view frames Result Recorded at time: 1702410946.205079 world Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default\_authority Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base\_link\_inertia base Broadcaster: default authority Average rate:  $6\overline{0}.12$ Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 shoulder link Broadcaster: default authority Average rate: 60.12 Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 upper\_arm\_link Broadcaster: default authority Average rate:  $6\overline{0}.12$ Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 forearm\_link Broadcaster: default authority Average rate:  $6\overline{0}.12$ Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 wrist 1 link Broadcaster: default authority Average rate:  $6\overline{0}.12$ Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 wrist\_2\_link Broadcaster: default authority Average rate: 60.12 Buffer length: 4.99 Most recent transform: 1141.02 Oldest transform: 1136.03 wrist\_3\_link Broadcaster: default authority Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 ft\_frame flange Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 tool0 Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 robotiq\_85\_base\_link Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate:  $6\overline{0}.12$ Average rate:  $6\overline{0}.12$ Average rate:  $6\overline{0}.12$ Average rate:  $6\overline{0}.12$ Buffer length: 4.99 Buffer length: 4.99 Buffer length: 4.99 Buffer length: 4.99 Most recent transform: 1141.02 Most recent transform: 1141.02 Most recent transform: 1141.02 Most recent transform: 1141.02 Oldest transform: 1136.03 Oldest transform: 1136.03 Oldest transform: 1136.03 Oldest transform: 1136.03 robotiq\_85\_left\_knuckle\_link robotiq\_85\_right\_knuckle\_link robotiq 85 left inner knuckle link robotiq\_85\_right\_inner\_knuckle\_link Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Broadcaster: default authority Average rate:  $6\overline{0}.12$ Average rate:  $6\overline{0}.12$ Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.99 Buffer length: 4.99 Most recent transform: 1141.02 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1141.02 Oldest transform: 0.0 Oldest transform: 1136.03 Oldest transform: 1136.03 Oldest transform: 0.0 robotiq\_85\_left\_finger\_link robotiq\_85\_right\_finger\_tip\_link robotiq\_85\_right\_finger\_link robotiq 85 left finger tip link