

**LAB REPORT**

**ENGINEERING LABORATORY**

**ENGR 1204, FALL 2022**

**Laboratory Exercise #7**

**Laboratory Name: Benchtop Pulse Width  
Modulation**

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**Lab Partner: Janoy Johnson**

**Lab Partner: Matthew Walkey**

**Date of Lab Exercise: 11/01/22**



**WENTWORTH**  
Institute of Technology

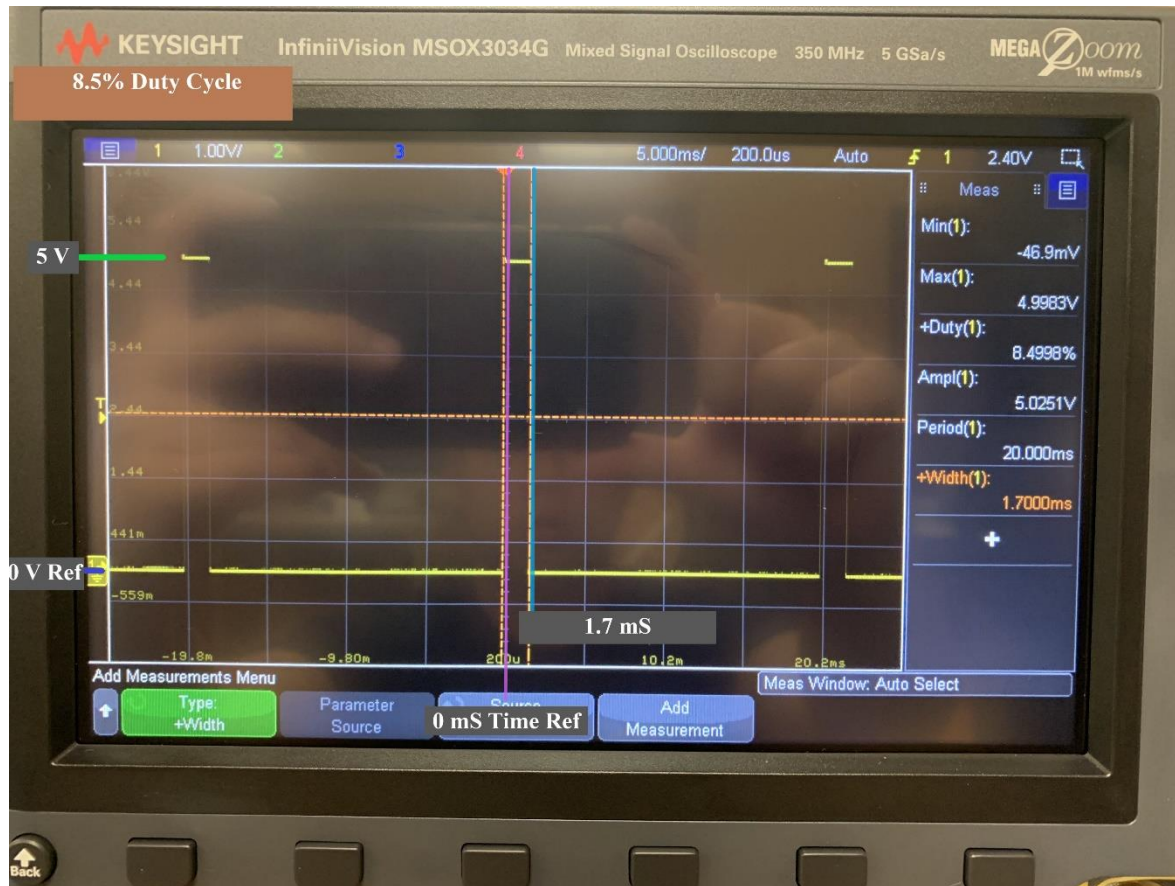
**Objective:** This lab tests a servo motor's rotation as different values of Pulse width and duty cycle percentage is inputted. Max and minimum rotation is recorded from both the clockwise and counterclockwise direction. Pulse width and data cycle is also recorded for values when the servo motor does not rotate. All duty cycle values inputted are within the servo motor's Pulse width range of 1.3 milliseconds to 1.7 milliseconds.

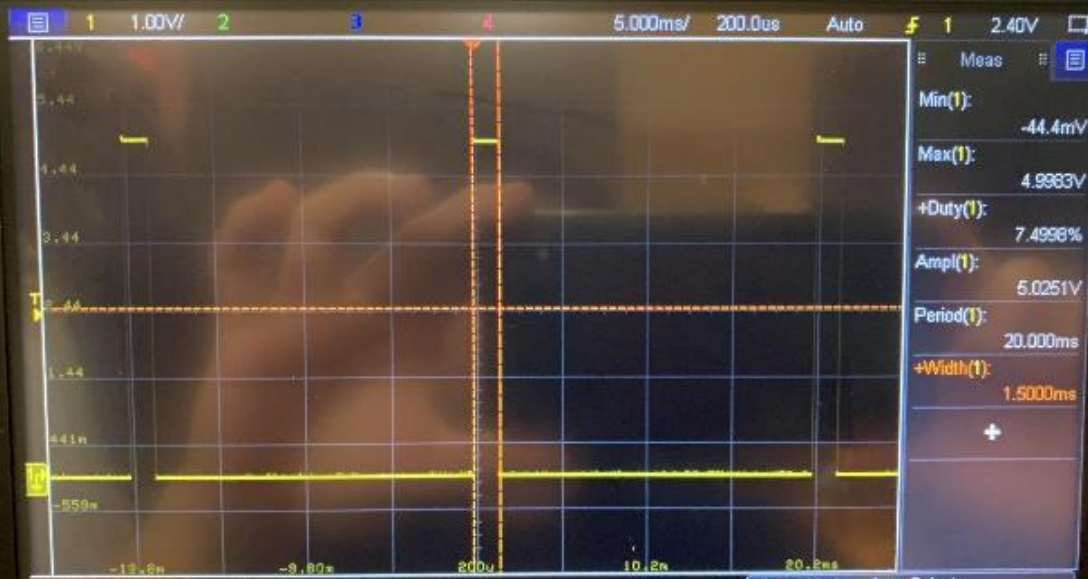
**Procedure & Results:** A servo motor's speed and direction of rotation is tested through various duty cycle percentages and pulse widths using a Waveform Generator and Oscilloscope.

Motor Behavior	Duty Cycle (%)	PW (ms)
Max Clockwise Rotation	6.5%	1.3 <del>ms</del>
Slow Clockwise Rotation	7.4%	1.480 <del>ms</del>
Stopped (no rotation)	7.5%	1.5 <del>ms</del>
Slow Counterclockwise Rotation	7.6%	1.520 <del>ms</del>
Max Counterclockwise Rotation	8.5%	1.7 <del>ms</del>

The servo motor did not rotate at 7.5%; knowing this, values close to this percentage were inputted to get slow clockwise and counterclockwise rotation. A duty cycle of 7.4% was tested to get the slow clockwise rotation. 7.6% was inputted which resulted in the duty cycle for the slow counterclockwise rotation. Max clockwise rotation was just the minimum allowed duty cycle (6.5%) of the servo motor. The max counterclockwise rotation was the maximum allowed duty

cycle (8.5%) of the servo motor.

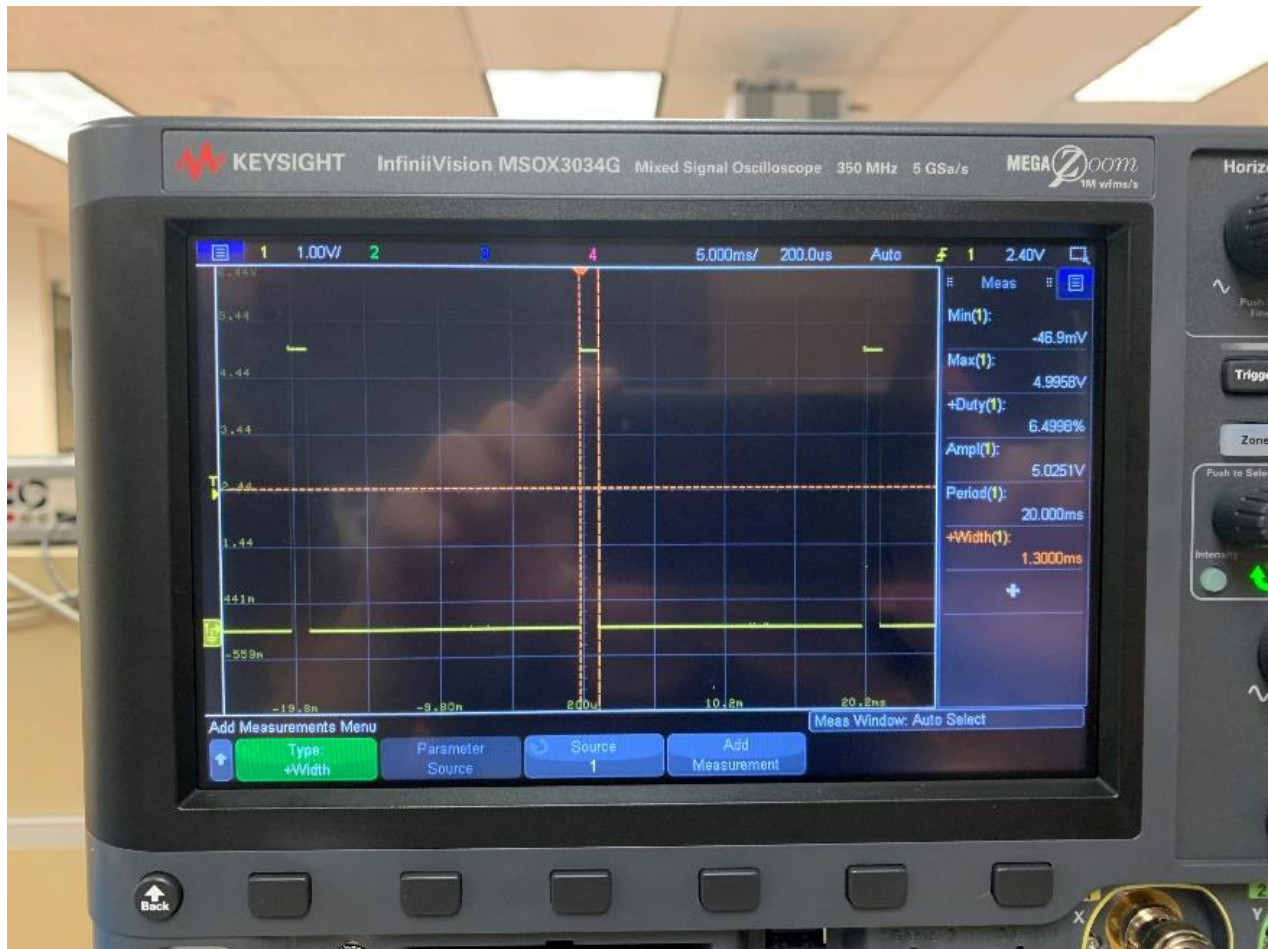




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**Summary:** This lab successfully shows the different types of rotations of a servo motor using different pulse widths values within the servo motor's range. Initially, there was difficulty properly setting up the oscilloscope because the minimum and maximum voltage values of the square wave did not match the set-up instructions. It was later known that the noise of the oscilloscope machine was what made the signal less accurate. It was only when we applied a setting on the oscilloscope that helped to stabilize the minimum and maximum values.