send data via radio
  SensorData sendPackage[] = { light, temperature };
  radio.write(&sendPackage, sizeof(sendPackage));
  Serial.println("Sending data...\n");
  // delay process
  delay(5000);
```