# COMP 3711 Course Notes

# Design and Analysis of Algorithms

LIN, Xuanyu

ALGORITHMS

 $\operatorname{COMP}$ 3711 Design and Analysis of Algorithms



September 13, 2023



## 1 Asymptotic Notation

```
Upper Bounds T(n) = O(f(n)) if exist constants c > 0 and n_0 \ge 0 such that for all n \ge n_0, T(n) \le c \cdot f(n). Lower Bounds T(n) = \Omega(f(n)) if exist constants c > 0 and n_0 \ge 0 such that for all n \ge n_0, T(n) \ge c \cdot f(n). Tight Bounds T(n) = \Theta(f(n)) if T(n) = O(f(n)) and T(n) = \Omega(f(n)). Note: Here "=" means "is", not equal.
```

# 2 Introduction - The Sorting Problem

#### 2.1 Selection Sort

```
Algorithm 1: Selection Sort

Input: An array A[1...n] of elements

Output: Array A[1...n] of elements in sorted order (asending)

for i \leftarrow 1 to n - 1 do

for j \leftarrow i + 1 to n do

if A[i] > A[j] then

| swap A[i] and A[j]
| end
| end
| end
```

```
Running Time: \frac{n(n-1)}{2}
Best-Case = Worst-Case: T(n) = \Theta(\frac{n(n-1)}{2}) = \Theta(n^2)
```

## 2.2 Insertion Sort

```
Algorithm 2: Insertion Sort

Input: An array A[1...n] of elements

Output: Array A[1...n] of elements in sorted order (asending)

for i \leftarrow 2 to n do

 \begin{vmatrix} j \leftarrow i - 1 \text{ while } j \geq 1 \text{ and } A[j] > A[j+1] \text{ do} \\ | \text{swap } A[j] \text{ and } A[j+1] \end{vmatrix} 
end
 \begin{vmatrix} j \leftarrow j - 1 \\ \text{end} \\ | \text{end} \end{vmatrix}
```

```
Running Time: Depends on the input array, ranges between (n-1) and \frac{n(n-1)}{2} Best-Case: T(n) = n-1 = \Theta(n) (Useless) Worst-Case: T(n) = \Theta(\frac{n(n-1)}{2}) = \Theta(n^2) (Commonly-Used) Average-Case: T(n) = \Theta(\sum_{i=2}^n \frac{i-1}{2}) = \Theta(\frac{n(n-1)}{4}) = \Theta(n^2) (Sometimes Used)
```

## 2.3 Wild-Guess Sort

Running Time: Depends on the random generation, could be faster than the insertion sort.

### 2.4 Worst-Case Analysis

The algorithm's worst case running time is  $O(f(n)) \implies On$  all inputs of (large) size n, the running time of the algorithm is  $\leq c \cdot f(n)$ .



## Algorithm 3: Wild-Guess Sort

**Input:** An array A[1...n] of elements

**Output:** Array A[1...n] of elements in sorted order (asending)

 $\pi \leftarrow [4,7,1,3,8,11,5,...]$  Create random permutation Check if  $A[\pi[i]] \leq A[\pi[i+1]]$  for all i=1,2,...,n-1 If yes, output A according to  $\pi$  and terminate else Insertion - Sort(A)

The algorithm's worst case running time is  $\Omega(f(n)) \Longrightarrow$  There exists at least one input of (large) size n for which the running time of the algorithm is  $\geq c \cdot f(n)$ .

Thus, Insertion sort runs in  $\Theta(n^2)$  time.

#### Notice

Selection sort, insertion sort, and wild-guess sort all have worst-case running time  $\Theta(n^2)$ . How to distinguish between them?

- Closer examination of hidden constants
- Careful analysis of typical expected inputs
- Other factors such as cache efficiency, parallelization are important
- Empirical comparison

## Stirling's Formula

Prove that  $\log(n!) = \Theta(n \log n)$ 

First  $\log(n!) = O(n \log n)$  since:

$$\log(n!) = \sum_{i=1}^{n} \log i \le n \times \log n = O(n \log n)$$

Second  $\log(n!) = \Omega(n \log n)$  since:

$$\log(n!) = \sum_{i=1}^{n} \log i \ge \sum_{i=n/2}^{n} \log i \ge n/2 \times \log n/2 = n/2(\log n - \log 2) = \Omega(n \log n)$$

Thus,  $\log(n!) = \Theta(n \log n)$ 



# 3 Divide & Conquer

Main idea of D & C: Solve a problem of size n by breaking it into one or more smaller problems of size less than n. Solve the smaller problems recursively and combine their solutions, to solve the large problem.

## 3.1 Binary Search

```
Example: Binary Search
Input: A sorted array A[1,...,n], and an element x
Output: Return the position of x, if it is in A; otherwise output nil
Idea of the binary search: Set q \leftarrow middle of the array. If x = A[q], return q. If x < A[q], search A[1,...,q-1], else search A[q+1,...,n].
```

#### Algorithm 4: Binary Search

```
Input: Array A[1...n] of elements in sorted order BinarySearch(A[], p, r, x) (p, r being the left & right iteration, x being the element being searched) if p > r then return nil end q \leftarrow [(p+r)/2] if x = A[q] then return q end if x < A[q] then BinarySearch(A[], p, q-1, x) end else BinarySearch(A[], q+1, r, x) end
```

```
Recurrence of the algorithm, supposing T(n) being the number of the comparisons needed for n elements: T(n) = T(\frac{n}{2}) + 2 if n > 1, with T(1) = 2. \implies T(n) = 2\log_2 n + 2 \implies O(\log n) algorithm
```

## Example: Binary Search in Rotated Array

Suppose you are given a sorted array A of n distinct numbers that has been rotated k steps, for some unknown integer k between 1 and n-1. That is, A[1...k] is sorted in increasing order, and A[k+1...n] is also sorted in increasing order, and A[n] < A[1].

Design an  $O(\log n)$ -time algorithm that for any given x, finds x in the rotated sorted array, or reports that it does not exist.

#### Algorithm:

First conduct a  $O(\log n)$  algorithm to find the value of k, then search for the target value in either the first part or the second part.

```
\begin{aligned} & Find - x(A,x) \\ & k \leftarrow Find - k(A,1,n) \text{ (First find } k) \\ & if \ x \geq A[1] \ then \ return \ BinarySearch(A,1,k,x) \\ & Else \ return \ BinarySearch(A,k+1,n,x) \end{aligned}
```



## Example: Finding the last 0

You are given an array A[1...n] that contains a sequence of 0 followed by a sequence of 1 (e.g., 0001111111). A contains k 0(s) (k > 0 and k << n) and at least one 1.

Design an  $O(\log k)$ -time algorithm that finds the position k of the last 0.

#### Algorithm:

```
\begin{aligned} i \leftarrow 1 \\ while \ A[i] &= 0 \\ i \leftarrow 2i \\ find - k(A[i/2...i]) \end{aligned}
```

## 3.2 Merge Sort

Principle of the Merge Sort:

- Divide array into two halves.
- Recursively sort each half.
- Merge two halves to make sorted whole.

### Algorithm 5: Merge Sort

```
MergeSort(A, p, r)(p, r being the left & right side of the array to be sorted)

if p = r then

return

end

q \leftarrow [(p+r)/2]

MergeSort(A, p, q)

MergeSort(A, p, q, r)

First Call: MergeSort(A, 1, n)
```

## Algorithm 6: Merge

```
Input: Two Arrays L \leftarrow A[p...q] and R \leftarrow A[q+1...r] of elements in sorted order Merge (A, p, q, r)
Append \infty at the end of L and R
i \leftarrow 1, \ j \leftarrow 1
for k \leftarrow p to r do

if L[i] \leq R[j] then

A[k] \leftarrow L[i]
i \leftarrow i+1
end
else
A[k] \leftarrow R[j]
j \leftarrow j+1
end
end
```

Let T(n) be the running time of the algorithm on an array of size n.

### Merge Sort Recurrence:

$$T(n) \le T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + O(n), \quad n > 1, \quad T(1) = O(1)$$

**Simplification:** 

$$\implies T(n) = 2T(n/2) + n, \quad n > 1, \quad T(1) = 1$$

Result:

$$T(n) = n \log_2 n + n = O(n \log n)$$