

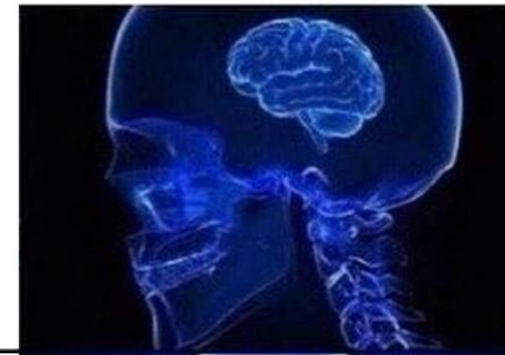
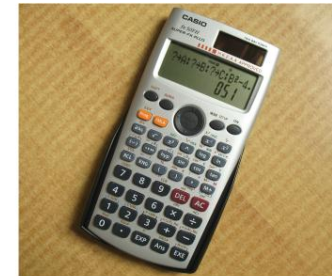
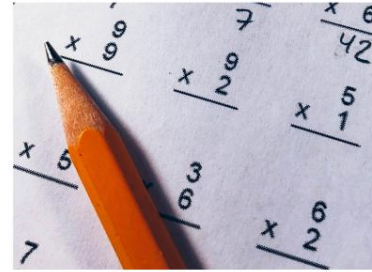
MATH2221

Mathematics Laboratory II

Lecture 11: Calculus and Optimization Using MATLAB

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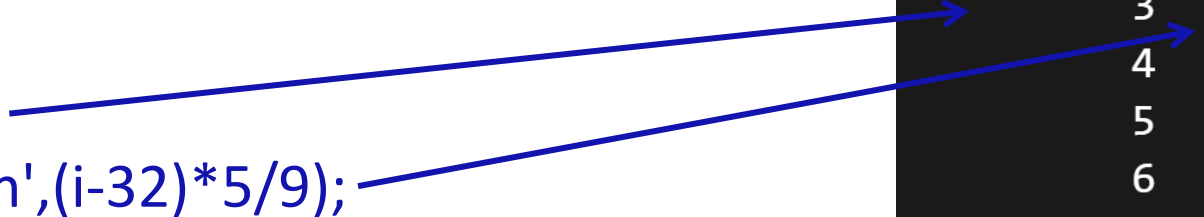


Recall: Reading/writing files and path/file management

- Reading/writing files with specific data format
 - `fopen`, `fprintf`, `fscanf`, `fclose`
 - Easily specify number of spaces/ decimal places

- Example:

```
fprintf(datafile,'%11i',i);  
fprintf(datafile,'%11.5f\n',(i-32)*5/9);
```



	Fahrenheit	Celsius
	0	-17.77778
	1	-17.22222
	2	-16.66667
	3	-16.11111
	4	-15.55556
	5	-15.00000
	6	-14.44444
	7	-13.88889
	8	-13.33333
	9	-12.77778
	10	-12.22222
	11	-11.66667
	12	-11.11111

- Path/file management
 - Change current directory:
 - `cd('newfolderpath')` , `cd('..')` , ...
 - Show all files in the current directory
 - `dir`, `dir *.txt`, ...
 - Include/exclude folders from your path:
 - `addpath`, `rmpath`

Recall: Image processing in MATLAB

- Reading an image: **imread**
- Writing an image: **imwrite**
- Displaying an image:
 - **imshow**
 - **imshowpair**
- Image type conversion:
 - **rgb2gray**
 - **imbinarize**
- Image editing:
 - **imresize**, **imcrop**, **imadjust**, **imrotate**, **imwarp**



Recall: Video processing in MATLAB

- Reading a video:
`v = VideoReader(filename)`
- Reading a frame:
 - `read(v,i)`
 - `hasFrame`, `readFrame`
- Writing a video:
 - `v = VideoWriter(filename,profile)`
`open(v)`
`writeVideo(v,...)`
`close(v)`



Calculus using MATLAB

- MATLAB can be used (and is indeed **very powerful**) for Calculus!
- **Differentiation**
 - Approximating derivatives and gradients
- **Integration**
 - Integrating numeric data
 - Integrating functional expressions
- **Differential equations**
 - Solving differential equations
 - Solving systems of differential equations

Differentiation using MATLAB

- **Difference operator:** $Y = \text{diff}(X)$
 - Calculates differences between adjacent elements of X
 - i.e. $Y = [X(2) - X(1), X(3) - X(2), \dots, X(m) - X(m-1)]$
 - If $\text{length}(X) = m$, then $\text{length}(Y) = m - 1$

Example:

```
>> X = [0,1,4,9,16];
```

```
>> Y = diff(X)
```

```
Y =
```

```
    1    3    5    7
```

- **Computing the n-th difference:** $Y = \text{diff}(X,n)$
 - i.e. $\text{diff}(X,2) = \text{diff}(\text{diff}(X))$ and so on

Example:

```
>> X = [0,1,4,9,16];
```

```
>> Y = diff(X,2)
```

```
Y =
```

```
    2    2    2
```

Differentiation using MATLAB

- **Approximate derivatives:** $Y = \text{diff}(f)/h$

- f : some function values evaluated over some domain X
- h : step size

- Example: For $f(x) = \sin x$, compute $f'(x)$, $f''(x)$

$h = 0.01$; % step size

$X = -\pi:h:\pi$; % domain

$f = \sin(X)$; % the function values

$Y = \text{diff}(f)/h$; % first derivative

$Z = \text{diff}(Y)/h$; % second derivative

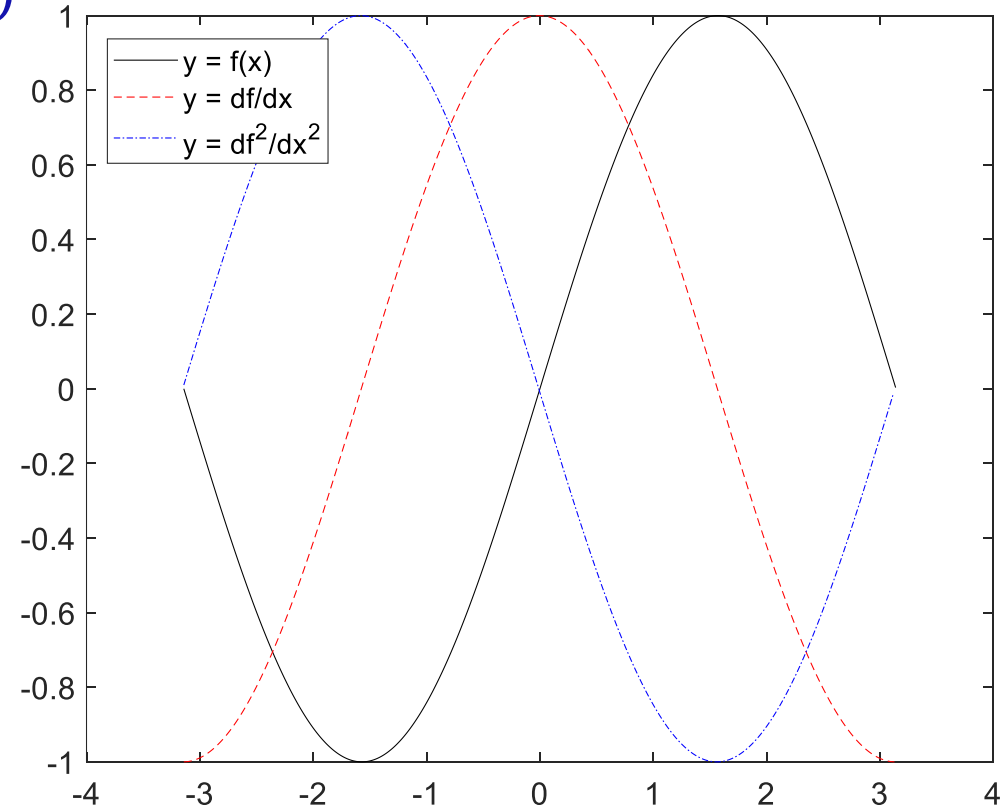
figure;

plot(X,f,'k-');hold on;

plot(X(:,1:length(Y)),Y,'r--');

plot(X(:,1:length(Z)),Z,'b-.');

legend('y = f(x)', 'y = df/dx', 'y = df^2/dx^2');



Differentiation using MATLAB

- **Gradient operator:** `gradient`
 - `[FX,FY] = gradient(F)`
 - F: a matrix
 - FX, FY: the partial derivatives $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$

- **Example:**

```
[X,Y] = meshgrid(0:0.2:2*pi, 0:0.2:2*pi);
```

```
Z = sin(X).*sin(Y);
```

```
[FX,FY] = gradient(Z);
```

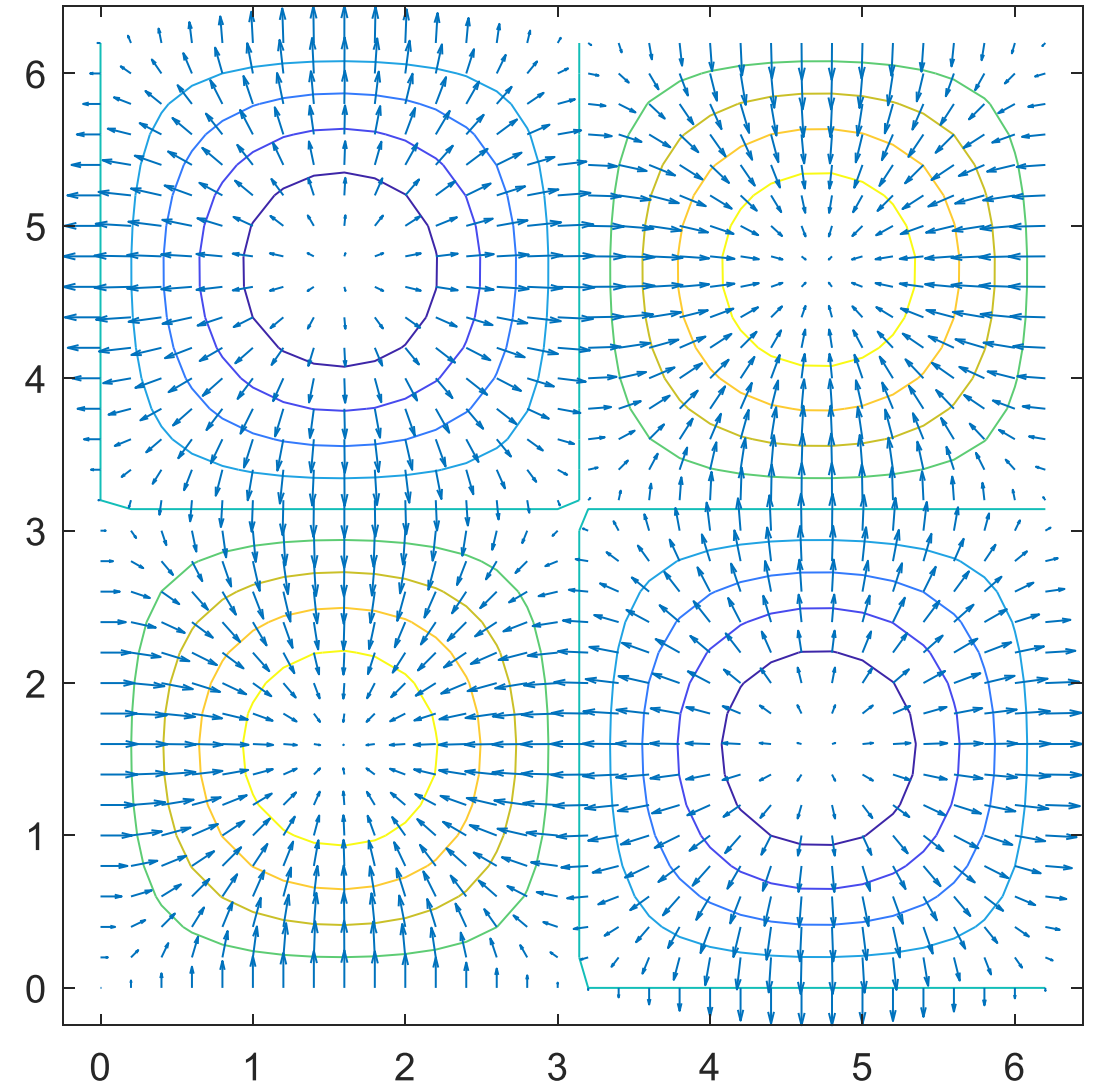
```
figure;
```

```
contour(X,Y,Z);
```

```
hold on;
```

```
quiver(X,Y,FX,FY);
```

```
axis equal
```



- More general command: `[FX,FY,FZ,...,FN] = gradient(F,hx,hy,...,hN)`

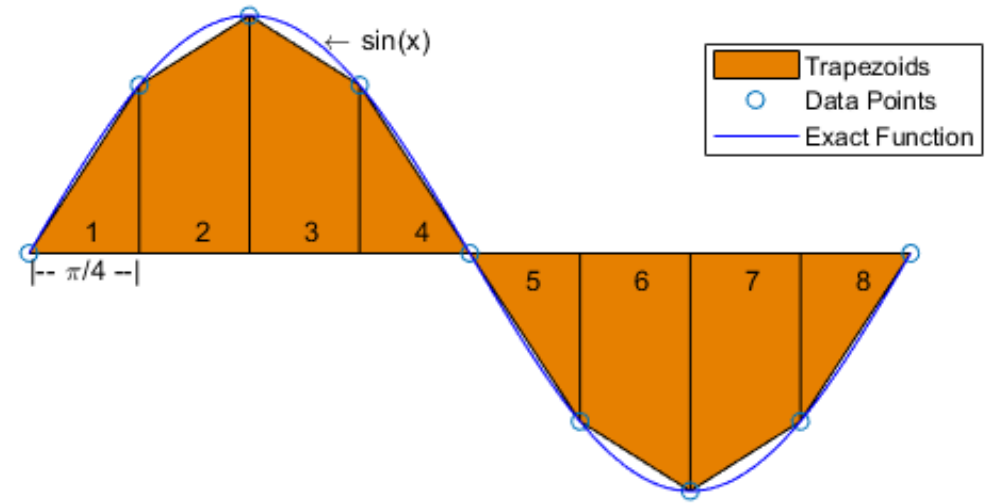
Integration using MATLAB

- Integrating **numeric data**: **trapz**
 - Trapezoidal numerical integration

$$\int_a^b f(x) \approx \frac{1}{2} \sum_{n=1}^N \Delta x_n (f(x_n) + f(x_{n+1}))$$

where $a = x_1 < x_2 < \dots < x_{N+1} = b$ and $\Delta x_n = x_{n+1} - x_n$

- MATLAB commands:
 - **Q = trapz(Y)**: computes the approximate integral of Y with unit spacing
 - i.e. $Y = [f(x_1), f(x_2), \dots, f(x_{N+1})]$ and $\Delta x_n = 1$ for all n
 - **Q = trapz(X,Y)**: integrates Y with respect to the spacing specified by X
 - i.e. $Y = [f(x_1), f(x_2), \dots, f(x_{N+1})]$ and $X = [x_1, x_2, \dots, x_{N+1}]$



Integration using MATLAB

- Example: Integrate $f(x) = x^2$ in the domain $[0,5]$.

```
>> Y = [0, 1, 4, 9, 16, 25];
```

```
>> Q = trapz(Y)
```

```
Q =
```

```
42.5000
```

(Actual: $\left[\frac{x^3}{3}\right]_0^5 \approx 41.6667$)

- Example: Integrate $f(x) = \sin x$ from 0 to π

```
>> X = 0:pi/100:pi;
```

```
>> Y = sin(X);
```

```
>> Q = trapz(X,Y)
```

```
Q =
```

```
1.9998
```

(Actual: $[-\cos x]_0^\pi = 2$)

Integration using MATLAB

- We can also integrate **functional expressions**
- MATLAB command: **q = integral(fun,xmin,xmax)**
 - fun: a functional expression defined using a *function handle* (@(x) ...) or a *function file* (.m)
 - xmin: lower limit
 - xmax: upper limit
 - can also handle improper integral
- Example: $\int_0^1 \sin(\cos(\tan x)) dx$
>> f = @(x) sin(cos(tan(x)));
>> q = integral(f,0,1)
q =
0.6596
- Example: $\int_0^\infty e^{-x^4} (\ln x)^3 dx$
>> f = @(x) exp(-x.^4).*log(x).^3;
>> q = integral(f,0,Inf)
q =
-5.9905

Integration using MATLAB

- **Double integral:** $q = \text{integral2}(\text{fun}, \text{xmin}, \text{xmax}, \text{ymin}, \text{ymax})$
 - Similar to the 1D case
 - xmin, xmax must be scalar
 - ymin, ymax can be scalar or **function handle of x**
- Example: Integrate $f(x, y) = \frac{\sin x + \cos y}{\sqrt{x^2 + y^2 + 1}}$ over the triangular region bounded by $0 \leq x \leq 1$ and $0 \leq y \leq 1 - x$.

```
>> f = @(x,y) (sin(x) + cos(y))./sqrt(x.^2+y.^2+1);  
>> ymax = @(x) 1-x;  
>> q = integral2(f,0,1,0,ymax)  
q =  
    0.5388
```
- **Triple integral:** $q = \text{integral3}(\text{fun}, \text{xmin}, \text{xmax}, \text{ymin}, \text{ymax}, \text{zmin}, \text{zmax})$
 - Similar to the 2D case, where ymin, ymax can be function handles (of x) and zmin, zmax can be function handles (of x and y)

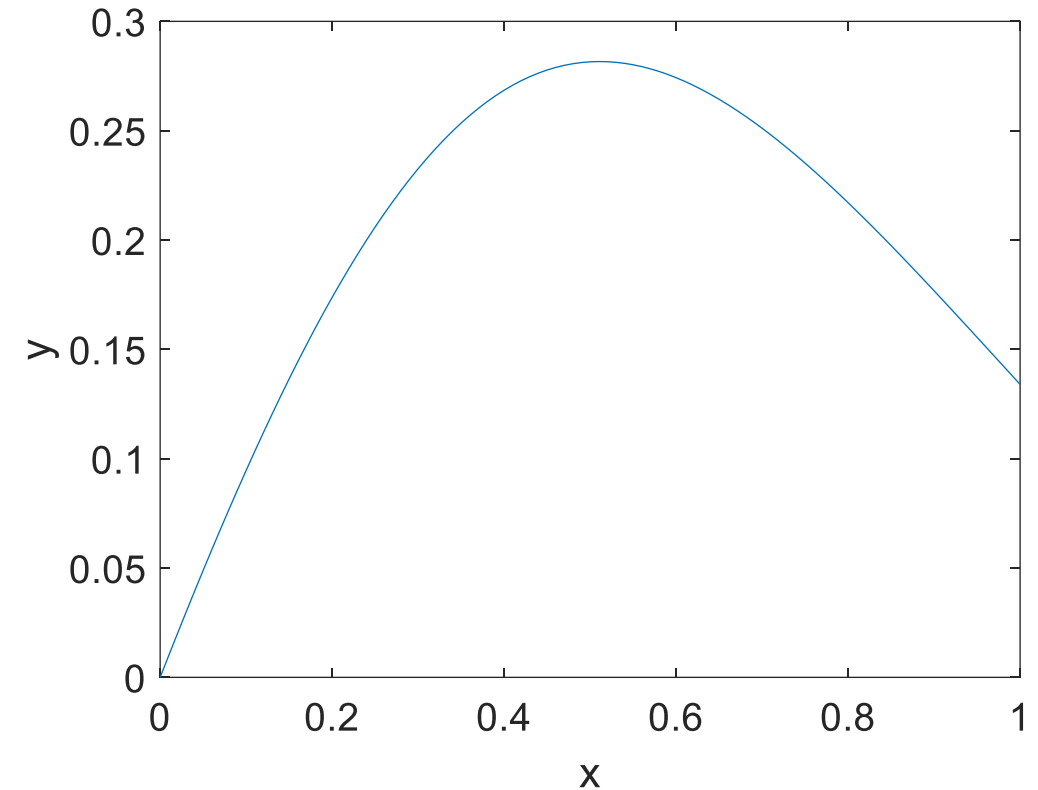
Solving differential equations using MATLAB

- Basic idea:
 - Replace derivatives with **finite difference**
 - $y'(x_n) \approx \frac{y_{n+1} - y_n}{h}$ (forward difference)
 - $y'(x_n) \approx \frac{y_n - y_{n-1}}{h}$ (backward difference)
 - $y'(x_n) \approx \frac{y_{n+1} - y_{n-1}}{2h}$ (central difference)
 - Then solve the differential equation using linear algebra methods and/or iterative schemes
- Example: Solve $\frac{dy}{dx} = f(x, y) = 2x - 3xe^y + 1$ with $y(0) = 0$
 - Using forward difference, we have
$$\frac{y_{n+1} - y_n}{h} = 2x_n - 3x_n e^{y_n} + 1 \Rightarrow y_{n+1} = y_n + h(2x_n - 3x_n e^{y_n} + 1)$$
which can be computed using a for-loop

Solving differential equations using MATLAB

- Example:

```
y = zeros(1,101);  
x = linspace(0,1,101);  
h = 0.01;  
for n = 1:100  
    y(n+1) = y(n)+h*(2*x(n) - 3*x(n)*exp(y(n))+1);  
end  
figure;  
plot(x,y);  
xlabel('x')  
ylabel('y')
```

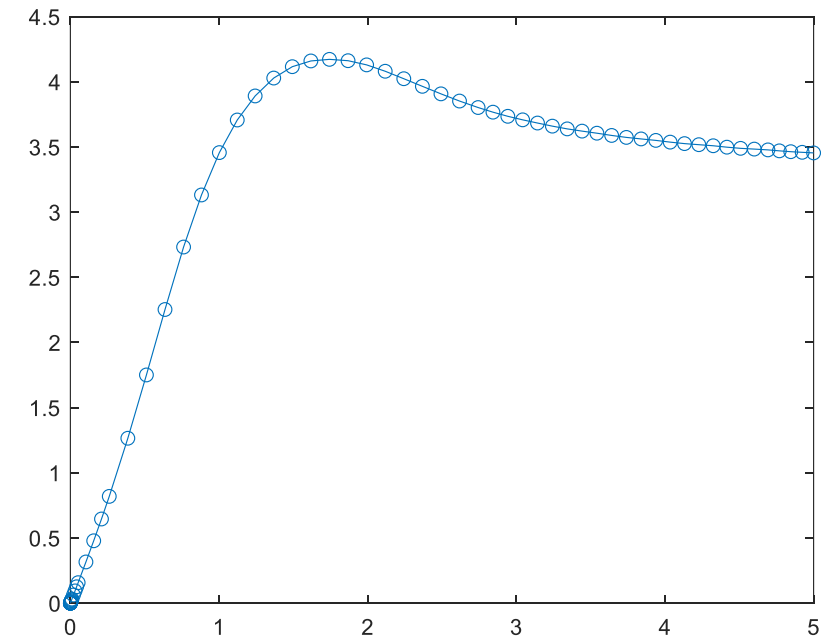


- Remark:

- For backward difference, we have $\frac{y_n - y_{n-1}}{h} = f(x_n, y_n)$
- May not be able to express y_n in terms of x_n, y_{n-1} explicitly
- In this case, we may need to solve a matrix equation using `\` or solve a nonlinear equation using `fsolve` or `fzero`

Solving differential equations using MATLAB

- A very powerful **ODE solver** in MATLAB: **ode45**
 - Solve $\frac{dy}{dt} = f(t, y)$ with $y(t_0) = y_0$
 - Based on a type of *Runge-Kutta* methods (see MATH3230 and 3240)
- MATLAB command: **[t,y] = ode45(odefun,tspan,y0)**
 - odefun: function handle or function file for $f(t, y)$
 - tspan: [t0, tf], where t0 is the starting point and tf is the ending point
 - y0: the initial condition (i.e. $y(t_0) = y_0$)
- Example: Solve $y' = 2t \sin y + 3$
in the time interval [0,5] with $y_0 = 0$
>> **[t,y] = ode45(@(t,y) 2*t*sin(y)+3, [0,5], 0);**
>> **figure;**
>> **plot(t,y,'-o');**



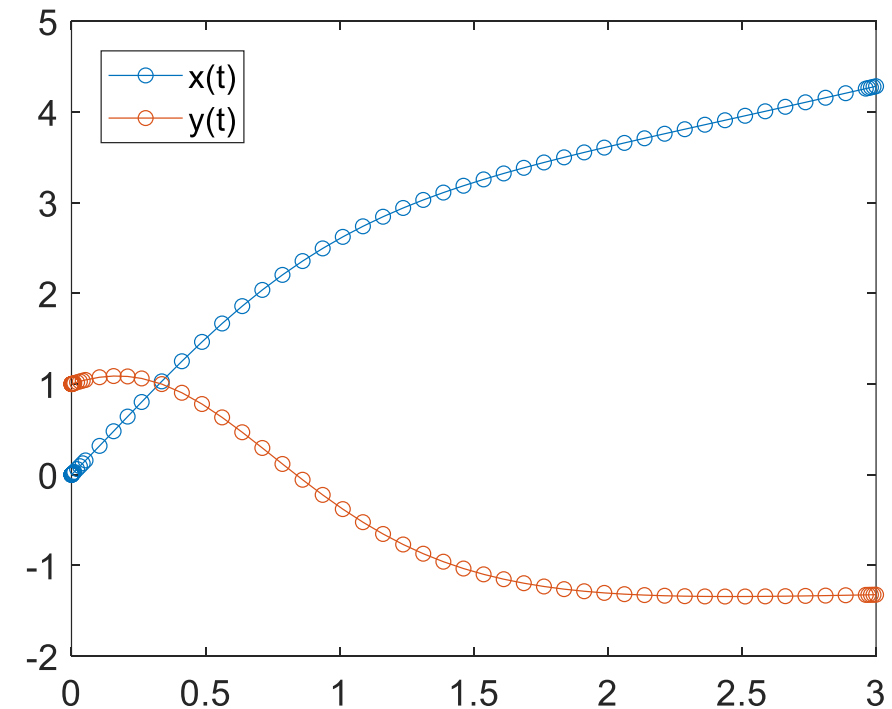
Solving differential equations using MATLAB

- Note: **ode45** can also solve **systems of ODEs**
 - In **[t,y] = ode45(odefun,tspan,y0)**, use a vector for odefun and y0

- Example: Solve
$$\begin{cases} x'(t) = y(t) + 2 \\ y'(t) = (1 - x(t))y(t) - x(t) \end{cases}$$
 with $x(0) = 0, y(0) = 1$ in the time interval $[0,3]$

```
[t,y] = ode45(@ (t,y) [y(2)+2; ...  
                    (1-y(1))*y(2)-y(1)], [0,3], [0;1]);
```

```
figure;  
plot(t,y,'-o');  
legend('x(t)','y(t)')
```



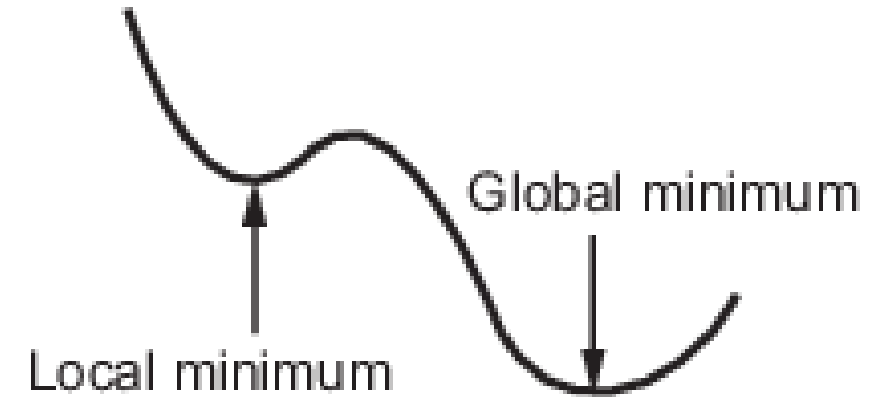
Solving differential equations using MATLAB

- What about high-order ODE/ODE systems?
 - Try to rewrite them as first-order ODE systems
 - Then use **ode45**
- Example: $y'' + p(t)y' + q(t)y = r(t)$
 - Let $y_1(t) = y$, $y_2(t) = y'$
 - Then we have
$$\begin{cases} y_1' = y_2 \\ y_2' = r(t) - p(t)y_2 - q(t)y_1 \end{cases}$$
 - *a first-order ODE system!*
- More generally, every **n -th order linear ODE** can be rewritten as a **system of n first-order ODEs**

Optimization using MATLAB

- We can use MATLAB to solve various **optimization problems!**

- **Unconstrained** optimization
- **Constrained** optimization



- Remarks:
 - Similar to many numerical optimization schemes, MATLAB optimization solvers are typically based on gradient descent
 - They typically return **a local minimum** but not necessarily the global minimum

fminbnd: single-variable optimization problem on a fixed interval

- Find a (local) minimum of a single-variable function on a fixed interval

$$\min_x f(x) \quad \text{with} \quad x_1 < x < x_2$$

- MATLAB command: `[x,fval] = fminbnd(fun,x1,x2)`

- fun: Function to minimize
- x1: Lower bound
- x2: Upper bound
- x: the solution x
- fval: the value of the objective function at x

- Example: Minimize $x^3 - e^x$ in (0,1)

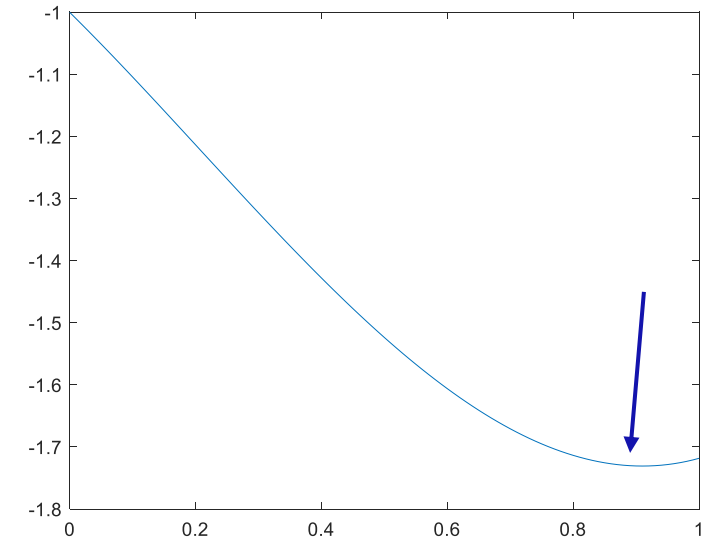
`f = @(x) x^3 - exp(x);`

`[x,fval] = fminbnd(f,0,1)`

`x =`
0.9100 `fval =`
-1.7308

- More generally, we have `x = fminbnd(fun,x1,x2,options)`

- options: control the displayed information, maximum number of iterations, etc.
- e.g. `options = optimset('Display','iter','MaxIter',20);`



fminunc: Unconstrained optimization of multivariable function

- Find the minimum of a multivariable function without constraints

$$\min_{x_1, x_2, \dots, x_n} f(x_1, x_2, \dots, x_n)$$

- MATLAB command: `[x,fval] = fminunc(fun,x0)`
 - fun: Function to minimize
 - x0: the initial guess (a vector with the size being the number of variables in f)
 - x: the solution x (a vector)
 - fval: the value of the objective function at x
- Example: Minimize $f(x_1, x_2) = 3x_1^2 + 2x_1x_2 + x_2^2 - 4x_1 + 5x_2$

```
f = @(x)3*x(1)^2 + 2*x(1)*x(2) + x(2)^2 - 4*x(1) + 5*x(2);
```

```
x0 = [1,1]; % initial guess
```

```
[x,fval] = fminunc(f,x0)
```

```
x =
```

```
2.2500 -4.7500
```

```
fval =
```

```
-16.3750
```

fminunc: Unconstrained optimization of multivariable function

- More generally, we have $[x, fval] = \text{fminunc}(\text{fun}, x0, \text{options})$
 - As in fminbnd, we can use options to control the displayed information, maximum number of iterations, etc.
 - e.g. `options = optimset('Display','iter','MaxIter',20);`
- Additionally, we can **specify the gradient** to improve the optimization process
 - Use a function file (.m) to create **fun** with *both the function and the gradient*
 - Set `options = optimoptions('fminunc', 'SpecifyObjectiveGradient', true)`

- Example: $f(x_1, x_2) = x_1^2 + x_2 + 100 \sin x_1 x_2$

Step 1: create a function

```
function [f,g] = myfun(x)
```

```
% the objective function f
```

```
f = x(1)^2 + x(2) + 100*sin(x(1)*x(2));
```

```
% the gradient g
```

```
g = [2*x(1) + 100*x(2)*cos(x(1)*x(2));  
     1 + 100*x(1)*cos(x(1)*x(2))];
```

```
end
```

Step 2: run fminunc

```
>> x0 = [0,1];
```

```
>> fun = @myfun;
```

```
>> options = optimoptions('fminunc', ...  
    'SpecifyObjectiveGradient', true);
```

```
>> [x,fval] = fminunc(fun,x0,options)
```

```
x =
```

```
    -0.9205    1.6947
```

```
fval =
```

```
   -97.4521
```

fmincon: Constrained optimization of multivariable function

- Find minimum of constrained nonlinear multivariable function

$$\min_x f(x) \text{ such that } \begin{cases} c(x) \leq 0 \\ ceq(x) = 0 \\ A \cdot x \leq b \\ Aeq \cdot x = beq \\ lb \leq x \leq ub, \end{cases}$$

- MATLAB command: `[x,fval] = fmincon(fun,x0,A,b,Aeq,beq,lb,ub,nonlcon,options)`
 - Can set the inputs as `[]` if they are not applicable

- Example: Minimize $f(x_1, x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$ with $x_1 + 2x_2 \leq 1$

`fun = @(x)100*(x(2)-x(1)^2)^2 + (1-x(1))^2;`

`x0 = [-1,2];`

`A = [1,2];`

`b = 1;`

`[x, fval] = fmincon(fun,x0,A,b)`

`x =`

0.5022 0.2489

`fval =`

0.2489

Reminder: Lab 9 this week

January

Sun	Mon	Tue	Wed	Thu	Fri	Sat
			1	2	3	4
5	6	7	8	9	10	11
12	13	14	15	16	17	18
19	20	21	22	23	24	25
26	27	[28]	[29]	[30]	[31]	

February

Sun	Mon	Tue	Wed	Thu	Fri	Sat
						[1]
[2]	[3]	4	5	6	7	8
9	10	11	12	13	14	15
16	17	18	19	20	21	22
23	24	25	26	27	28	1



**Lecture 1-
Lecture 13**



**Lab 1 - Lab 10
(40%)**

March

Sun	Mon	Tue	Wed	Thu	Fri	Sat
2	[3]	[4]	[5]	[6]	[7]	[8]
9	10	11	12	13	14	15
16	17	18	19	20	21	22
23	24	25	26	27	28	29
30	31					

April

Sun	Mon	Tue	Wed	Thu	Fri	Sat
		1	2	3	4	5
6	7	8	9	10	11	12
13	14	15	16	17		



**Test 1 (30%)
Test 2 (30%)**

Thank you!

Next time:

- Symbolic computation using MATLAB