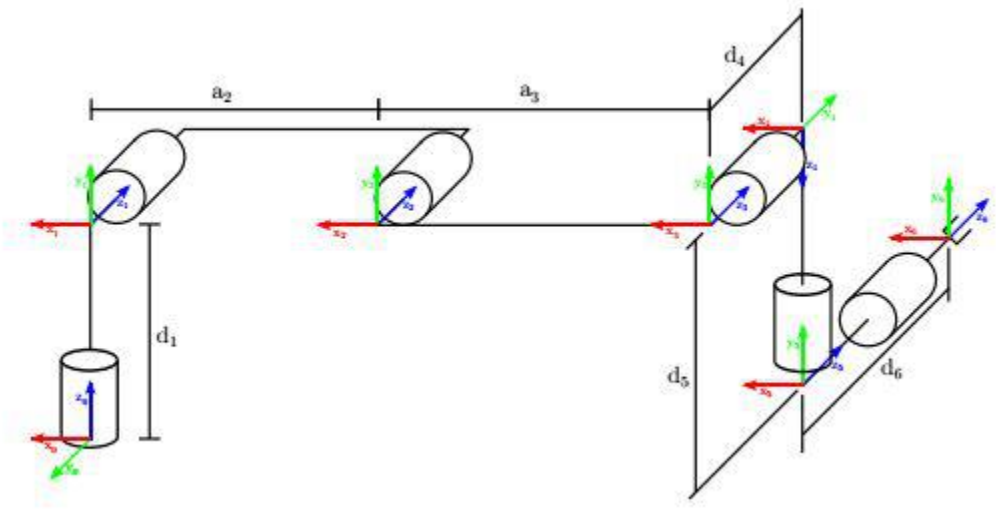
1、CR 5 建模



2、CR 5_Modified DH

	Theta[rad]	a[m]	d[m]	Alpha[rad]
Joint1	0	0	d1 = 0.147	0
Joint2	-π/2	0	0	π/2
Joint3	0	a2 = -0.427	0	0
Joint4	-π/2	a3 = -0.357	d4 = 0.141	0
Joint5	0	0	d5 = 0.116	π/2
Joint6	0	0	d6 = 0.104.5	-π/2

3、CR 5_Standard DH

	Theta[rad]	a[m]	d[m]	Alpha[rad]
Joint1	0	0	d1 = 0.147	π/2
Joint2	-π/2	a2 = -0.427	0	0
Joint3	0	a3 = -0.357	0	0
Joint4	-π/2	0	d4 = 0.141	π/2
Joint5	0	0	d5 = 0.116	-π/2
Joint6	0	0	d6 = 0.104.5	0