

# Design and Analysis of Algorithms

# Divide and Conquer

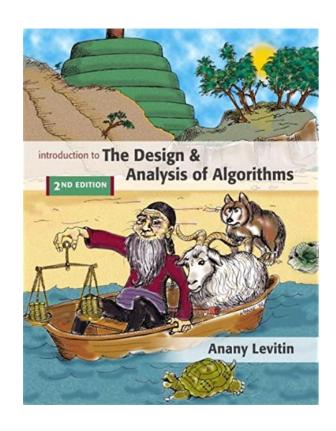
Manjula L

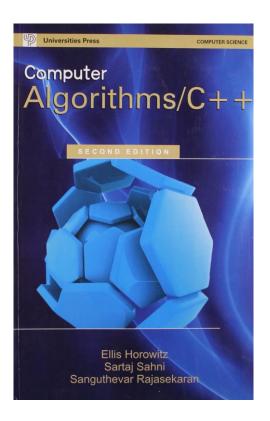
**Asst. Prof. Dept. of CSE** 

RNSIT, Bengaluru, India



### **Text Books**







- Divide-and-Conquer (DaC) is probably the best-known general algorithm design technique.
- Given a function to compute on n input the DaC approach suggests splitting the inputs into k distinct subsets,1< k < n, yielding k subproblems
- These subproblem must be solved and then a method must be found to combine solutions into a solution of the whole.
- If the sub problems are relatively large then the divide and conquer approach can possibly be reapplied
- Often the sub problems resulting from our divide and conquer design are of the same type as the original problem.
- Fur those cases the re application of the divide and conquer principle is naturally expressed by a recursive algorithm
- The smaller and smaller sub problems of the same kind are generated until eventually sub problems that are small enough to be solved without splitting are produced



**Example:** Detecting a counterfeit coin

- Given a bag of n coins and a machine that weighs 2 sets of coins, the task is to find
  - Whether the bag contains a counterfeit coin
  - If present then identify the Counterfeit coin



#### **Control abstraction for Divide and Conquer approach**

```
Algorithm DAndC(P)
                                        Boolean valued function that determines
                                        whether the input is small enough or not
       if Small(P) then return S(P) Solution to the problem
        else
          divide P into Smaller instances P1, P2, P3 ... Pk, k≥1;
          Apply DAndC to each of these subproblems;
          return Combine(DAndC(P1), DAndC(P2),...DAndC(Pk));
```

A function that determines the solution to

**P** using the solutions to **k** subproblems



• If the size of **P** is **n**, And the sizes of the **k** subproblems are **n1**, **n2**, **n3**... **nk**, respectively, then the computing time of DAndC is described by the recurrence relation

$$T(n) = \begin{cases} g(n) & n \text{ small} \\ T(n_1) + T(n_2) + \dots + T(n_k) \text{ otherwise} \end{cases}$$

#### Where,

- **T(n)** is the time for DAndC on any input of size n
- **g(n)** is the time to compute the answer directly for small inputs
- **f(n)** is the time for dividing **P** and combining the solutions to subproblems.



• The complexity of many divide and conquer is given by recurrences of the form

$$T(n) = \begin{cases} T(1) & n = 1 \\ aT(\frac{n}{b}) + f(n) & n > 1 \end{cases}$$

#### Where,

- **a** and **b** are constants
- **T(1)** is known
- $\mathbf{n}$  is a power of  $\mathbf{b}$  (i.e.,  $\mathbf{n}=\mathbf{b}^{\mathbf{k}}$ )



# Binary Search

- Binary search is a remarkably efficient algorithm for searching in a sorted array
- It works by comparing a search key **K** with the array's middle element **A**[m].
- If they match, the algorithm stops; otherwise, the same operation is repeated recursively for the first half of the array if K < A[m], and for the second half if K > A[m]

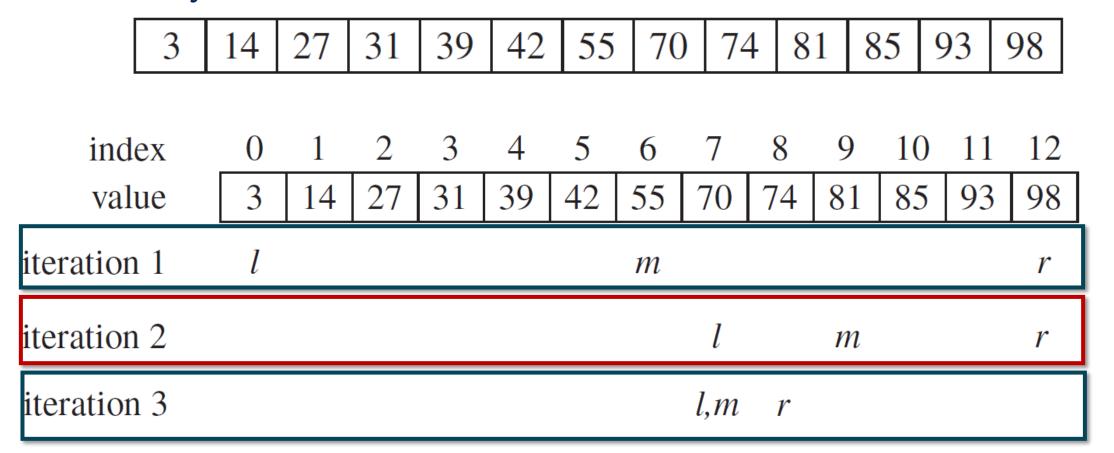
$$\underbrace{A[0] \dots A[m-1]}_{\text{search here if}} A[m] \underbrace{A[m+1] \dots A[n-1]}_{\text{search here if}}.$$



# **Binary Search**

#### **Example**

Apply binary search algorithm to the following set of numbers considering 70
as the key





# Binary Search: Non-Recursive

```
Algorithm BinSearch(a, n, x)
  // Given an array a[1:n] of elements in nondecreasing
   // order, n \geq 0, determine whether x is present, and
    // if so, return j such that x = a[j]; else return 0.
5
6
        low := 1; high := n;
        while (low \le high) do
            mid := |(low + high)/2|;
            if (x < a[mid]) then high := mid - 1;
            else if (x > a[mid]) then low := mid + 1;
                  else return mid;
14
        return 0;
15
```



# Binary Search: Recursive

```
Algorithm BinSrch(a, i, l, x)
    // Given an array a[i:l] of elements in nondecreasing
    // order, 1 \le i \le l, determine whether x is present, and
     // if so, return j such that x = a[j]; else return 0.
5
         if (l = i) then // If Small(P)
             if (x = a[i]) then return i;
              else return 0;
10
11
         else
         \{ // \text{ Reduce } P \text{ into a smaller subproblem. } \}
12
              mid := \lfloor (i+l)/2 \rfloor;
13
             if (x = a[mid]) then return mid;
14
              else if (x < a[mid]) then
15
                        return BinSrch(a, i, mid - 1, x);
16
                    else return BinSrch(a, mid + 1, l, x);
17
18
19
```



# Binary Search: Analysis

#### **Recurrence Relation**

$$T(n) = \begin{cases} 1 & n = 1 \\ T\left(\frac{n}{2}\right) + 1 & n > 1 \end{cases}$$

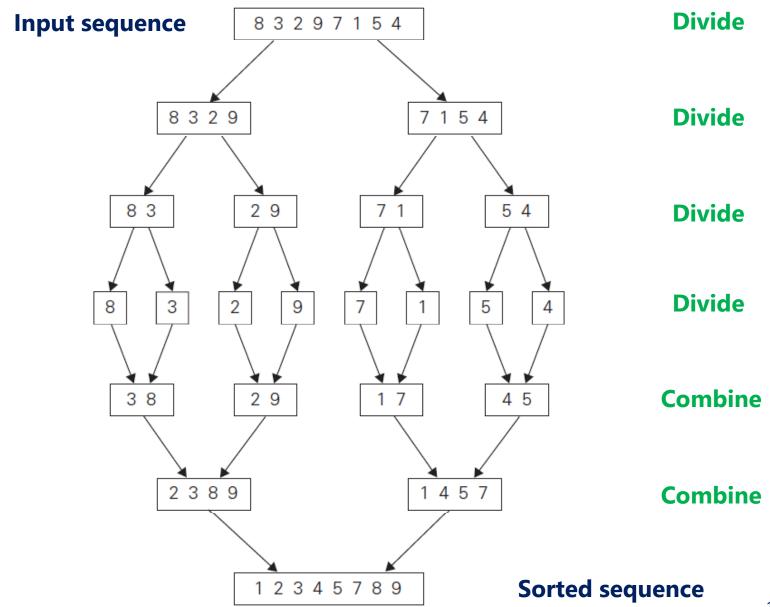
#### **Solution**

```
T(n) = T(n/2) + 1
    = [T(n/4)+1]+1 = T(n/4)+2
    =[T(n/8)+1]+2 = T(n/8)+3
=T(n/2^k)+k  n=b^k, n=2^k, logn=log2^k, k=logn
  =T(n/n)+k
   =1+k
    =1+\log n
T(n)=O(\log n)
```



- Merge sort is a perfect example of a successful application of the divide-and conquer technique.
- It has the nice property that in the worst case its complexity is **O(nlogn)**.
- Let us assume that the set of elements are to be sorted in **non-decreasing** order that is in **ascending** order.
- Given a sequence of n elements, a[1].....a[n], the idea is to imagine them split into two sets a[1].....a[ $\lfloor n/2 \rfloor$ ] and a[ $\lfloor n/2 \rfloor + 1$ ].....a[n].
- Each set is individually sorted, and the resulting sorted sequences are merged to produce a single sorted sequence of **n** elements
- This is an ideal example of the divide-and-conquer strategy in which the splitting is into two equal-sized sets and the combining operation is the merging of two sorted sets into one







#### Do it yourself

Consider the input sequence

11, 44, 22, 99, 66, 33, 88, 55, 77, 00

Obtain the merge sort tree representation showing the divide and combine phase



# Merge Sort – algorithm

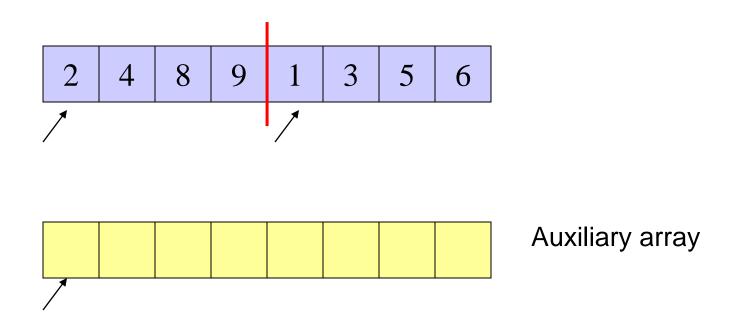
```
Algorithm MergeSort(low, high)
   //a[low:high] is a global array to be sorted.
   // Small(P) is true if there is only one element
    // to sort. In this case the list is already sorted.
5
6
        if (low < high) then // If there are more than one element
             // Divide P into subproblems.
8
                 // Find where to split the set.
9
                      mid := \lfloor (low + high)/2 \rfloor;
10
             // Solve the subproblems.
                 MergeSort(low, mid);
12
                 MergeSort(mid + 1, high);
13
             // Combine the solutions.
14
                 Merge(low, mid, high);
15
16
17
```



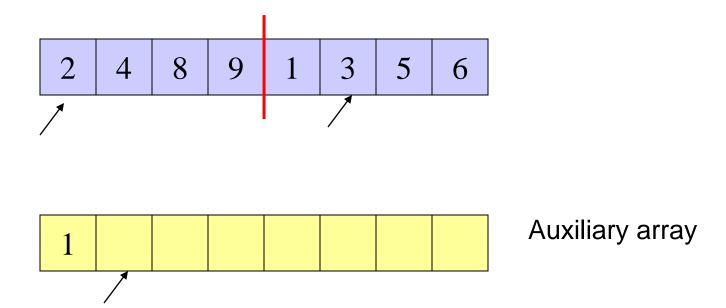
# Merge Sort – algorithm

```
Algorithm Merge(low, mid, high)
    // a[low:high] is a global array containing two sorted
    // subsets in a[low:mid] and in a[mid+1:high]. The goal
    // is to merge these two sets into a single set residing
     // in a[low:high]. b[] is an auxiliary global array.
         h := low; i := low; j := mid + 1;
         while ((h \leq mid) \text{ and } (j \leq high)) do
10
             if (a[h] \leq a[j]) then
11
                  b[i] := a[h]; h := h + 1;
12
13
14
             else
15
16
                 b[i] := a[j]; j := j + 1;
17
             i := i + 1;
18
19
20
         if (h > mid) then
21
             for k := j to high do
22
                 b[i] := a[k]; i := i + 1;
23
^{24}
25
         else
26
             for k := h to mid do
27
28
                 b[i] := a[k]; i := i + 1;
29
         for \hat{k} := low to high do a[k] := b[k];
30
31 }
```

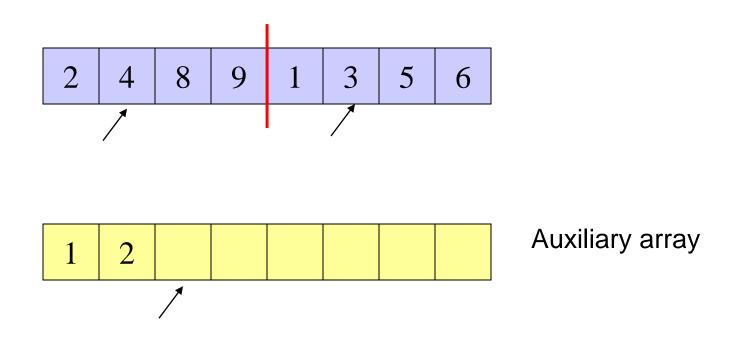




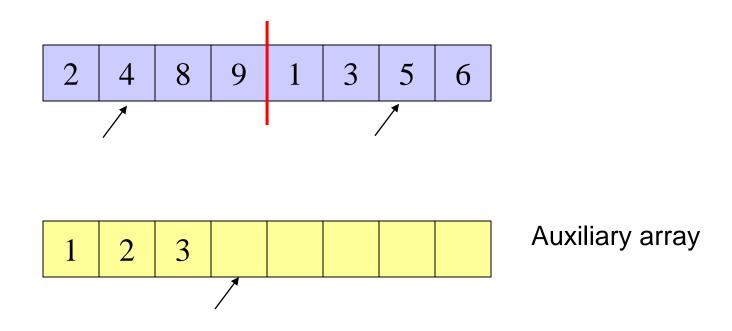




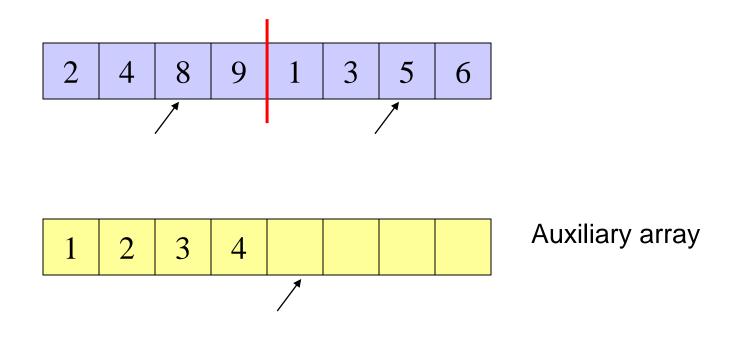




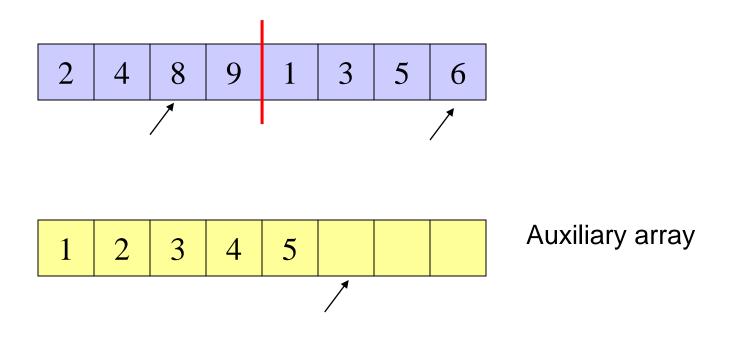




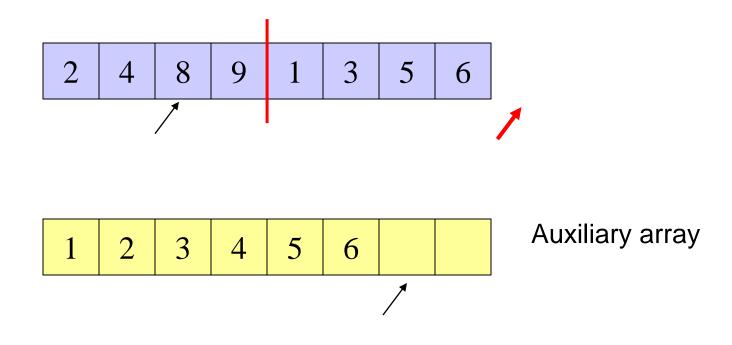




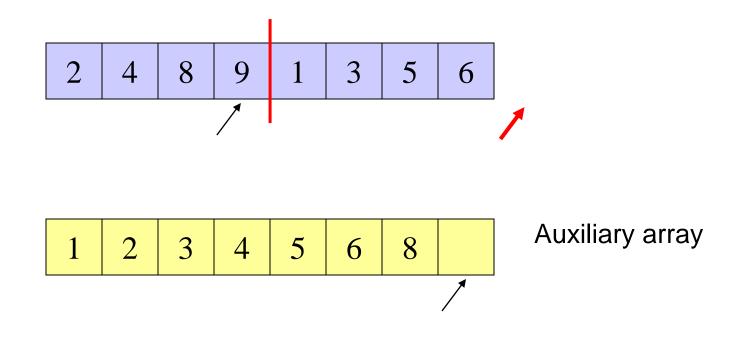




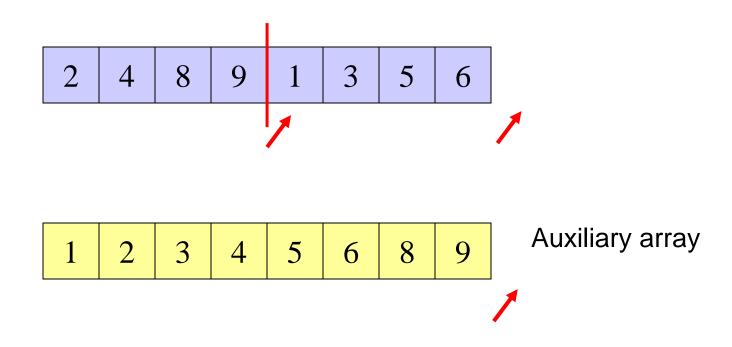














Lets Trace the algorithm

```
Algorithm MergeSort(low, high)
       if (low<high) then
          mid = \lfloor (low + high)/2 \rfloor
       MergeSort(low, mid)
       MergeSort(mid+1, high)
          Merge(low, mid, high)
```

Find the tracing in the video



# Merge Sort -Analysis

■ The recurrence relation for Merge sort is given by

$$T(n) = \begin{cases} a & n = 1, a \text{ is a constant} \\ 2T\left(\frac{n}{2}\right) + cn & n > 1, c \text{ is a constant} \end{cases}$$

#### Solution

```
In the given relation a=2, b=2, f(n)=cn, n is power of b so n=b^k, n=2^k
T(n)=2T(n/2) + cn substitute T(n/2)=2T(n/4)+c(n/2)
    = 2[2[T(n/4)+cn/2)] + cn
    =4T(n/4)+2cn substitute T(n/4)=2T(n/8)+c(n/4)
    =4[2T(n/8)+cn/4)+2cn
    =8T(n/8)+3cn
The general pattern?
    = 2^k T(n/2^k) + kcn  n=2^k, k=logn
    =nT(1)+logncn
    = n+cnlogn considering only leading term and ignoring constants we get
T(n) = \Theta(n \log n)
```



# Merge Sort -Summary

#### **Properties summarized**

- Merge Sort is useful for sorting linked lists.
- Merge Sort is a stable sort which means that the same element in an array maintain their original positions with respect to each other.
- Overall time complexity of Merge sort is  $\Theta(nlogn)$ .
  - i.e. its best, worst and average case time complexity is  $\Theta(nlogn)$ .
- It is more efficient as it is in worst case also the runtime is  $\Theta(n \log n)$
- The space complexity of Merge sort is O(n). This means that this algorithm takes a lot of space and may slower down operations for the large data sets.
- Merge sort is not in-place sorting



- Quicksort is the other important sorting algorithm that is based on the divideand conquer approach.
- Unlike merge sort, which divides its input elements according to their position in the array, quicksort divides them according to their value.
- The idea of array partition is used in this sorting.
- A partition is an arrangement of the array's elements so that all the elements to the left of some element A[s] are less than or equal to A[s], and all the elements to the right  $\frac{bf}{A[s]}$  are greater than or equal to it:

 $A[1] \dots A[S-1]$  A[S]  $A[S+1] \dots A[n]$ 

• Obviously, after a partition is achieved, A[s] will be in its final position in the sorted array, and we can continue sorting the two subarrays to the left and to the right of A[s] independently

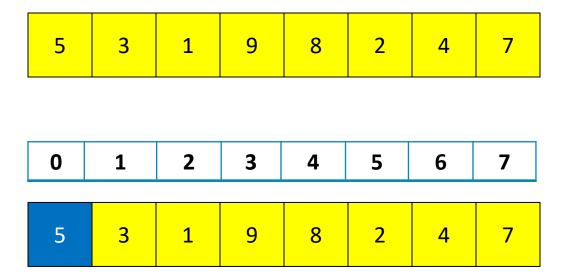


- Now note the difference between the working of Merge sort and Quick sort
- In Merge sort the division of the problem into two subproblems is immediate and the entire work happens in combining their solutions;
- In Quick sort, the entire work happens in the division stage, with no work required to combine the solutions to the subproblems.



#### **Pivot Element**

- There are a number of ways to pick the pivot element.
- In this example, we will use the first element in the array:



**Pivot** 



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
       swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[1],a[j])
                    0
                         1
                                            5
return j
                         3
                              1
                                  9
                                            2
```



```
Let the pivot element be p, i.e., p=a[l], i=l, j=r+1
Following are the rules repeat

Increment i until a[i] \ge p [till u get greater number than pivot ]

Decrement j until a[j] \le v [till u get lesser number than pivot ]

swap a[i] and a[j]
```

```
until i ≥ j
swap (a[i],a[j])
swap(a[l],a[j])
return j
```

0	1	2	3	4	5	6	7
5	3	1	9	8	2	4	7
p							1
i		j					



```
Let the pivot element be p, i.e., p=a[l], i=l, j=r+1

Following are the rules

repeat

Increment i until a[i] ≥ p [till u get greater
```

```
Increment i until a[i] ≥ p [till u get greater number than pivot ]
Decrement j until a[j] ≤ v [till u get lesser number than pivot ]
swap a[i] and a[j]
```

until i ≥ j swap (a[i],a[j]) swap(a[l],a[j]) return j

0	1	2	3	4	5	6	7	
5	3	1	9	8	2	4	7	
p				1				
i				j				



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
       swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[1],a[j])
                    0
                         1
                                            5
return j
                         3
                              1
                                            2
                   p
```

stop



```
Let the pivot element be p, i.e., p=a[l], i=l,j=r+1
Following are the rules
repeat

Increment i until a[i] ≥ p [till u get greater number than pivot]

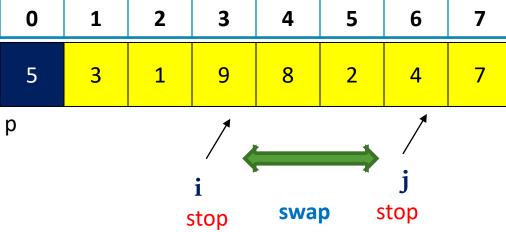
Decrement j until a[j] ≤ v [till u get lesser number than pivot]

swap a[i] and a[j]

until i ≥ j

swap (a[i],a[j])
```

until $1 \ge J$
swap (a[i],a[j])
<pre>swap(a[l],a[j])</pre>
return j





```
Let the pivot element be p, i.e., p=a[l], i=l, j=r+1
Following are the rules
repeat

Increment i until a[i] ≥ p [till u get greater number than pivot]

Decrement j until a[j] ≤ v [till u get lesser number than pivot]

swap a[i] and a[j]
```

```
until i ≥ j
swap (a[i],a[j])
swap(a[l],a[j])
return j
```

0	1	2	3	4	5	6	7
5	3	1	4	8	2	9	7
р					1		
	i				J		



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) 0
                     1
                          2
                                        5
return j
                     3
                          1
               p
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) 0
                     1
                          2
                                        5
                                             6
return j
                     3
                          1
               p
```

swap



```
Let the pivot element be p, i.e., p=a[l], i=l, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) 0
                     1
                          2
                                        5
return j
                     3
                          1
               p
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) o
                     1
                          2
                                        5
                                             6
return j
                     3
                          1
               p
                                                        stop
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) o
                     1
                          2
                                        5
                                             6
return j
                     3
                          1
               p
                                                        stop
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
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   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) o
                     1
                          2
                                        5
                                             6
return j
                     3
                          1
               p
                                                        stop
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
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      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) o
                     1
                          2
                                        5
return j
                     3
                          1
               p
                 swap
```



```
Let the pivot element be p, i.e., p=a[1], i=1, j=r+1
Following are the rules
repeat
   Increment i until a[i] \ge p [till u get greater number than pivot]
   Decrement j until a[j] \le v [till u get lesser number than pivot]
      swap a[i] and a[j]
until i \ge j
swap (a[i],a[j])
swap(a[l],a[j]) o
                     1
                          2
                                        5
return j
                     3
                          1
               p
                 swap
```



#### Do it yourself

• Obtain the first partition for the following set of elements considering the first element as the pivot element

■ Apply quicksort to sort the list **E**, **X**, **A**, **M**, **P**, **L**, **E** in alphabetical order



```
ALGORITHM Quicksort(A[l..r])
    //Sorts a subarray by quicksort
    //Input: A subarray A[l..r] of A[0..n-1], defined by its left and right indices
            l and r
    //Output: Subarray A[l..r] sorted in nondecreasing order
    if l < r
        s \leftarrow Partition(A[t..r]) //s is a split position
        Quicksort(A[l..s-1])
        Quicksort(A[s+1..r])
```



```
ALGORITHM Partition(A[l..r])
    //Partitions a subarray by using its first element as a pivot
    //Input: A subarray A[l..r] of A[0..n-1], defined by its left and right
             indices l and r (l < r)
    //Output: A partition of A[l..r], with the split position returned as
                this function's value
    p \leftarrow A[l]
    i \leftarrow l; j \leftarrow r + 1
    repeat
         repeat i \leftarrow i + 1 until A[i] \geq p
        repeat j \leftarrow j-1 until A[j] \leq p
         swap(A[i], A[j])
    until i \geq j
    \operatorname{swap}(A[i], A[j]) //undo last swap when i \geq j
    swap(A[l], A[j])
    return j
```



## Quick Sort – Analysis (Best Case)

• The recurrence relation is given by

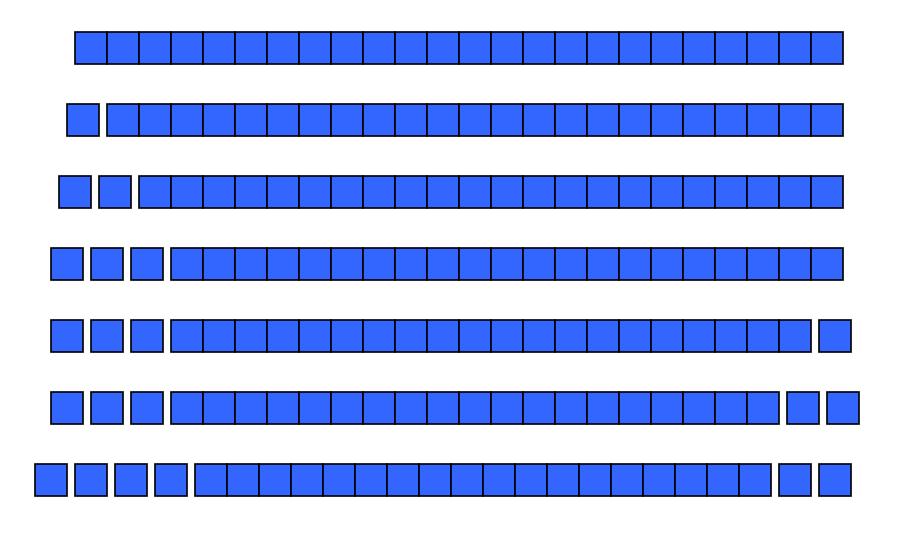
$$T(n) = \begin{cases} a & n = 1, a \text{ is a constant} \\ 2T(\frac{n}{2}) + n & n > 1, c \text{ is a constant} \end{cases}$$

#### Solution

```
In the given relation a=2, b=2, f(n)=cn, n is power of b so n=b^k, n=2^k
T(n)=2T(n/2)+n substitute T(n/2)=2T(n/4)+(n/2)
    = 2[2[T(n/4)+n/2)] + n
    =4T(n/4)+2n substitute T(n/4)=2T(n/8)+(n/4)
    =4[2T(n/8)+n/4)+2n
    =8T(n/8)+3n
The general pattern?
    = 2^{k}T(n/2^{k})+kn \qquad n=2^{k}, \quad k=logn
    =nT(1)+logn n
    = n+cnlogn considering only leading term and ignoring constants we get
                               T(n)_{Regt} = \Theta(nlogn)
```



## Quick Sort- Analysis (Worst Case)





## Quick Sort- Analysis (Worst Case)

■ The recurrence relation for worst case analysis is given by

$$T(n) = o + T(n-1) + n$$



#### Average case

$$C_{avg}(n) = \frac{1}{n} \sum_{s=0}^{n-1} [(n+1) + C_{avg}(s) + C_{avg}(n-1-s)] \quad \text{for } n > 1,$$

$$C_{avg}(0) = 0, \quad C_{avg}(1) = 0.$$

$$C_{avg}(n) \approx 2n \ln n \approx 1.38n \log_2 n$$
.



# Design and Analysis of Algorithms

## Divide and Conquer

Manjula L

Asst. Prof. Dept. of CSE RNSIT, Bengaluru, India



- Let A and B be two n x n matrices
- The product matrix C= AB is also an n x n matrix whose i, j<sup>th</sup>element is formed by taking the elements in the i<sup>th</sup> row of **A**and j<sup>th</sup> column of **B** and multiplying them to get
- $C(i,j) = \sum_{1 \le k \le n} A(i,k)B(k,j)$  for all i and j between 1 and n
- To compute C(i, j) using the formula above how many multiplications are needed?
- Consider an example

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \qquad B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \text{ then } C = \begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix}$$

Where,

$$c_{11} = a_{11}b_{11} + a_{12}b_{21}$$

$$c_{12} = a_{11}b_{12} + a_{12}b_{22}$$

$$c_{21} = a_{21}b_{11} + a_{22}b_{21}$$

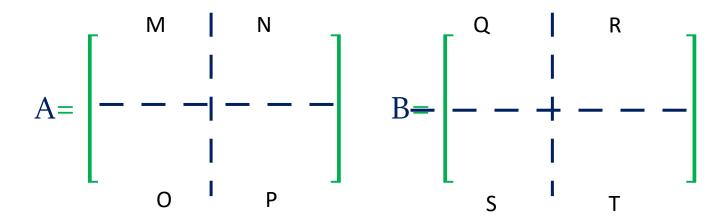
$$c_{22} = a_{21}b_{12} + a_{22}b_{22}$$

8 multiplications

Time complexity?  $\Theta(n^3)$ 



- Can we use **Divide and Conquer** approach to multiply two **n** x **n** matrices ?
- Let's assume that  $\mathbf{n}$  is power of  $\mathbf{2}$ , i.e., there exists a non-negative constant  $\mathbf{k}$  such that  $\mathbf{n} = \mathbf{2}^{\mathbf{k}}$
- If **n** is not power of **2** then add enough rows and columns of **zeros** to both **A** and **B** so that the resultant dimensions are power of **2**.
- Here is the application of Divide and Conquer approach







Consider the following situation

$$\left[\begin{array}{ccc} A_{11} & A_{12} \\ A_{21} & A_{22} \end{array}\right] \left[\begin{array}{ccc} B_{11} & B_{12} \\ B_{21} & B_{22} \end{array}\right] = \left[\begin{array}{ccc} C_{11} & C_{12} \\ C_{21} & C_{22} \end{array}\right]$$

Then

$$egin{array}{lcl} C_{11} & = & P + S - T + V \ C_{12} & = & R + T \ C_{21} & = & Q + S \ C_{22} & = & P + R - Q + U \ \end{array}$$

Where

$$P = (A_{11} + A_{22})(B_{11} + B_{22})$$

$$Q = (A_{21} + A_{22})B_{11}$$

$$R = A_{11}(B_{12} - B_{22})$$

$$S = A_{22}(B_{21} - B_{11})$$

$$T = (A_{11} + A_{12})B_{22}$$

$$U = (A_{21} - A_{11})(B_{11} + B_{12})$$

$$V = (A_{12} - A_{22})(B_{21} + B_{22})$$



• Consider the following matrices and compute the product using Strassen's Method C = P + S - T + V

■ A= 
$$\begin{bmatrix} 2 & 4 \\ 3 & 5 \end{bmatrix}$$
 B=  $\begin{bmatrix} 1 & 3 \\ 4 & 7 \end{bmatrix}$   
P= (2+5) (1+7)= 7\* 8= 56  
Q= (3+5)\* 1= 8  
R= 2\* (3-7)= -8  
S= 5\*(4-1)= 15  
T= (2+4) \*7= 42  
U= (3-2)\* (1+3)= 4  
V= (4-5)\* (4+7)=-11

$$egin{array}{lll} C_{11} & = & P+S-T+V \ C_{12} & = & R+T \ C_{21} & = & Q+S \ C_{22} & = & P+R-Q+U \ \end{array}$$

$$P = (A_{11} + A_{22})(B_{11} + B_{22})$$

$$Q = (A_{21} + A_{22})B_{11}$$

$$R = A_{11}(B_{12} - B_{22})$$

$$S = A_{22}(B_{21} - B_{11})$$

$$T = (A_{11} + A_{12})B_{22}$$

$$U = (A_{21} - A_{11})(B_{11} + B_{12})$$

$$V = (A_{12} - A_{22})(B_{21} + B_{22})$$



$$\begin{pmatrix} 5 & 2 & 6 & 1 \\ 0 & 6 & 2 & 0 \\ 3 & 8 & 1 & 4 \\ 1 & 8 & 5 & 6 \end{pmatrix} \times \begin{pmatrix} 7 & 5 & 8 & 0 \\ 1 & 8 & 2 & 6 \\ 9 & 4 & 3 & 8 \\ 5 & 3 & 7 & 9 \end{pmatrix} = \begin{pmatrix} 96 & 68 & 69 & 69 \\ 24 & 56 & 18 & 52 \\ 58 & 95 & 71 & 92 \\ 90 & 107 & 81 & 142 \end{pmatrix}$$

I now want to use strassen's method which I learned as follows:

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} \times \begin{pmatrix} E & F \\ G & H \end{pmatrix} = \begin{pmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{pmatrix}$$



## Time efficiency

- M(n) = 7 M(n/2) for n > 1, M(1) = 1
- Since n= 2 ^ k
- $M(2^K) = 7M(2^K-1)$

- 7 ^ i M(2 ^ (k-k)
- 7^k
- K=log2 n
- n ^ 2.807



## Pros of Divide and Conquer Strategy

- Solving difficult problems
- Algorithm efficiency
- Parallelism Suitable for multiprocessor machines
- Memory access optimal cache-oblivious algorithms



## Cons of Divide and Conquer Strategy

- Divide and Conquer strategy uses recursion that makes it a little slower and if a little error occurs in the code the program may enter into an infinite loop.
- Usage of explicit stacks may make use of extra space.

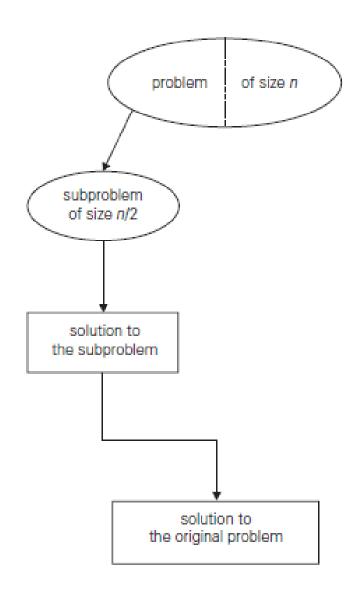


### Decrease and Conquer

- This technique is based on exploiting the relationship between a solution to a given instance of a problem and a solution to a smaller instance of the same problem. Once such relationship is established, it can be exploited either top down (recursively) or bottom up (without a recursion).
- There are three major variations of decrease-and-conquer:
  - Decrease by a constant.
  - Decrease by a constant factor.
  - Variable size decrease.



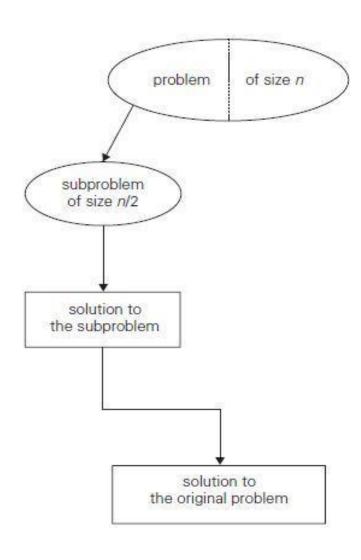
## Decrease by a constant



$$f(n) = \begin{cases} f(n-1) \cdot a & \text{if } n > 0, \\ 1 & \text{if } n = 0, \end{cases}$$



## Decrease by a constant Factor



$$a^{n} = \begin{cases} (a^{n/2})^{2} & \text{if } n \text{ is even and positive,} \\ (a^{(n-1)/2})^{2} \cdot a & \text{if } n \text{ is odd,} \\ 1 & \text{if } n = 0. \end{cases}$$



#### Variable size decrease

$$\blacksquare$$
gcd (m, n) = gcd (n, m mod n).



# THANK YOU