view_frames Result

Recorded at time: 1556798191.155

map

Broadcaster: /ekf_se_odom
Average rate: 30.010 Hz
Most recent transform: 1556798191.082 (0.073 sec old)
Buffer length: 4.798 sec

Broadcaster: /initialize_origin
Average rate: 1.250 Hz
Most recent transform: 1556798190.834 (0.321 sec old)
Buffer length: 4.000 sec

odom

map__identity

Broadcaster: /encoder_noder
Average rate: 20.216 Hz
Most recent transform: 1556798191.131 (0.024 sec old)
Buffer length: 4.848 sec

base_link

Broadcaster: /baselink_to_chassis_broadcaster
Average rate: 10.174 Hz
Most recent transform: 1556798191.163 (-0.008 sec old)
Buffer length: 4.718 sec

chassis

Broadcaster: /chassis_to_pointcloud_broadcaster
Average rate: 10.157 Hz
Most recent transform: 1556798191.227 (-0.071 sec old)
Buffer length: 4.923 sec

Broadcaster: /chassis_to_gps_broadcaster
Average rate: 10.165 Hz
Most recent transform: 1556798191.193 (-0.038 sec old)
Buffer length: 4.820 sec

Broadcaster: /chassis_to_imu_broadcaster
Average rate: 10.180 Hz
Most recent transform: 1556798191.191 (-0.036 sec old)
Buffer length: 4.814 sec

pointcloud_frame

gps

imu

Broadcaster: /pointcloud_to_kinect_broadcaster
Average rate: 10.174 Hz
Most recent transform: 1556798191.216 (-0.061 sec old)
Buffer length: 4.816 sec

kinect2_rgb_optical_frame