x(t), y(t) and z(t)x(t) 1 0 -10.030 0.000 0.005 0.010 0.015 0.020 0.025 y(t) 0 0.010 0.015 0.025 0.000 0.005 0.020 0.030 z(t) 1 0 0.005 0.010 0.020 0.025 0.030 0.015 0.000