

Structure parts

Robot mechanics of the product brand



Manufacturer:

autonox Robotics GmbH Industriestrasse 1 • 77731 Willstaett • Germany Tel.: +49 7852 4273 0 • Fax: +49 7852 4273 111

E-mail: info@autonox.com • www.autonox.com

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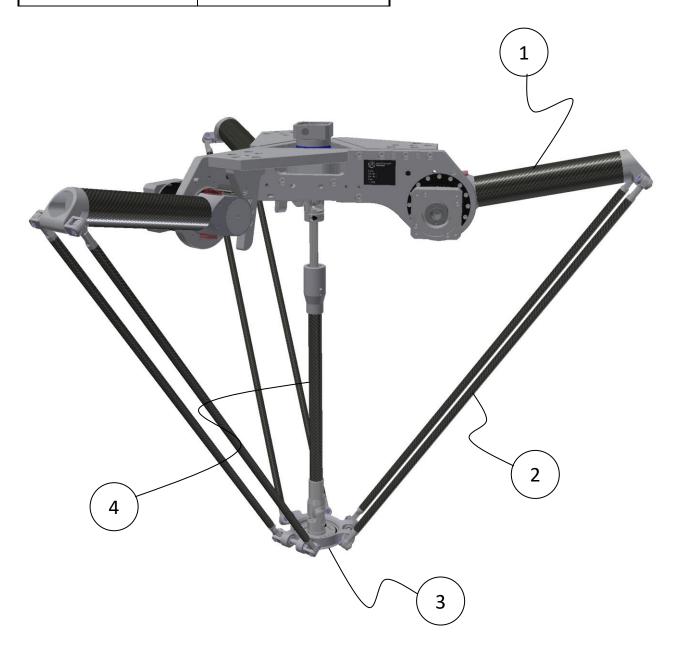
Structure parts of the **autonox** robot mechanics.

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- A_00036-02

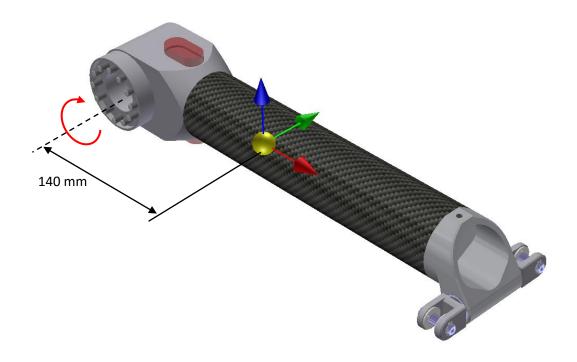


| Gearbox for | Moment of inertia (regarding gearbox input) |
|-------------------------|--|
| Axes 1 – 3 (upper arms) | 0,50 kg cm² |
| Axis 4 | 0,17 kg cm² |





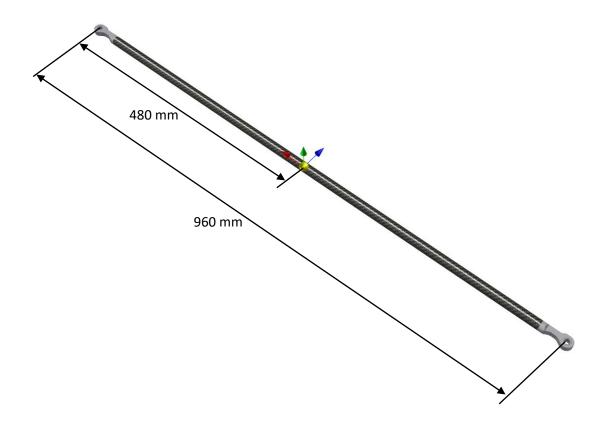
1. Upper arm



Mass = 1,636 kg

Inertia = 696,47 kg cm²

2. Forearm

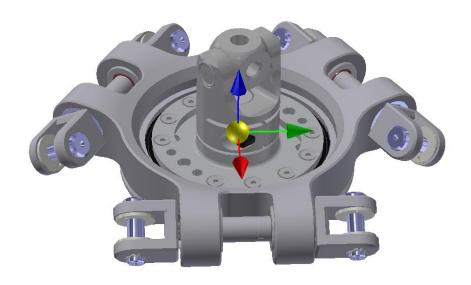


Mass = 0,167 kg

Twice per Drive!

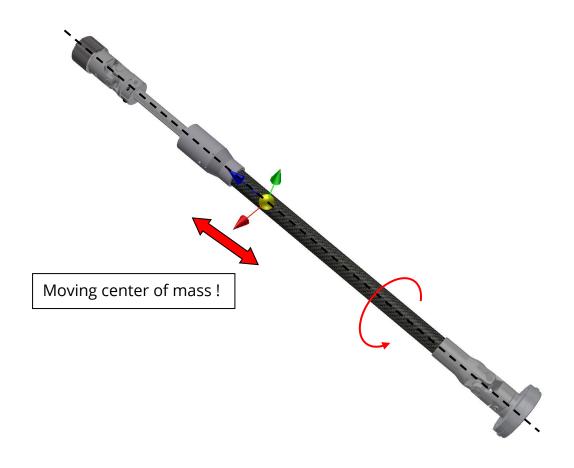


3. Tool holder



Mass = 1,542 kg

4. Telescopic shaft A4 (Axis 4)

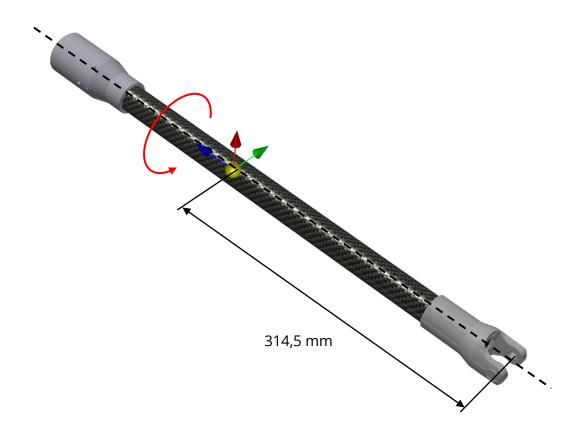


Mass = 2,741 kg

Inertia = $6,41 \text{ kg cm}^2$



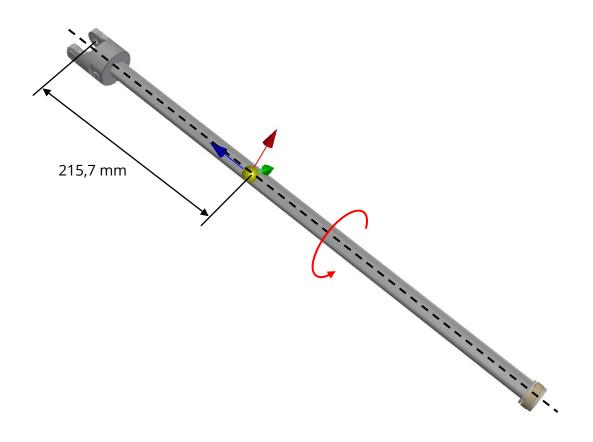
4.1 Telescopic shaft A4 (Axis 4) – lower part



Mass = 0,659 kg

Inertia = 1,62 kg cm²

4.2 Telescopic shaft A4 (Axis 4) – upper part



Mass = 0,939 kg

Inertia = 0,82 kg cm²



| Notes: | | |
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