

$$9.81 \text{ m/s}^2$$

$$v = 936 \text{ km/h}$$

$$936 \text{ km/h} \left( \frac{1 \text{ h}}{3600 \text{ s}} \right) \left( \frac{1 \text{ km}}{1000} \right)$$

$$m = 12 \text{ kg}$$

$$h = 1 \text{ m}$$

$$(2)(9.81)(12)$$

$$v = 4.6 \text{ m/s}$$

$$t = \frac{4.6 - 0}{9.81}$$

$$m = 3 \text{ kg}$$

$$A \text{ EP } 58.86$$

$$C = 29$$

$$a = \frac{F}{m}$$

$$100 \text{ N}$$

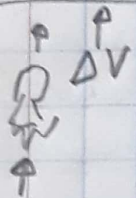
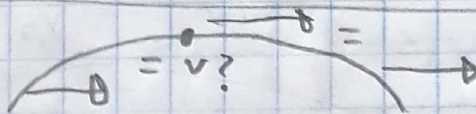
$$17 = 5.88$$

$$18 = 5.55$$

$$16 = 6.25$$

$$V = ?$$

$$P_y 89^\circ$$



$$t = 2 \text{ s}$$

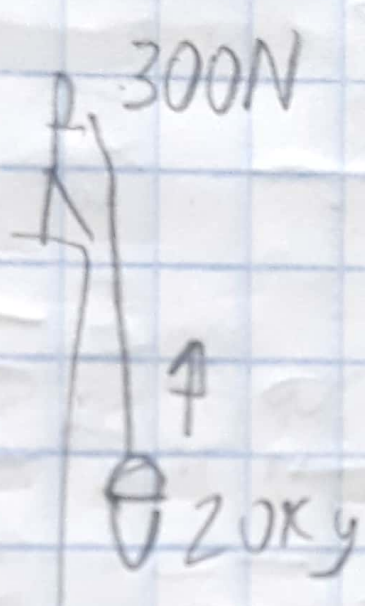
$$a ?$$

$$V_0 = 23.8 \text{ m/s}$$

$$V_f = 35.7 \text{ m/s}$$

$$20 = 20 - 10(a)$$

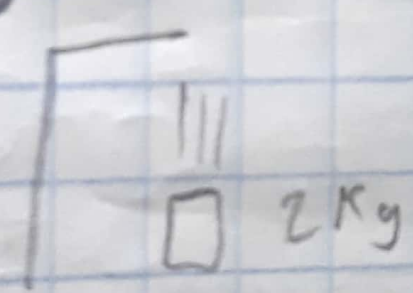
$$5 = 8$$



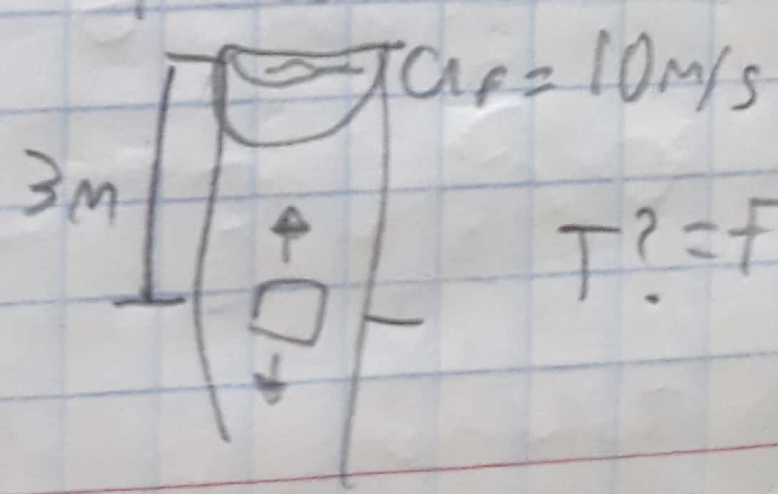
$$m = 10 \quad m_A = 6 \quad m_B = 4 \quad \text{Kg}$$

$$F = 10 \text{ N}$$

$$FF_t = 3$$



$$F = ma$$



$$T = F \times d$$

$$x^0 - a - 0 = 2A$$

Scribe



M 60  
n 30

$$EC = \frac{7}{2} \begin{pmatrix} 60 \\ 30 \end{pmatrix} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = 120$$

70 kg  $\left( \frac{0.7 N}{0.10147 kg} \right)$

$a = \frac{20N}{8} = 2.5$   
 ~~$10s$~~   
 ~~$2$~~   
 ~~$10 m/s$~~

[A]

F = 150N  
m = 30 kg  
a = 3 m/s<sup>2</sup>  
F<sub>f</sub> = ?

$$F - F_f = ma + F_f = f - (ma)$$

t = ?  
v<sub>x</sub> = 10 m/s  
v<sub>y</sub> =

g = 4g

$$\frac{2v_y}{g} = \frac{20}{40}$$



$$v_{inst} = \frac{\Delta x}{\Delta t} = \frac{dx}{dt} = v_{inst.}$$

$$r_{med.} = \frac{x_2 - x_1}{t_2 - t_1}$$

$$a_{med.} = \frac{\Delta v_x}{\Delta t}$$

$$a_{inst.} = \lim_{\Delta t \rightarrow 0} \frac{\Delta v_x}{\Delta t} = \frac{dv_x}{dt}$$

## R. Formulario:

$$h = \frac{1}{2} a t^2$$

$$F_{net} = \Sigma F = 0$$

↑ equilibrio mecánico

$$r = \frac{d}{t}$$

$$r_{med} = \frac{\Sigma d}{\Sigma t}$$

$$d = r \times t$$

$$V_F = V_i + a t$$

$$a = \frac{\Delta v}{\Delta t} = \frac{v_f - v_o}{t}$$

$$v = a \times t$$

caída libre:

$$a \sim F_{net}$$

$$\text{Peso} = m g$$

$$v = g t$$

$$d = \frac{1}{2} g t^2$$

$$a \sim \frac{1}{\text{masa}}$$

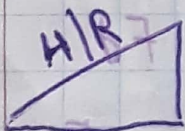
$$F = m a$$

$$a = \frac{F}{m}$$

$$t = \sqrt{\frac{2d}{g}}$$

$$v_{prom} = \frac{1}{2} g t$$

$$a \sim \frac{F_{net}}{m} = \frac{m g - \text{Resistencia}}{m}$$



$$\frac{A_x}{A} = \cos \theta$$

$$\vec{A} = A_x \uparrow + A_y \rightarrow$$

$$A_x = A \cos \theta$$

$$\vec{A}_x = A_x \uparrow$$

$$\frac{A_y}{A} = \sin \theta$$

$$\vec{A}_y = A_y \rightarrow$$

$$\theta = \tan^{-1} \frac{A_y}{A_x}$$

$$A_y = A \sin \theta$$

$$\tan \theta = \frac{A_y}{A_x}$$

$$A = \sqrt{A_x^2 + A_y^2}$$

Cantidad de mov.

$$CDM = mv$$

$$\text{Impulso} = F t = \Delta(mv)$$



Posición:

$$x = x_0 + v_{x0}t + \frac{1}{2} a_x t^2 \quad (a = \text{const})$$

$$v_x^2 = v_{x0}^2 + 2a(x - x_0)$$

$$x - x_0 = \left( \frac{v_0 + v}{2} \right) t \quad (a = \text{const})$$

Cantidad de mov. =  $mv$

impulso =  $Ft$

$$Ft = \Delta(mv)$$

$$F = \frac{m \Delta v}{t}$$

Choques:

$$\text{inelástico} = m_1 v_1 + m_2 v_2 = m_f v_f$$

$$\text{elástico} = m_1 v_1 + m_2 v_2 = m_1 v_1 + m_2 v_2$$

$$\text{Trabajo: } T = F \times d = Fd \quad (\text{Nm}) = (\text{J})$$

$$\text{Potencia} = \frac{\text{Trabajo}}{\text{intervalo de tiempo}} = \frac{T}{t} \quad (746 \text{ W} = 1 \text{ Hp})$$

horse power

$h = \text{altura}$

$$\text{Energía potencial gravitacional } E_{Pg} = mgh$$

$$\text{Energía cinética} = E_C = \frac{1}{2} m v^2 \quad T = Fd$$

$$\text{Teorema del trabajo y energía } T = \Delta E_C = E_{C2} - E_{C1}$$

$$\text{maquinas} = (T_1 = T_2) = (Fd)_0 = (Fd)_f$$

$$\text{Eficiencia} = \frac{\text{energía útil}}{\text{energía alimentada}}$$

$$N = \text{Kg m/s}^2$$

$$\text{Momento } p = mv$$



caída libre

$$V_f = V_0 + gt$$

$$V_f^2 = V_0^2 + 2gh$$

$$h = V_0 t + \frac{1}{2} g t^2$$

$$h = \left( \frac{V + V_0}{2} t \right)$$

$$t = \frac{V - V_0}{g}$$

$$t = \sqrt{\frac{2h}{g}}$$

Rapidez Tangencial

$$V \sim r \omega$$

$r =$  radio

$\omega =$  rapidez rotacional

Centro de masa

$$X_{cm} = \frac{M_1 x_1 + M_2 x_2 + M_3 x_3 + \dots}{M_1 + M_2 + M_3 + \dots}$$

$$M_1 + M_2 + M_3 + \dots$$

Fuerza centrípeta

$$F = \frac{M V^2}{r}$$

$V =$  rapidez tangencial

Cantidad de movimiento angular

$$= \text{inercia de rotación} \times \text{velocidad de rotación} = I \omega = M V r$$

Momento de torsión

$$= \text{brazo de palanca} \times \text{Fuerza}$$

Proyectiles:

$$x = (V_0 \cos \alpha_0) t$$

$$y = (V_0 \sin \alpha_0) t - \frac{1}{2} g t^2$$

$$r = \sqrt{x^2 + y^2}$$

$$V_x = V_0 \cos \alpha_0$$

$$V_y = V_0 \sin \alpha_0 - g t$$

$$V = \sqrt{V_x^2 + V_y^2}$$