

# Bugged Coders

## 1 templates

### 1.1 Template

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 #define io ios::sync_with_stdio(0);cin.tie(0);cout.tie(0);
4 #define rep(i,a,b) for(int i=a;i<b;i++)
5 #define endl "\n"
6 #define pb push_back
7 #define each(i,x) for(auto &i:x)
8 #define deb(x) cout<<#x<<" "<<x<<endl;
9 #define ll long long

```

## 2 Data sctrucutres

### 2.1 Segment tree

```

1 int nums[]={1,3,4,5,7};
2 struct segmentTree{
3     int l, r,sum;
4     segmentTree *nodeLeft,*nodeRight;
5     segmentTree(int a, int b){
6         l=a;
7         r=b;
8         int m=(l+r)/2;
9         if(l!=r){
10             nodeLeft=new segmentTree(l,m);
11             nodeRight=new segmentTree(m+1,r);
12             sum=nodeLeft->sum+nodeRight->sum;
13         }
14         else sum=nums[l];
15     }
16     int query(int a, int b){
17         if(b<l || a>r) return 0;
18         if(a<=l && r<=b) return sum;
19         return nodeLeft->query(a,b)+nodeRight->query(a,b);
20     }
21     void update(int pos, int v){

```

```

22         if(l!=r){
23             int m=(l+r)/2;
24             if(pos<=m) nodeLeft->update(pos,v);
25             else nodeRight->update(pos,v);
26             sum=nodeLeft->sum+nodeRight->sum;
27         }
28         else sum=v;
29     }
30 };

```

### 2.2 Segment tree iterative

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 #define io ios::sync_with_stdio(0);cin.tie(0);cout.tie(0);
4 #define rep(i,a,b) for(int i=a;i<b;i++)
5 #define endl "\n"
6 #define pb push_back
7 #define each(i,x) for(auto &i:x)
8 #define deb(x) cout<<#x<<" "<<x<<endl;
9 #define ll long long

```

### 2.3 Segment tree- Lazy Propagation

```

1 int nums[]={1,3,5,7,9,11};
2 struct segmentTree{
3     int l, r,sum,lazy;
4     segmentTree *nodeLeft,*nodeRight;
5     segmentTree(int a, int b){
6         l=a;
7         r=b;
8         int m=(l+r)/2;
9         lazy=0;
10        if(l!=r){
11            nodeLeft=new segmentTree(l,m);
12            nodeRight=new segmentTree(m+1,r);
13            sum=nodeLeft->sum+nodeRight->sum;
14        }
15        else sum=nums[l];
16    }
17    int query(int a, int b){
18        if(nodeLeft!=nullptr && lazy!=0) nodeLeft->lazy=lazy;
19        if(nodeRight!=nullptr && lazy!=0) nodeRight->lazy=lazy;
20        sum+=(r-l+1)*lazy;lazy=0;

```

```

21     if(b<l || a>r) return 0;
22     if(a<=l && r<=b) return sum;
23     return nodeLeft->query(a,b)+nodeRight->query(a,b);
24 }
25 int update(int a, int b, int v){
26     int increment=0;
27     if(b<l || a>r) return 0;
28     if(a<=l && r<=b){
29         if(nodeLeft!=nullptr) nodeLeft->lazy+=lazy;
30         if(nodeRight!=nullptr) nodeRight->lazy+=lazy;
31         increment=(r-l+1)*v;
32         sum+=increment;
33         return increment;
34     }
35     increment=nodeLeft->update(a,b,v)+nodeRight->update(a,b,v);
36     sum+=increment;
37     return increment;
38 }
39 };

```

## 2.4 Segment tree Lazy Iterative

```

1  #include <bits/stdc++.h>
2  using namespace std;
3  #define ios ios::sync_with_stdio(0);cin.tie(0);cout.tie(0);
4  #define endl "\n"
5  #define pb push_back
6  #define each(i,x) for(auto &i:x)
7  #define all(x) x.begin(),x.end()
8  #define sz(x) (int)x.size()
9  #define rep(i,a,b) for(int i=a;i<b;i++)
10 #define ll long long
11
12 const int N=2e5+10;
13 ll st[4*N+10],lazy[4*N+10],arr[N];
14 void build(int l, int r, int i){
15     lazy[i]=0;
16     if(l==r){st[i]=arr[l];return;}
17     int m=(l+r)>>1;
18     build(l,m,2*i+1);
19     build(m+1,r,2*i+2);
20     st[i]=st[2*i+1]+st[2*i+2];
21 }

```

```

22 void push(int l, int r, int i){
23     if(!lazy[i])return;
24     st[i]+=(r-l+1)*lazy[i];
25     if(l!=r){
26         lazy[2*i+1]+=lazy[i];
27         lazy[2*i+2]+=lazy[i];
28     }
29     lazy[i]=0;
30 }
31 void update(int l, int r, int a, int b, ll x, int i){
32     push(l,r,i);
33     if(a>r || b<l)return;
34     if(a<=l&&r<=b){
35         lazy[i]+=x;
36         push(l,r,i);
37         return;
38     }
39     int m=(l+r)>>1;
40     update(l,m,a,b,x,2*i+1);update(m+1,r,a,b,x,2*i+2);
41     st[i]=st[2*i+1]+st[2*i+2];
42 }
43 ll query(int l, int r, int a, int b, int i){
44     if(a>r || b<l)return 0;
45     push(l,r,i);
46     if(a<=l&&r<=b) return st[i];
47     int m=(l+r)>>1;
48     return query(l,m,a,b,2*i+1)+query(m+1,r,a,b,2*i+2);
49 }
50 int main(){ios
51     ll n,q;cin>>n>>q;
52     rep(i,0,n)cin>>arr[i];
53     build(0,n-1,0);
54     rep(i,0,q){
55         int op;cin>>op;
56         if(op==1){
57             int a,b; ll x;
58             cin>>a>>b>>x;a--;b--;
59             update(0,n-1,a,b,x,0);
60         }
61         else{
62             int k;cin>>k;k--;
63             cout<<query(0,n-1,k,k,0)<<endl;
64         }

```

```

65     }
66     return 0;
67 }

```

## 2.5 Disjoin Set

```

1 //Se usa para detectar cyclos en un grafo no dirigido convexo & en el
  algoritmo de Krustal.
2 vector<pair<int,int>>ds;
3 void init(int n){
4     ds.assign(n+1,{-1,0});
5 }
6 int find(int x){
7     if(-1==ds[x].first) return x;
8     return ds[x].first=find(ds[x].first);
9 }
10 bool unionDs(int x, int y){
11     int px=find(x),py=find(y);
12     int &rx=ds[px].second,&ry=ds[py].second;
13     if(px==py) return false;
14     else{
15         if(rx>ry) ds[py].first=px;
16         else{
17             ds[px].first=py;
18             if(rx==ry) ry+=1;
19         }
20     }
21     return true;
22 }

```

## 2.6 Sparce Table

```

1 //Se usa para RMQ porque se puede hacer en O(1), no acepta updates
2 vector<int>lg;
3 vector<vector<int>>st;
4 int *nums;
5 void init(int n){
6     int logn=(int) log2(n)+1;
7     lg.assign(n+1,0);
8     st.assign(logn,vector<int>(n+1));
9     for(int i=0;i<n;i++) st[0][i]=nums[i];
10    lg[1]=0;
11    for(int i=2;i<=n;i++) lg[i]=lg[i/2]+1;
12    for(int i=1;i<logn;i++)

```

```

13        for(int j=0;j+(1<<i)<n;j++)st[i][j]=min(st[i-1][j],st[i-1][j
14            +(1<<(i-1))]);
15    }
16    int query(int a,int b){
17        int logn=lg[(b-a+1)];
18        cout<<st[logn][a]<<endl;
19        return min(st[logn][a],st[logn][b-(1<<logn)+1]);
20    }

```

## 2.7 Treap

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 typedef struct Node *pitem;
4 struct Node{
5     int value,key;
6     pitem l,r;
7     Node(int v) value(v),key(rand()),l(nullptr),r(nullptr);
8 };
9 struct treap
10 {
11     void split(pitem t, int value, pitem& left,pitem& right){
12         if(!t) void(left=right=nullptr);
13         if(t->value<=x) split(t->r,value,t->r,right),left=t;
14         else split(t->l,value,left,t->l),right=t;
15     }
16     void marge(pitem t,pitem left,pitem right){
17         if(!left || ! right){t=left?left:right;return;}
18         if(left->key>right->key) marge(left->r,left->r,right), t=left;
19         else marge(right->l,left,right->l), t=right;
20     }
21     void insert(pitem &t,pitem x){
22         if(!t)t=x;
23         else if(x->key>t->key){
24             split(t,x->value,x->l,x->right), t=x;
25         }
26         else insert(x->value<t->value? t->l:t->r,x);
27     }
28 };

```

## 2.8 Trie

```

1 struct trie{
2     bool isFinal;

```

```

3     trie *children[26];
4     trie(){
5         isFinal=false;
6         for(int i=0;i<26;i++)children[i]=nullptr;
7     }
8 };
9
10 void inserString(string str,trie *root){
11     trie *aux=root;
12     for(int i=0;i<str.size();i++){
13         int index=str[i]-'a';
14         if(aux->children[index]==nullptr){
15             aux->children[index]=new trie();
16         }
17         aux=aux->children[index];
18     }
19     aux->isFinal=true;
20 }
21 bool existInTrie(string str,trie *root){
22     trie *aux=root;
23     for(int i=0;i<str.size();i++){
24         int index=str[i]-'a';
25         if(aux->children[index]==nullptr) return false;
26         aux=aux->children[index];
27     }
28     return aux->isFinal;
29 }

```

## 2.9 Cartesian Tree

```

1 #include<bits/stdc++.h>
2 using namespace std;
3 typedef long long ll;
4 struct node {
5     int idx, val, par, ch[2];
6     friend bool operator<(node a, node b) { return a.idx < b.idx; }
7     void init(int _idx, int _val, int _par) {
8         idx = _idx, val = _val, par = _par, ch[0] = ch[1] = 0;
9     }
10 } tree[N];
11 int root, top, stk[N];
12 int cartesian_build(int n) {
13     for (int i = 1; i <= n; i++) {

```

```

14     int k = i - 1;
15     while (tree[k].val > tree[i].val) k = tree[k].par;
16     tree[i].ch[0] = tree[k].ch[1];
17     tree[k].ch[1] = i;
18     tree[i].par = k;
19     tree[tree[i].ch[0]].par = i;
20 }
21 return tree[0].ch[1];
22 }
23 int dfs(int x) {
24     if (!x) return 0;
25     int sz = dfs(tree[x].ch[0]);
26     sz += dfs(tree[x].ch[1]);
27     ans = max(ans, (ll)(sz + 1) * tree[x].val);
28     return sz + 1;
29 }

```

## 2.10 BIT

```

1 struct FenwickTree {
2     vector<int> bit; // binary indexed tree
3     int n;
4
5     FenwickTree(int n) {
6         this->n = n;
7         bit.assign(n, 0);
8     }
9
10    FenwickTree(vector<int> const &a) : FenwickTree(a.size()) {
11        for (size_t i = 0; i < a.size(); i++)
12            add(i, a[i]);
13    }
14
15    int sum(int r) {
16        int ret = 0;
17        for (; r >= 0; r = (r & (r + 1)) - 1)
18            ret += bit[r];
19        return ret;
20    }
21
22    int sum(int l, int r) {
23        return sum(r) - sum(l - 1);
24    }

```

```

25
26 void add(int idx, int delta) {
27     for (; idx < n; idx = idx | (idx + 1))
28         bit[idx] += delta;
29 }
30 };

```

### 3 DP

#### 3.1 Digit DP

```

1 ll dp[20][20][3];
2 ll n,k,d;
3 vector<int>num;
4 ll bk(int i, int len, int t){
5     if(len>k) return 0;
6     if(i==n){
7         if(len==k) return 1;
8         return 0;
9     }
10    ll &res=dp[i][len][t];
11    if(res!=-1) return res;
12    res=0;
13    int tope;
14    if(t==0) tope=num[i];
15    else tope=9;
16    for(int j=0;j<=tope;j++){
17        int newt=t;
18        int newlen=len;
19        if(t==0 && j<tope) newt=1;
20        if(d==j) newlen++;
21        if(newlen<=k)res+=bk(i+1,newlen,newt);
22    }
23    return res;
24 }
25 ll rep(int a){
26     num.clear();
27     while(a>0){
28         num.push_back(a%10);
29         a/=10;
30     }
31     reverse(num.begin(),num.end());
32     n=num.size();

```

```

33     memset(dp,-1,sizeof(dp));
34     return bk(0,0,0);
35 }

```

#### 3.2 Prefix Sum 2D

```

1 const int MAX=50
2 ll prefix[MAX+4][MAX+4];
3 // x1-> left x2->right y1-> up y2 ->down x1<=x2 && y1<=y2
4 ll query(int x1, int x2,int y1,int y2){
5     return prefix[y2][x2]-prefix[y1-1][x2]-prefix[y2][x1-1]+prefix[y1
6         -1][x1-1];
7 }
8 //Inizialisate prefix[i][j] with original values of the grid
9 void prefixSum(){
10     for(int i=1;i<=n;i++){
11         for(int j=1;j<=n;j++) prefix[i][j]+=prefix[i][j-1]+prefix[i-1][j
12             ]-prefix[i-1][j-1];
13     }
14 }

```

### 4 Graph

#### 4.1 Krustal

```

1 // Este algoritmo sirve para buscar MST de un grafo convexo no dirigido
2 vector<tuple<int,int,int>>edges;
3 int n,m;
4 //Insertar Disjoin set
5 int krustal(){
6     sort(edges.begin(),edges.end());
7     int res=0;
8     for(int i=0;i<m;i++){
9         int c,a,b;
10        tie(c,a,b)=edges[i];
11        // Si en el disjoin set estan conectados retorna false
12        if(unionDs(a,b)==false) continue;
13        else res+=c;
14    }
15    return res;
16 }

```

#### 4.2 Kosaraju's (SCC)

```

1 //Sirve para encontrar los SCC
2 struct Kosaraju{
3     int s;
4     vector<vector<int>> g,gr;
5     vector<int> visited,ids,topologic_sort;
6     Kosaraju(int n){
7         s=n;
8         g.assign(n+1,vector<int>());
9         gr.assign(n+1,vector<int>());
10        visited.assign(n+1,0);
11        ids.assign(n+1,0);
12    }
13    void addEdge(int a,int b){
14        g[a].push_back(b);
15        gr[b].push_back(a);
16    }
17    void dfs(int u){
18        if(visited[u]!=0) return;
19        visited[u]=1;
20        for(int node:g[u])dfs(node);
21        topologic_sort.push_back(u);
22    }
23    void dfsr(int u,int id){
24        if(visited[u]!=0) return;
25        visited[u]=1;
26        ids[u]=id;
27        for(int node:gr[u])dfs(node,id);
28    }
29    void algo(){
30        for(int i=1;i<=s;i++) if(visited[i]==0) dfs(i);
31        fill(visited.begin(),visited.end(),0);
32        reverse(topologic_sort.begin(),topologic_sort.end());
33        int id=0;
34        for(int i=0;i<topologic_sort.size();i++){
35            if(visited[topologic_sort[i]]==0)dfsr(topologic_sort[i],id
36                ++);
37        }
38    } // Es el ago principal
39    int search(int node){
40        return ids[node];
41    } // Retorana el componente que esta el nodo
42 };

```

## 4.3 2 Sat

```

1 //Se usa para los problems en los cuales tengamos dos dosible variables
2 struct twoSat{
3     int s;
4     vector<vector<int>> g,gr;
5     vector<int> visited,ids,topologic_sort,val;
6     twoSat(int n){
7         s=n;
8         g.assign(n*2+1,vector<int>());
9         gr.assign(n*2+1,vector<int>());
10        visited.assign(n*2+1,0);
11        ids.assign(n*2+1,0);
12        val.assign(n+1,0);
13    }
14    void addEdge(int a,int b){
15        g[a].push_back(b);
16        gr[b].push_back(a);
17    }
18    void addOr(int a,bool ba,int b,bool bb){
19        addEdge(a+(ba?s:0),b+(bb?0:s));
20        addEdge(b+(bb?s:0),a+(ba?0:s));
21    }
22    void addXor(int a,bool ba,int b,bool bb){
23        addOr(a,ba,b,bb);
24        addOr(a,!ba,b,!bb);
25    }
26    void addAnd(int a,bool ba,int b,bool bb){
27        addXor(a,!ba,b,bb);
28    }
29    void dfs(int u){
30        if(visited[u]!=0) return;
31        visited[u]=1;
32        for(int node:g[u])dfs(node);
33        topologic_sort.push_back(u);
34    }
35    void dfsr(int u,int id){
36        if(visited[u]!=0) return;
37        visited[u]=1;
38        ids[u]=id;
39        for(int node:gr[u])dfs(node,id);
40    }
41    bool algo(){

```

```

42     for(int i=0;i<s*2;i++) if(visited[i]==0) dfs(i);
43     fill(visited.begin(),visited.end(),0);
44     reverse(topologic_sort.begin(),topologic_sort.end());
45     int id=0;
46     for(int i=0;i<topologic_sort.size();i++){
47         if(visited[topologic_sort[i]]==0)dfsr(topologic_sort[i],id
            ++);
48     }
49     for(int i=0;i<s;i++){
50         if(ids[i]==ids[i+s]) return false;
51         val[i]=(ids[i]>ids[i+s]?0:1);
52     }
53     return true;
54 }
55 };

```

## 5 Strings

### 5.1 KMP

```

1 vector<int> kmp(string s){
2     int n=s.size();
3     vector<int>pi(n);
4     for(int i=1;i<n;i++){
5         int j=pi[i-1];
6         while(j>0 && s[i]!=s[j])j=pi[j-1];
7         if(s[i]==s[j]) j++;
8         pi[i]=j;
9     }
10    return pi;
11 }

```

### 5.2 Hashing

```

1 struct Hash{
2     const int mod=1e9+123;
3     const int p=257;
4     vector<int> prefix;
5     static vector<int>pow;
6     Hash(string str){
7         int n=str.size();
8         while(pow.size()<=n){
9             pow.push_back(1LL*pow.back()*p%mod);

```

```

10    }
11    vector<int> aux(n+1);
12    prefix=aux;
13    for(int i=0;i<n;i++){
14        prefix[i+1]=(prefix[i]+1LL*str[i]*pow[i])%mod;
15    }
16 }
17 inline int getHashInInterval(int i,int len,int MxPow){
18     int hashing=prefix[i+len]-prefix[i];
19     if(hashing<0) hashing+=mod;
20     hashing=1LL*hashing*pow[MxPow-(len+i-1)]%mod;
21     return hashing;
22 }
23 };
24 vector<int> Hash::pow{1};

```

## 6 Math

### 6.1 Linear Sieve

```

1 //O(N) for find all the primes in the given range
2 bool is_compositive[10000000+1];
3 vector<int>primes;
4 void sieve(int n){
5     primes.clear();
6     fill(is_compositive,is_compositive+n,false);
7     for(int i=2;i<=n;i++){
8         if(!is_compositive[i]) primes.push_back(i);
9         for(int j=0;j<primes.size() && primes[j]*i<=n;j++){
10             is_compositive[i*primes[j]]=true;
11             if(!(i%primes[j])) break;
12         }
13     }
14 }
15
16 int n;cin>>n;
17 sieve(n);
18 cout<<primes.size()<<endl;
19 for(int i=0;i<primes.size();i++){
20     cout<<primes[i]<<endl;
21 }
22 }

```

## 6.2 Euler Sieve

```

1 //this is a sieve for a euler funciton that given the number of coprime
  numbers of x but in a range
2 vector<int>sieve;
3 void eulerSieve(int n){
4     sieve.clear();
5     sieve.push_back(0);
6     for(int i=1;i<=n;i++){
7         sieve.push_back(i);
8     }
9     for(int i=2;i<=n;i++){
10        if(sieve[i]==i)
11            for(int j=i;j<=n;j+=i)sieve[j]-=(sieve[j]/i);
12    }
13 }
```

## 6.3 Euler Sieve Gauss Reduction

```

1 // sum(pi(n)) of the divisors of n is equal to n
2 vector<int>sieve;
3 void eulerSieve(int n){
4     sieve.clear();
5     sieve.push_back(0);
6     sieve.push_back(1);
7     for(int i=2;i<=n;i++){
8         sieve.push_back(i-1);
9     }
10    for(int i=2;i<=n;i++){
11        for(int j=i*2;j<=n;j+=i)sieve[j]-=sieve[i];
12    }
13 }
```

## 6.4 Mobius Sieve

```

1 /* f(x)=0 if has square prime factor
2 f(x)=1 if if is square-free and even
3 f(x)=-1 if is square-free and odd
4 properti the sum of function of divisors of x is equal to 0 if x>1*/
5 vector<int>sieve;
6 void ms(int n){
7     sieve.assign(n+1,-1);
8     sieve[1]=1;
9     for(int i=2;i<=n;i++)
```

```

10     for(int j=i*2;j<=n;j+=i)sieve[j]-=sieve[i];
11 }
```

## 6.5 Binary Exponentiation

```

1 long long binPow(long long a, long long b) {
2     long long res = 1;
3     while (b > 0) {
4         if (b & 1)
5             res = res * a;
6         a = a * a;
7         b >>= 1;
8     }
9     return res;
10 }
```

## 7 Flows

### 7.1 Dinics

```

1 struct dinics{
2     int m,n;
3     ll mF=1e18;
4     vector<tuple<int,ll,ll>>edge;
5     vector<vector<int>>adj;
6     vector<int>level,id;
7     void init(int _n){
8         m=0;
9         n=_n;
10        level.resize(n+1);
11        id.resize(n+1);
12        adj.resize(n+1);
13    }
14    void addEdge(int u,int v,ll f,bool directed=true){
15        edge.push_back({v,f,0});
16        adj[u].push_back(m);
17        edge.push_back({u,(directed?0:f),0});
18        adj[v].push_back(m+1);
19        m+=2;
20    }
21    bool bfs(int s, int t){
22        fill(level.begin(),level.end(),-1);
23        queue<int>aux;
```



```

24     aux.push(s);
25     level[s]=0;
26     while(!aux.empty()){
27         int v=aux.front();aux.pop();
28         for(auto idx:adj[v]){
29             auto &[u,c,f]=edge[idx];
30             if(c-f<1 || level[u]!=-1) continue;
31             aux.push(u);
32             level[u]=level[v]+1;
33         }
34     }
35     return level[t]!=-1?1:0;
36 }
37 ll dfs(int u,int t, ll f){
38     if(u==t || f==0) return f;
39     for(auto &cdx=id[u];cdx<adj[u].size();cdx++){
40         int idx=adj[u][cdx];
41         auto &[v,c,fv]=edge[idx];
42         if(level[v]!=level[u]+1 || c-fv<1) continue;
43         ll res=dfs(v,t,min(f,c-fv));
44         if(!res) continue;
45         auto &fr=get<2>(edge[idx^1]);
46         fv+=res;
47         fr-=res;
48         return res;
49     }
50     return 0;
51 }
52 ll maxFlow(int s,int t){
53     ll mf=0;
54     while(bfs(s,t)){
55         fill(id.begin(),id.end(),0);
56         while(ll f=dfs(s,t,mf)) mf+=f;
57     }
58     return mf;
59 }
60 };

```

## 8 Tree

### 8.1 Binary-Lifting

1 //For get the k-th atecesor of a node in a tree 1 indexed

```

2 vector<int> *T;
3 vector<vector<int>>>up;
4 vector<int>deep;
5 int lg;
6 void init(int n){
7     lg=ceil(log2(n))+1;
8     T=new vector<int>[n+1];
9     up.assign(n+1,vector<int>(lg+1,1));
10    deep.assign(n+1,0);
11 }
12 void dfs(int node){
13     for(auto ch:T[node]){
14         deep[ch]=deep[node]+1;
15         up[ch][0]=node;
16         for(int i=1;i<lg;i++){
17             up[ch][i]=up[up[ch][i-1]][i-1];
18         }
19         dfs(ch);
20     }
21 }
22 int getkthAtecesor(int node, int k){
23     int res=node;
24     for(int i=lg-1;i>=0;i--){
25         if(k & (1<<i)) res=up[res][i];
26     }
27     return res;
28 }

```

### 8.2 Euler Tour

```

1 #include <bits/stdc++.h>
2 using namespace std;
3 const int MAX=2e5+300;
4 int S[MAX];
5 int F[MAX];
6 int FT[MAX];
7 vector<int>T[MAX];
8 //Inicalizar en 0 para 0 indexado y 1 par 1 indexado
9 int timer;
10 int n;
11 void dfs(int node,int par){
12     S[node]=timer;
13     FT[timer]=node;

```

```

14     timer++;
15     for(auto i:T[node])
16         if(i!=par) dfs(i,node);
17     F[node]=timer;
18     FT[timer]=node;
19     timer++;
20 }

```

## 9 Geometry

## 10 Others

### 10.1 Mo's algorithm

```

1 void remove(idx); // TODO: remove value at idx from data structure
2 void add(idx); // TODO: add value at idx from data structure
3 int get_answer(); // TODO: extract the current answer of the data
  structure
4
5 int block_size;
6
7 struct Query {
8     int l, r, idx;
9     bool operator<(Query other) const
10    {
11        return make_pair(l / block_size, r) <
12               make_pair(other.l / block_size, other.r);
13    }
14 };
15
16 vector<int> mo_s_algorithm(vector<Query> queries) {
17     vector<int> answers(queries.size());
18     sort(queries.begin(), queries.end());
19
20     // TODO: initialize data structure
21
22     int cur_l = 0;
23     int cur_r = -1;
24     // invariant: data structure will always reflect the range [cur_l,
25     cur_r]
26     for (Query q : queries) {
27         while (cur_l > q.l) {

```

```

28         add(cur_l);
29     }
30     while (cur_r < q.r) {
31         cur_r++;
32         add(cur_r);
33     }
34     while (cur_l < q.l) {
35         remove(cur_l);
36         cur_l++;
37     }
38     while (cur_r > q.r) {
39         remove(cur_r);
40         cur_r--;
41     }
42     answers[q.idx] = get_answer();
43 }
44 return answers;
45 }

```

### 10.2 Matrix

```

1 const int N=100, MOD=1e9+7;
2 struct Matrix {
3     ll a[N][N];
4     Matrix() {memset(a,0,sizeof(a));}
5     Matrix operator *(Matrix other) { // Product of a matrix
6         Matrix product=Matrix();
7         rep(i,0,N) rep(j,0,N) rep(k,0,N) {
8             product.a[i][k]+=a[i][j]*other.a[j][k];
9             product.a[i][k]%=MOD;
10        }
11        return product;
12    }
13 };
14 Matrix expo_power(Matrix a, ll n) { // Matrix exponentiation
15     Matrix res=Matrix();
16     rep(i,0,N) res.a[i][i]=1; // Matriz identidad
17     while(n){
18         if(n&1) res=res*a;
19         n>>=1;
20         a=a*a;
21     }
22     return res;

```

```
23 | } // Ej. Matrix M=Matrix(); M.a[0][0]=1; M=M*M; Matrix res=  
    |     expo_power(M,k);
```