# 1 Numerical Methods for ODEs

Consider the initial value problem of ordinary differential equation, f(t, u) is continuous on area  $G: 0 \le t \le T$ ,  $|u| < \infty$ , u = u(t) satisfy the equation

$$\begin{cases} \frac{du}{dt} = f(t, u), & 0 < t \le T, \\ u(0) = 0. \end{cases}$$

generally, f satisfy Lipschitz condition:  $|f(t, u_1) - f(t, u_2)| \leq L|u_1 - u_2|$ .

# 1.1 Euler Method

Euler method scheme:

$$u_{n+1} = u_n + h f(t_n, u_n)$$

$$\begin{cases} \frac{du}{dt} = t^2 + t - u, & t \in [0, 1] \\ u(0) = 0. \end{cases}$$

```
1 % Euler1.m
2 % Euler method for the ODE model
3 \% u'(t) = t^2 + t - u, t \sin [0,1]
4 % Initial condition : u(0)=0;
5 % Exact solution : u(t) = -\exp(-t) + t^2 - t + 1.
6 clear all
_{7} h=0.1;
8 x=0:h:1;
                                    % function interval
9 n=length(x)-1;
10 u(1) = 0;
                                    % initial value
11 fun=@(t,u) t.^2+t-u;
                                    % RHS
12 for i=1:n
       u(i+1)=u(i)+h.*fun(x(i),u(i));
15 ue=-exp(-x)+x.^2-x+1;
                                    % exact solution
16 plot(x,ue,'b-',x,u,'r+','LineWidth',1.5)
17 xlabel('x', 'fontsize', 16), ylabel('y', 'fontsize', 16, 'Rotation', 0)
18 legend('Exact ','Numerical','location','North')
19 title('Euler Method', 'fontsize', 14)
20 set(gca,'fontsize',14)
```

# 1.2 Modified Euler Method

Modified Euler method scheme:

$$u_{n+1} = u_n + \frac{h}{2} [f(t_n, u_n) + f(t_{n+1}, u_{n+1})]$$

$$\begin{cases} \frac{du}{dt} = t^2 + t - u, & t \in [0, 1] \\ u(0) = 0. \end{cases}$$

```
1 % Euler2.m
2 % Modified Euler method for the ODE model
3 \% u'=t^2+t-u, t \sin [0,1]
4 % Initial condition : u(0)=0
5 % Exact solution : u(t) = -\exp(-t) + t^2 - t + 1.
6 clear all
_{7} h=0.1;
8 x=0:h:1;
                                % function interval
9 n=length(x)-1;
u(1) = 0;
                               % initial value
11 fun=@(t,u) t.^2+t-u;
                               % RHS
12 for i=1:n
      k1=fun(x(i),u(i));
      k2=fun(x(i+1),u(i)+h*k1);
      u(i+1)=u(i)+(h/2)*(k1+k2);
16 end
17 ue=-exp(-x)+x.^2-x+1;
                            % exact solution
18 plot(x,ue,'b-',x,u,'r+','LineWidth',1.5)
19 xlabel('x', 'fontsize', 16), ylabel('y', 'fontsize', 16, 'Rotation', 0)
20 legend('Exact','Numerical','location','North')
21 title('Modified Euler Method', 'fontsize', 14)
22 set(gca,'fontsize',14)
```

# 1.3 Runge-Kutta Method

Runge-Kutta method scheme:

$$\begin{cases} u_{n+1} = u_n + \frac{h}{6} (k_1 + 2k_2 + 2k_3 + k_4) \\ k_1 = f (t_n, u_n) \\ k_2 = f \left( t_n + \frac{h}{2}, u_n + \frac{1}{2} k_1 \right) \\ k_3 = f \left( t_n + \frac{h}{2}, u_n + \frac{1}{2} k_2 \right) \\ k_4 = f (t_n + h, u_n + k_3) \end{cases}$$

$$\begin{cases} \frac{du}{dt} = t^2 + t - u, & t \in [0, 1] \\ u(0) = 0. \end{cases}$$

```
1 % RungeKutta.m
2 % Runge-Kutta method for the ODE model
3 \% u'=t^2+t-u, t \sin [0,1]
4 % Initial condition : u(0)=0
5 % Exact : u(t) = -\exp(-t) + t^2 - t + 1.
6 clear all
_{7} h=0.1;
s x=0:h:1;
                             % function interval
9 n=length(x)-1;
u(1) = 0;
                             % initial value
11 fun=@(t,u) t.^2+t-u;
                             % RHS
12 for i=1:n
      k1 = fun(x(i), u(i));
       k2=fun(x(i)+h./2,u(i)+h.*k1/2);
      k3=fun(x(i)+h./2,u(i)+h.*k2/2);
       k4 = fun(x(i) + h, u(i) + h. *k3);
       u(i+1)=u(i)+h.*(k1+2.*k2+2.*k3+k4)./6;
17
19 ue=-exp(-x)+x.^2-x+1;
                             % exact solution
20 plot(x,ue,'b-',x,u,'r+','LineWidth',1.5)
21 xlabel('x', 'fontsize', 16), ylabel('y', 'fontsize', 16, 'Rotation', 0)
22 legend('Exact','Numerical','location','North')
23 title('Runge-Kutta Method','fontsize',14)
24 set(gca,'fontsize',14)
```

The general s-stage Runge-Kutta method for the problem

$$y' = f(x, y), \quad y(a) = \eta, \quad f: \mathbb{R} \times \mathbb{R}^m \to \mathbb{R}^m$$

is defined by

(I) 
$$\begin{cases} y_{n+1} = y_n + h \sum_{i=1}^s b_i k_i \\ k_i = f(x_n + c_i h, y_n + h \sum_{j=1}^s a_{ij} k_j), & i = 1, 2, \dots, s \end{cases}$$

Assume that the following (the row-sum condition) holds

$$c_i = \sum_{j=1}^{s} a_{ij}, \quad i = 1, 2, \dots, s$$

It is convenient to display the coefficients as a Butcher array:

$$c = [c_1, c_2, \dots, c_s]^T, \quad b = [b_1, b_2, \dots, b_s]^T, \quad A = (a_{ij})_s$$

(II) 
$$\begin{cases} y_{n+1} = y_n + h \sum_{i=1}^{s} b_i f(x_n + c_i h, Y_i) \\ Y_i = y_n + h \sum_{j=1}^{s} a_{ij} f(x_n + c_j h, Y_j), & i = 1, 2, \dots, s \end{cases}$$

The forms (I) and (II) are seen to be equivalent if we make the interpretation

$$k_i = f(x_n + c_i h, Y_i), \quad i = 1, 2, \dots, s$$

Implicit Runge-Kutta Method (Gauss Method) 2 stage order 4:

(I) 
$$\begin{cases} y_{n+1} = y_n + \frac{1}{2} (K_1 + K_2), & n = 0, 1, \dots, N - 1, \\ K_1 = hf \left( t_n + (\frac{1}{2} - \frac{\sqrt{3}}{6})h, y_n + \frac{1}{4}K_1 + (\frac{1}{4} - \frac{\sqrt{3}}{6})K_2 \right), \\ K_2 = hf \left( t_n + (\frac{1}{2} + \frac{\sqrt{3}}{6})h, y_n + (\frac{1}{4} + \frac{\sqrt{3}}{6})K_1 + \frac{1}{4}K_2 \right). \end{cases}$$

Butcher array

$$\begin{array}{c|ccccc}
\frac{1}{2} - \frac{\sqrt{3}}{6} & \frac{1}{4} & \frac{1}{4} - \frac{\sqrt{3}}{6} \\
\frac{1}{2} + \frac{\sqrt{3}}{6} & \frac{1}{4} + \frac{\sqrt{3}}{6} & \frac{1}{4} \\
& \frac{1}{2} & \frac{1}{2}
\end{array}$$

(II) 
$$\begin{cases} y_{n+1} = y_n + h \sum_{i=1}^{2} b_i f(x_n + c_i h, Y_i), \\ Y_1 = y_n + h \sum_{j=1}^{2} a_{1j} f(x_n + c_j h, Y_j), \\ Y_2 = y_n + h \sum_{j=1}^{2} a_{2j} f(x_n + c_j h, Y_j), \end{cases}$$

$$\begin{cases} \frac{du}{dt} = u, & t \in [0, 1] \\ u(0) = 1. \end{cases}$$

```
1 % IRK2s_error.m
2 % Implicit Runge-Kutta (Gauss method) 2 stage and order 4
3 \% u'=u in [0,1] with initial condition <math>u(0)=1
4 % exact solution: ue=exp(x)
5 clear all
6 Nvec=[10 50 100 200 500 1000];
7 Err=[];
8 for n=1:length(Nvec)
       N=Nvec(n); h=1/N;
       x=[0:h:1];
       u(1)=1;
11
       X0 = [1; 1];
12
       % Newton iteration
       for i=1:N
           k=u(i);
15
           r=X0; tol=1;
           while tol>1.0e-6
17
               X=r;
               D=[1-0.25*h, -h*(0.25-(sqrt(3))/6);...
19
               -h*(0.25+(sqrt(3))/6),1-h*0.25]; % Jacobian matrix
20
               F = [X(1) - k - h * (0.25 * X(1) + (0.25 - (sqrt(3))/6) * X(2)); ...
               X(2)-k-h*((0.25+(sqrt(3))/6)*X(1)+0.25*X(2))]; % RHS
22
               r=X-D\setminus F;
23
               tol=norm(r-X);
24
           end
25
           k1=r(1); k2=r(2);
26
           u(i+1)=k+(h/2)*(k1+k2);
       end
28
                               % exact solution
       ue=exp(x);
       err=max(abs(u-ue)); % maximum error
30
       Err=[Err,err];
31
32 end
33 plot(log10(Nvec),log10(Err),'ro-','MarkerFaceColor','w','LineWidth',1.5)
34 hold on,
35 plot(log10(Nvec), log10(Nvec.^(-4)), '--')
36 grid on,
37 xlabel('log_{10}N', 'fontsize', 16), ylabel('log_{10}Error', 'fontsize', 16)
38 title('Convergence order of Gauss method ','fontsize',14)
39 set(gca,'fontsize',14)
40 for i=1:length(Nvec)-1
                             % computating convergence order
       order(i) = -log(Err(i)/Err(i+1))/(log(Nvec(i)/Nvec(i+1)));
42 end
43 Err
44 order
```