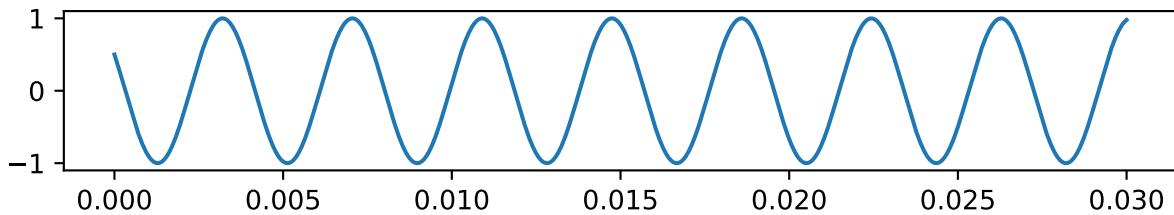
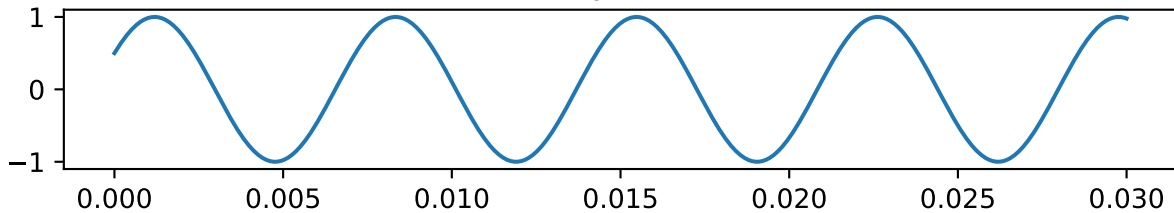


$x(t)$, $y(t)$ and $z(t)$

$x(t)$



$y(t)$



$z(t)$

