

智慧型控制期末報告

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- 一、 求 $F(x_1, x_2) = x_1^2 + 2x_2^2 + 2x_1x_2 + x_1 + 1$ 之最小值。
 - a. 使用 steepest descent 法, $x_1(0) = x_2(0) = 0.5$,學習率 $\alpha = 0.01$ 。
 - 1. 程式碼

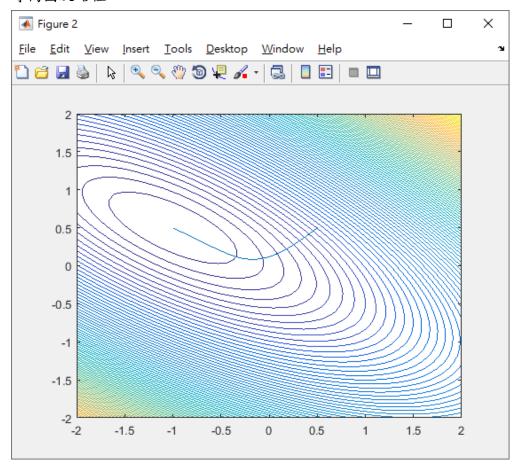
```
NND_test1_a.m × NND_test1_b.m ×
                                               +
1 -
         clc;
2 -
         clear;
3
         x1=linspace(-2,2,50);
5 -
         x2=linspace(-2,2,50);
 6
         [x1NEW,x2NEW]=meshgrid(x1,x2);
8 -
         f=x1NEW.^2+2*x2NEW.^2+2*x1NEW.*x2NEW+x1NEW+1;
9
10 -
         figure(1);
11 -
         mesh(x1NEW,x2NEW,f);%指定figure 1 為3D立體圖
12 -
13 -
         contour(x1NEW,x2NEW,f,100);%指定figure 2 為2D等高圖
14
15 -
         x11=0.5;
16 -
         x22=0.5;
17 -
         x0=[x11;x22];
18
      □ while 1
19 -
20
21 -
           f1 = 2*x11+2*x22+1;
22 -
           f2 = 2*x11+4*x22;
23
24 -
           g = [f1;f2];
25
26 -
          x=x0-0.01*g;
27
           if abs(x0-x)<=[0.00001;0.00001],
28 -
29 -
             x11=x(1);
30 -
              x22=x(2);
31 -
              break
32 -
            end
          x0=x;
33 -
34 -
          line([x11 x(1)],[x22 x(2)]);
35 -
          x11=x(1);
36 -
          x22=x(2);
37 -
38
         f=x11.^2+2*x22.^2+2*x11.*x22+x11+1
39 -
```

2. F之最小值

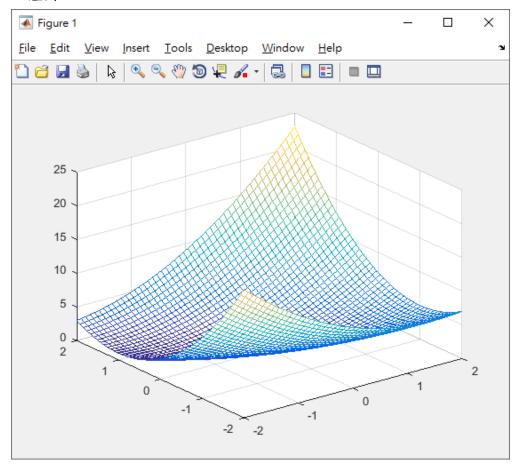


F之最小值為 0.5。

3. 等高圖及路徑



4. 立體圖



b. 使用 minimizing aling a line 之梯度法, $x_1(0) = x_2(0) = 0.5$ 。

1. 程式碼

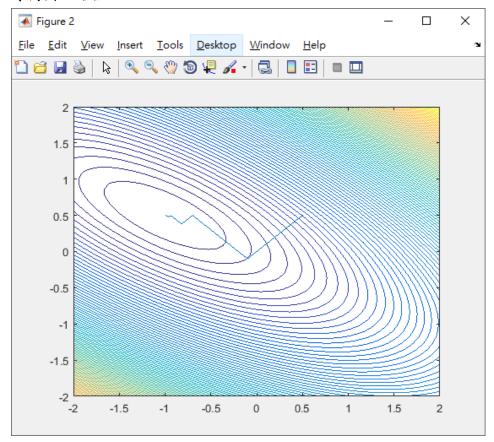
```
NND_test1_a.m
                          NND_test1_b.m ×
                                                +
         clc;
1 -
2 -
         clear;
3
4 -
         x1=linspace(-2,2,50);
5 -
         x2=linspace(-2,2,50);
6
         [x1NEW,x2NEW]=meshgrid(x1,x2);
8 -
         f=x1NEW.^2+2*x2NEW.^2+2*x1NEW.*x2NEW+x1NEW+1;
9
10 -
         figure(1);
11 -
         mesh(x1NEW,x2NEW,f);%指定figure 1 為3D立體圖
12 -
13 -
         figure(2);
         contour(x1NEW,x2NEW,f,100);%指定figure 2 為2D等高圖
14
15 -
         x11=0.5;
16 -
         x22=0.5;
17 -
         x0=[x11;x22];
18
19 -
      □ while 1
20
21 -
22 -
           f1 = 2*x11+2*x22+1;
           f2 = 2*x11+4*x22;
23
24 -
           f11=2;
25 -
           f12=2;
26 -
           f21=2;
27 -
           f22=4;
28
29 -
           g1 = [f1;f2];
30 -
           g2 = [f11 f12; f21 f22];
31
32 -
           33
34 -
           x=x0-a*g1;
35
36 -
           if abs(x0-x) <= [0.00001; 0.00001],
37 -
              x11=x(1);
38 -
39 -
              x22=x(2);
              break
40 -
           end
41
42 -
43 -
44 -
          x0=x;
          line([x11 x(1)],[x22 x(2)]);
          x11=x(1);
45 -
          x22=x(2);
46 -
         end
47
48 -
         f=x11.^2+2*x22.^2+2*x11.*x22+x11+1
```

2. F之最小值

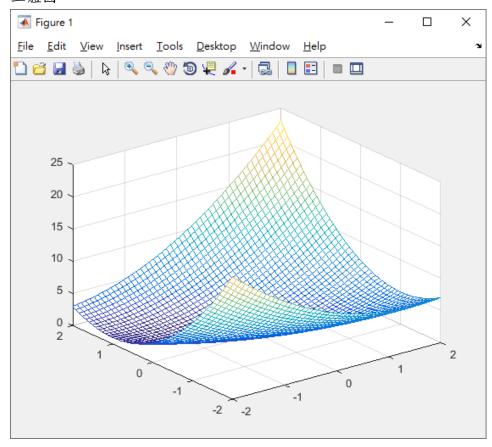


F之最小值為 0.5。

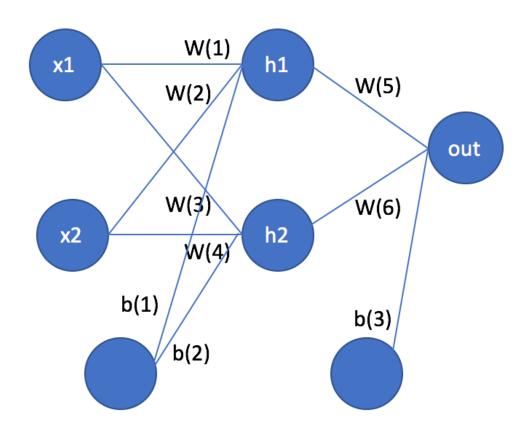
3. 等高圖及路徑



4. 立體圖



二、 使用 2-2-1 feedforward NN 及倒傳遞演算法執行 2 輸入 1 輸出之 XOR 功能。1. NN 結構圖



2. 程式

```
📝 Editor – /Users/andy_cho/Desktop/智慧型控制/matlab/NND_test2.m
                                                                                                                 NND_test1_a.m × NND_test2.m × untitled* × +
1 -
        clc;
2 -
       clear:
3
 4 -
       w_{\equiv} rand(1,6)
 5 -
       b = rand(1,3)
 6 -
       a=1.0;
 7 -
       tol=0.001;
 8 -
       x1=[0 \ 0 \ 1 \ 1];
 9 -
       x2=[0 1 0 1];
10 -
       tar=[0.05 0.95 0.95 0.05];
11 -
       int=1:
12
13 -

¬ for i=1:4
14 -
            while 1
15 -
             int=int+1;
16 -
             net_h1=w(1)*x1(i)+w(2)*x2(i)+b(1);
17 -
             net_h2=w(3)*x1(i)+w(4)*x2(i)+b(2);
18 -
             out_h1=1/(1+exp(-net_h1));
19 -
             out_h2=1/(1+exp(-net_h2));
20
             net_o=out_h1*w(5)+out_h2*w(6)+b(3);
21 -
22 -
             out_o=net_o;
23
24 -
             Etol=0.5*(tar(i)-out_o)^2;
25

☑ Editor – /Users/andy_cho/Desktop/智慧型控制/matlab/NND_test2.m

                                                                                                                (T)
   NND_test1_a.m × NND_test2.m × untitled* × +
25
26 -
                if(Etol>0.0001)
27 -
                      partE_6=-(tar(i)-out_o)*out_o*(1-out_o)*out_h2;
28 -
                     partE_5=-(tar(i)-out_o)*out_o*(1-out_o)*out_h1;
29
30 -
                     w(6)=w(6)-a*partE_6;
31 -
                     w(5)=w(5)-a*partE_5;
32
33 -
                     partE_4=-(tar(i)-out_o)*(out_o*(1-out_o))*w(6)*(out_h2*(1-out_h2))*x2(i);
34 -
35 -
                     partE_3=-(tar(i)-out_o)*(out_o*(1-out_o))*w(6)*(out_h2*(1-out_h2))*x1(i);
                      partE_2=-(tar(i)-out_o)*(out_o*(1-out_o))*w(5)*(out_h1*(1-out_h1))*x2(i);
36 -
                     partE_1=-(tar(i)-out_o)*(out_o*(1-out_o))*w(5)*(out_h1*(1-out_h1))*x1(i);
37
38 -
                     w(4)=w(5)-a*partE 4:
39 -
                     w(3)=w(5)-a*partE_3;
40 -
                     w(2)=w(5)-a*partE_2;
41 -
                     w(1)=w(5)-a*partE_1;
42
43 -
                     partb_3=-(tar(i)-out_o)*out_o*(1-out_o)*1;
44 -
45 -
                     partb_2=-(tar(i)-out_o)*(out_o*(1-out_o))*w(6)*(out_h2*(1-out_h2))*1;
                     partb_1=-(tar(i)-out_o)*(out_o*(1-out_o))*w(5)*(out_h1*(1-out_h1))*1;
46
47 -
                      b(3)=b(3)-a*partb_3;
48 -
                     b(2)=b(2)-a*partb_2;
49 -
                     b(1)=b(1)-a*partb_1;
50
 50
 51 -
                 else
 52 -
                     out(i)=out_o;
 53
 54 -
                     x=linspace(0,int,int);
 55 -
                      fig=plot(x,tar(i)-out_o);
 56 -
                     break:
 57 -
                 end
 58 -
             end
 59 -
              int=int+1;
 60
 61 -
         end
 62 -
         out
```

3. 最終NN及參數

Command Window

New to MATLAB? See resources for <u>Getting Started</u>.

```
w =
     0.0842     0.1639     0.3242     0.3017     0.0117     0.5399
b =
     0.0954     0.1465     0.6311

out =
     0.0640     0.9367     0.9367     0.0636
```

4. 誤差收斂圖

