4_sim_rl_true.py

1. For all bots which are currently at a node & idle

Update:

- true idleness of all nodes in graph (true) = $+\Delta t$
- expected idleness of all edges in the graph (expect) = $+\Delta t$

Calculate: here, learning rate (α) = 0.1, discount factor (γ) = 0.95

• Value function all edges where bots are present (Q) =

$$Q^{new}(s_t, a_t) \leftarrow \underbrace{Q(s_t, a_t)}_{\text{old value}} + \underbrace{\alpha}_{\text{learning rate}} \cdot \underbrace{\left(\underbrace{r_t}_{\text{reward}} + \underbrace{\gamma}_{\text{discount factor}} \cdot \underbrace{\max_{a} Q(s_{t+1}, a)}_{\text{estimate of optimal future value}} - \underbrace{Q(s_t, a_t)}_{\text{old value}}\right)}_{\text{new value (temporal difference target)}}$$

- Reward (r_t) = true idleness
- Softmax of Value function = value_exp = $\frac{e^{Q_i}}{\sum_{j=i}^{k} e^{Q_j}}$ (summation over all edges)

Set:

- True idleness of nodes where bots are present = 0
- Expected idleness of nodes wrt the corresponding bot = 0

NOTE: So effectively, we are calculating expected idleness perceived by the bot as the time elapsed since this bot last visited the node.

This is the **AGENT model** where the bot is calculating expected idleness by seeing the time elapsed since its last visit. Hence there is **no notion of memory** (estimating the expected idleness based on previous visits)

The name 4_sim_rl_true indicates => sim = simple estimation of expected idleness (AGENT model)

rl = using reinforcement learning (Q-learning algorithm to calculate the value function)
true = since reward is changed to true idleness

2. For a bot deciding the next node to visit

Set:

- True idleness of the node where the bot is present = 0
- Expected idleness of the node wrt the corresponding bot = 0

Decision Making: here, we chose ε =0.1

• With $(1 - \varepsilon)$ probability, check all neighbours and visit the one with highest value of = $[expected\ idleness] \times max([value_exp])$

Here, for each neighbour, we first calculate the maximum value_exp value we can get going to that node. Then we choose the highest value of { expect*max(value_exp) } over all neighbours.

• With ε probability, go to a random node	
END	