

1. Provide a set of vectors $\bar{\mathbf{v}}_1, \bar{\mathbf{v}}_2, \bar{\mathbf{v}}_3, \bar{\mathbf{v}}_4$ in \mathbb{R}^4 that are linearly independent, given that

$$\bar{\mathbf{v}}_1 = (0, 1, 2, 1)^t.$$

2. Find a basis of the null space of A , $N(A)$, where

$$A = \begin{bmatrix} 3 & -1 & -1 & -3 \\ -2 & 2 & -2 & 2 \\ -1 & -1 & 3 & 1 \end{bmatrix}$$

3. Find the rank and nullity of A , if

$$A = \begin{bmatrix} 1 & 2 & -1 & 4 \\ -1 & -2 & 6 & -7 \\ 2 & 4 & 3 & 5 \end{bmatrix}$$

4. Find the rank without any calculations:

$$A = \begin{bmatrix} 2 & 4 & 3 \\ 3 & 7 & 5 \end{bmatrix}$$

5. For $\alpha = (2, 4, 5)^t$, what are the coordinates of α in the basis $\beta_1 = (1, 1, 1)^t$, $\beta_2 = (0, 1, 1)^t$, $\beta_3 = (1, 1, 0)^t$?

6. Take the bases of \mathbb{R}^3 given by

$$\{\bar{\mathbf{v}}\} = \left\{ \begin{pmatrix} 2 \\ 3 \\ 2 \end{pmatrix}, \begin{pmatrix} 7 \\ 10 \\ 6 \end{pmatrix}, \begin{pmatrix} 6 \\ 10 \\ 7 \end{pmatrix} \right\}, \quad \{\bar{\mathbf{w}}\} = \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \right\}.$$

Find the matrix that produces the change of basis ${}_{\{\bar{\mathbf{w}}\}}M_{\{\bar{\mathbf{v}}\}}$.

7. Find M , the matrix representation of the differentiation operator D , in the space \mathcal{P}_3 of polynomials of degree up to 3, with respect to the bases $\{\bar{\mathbf{v}}\} = \{2, x + 1, x^2 - x, x^3 - x - 1\}$ of \mathcal{P}_3 , and $\{\bar{\mathbf{w}}\} = \{2, x - 1, x^2 + x\}$ of \mathcal{P}_2 .

8. Find the matrix representation of a rotation in \mathbb{R}^3 with respect to the x -axis by an angle θ . Repeat with respect to the y -axis, z -axis.

9. Consider the transformation in \mathbb{R}^3 given by $\bar{\mathbf{x}} \mapsto A\bar{\mathbf{x}}$ for $A = \begin{pmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{pmatrix}$. Describe the image of points (x, y, z) in \mathbb{R}^3 . Is it linear?

10. Is the translation $(x, y, z) \mapsto (x - a, y - b, z - c)$ a linear transformation?
11. Let τ be the linear transformation on \mathbb{R}^3 , which is represented, relative to the canonical basis, by

$$T = {}_{\{\bar{e}\}}M_{{}_{\{\bar{e}\}}} = \begin{pmatrix} 7 & -8 & -8 \\ 9 & -16 & -18 \\ -5 & 11 & 13 \end{pmatrix}.$$

Find ${}_{\{\bar{\alpha}\}}M_{{}_{\{\bar{\alpha}\}}}$, where $\alpha_1 = (0, -1, 1)^t$, $\alpha_2 = (1, 3, -2)^t$, $\alpha_3 = (2, 0, 1)^t$.

12. Consider the transformation $\tau : \mathbb{R}^3 \rightarrow \mathbb{R}^3$: $\tau \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3x_1 + x_2 \\ 3x_2 \\ 5x_3 \end{pmatrix}$. What is the matrix representation of τ^2 ? And of $\tau^3 + 7\tau + 1$? (Consider the standard basis, and remember that $\tau^2(\bar{\mathbf{x}}) = \tau \circ \tau(\bar{\mathbf{x}}) = \tau(\tau(\bar{\mathbf{x}}))$.)
13. Consider the standard basis of \mathbb{R}^2 . What is the matrix representation H_θ of the reflection through the θ line? What is the matrix representation P_θ of the projection onto the θ line? Show that $H_\theta^2 = I$, $P_\theta^2 = P_\theta$, and $H_\theta = 2P_\theta - I$.
14. Consider $\alpha_1 = (1, 1, 2)^t$, $\alpha_2 = (-2, 0, 1)^t$. Find β_3 such that $\beta_1 = \alpha_1/||\alpha_1||$, $\beta_2 = \alpha_2/||\alpha_2||$ and β_3 are orthogonal.
15. Find an orthonormal basis for the null space of D , where

$$D = \begin{pmatrix} 1 & 0 & 5 & -2 & -1 \\ 0 & 1 & -2 & 4 & 2 \end{pmatrix}.$$

Solutions to some problems

2. $\{(1, 2, 1, 0)^t, (1, 0, 0, 1)^t\}$.

3. Nullity=2, Rank=2.

4. Rank is 2.

5. $\Psi_\beta(\alpha) = (3, 2, -1)^t$.

6.

$$\begin{pmatrix} 1 & 3 & 3 \\ 1 & 3 & 4 \\ 1 & 4 & 3 \end{pmatrix}.$$

7.

$$\begin{pmatrix} 0 & 1/2 & 1/2 & -2 \\ 0 & 0 & 2 & -3 \\ 0 & 0 & 0 & 3 \end{pmatrix}.$$

10. Not linear. For instance, show $T(\bar{\mathbf{x}} + \bar{\mathbf{y}}) \neq T(\bar{\mathbf{x}}) + T(\bar{\mathbf{y}})$.

11.

$$\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 3 \end{pmatrix}.$$

14. $\beta_3 = (1, -5, 2)$

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$$\bar{\mathbf{q}}_1 = \begin{pmatrix} -5 \\ 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} \frac{1}{\sqrt{30}}, \quad \bar{\mathbf{q}}_2 = \begin{pmatrix} -5 \\ -14 \\ 3 \\ 5 \\ 0 \end{pmatrix} \frac{1}{\sqrt{255}}, \quad \bar{\mathbf{q}}_3 = \begin{pmatrix} -5/102 \\ -7/51 \\ 1/39 \\ 23/51 \\ 1 \end{pmatrix} \frac{1}{\sqrt{125/102}}.$$