



## Compilation Principle 编译原理

第22讲: 代码优化(2)

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#### Review Questions

 Q1: Code optimizations are to generate better code, list some 'better' metrics.

Execution time, memory usage, energy, binary size...

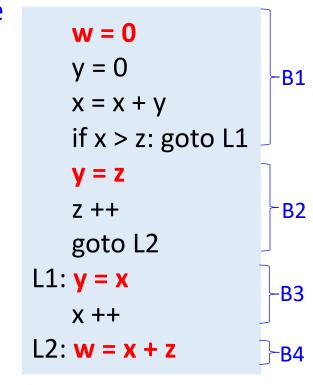
- Q2: what is a Basic Block?
   A straight-line sequence of code with only one entry point and only one exit.
- Q3: how to partition code into BBs? Identify leader insts; a BB consists of a leader inst and subsequent insts before next leader.
- Q4: What is a control-flow graph?
   A directed graph where nodes are BBs, edges show flow of execution between BBs.
- Q5: What is the CFG of the listed code?

**B3** 

B1

**B4** 

**B2** 







#### Local and Global Optimizations

- Local optimizations[局部优化]
  - Optimizations performed exclusively within a basic block
  - Typically the easiest, never consider any control flow info
    - All instructions in scope executed exactly once
  - Examples:
    - □ constant folding[常量折叠]
    - □ common subexpression elimination[删除公共子表达式]
- Global optimizations[全局优化]
  - Optimizations performed across basic blocks
    - Scope can contain if / while / for statements
    - Some insts may not execute, or even execute multiple times
  - Note: global here doesn't mean across the entire program
    - We usually optimize one function at a time





#### ## Local Optimization: Examples

- Common subexpression elimination[删除公共子表达式]
  - Two operations are common if they produce the same result
    - □ It is likely more efficient to compute the result once and reference it the second time rather than re-evaluate it[避兔重复计算]
- Dead code elimination[删除无用代码]
  - If an instruction's result is never used, the instruction is considered "dead" and can be removed from the instruction stream[结果从不使用]

$$y = x + z;$$

$$y = x + z;$$

$$t_1 = x * x$$

$$t_2 = x / 3$$

$$y = t_1 + t_2$$

$$t_3 = x * x$$

$$z = t_3 + y;$$

$$y = x + z;$$

$$t_1 = x * x$$

$$t_2 = x / 3$$

$$y = t_1 + t_2$$

$$t_3 = x * x$$

$$z = t_1 + y;$$





#### DAG of Basic Blocks

• Many important techniques for local optimization begin by transforming a BB into a DAG (directed acyclic graph)[ 无环有向图]

- To construct a DAG for a BB as follows
  - Create a node for each of the initial values of the variables appearing in the BB[为变量初始值创建节点,叶子]
  - Create a node N associated with each statement s within the block[为声明语句创建节点,中间]
    - The children of N are those nodes corresponding to statements that are the last definitions, prior to s, of the operands used by s
    - □ Label N by the operator applied at s[用运算符标注节点]
  - Certain nodes are designated output nodes[某些为输出节点]
    - These are the nodes whose variables are <u>live on exit</u> from the block (i.e., their values may be used later, in another block of the flow graph)





#### Example: DAG

- (3) c = b + c
  - b refers to the node labelled '-'
    - Most recent definition of b

• 
$$(4) d = a - d$$

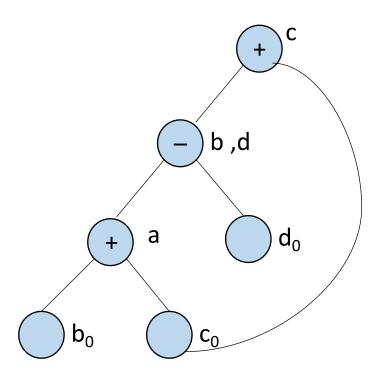
- Operator and children are the same as the 2<sup>nd</sup> statement
  - Reuse the node

$$(1) a = b + c$$

$$(2) b = a - d$$

$$(3) c = b + c$$

$$(4) d = a - d$$







#### Local Opt.: Elimination

- If b is not live on exit from the block
  - No need to keep b = a d
- If both b and d are live
  - Remove either (2) or (4):common subexpr elimination
  - Add a 4<sup>th</sup> statement to copy one to the other
- If only a is live on exit
  - Then remove nodes from the DAG correspond to dead code

$$-c -> b, d -> d_0$$

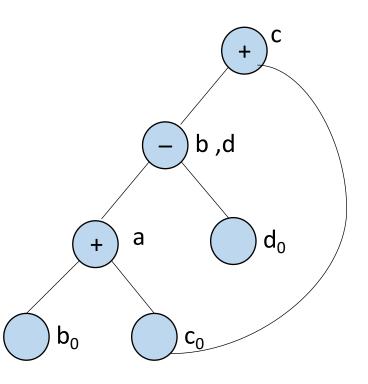
This is actually dead code
 elimination

$$(1) a = b + c$$

$$(2) b = a - d$$

$$(3) c = b + c$$

$$(4) d = a - d$$







## Local Opt.: Elimination (cont.)

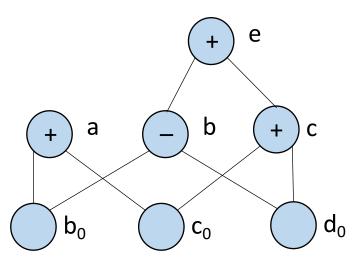
- When finding common subexprs, we really are finding exprs that are guaranteed to compute the same value, no matter how that value is computed[过于严苛]
  - Thus miss the fact that (1) and (4)
     are the same

$$b + c = (b - d) + (c + d) = b_0 + c_0$$

• **Solution**: algebraic identities[代数 恒等式]

(1) 
$$a = b + c$$
  
(2)  $b = b - d$   
(3)  $c = c + d$ 

$$(4) e = b + c$$







#### Local Opt.: Algebraic Identities[代数恒等式]

- Eliminate computations by applying mathematical rules[ 使用数学规则]
  - Identities:  $a * 1 \equiv a$ ,  $a * 0 \equiv 0$ ,  $b \& true \equiv b$
  - Reassociation and commutativity[重组合、交换]

```
a = (a + b) + c = a + (b + c), a + b = b + a
```

- Strength Reduction[强度削减]
  - Replacing expensive operations (multiplication, division) by less expensive operations (add, sub, shift)
  - Some ops can be replaced with cheaper ops
  - Examples

```
x=y/8 --> x=y > 3
```

$$y=y*8 --> x=y*3$$

$$2 * x --> x + x$$





#### Local Opt.: Constant Folding[常量折叠]

#### Constant Folding

- Computing operations on constants at compile time
- Example:

```
#define LEN 100
x = 2 * LEN;
if (LEN < 0) print("error");</pre>
```

After constant folding

```
x = 200;
if (false) print("error");
```

- Dead code elimination can further remove the above if statement
- Inherently local since scope limited to statement



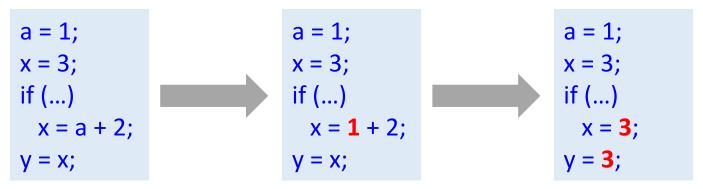


#### Local Opt.: Constant Propagation[常量传播]

#### Constant Propagation

- Substituting values of known constants at compile time
- Local Constant Propagation (LCP)

- Some optimizations have both local and global versions
  - Global Constant Propagation (GCP)



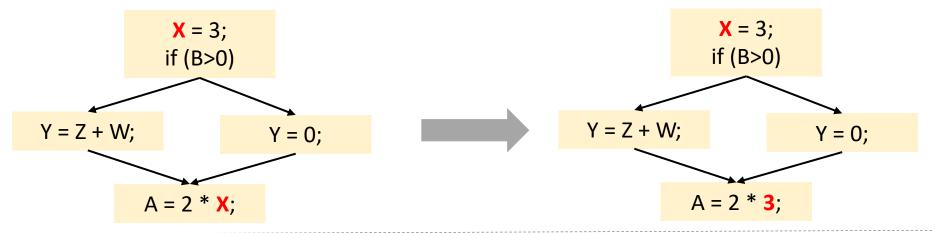
- GCP more powerful than LCP but also more complicated
  - Must determine x is constant across all paths reaching x

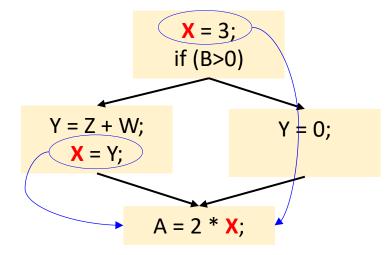




#### ## Global Optimizations

- Extend optimizations to flow of control, i.e. CFG
  - Along all paths, the last assignment to X is "X=C"
  - Optimization must be stopped if incorrect in even one path









#### Global Opt.: Conservative[需保守]

- Compiler must prove some property X at a particular point
  - Need to prove at that point property X holds along all paths
  - Need to be conservative to ensure correctness
    - An optimization is enabled only when X is definitely true
    - If not sure if it is true or not, it is safe to say don't know
    - If analysis result is don't know, no optimization done
    - May lose opt. opportunities but guarantees correctness
- Property X often involves data flow of program
  - E.g. Global Constant Propagation (GCP):

```
X = 7;
...
```

Y = X + 3; // Does value of 7 flow into this use of X?

- Needs knowledge of data flow, as well as control flow
  - Whether data flow is interrupted between points A and B





#### Global Opt.: Data Flow[数据流]

- Most optimizations rely on a property at given point
  - For Global Constant Propagation (GCP):

```
A = B + C; // Property: {A=?, B=10, C=?}
```

After optimization:

$$A = 10 + C;$$

- For this discussion, let's call these properties values
- Dataflow analysis: compiler analysis that calculates values for each point in a program
  - Values get propagated from one statement to the next
  - Statements can modify values (for GCP, assigning to vars)
  - Requires CFG since values flow through control flow edges
- Dataflow analysis framework: a framework for dataflow analysis that guarantees correctness for all paths
  - Does not traverse all possible paths (could be infinite)
  - To be feasible, makes **conservative** approximations





## Global Constant Propagation (GCP)

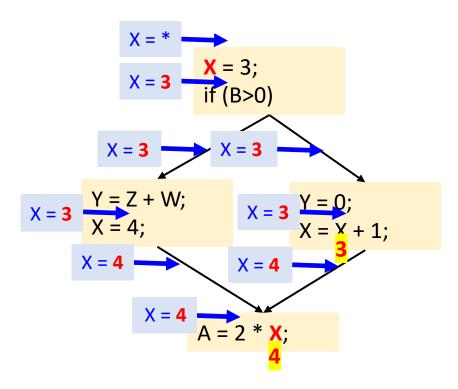
- Let's apply dataflow analysis to compute values for GCP
  - Emulates what human does when tracing through code
- Let's use following notation to express the state of a var:
  - x=\*: not assigned (default)
  - -x=1, x=2, ...: assigned to a constant value
  - x=#: assigned to multiple values
- All values start as x=\* and are iteratively refined
  - Until they stabilize and reach a fixed point
- Once fixed point is reached, can replace with constants:
  - x=\*: replace with any constant (typically 0)
  - -x=1, x=2, ...: replace with given constant value
  - x=#: cannot do anything





## Example

- In this example, constants can be propagated to X+1, 2\*X
- Statements visited in reverse postorder (predecessor first)



x=\*: not assigned (default)

x=1, x=2, ...: assigned to a constant value

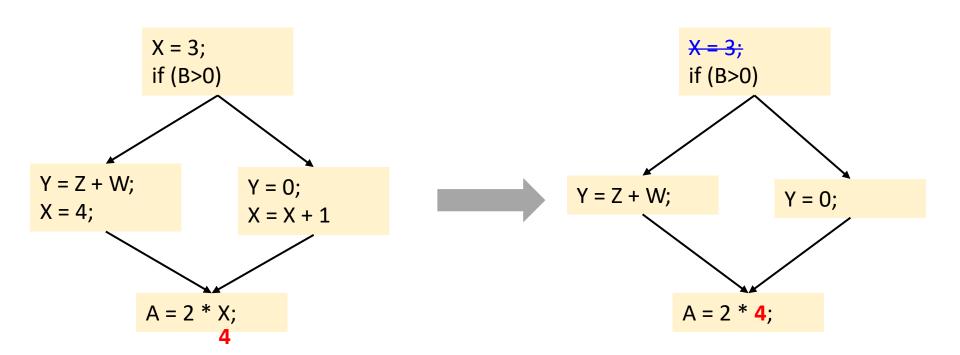
x=#: assigned to multiple values





## Example (cont.)

 Once constants have been globally propagated, we would like to eliminate the dead code







#### Machine Optimizations[机器相关优化]

- After performing IR optimizations
  - We need to further convert the optimized IR into the target language (e.g. assembly, machine code)
- Specific machines features are taken into account to produce code optimized for the particular architecture[考虑特定的架构特性]
  - E.g., specialized instructions, hardware pipeline abilities, register details
- Typical machine optimizations[典型的优化方案]
  - Instruction selection and scheduling: select insts to implement the operators in IR
  - Register allocation: map values to registers and manage
  - Peephole optimization: locally improve the target code





#### Instruction Selection[指令选取]

- To find an efficient mapping from the IR of a program to a target-specific assembly listing[IR到汇编的映射]
- Instruction selection is particularly important when targeting architectures with CISC (e.g., x86)
  - In these architectures there are typically several possible implementations of the same IR operation, each with different properties
  - e.g., on x86 an addition of one can be implemented by an inc, add, or lea instruction





#### Instruction Scheduling[指令调度]

- Some facts
  - Instructions take clock cycles to execute (latency)
  - Modern machines issue several operations per cycle (Out-of-Order execution)
  - Cannot use results until ready, can do something else
  - Execution time is order-dependent
- Goal: reorder the operations to minimize execution time
  - Minimize wasted cycles
  - Avoid spilling registers
  - Improve locality



(Now C=y; can execute while waiting for A=x\*y;)



#### Register Allocation[寄存器分配]

- In TAC, there are an unlimited number of variables
  - On a physical machine there are a small number of registers
- Register allocation is the process of assigning variables to registers and managing data transfer in and out of registers
  - How to assign variables to finitely many registers?
  - What to do when it can't be done?
  - How to do so efficiently?
- Using registers intelligently is a critical step in any compiler
  - Accesses to memory are costly, even with caches
  - A good register allocator can generate code orders of magnitude better than a bad register allocator





## Register Allocation (cont.)

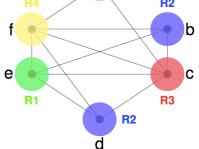
- Goals of register allocation
  - Keep frequently accessed variables in registers
  - Keep variables in registers only as long as they are live
- Local register allocation[局部]
  - Allocate registers basic block by basic block
  - Makes decisions on a per-block basis (hence 'local')
- Global register allocation[全局]
  - Makes global decisions about register allocation such that
    - Var to reg mappings remain consistent across blocks
    - Structure of CFG is taken into account on decisions
- Three well-known register allocation algorithms
  - Graph coloring allocator[图着色]
  - Linear scan allocator[线性扫描]
  - LP (Integer Linear Programming) allocator[整数线性规划]





#### Graph Coloring[图着色]

- Register interference graph (RIG)[相交图]
  - Each node represents a variable
  - An edge between two nodes V₁ and V₂ represents an interference in live ranges[活跃期/生存期]
- Based on RIG,
  - Two variables can be allocated in the same register if there is no edge between them[若无边相连,可使用同一寄存器]
  - Otherwise, they cannot be allocated in the same register
- Problem of register allocation maps to graph coloring
  - Once solved, k colors can be mapped back to k registers
  - If the graph is k-colorable, it's k-register-allocatable





#### Register Spilling[寄存器溢出]

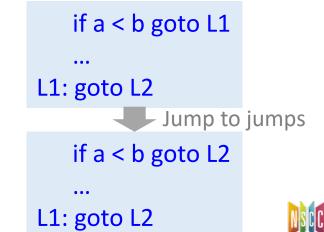
- Determining whether a graph is k-colorable is NP-complete
  - Therefore, problem of k-register allocation is NP-complete
  - In practice: use heuristic polynomial algorithm that gives close to optimal allocations most of the time
  - Chaitin's graph coloring is a popular heuristic algorithm
     E.g. most backends of GCC use Chaitin's algorithm
- What if k-register allocation does not exist?
  - Spill a variable to memory to reduce RIG and try again
  - Spilled var stays in memory and is not allocated a reg
- Spilling is slow
  - Placed into memory, loaded into register when needed, and written back to memory when no longer used





#### Peephole Optimization[窥孔优化]

- Optimization ways
  - Usual: produce good code through careful inst selection and register allocation
  - Alternative: generate naïve target code and then improve
- A simple but effective technique for locally improving the target code[很局部的优化,但可能带来性能的极大提升]
  - Done by examining a sliding window of target instructions (called peephole) and replacing instruction sequences within the peephole by a shorter or faster sequence, whenever psbl
  - Can also be applied directly after IR generation to improve IR
- Example transformations
  - Redundant-instruction elimination
  - Flow-of-control optimizations
  - Algebraic simplifications
  - Use of machine idioms





#### Summary[总结]

- Code can be optimized at different levels with various techniques
  - IR: local, global, common subexpression elimination, constant folding and propagation, ...
  - Target: instruction, register, peephole, ...
- Interactions between the various optimization techniques
  - Some transformations may expose possibilities for others
  - One opt. may obscure or remove possibilities for others
- Affect of compiler opts are intertwined and hard to separate
  - Finding optimal opt combinations is in itself research
  - Compilers package opts that typically go together into levels (e.g -O1, -O2, -O3)





# The END is Near

## 期末考试

- 编译原理
  - 课堂参与(10%) 点名、提问、测试
  - 课程作业 (20%) 4次左右, 理论
  - 期中考查 (10%) 课下习题
  - 期末考试 (60%) 闭卷
- 果下习题 [1次练习]

- 考试时间
  - 14:30-16:30
  - 7月8日(周四)

- 题目类型
  - 判断题
  - 简答题
  - 应用题
  - 综合应用题

• 主要内容

[3次测试]

- 词法分析
- 语法分析
- 语义分析
- 代码生成及优化

[2次作业] 参考答案已上传





#### Exam should NOT be the END ...

Front-end (15x2学时) Back-end (7x2学时) Talk (2x2学时) Intro+Review (2x2学时)

期末考试分值分布

科研/工作相关性





