

# Library Evolutionary Algorithms for Clustering (LEAC)

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User guide  
for LEAC version 1.8  
7 March 2016

by Hermes Robles, Sebastian Ventura, Amelia Zafra.

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This user guide is for Library LEAC (version 1.8, 7 March 2016), and documents commands for clustering analysis.

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# Table of Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
<b>2</b>	<b>Preliminaries</b>	<b>3</b>
2.1	Definitions	3
<b>3</b>	<b>LEAC Software</b>	<b>7</b>
3.1	Genetic algorithm introduction	7
3.2	Building an application	8
3.2.1	Encoding criterion	8
3.2.1.1	Cluster labels	10
	String-of-group-numbers encoding	10
	Matrix-based binary encoding	10
3.2.1.4	Centroid-based	11
	Real encoding	11
	Binary encoding	12
3.2.1.7	Medoid-based	14
	Integer encoding	14
	Binary encoding	14
3.2.1.10	Graph-based	14
	Binary encoding	15
3.2.2	Initialization of population	15
3.2.3	Fitness function	16
3.2.3.1	Distances	16
3.2.3.2	Unsupervised measures	19
	Sum of quadratic errors (SSE)	19
	Least-squared errors functional	21
	Sum of Euclidean Distance	22
	Davis-Bouldin Index	23
	Silhouette	23
	Simplified Silhouette	24
	CS measure	24
	Dunn's index	25
	Simplified Dunn's index	25
	Variance ratio criterion	26
	Intra- and inter-cluster distance	27
	Validity index I	27
	Xie-Beni index	28
3.2.3.16	Supervised measures	29
	Rand Index	29
	Purity	30
	Precision	30
	Recall	30

3.2.4	Stop Criterion.....	30
3.2.5	Evolution schema .....	30
3.2.6	Criterion for selecting parents .....	31
3.2.7	Crossover operator .....	31
3.2.8	Mutation operator .....	32
3.2.9	Other parameters .....	32
<b>4</b>	<b>Get and Install LEAC software .....</b>	<b>35</b>
4.1	Getting the software LEAC .....	35
<b>5</b>	<b>Illustrative examples .....</b>	<b>39</b>
5.1	Partition for fixed k-cluster.....	39
5.1.1	Based on the centroids .....	40
5.1.2	Based on the most representative.....	51
5.2	Partition for variable k-cluster.....	55
5.2.1	Based on the centroids .....	55
5.2.2	Based on cluster label .....	60
5.2.3	Based on other schemes .....	64
<b>6</b>	<b>Reporting Bugs.....</b>	<b>67</b>
<b>Appendix A</b>	<b>Example source code .....</b>	<b>69</b>
A.1	KGA algorithm.....	69
A.2	GA algorithm .....	88
<b>Bibliography</b> .....		<b>111</b>
<b>Appendix B</b>	<b>GNU Free Documentation License</b> .....	<b>115</b>
<b>Appendix C</b>	<b>Concept index.....</b>	<b>123</b>

# 1 Introduction

Library Evolutionary Algorithms for Clustering (LEAC) is a library for the implementation of evolutionary and genetic algorithms to solve the problem of *partition clustering* (See [HK17], page 112).

Clustering is useful in several exploratory *pattern-analysis*, *grouping*, *decision-making*, and *machine-learning situations*, including *data mining*, *document retrieval*, *image segmentation*, and *pattern classification* [JMF99], page 112. \cite Jain:Murty:Flynn:ClusteringSurvey:1999

LEAC is based on the current standards of the C++ language, as well as on Standard Template Library (STL) and also OpenBLAS to have a better performance. Taking advantage of the characteristics of the C++ language as hybrid language, generic programming, multi-paradigms and lambda function and the C++11 versions and C++14. It allowed the implementation of different evolutionary and genetic algorithms. The approach of LEAC to implement the particular characteristics of each algorithm is to encode the diversity of the proposed genetic operators and to use the containers and interpliers of STL to evolve the population according to the flowchart of the algorithms.

LEAC in addition to being used as a modular library, as part of this includes a wide collection of genetic and evolutionary programs (EAC). From the point of view of the user who needs to process a data set, these programs can be used to obtain a pattern or an exploratory classification using grouping techniques, the list of programs together with the paper on which it is based are listed below:

## Fixed-K

### Encode label

GA `gaclustering_fklabel`, [MC96], page 113

GKA `gka_fklabel`, [KM99], page 112

IGKA `igka_fklabel`, [LLF+04b], page 113

FGKA `fgka_fklabel`, [LLF+04a], page 113

### Encode crisp matrix

GA `gaclustering_fkcrispmatrix`, [BBHB94], page 111

### Encode centroids

GAS `gas_fkcentroid`, [MB00], page 113

KGA `kga_fkcentroid`, [BM02a], page 111

GAGR `gagr_fkcentroid`, [CZZ09], page 112

CBGA `cbga_fkcentroid_int` with integer arithmetic [FKKN97], page 112, and an extension for instances with real attributes `cbga_fkcentroid`

## Medoid

### GA-Prototypes

`gaprototypes_fkmedoid`, [KB97], page 112

HKA `hka_fkmedoid`, [SL04], page 113

GCA    gca\_fkmedoid, [LDK93], page 113

Variable-K

  Encode label

    GGA    gga\_vklabeledbindex and  
          gga\_vklabelsilhouette, [ABSSJF+12], page 111

    CGA    cga\_vklabel, [HE03], page 112

    EAC    eac\_vklabel, [HCdC06], page 112

    EAC I    eaci\_vklabel, [ACH06], page 111

    EAC II    eacii\_vklabel, [ACH06], page 111

    EAC III    eaciii\_vklabel, [ACH06], page 111

    FEAC    feac\_vklabel, [ACH06], page 111

  Encode centroids

    GCUK    gcuk\_vkcentroid, [BM02b], page 111

    TGCA    tgca\_vkcentroid, [HT12], page 112

  Encode other

    CLUSTERING

      clustering\_vksubclusterbinary, [TY01], page 113

    GA    gaclustering\_vktreebinary, [CdLM03], page 111

## 2 Preliminaries

### 2.1 Definitions

A common input for clustering algorithms is a dataset  $X$  having  $n$   $d$ -dimensional *object* or *instance*  $X = \{x_1, x_2, \dots, x_n\}$ . To manipulate dataset we use the following convention for subscripts  $i$ ;  $i \in \{1, 2, \dots, n\}$ , where  $x_i$  represents the object  $i$ th. The terms *object*, *instances*, *object*, *points* or *prototype* usually have the same meaning in the literature on *clustering analysis* and will be freely interchanged in this document. To refer to the dimensions of the objects we use  $l$ :  $l \in \{1, 2, \dots, d\}$ , so  $l$ th denotes the dimension of  $x_{il}$ . An artificial dataset for illustrative purposes is shown in the [Table 2.1](#) and [Figure 2.1](#) with  $n = 15$  and attributes  $d = 2$ . For the case of clustering analysis the input dataset may be classified or not as shown in the Class column, when included it is said to be a *supervised* analysis and when it is *unsupervised*. The class column for the case of clustering analysis can be used to verify the quality of the cluster.

Instance	$x_{i1}$	$x_{i2}$	Class
$x_1$	1	1	Class-1
$x_2$	2	1	Class-1
$x_3$	1	2	Class-1
$x_4$	2	3	Class-1
$x_5$	3	3	Class-1
$x_6$	4	6	Class-2
$x_7$	4	7	Class-2
$x_8$	5	7	Class-2
$x_9$	6	8	Class-2
$x_{10}$	6	9	Class-2
$x_{11}$	7	8	Class-2
$x_{12}$	8	2	Class-3
$x_{13}$	9	2	Class-3
$x_{14}$	9	3	Class-3
$x_{15}$	8	3	Class-3

Table 2.1: An artificial dataset for illustrative purposes.

The purpose of the *clustering problem* is to find an optimal partition of  $X$  in  $k$  subsets  $C_1, C_2, \dots, C_k$  ( $k \leq n$ ). So that the objects that are in the same group are more similar between them and the objects of the other groups are the most different. The subscript for the groups is  $j$ ;  $j \in \{1, 2, \dots, k\}$  and the centroid of cluster  $C_j$  is denoted as  $\mu_j$ .

Formally under the partitioning approach the problem of clustering is defined as [\[NP14\]](#), [page 113](#)

$$\begin{aligned}
 &C_j \neq \emptyset \quad \forall j = 1, 2, \dots, k; \\
 &C_j \cap C_{j'} = \emptyset \quad \forall j, j' = 1, \dots, k \quad \text{and} \quad \cup_{j=1}^k C_j = X.
 \end{aligned} \tag{1.1}$$

The clustering operation is dependent on the similarity between elements present in the data set. If  $f$  denotes the fitness function then the clustering task is viewed as an optimization problem as

$$\text{Optimize}_{C_k} [f(X, C_j)] \quad \forall j = 1, 2, \dots, k$$

A possible partition for the dataset of the Table 2.1, for  $k = 3$  clusters is

$$\begin{aligned} C_1 &= \{x_{12}, x_{13}, x_{14}, x_{15}\}, \\ C_2 &= \{x_6, x_7, x_8, x_9, x_{10}, x_{11}\}, \\ C_3 &= \{x_1, x_2, x_3, x_4, x_5\}. \end{aligned} \tag{1.1}$$

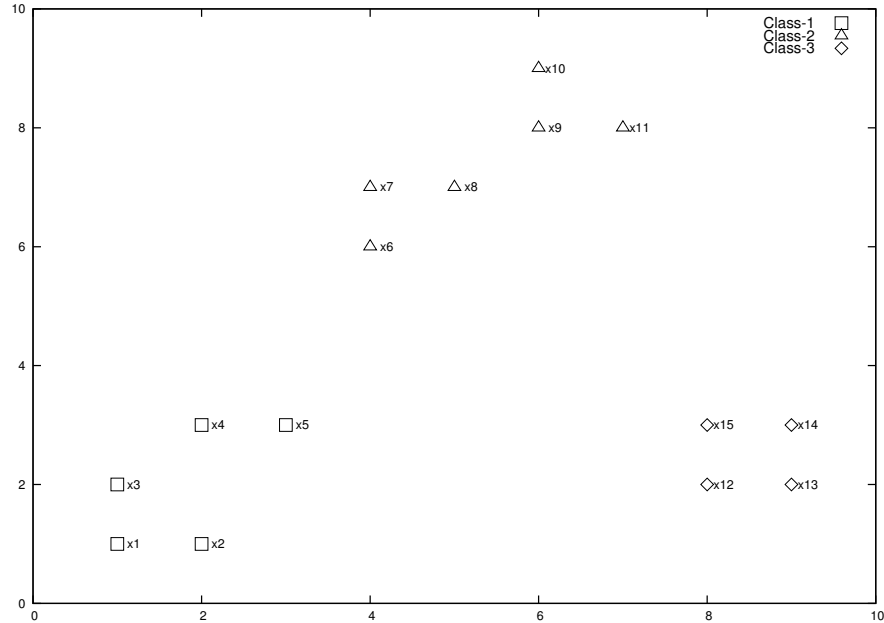


Figure 2.1: Graphic representation of artificial dataset for illustrative purposes.

There are several ways to represent a partition of a data set the three most common are:

#### Centroids

Implicitly, The partition can be derived by the *nearest object rule* into account the proximities between objects and centroids such a way that the  $i$ th object is assigned to the cluster represented by the closer (i.e., the most similar). With the centroids of the groups  $\mu_j$ , so the object  $x_i$  belongs to the cluster  $C_j$  if:

$$x_i \in C_j \leftrightarrow \|x_i - \mu_j\| \leq \min_k \|x_i - \mu_{j'}\|, \quad j' = 1, 2, \dots, k, \tag{2.1}$$

#### Prototypes

It is similar to the previous partition, the difference is that instead of using the centroids, the most representative instances are used to make the partitions.



**Membership label**

Explicitly clusters are defined by a vector length  $n$ , where  $n$  is the number of instances. The possible values in the vector are from 1 to  $k$  and the  $i$ th element establishes a relation of belonging from the  $i$ th instance to a cluster.



### 3 LEAC Software

LEAC library it is based on a *layered software architecture* and is conceptually composed of four layers, each of which consists of a set of related packets as shown in the [Figure 3.1](#). The description of each layer is described below:

#### Application

It consists of genetic and evolutionary algorithms, which use the metaheuristic layer based on genetic and evolutionary operators.

#### Metaheuristic

Implement what you need to configure GA: encoding criterion, initialization of population, criterion for selecting parents, crossover operator and mutation operator. Along with the support of the lower layers to achieve scheme of evolution.

#### Clustering

It is the layer referring to the domain of the problem.

Performance. It consists of low-level functions programmed under the current CPU architectures. For example, Data Alignment and Streaming SIMD Extensions (SSE) [\[Int10\]](#), [page 112](#). Allow top layers to work with high performance.

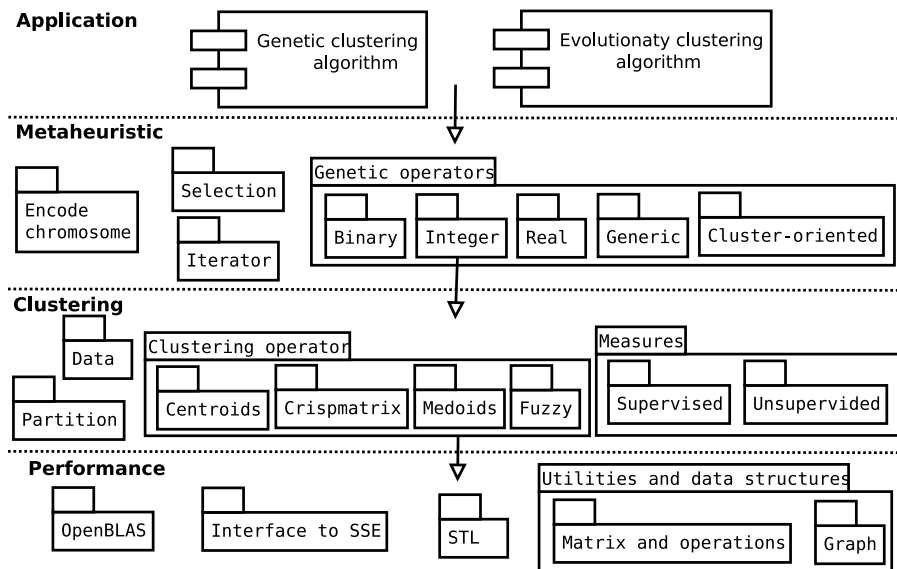


Figure 3.1: *Layered software architecture* of LEAC library.

### 3.1 Genetic algorithm introduction

Genetic Algorithms (GAs) are stochastic search methods based on the principle of natural genetic systems ([\[Gol89\]](#), [page 112](#); [\[Mic92\]](#), [page 113](#)). They perform a multi-dimensional search in order to provide an optimal value of an evaluation (fitness) function in an optimization problem. Unlike conventional search methods, GAs deal with multiple solutions simultaneously and compute the fitness function values for these solutions [\[MC96\]](#), [page 113](#).

GA creates new generations of the population by genetic operations, such as reproduction, crossover and mutation. The next generation consists of the possible survivors (i.e. the best individuals of the previous generation) and of the new individuals obtained from the previous population by the genetic operations [FKKN97], page 112.

To solve any problem the GAs must be configured, the criteria and steps to be considered are the following:

1. Encoding criterion
2. Initialization of population
3. Fitness function
4. Stop Criterion
5. Evolution schema
6. Criterion for selecting parents
7. Crossover operator
8. Mutation operator

Steps 3 through 8 correspond to the genetic cycle and are repeated until they fulfill a termination condition.

The following subsections describe how they can be implemented for the clustering problem

## 3.2 Building an application

### 3.2.1 Encoding criterion

There are different coding schemes proposed, for the case of the clustering problem traditional encoding string as *binary*, *integer* or *real*, You can also use others based on a partition of the objects in the dataset as pair of *partitioning table* and *cluster centroids*. The output of genetic and evolutionary algorithms depends on the type of coding used by each for the chromosomes and its associated phenotype: *centroid*-, *medoid*-, *label*-, *tree*-, or *graph-based* representations. The terms genotype, chromosome, and individual usually have the same meaning in the literature on evolutionary algorithms.

The different encodings are implemented in the LEAC chromosome class hierarchy shown in Figure 3.2.

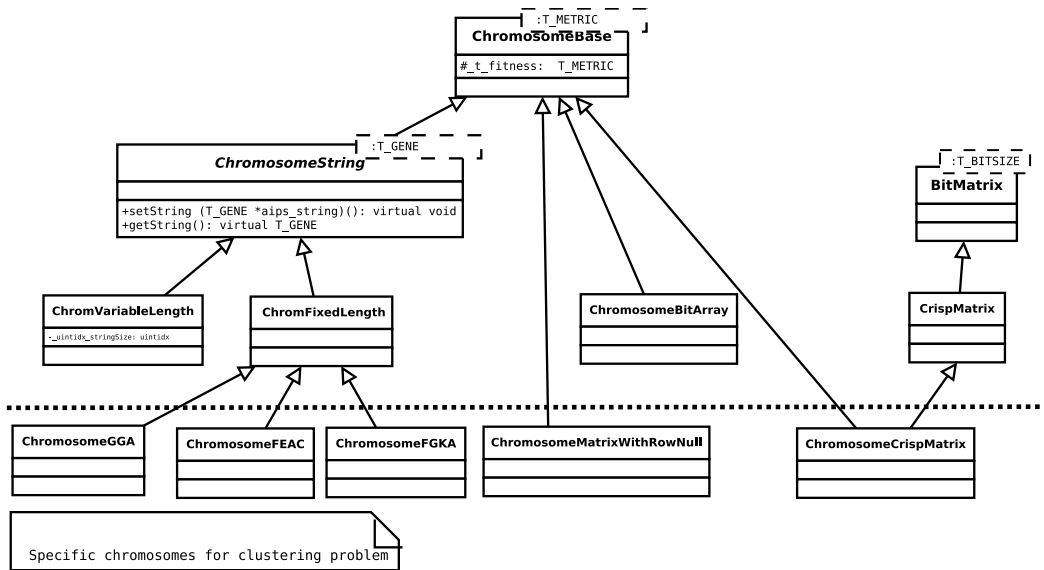


Figure 3.2: Class diagrams of the Chromosomes used for encoding.

In LEAC there are three general chromosomes that can be used to implement a large part of the encodings that are `gaencode::ChromFixedLength`, `gaencode::ChromVariableLength` and `gaencode::ChromosomeBitArray`.

**ChromFixedLength** [Method on `gaencode::ChromFixedLength`]  
`<T_GENE, T_METRIC>()`

Where `T_GENE` it is the type of data of each gene,  
`T_METRIC` it es the type of data for fitness function

Before creating the objects, you must specify the length that each chromosome will have with the following method:

**static void setStringSize** [Method on `gaencode::ChromFixedLength`]  
`(uintidx aiuintidx_stringSize)`

See [Example], page 71

**ChromVariableLength** [Method on `gaencode::ChromVariableLength`]  
`<T_GENE, T_METRIC>(const uintidx aiuintidx_stringSize)`

Where `T_GENE` it is the type of data of each gene,  
`T_METRIC` it es the type of data for fitness function

To model the binary chromosomes

**ChromosomeBitArray** [Method on `gaencode::ChromosomeBitArray`]  
`<T_BITSIZE, T_METRIC>(const uintidx aiintidx_numBits)`

Where `T_BITSIZE` size of the variable to store the bits,  
`T_METRIC` it es the type of data for fitness function

A classification based on the meaning of the coding (phenotype-genotype), used in different algorithms found in the literature is described in the following subsections.

### 3.2.1.1 Cluster labels

#### String-of-group-numbers encoding

It consists of an integer vector of length  $n$ , where  $n$  is the number of instances. The possible values in the vector are from 1 to  $k$  and the  $i$ th element establishes a relation of belonging from the  $i$ th instance to a cluster. The integer vector that encoding the partition (1.1) is:

$$[3333322222211111]$$

Graphically shown in the [Figure 3.3](#)

To instantiate the *string-of-group-numbers* chromosomes use. See [\[gaencode::ChromFixedLength\]](#), [page 9](#), where T\_GENE is integer type.

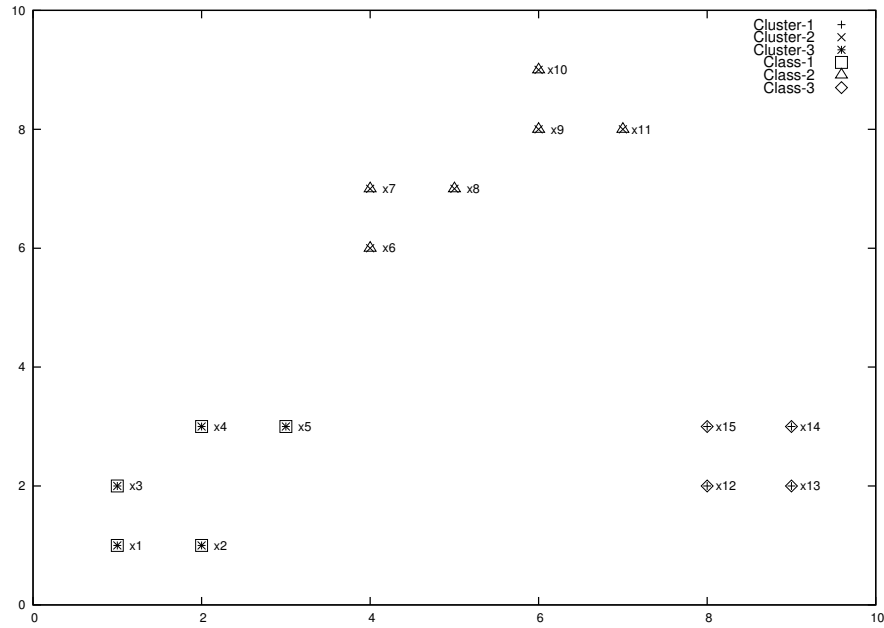


Figure 3.3: Example of *integer encoding* of artificial dataset.

#### Matrix-based binary encoding

A  $k \times n$  binary matrix can also be used to specify a partition of instances in clusters. Formally defined by [\[BEF84\]](#), [page 111](#) called *crisp partition* or *hard partition*:

$$M_c = \{U_{k \times n} | u_{ji} \in \{0, 1\}; \sum_{i=1}^n u_{ji} > 0, \text{ for all } j, \sum_{i=1}^n u_{ji} = 1, \text{ for all } i\} \quad (2.1)$$

In which the rows represent clusters and the columns represent instances. In this case, if the  $i^{th}$  object belongs to the  $j^{th}$  cluster, then 1 is assigned to element  $j^{th}$  rows and  $i$ th columns of the genotype, whereas the other elements of the same column receive 0. For the illustrative example (1.1), a possible encoding is as follows:

$$\begin{bmatrix} 000000000001111 \\ 000001111110000 \\ 111110000000000 \end{bmatrix}$$

**ChromosomeCrispMatrix** [Method on `gaencode::ChromosomeCrispMatrix`]  
`<T_BITSIZE, T_CLUSTERIDX, T_METRIC>`  
`(const uintidx aiuintidx_numRows, const uintidx aiuintidx_numColumns)`  
 Where T\_BITSIZE size of the variable to store the bits,  
 T\_CLUSTERIDX is integer index for clusters,  
 T\_METRIC it es the type of data for fitness function  
 See [\[Example ChromosomeCrispMatrix\]](#), page 91.

### 3.2.1.4 Centroid-based

#### Real encoding

A chromosome in this encoding is a vector of real numbers that contains the coordinates of each centroid consecutively of the clusters. For an  $d$ -dimensional space, the length of a genotype is  $d \times k$  words, where the first  $d$  positions (or, genes) represent the  $d$  dimensions of the first cluster centre, the next  $d$  positions represent those of the second cluster centre, and so on:

$$Ch = [g_{11}, g_{12}, \dots, g_{1d}, g_{21}, g_{22}, \dots, g_{2d}, \dots, g_{k1}, g_{k2}, \dots, g_{kd}] \quad (2.2)$$

For example, the chromosome equivalent to the (1.1) partition is [8.5 2.5 5.33333 7.5 1.8 2]

The graphical representation of the centroid-based partition is shown in Figure [Figure 3.4](#).

To encode a chromosome based on a centroid you can use the same class (See [\[gaencode::ChromFixedLength\]](#), page 9) parameterized for real numbers. See [\[Example gaencode::ChromFixedLength\]](#), page 71.

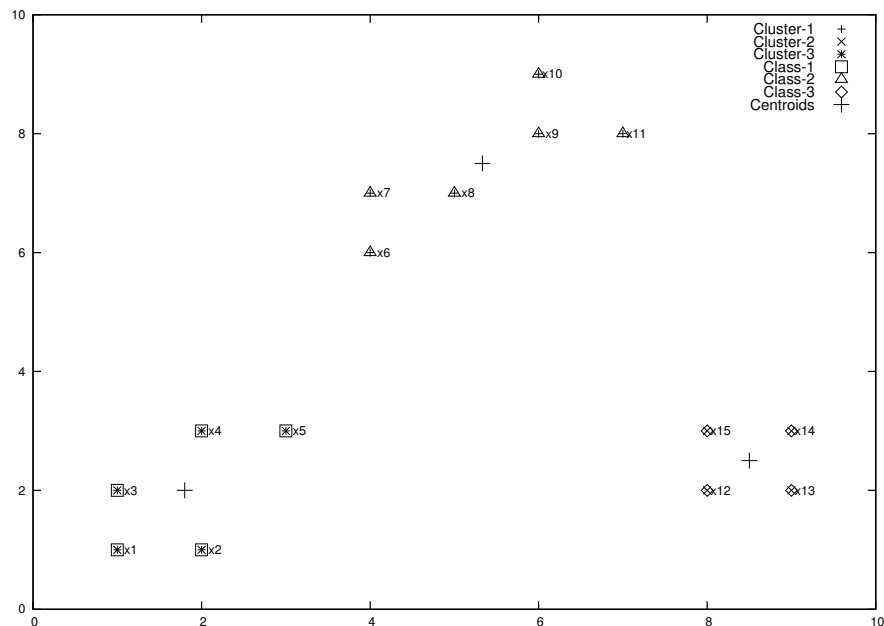


Figure 3.4: Example of *centroid-based* of Table 2.1 artificial dataset.

## Binary encoding

Another algorithm based centroids, and with a binary coding is proposed by [TY01], page 113. First a data reduction procedure is used, which consists in calculating an adjacency matrix  $A_{n \times n}$  and subsequently the *connected components*. The result is blocks  $\{B_1, B_2, \dots, B_m\}$ , with centroid  $\{V_1, V_2, \dots, V_m\}$  respectively, So every  $V_i$  is used as a seed to generate a higher level cluster. As an illustrative example see Figure 3.5 of  $B_i$  and  $V_i$ , for the didactic data set.

The length of each chromosomes is  $m$ , where the  $i^{th}$  position of the string will be ‘1’ therefore, centroid  $V_i$  is used as a seed to group those who have a ‘0’ gene and are closer to it. For example, the chromosome equivalent to the (1.1) partition is encoded by the chromosome ‘10011’. see Figure 3.6.



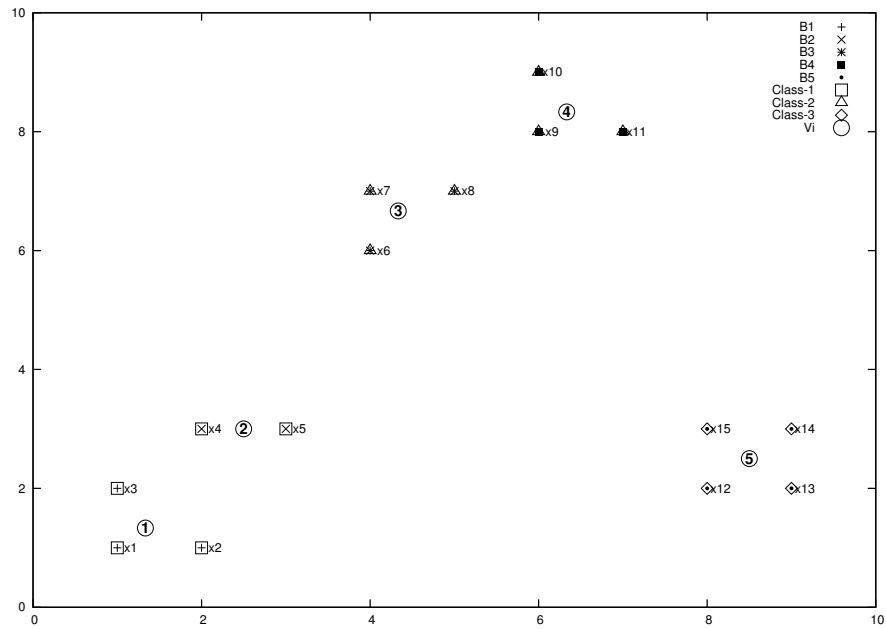


Figure 3.5: Example of *centroid-based* with *binary-encoding* of artificial dataset. Proposed by [TY01], page 113

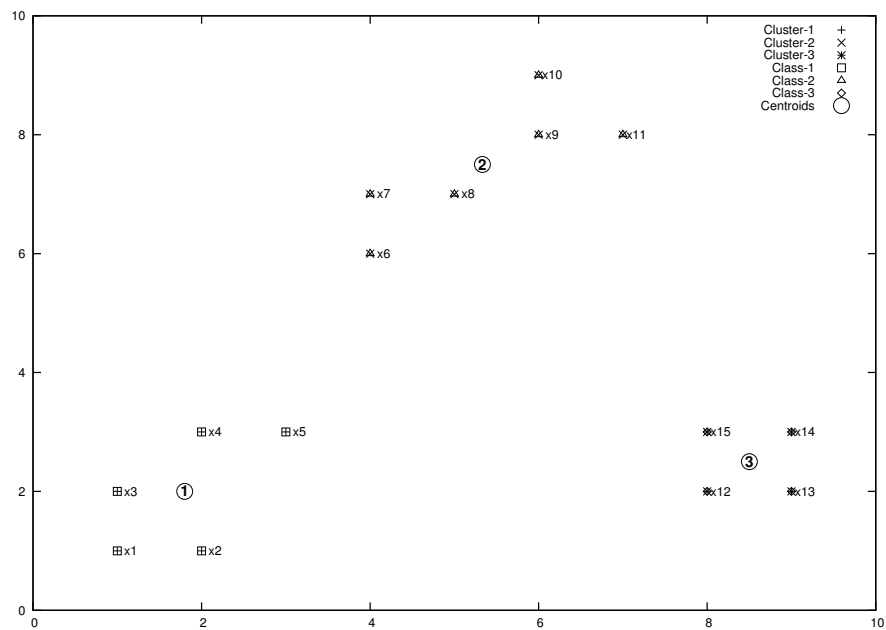


Figure 3.6: Example of *centroid-based* with *binary-encoding* of artificial dataset. Proposed by [TY01], page 113

### 3.2.1.7 Medoid-based

Another way to partition a data set is by selecting the most *representative object* of each cluster. In the literature there are two proposals for integer and binary encoding, which are described in the following subsections.

#### Integer encoding

Integer encoding scheme involves using an array of  $k$  elements to provide a medoid-based representation of the dataset. In this case, each array element represents the index of the object  $x_i$ , where  $i = 1, 2, \dots, n$ . For example, the medoid-based chromosome equivalent to the (1.1) partition is [14 9 3].

In the same way it is shown in the [Figure 3.7](#). For implementation you can use `gaencode::ChromFixedLength` with `T_GENE` as index data type. See [\[gaencode::ChromFixedLength\]](#), page 9.

#### Binary encoding

[\[KB97\]](#), page 112 they use binary encoding to define a medoid-based partition. Each chromosome has a length equal to the number of objects  $n$ . A bit on with index  $i$  indicates that object  $x_i$  is a prototype of a cluster  $C_j$ . The members of  $C_j$  will be determined by rule (2.1), changing the centroid  $\mu_j$  by the medoid  $m_j$ .

For example, the binary chromosome equivalent to the (1.1) partition is 001000001000010. For implementation you can use `gaencode::ChromosomeBitArray`. See [\[gaencode::ChromosomeBitArray\]](#), page 9.

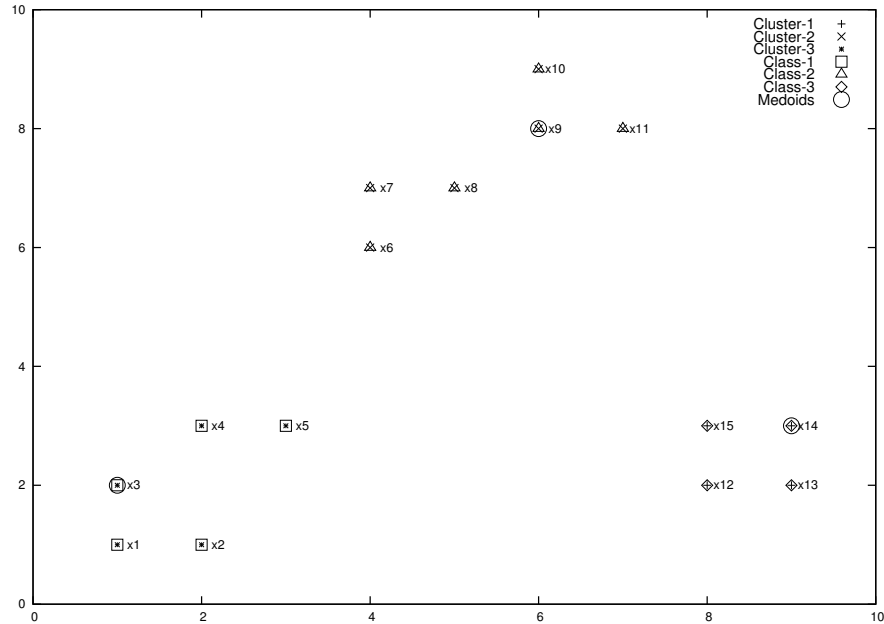


Figure 3.7: Example of *medoid-based encoding* of artificial dataset.

### 3.2.1.10 Graph-based

## Binary encoding

[CdLM03], page 111 use graph-based coding, for objects they get *minimum spanning tree* (MST). The genes represent the edges of the graph, and the vertices the data set objects. As the MST have  $n - 1$  edges. This is the length of the chromosomes. In the binary chromosome a value of “0” means that this edge remains, While a gene with value “1” means that this edge is eliminated. The number of elements with value “1” represents the value of  $k - 1$ . See Figure 3.8. For example, the chromosome equivalent to the (1.1) partition is 00001000000001.

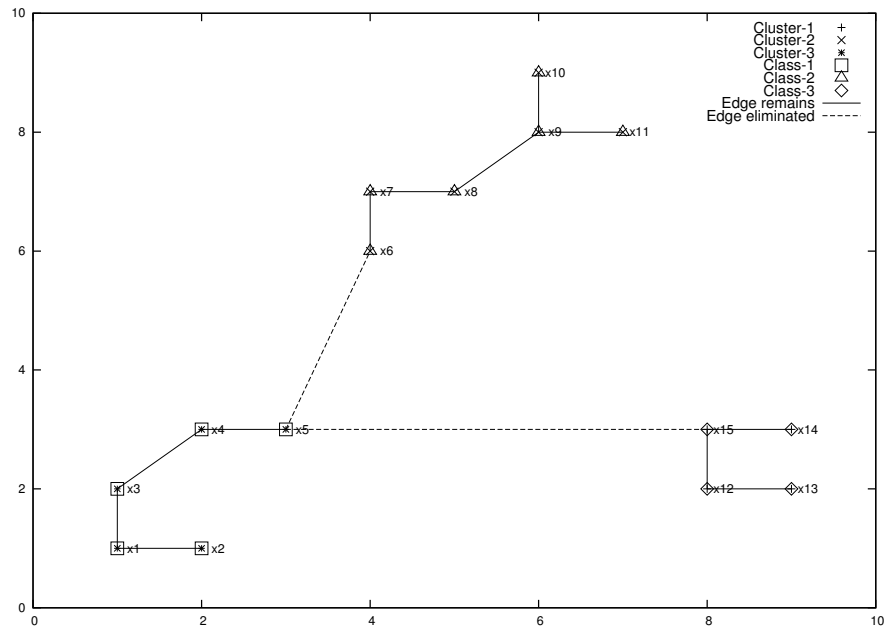


Figure 3.8: Example of *graph-based* encoding of artificial dataset. Proposed by [CdLM03], page 111

### 3.2.2 Initialization of population

Before initializing the population, you must create a container from the STL library, such as `std::vector` or `std::list`. See [Example a vector of chromosomes], page 71 to represent the population or pool mating.

Several approaches are proposed for the initialization of the population, The simplest procedure to initialize the population is random, objects are randomly assigned to a cluster. Such an initialization strategy usually results in unfavorable initial partitions, since the initial clusters are likely to be mixed up to a high degree. However, it constitutes an effective approach to test the algorithms against hard evaluation scenarios [HCFdC09], page 112.

In the case studies of this document See Section A.2 [GA algorithm], page 88 and See Section A.1 [KGA algorithm], page 69. They use an initialization of seed centroids, selected randomly from the instances and all instances are distributed in groups around these centroids by *nearest object rule*.

For the particular case of population initialization in the GA algorithm (See [Section A.2 \[GA algorithm\]](#), page 88), the following two functions are used:

With non-repeated instance indices, the centroids of the clusters can be constructed:

```
void clusteringop::randomInitialize [Function]
    (mat::MatrixBase<T_FEATURE> &aomatrixt_centroids,
     const INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast)
    See <undefined> [Example clusteringop::randomInitialize], page <undefined>
```

And finally with the centroids is created an initial partition:

```
void clusteringop::getPartition [Function]
    (mat::CrispMatrix<T_BITSIZE,T_CLUSTERIDX>
     &aobcrispmatrix_partition,
     mat::MatrixRow<T_FEATURE> &aimatrixt_instances,
     mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     dist::Dist<T_DIST,T_FEATURE> &aifunc2p_dist)
    See <undefined> [Example clusteringop::getPartition], page <undefined>
```

For the initialization of the other partition representations, LEAC provides equivalent functions, found in the header files: `clustering_operator_centroids.hpp`, `clustering_operator_crispmatrix.hpp`, `clustering_operator_fuzzy.hpp` and `clustering_operator_medoids.hpp`.

### 3.2.3 Fitness function

The GAs algorithms are based on the optimization of some objective function that guides the evolutionary search, In the clustering problem we use different measures used for the optimization function used to evaluate the so-called *fitness function*. For the metrics available by LEAC See [Section 3.2.3.2 \[Unsupervised measures\]](#), page 19.

#### 3.2.3.1 Distances

Distance measures is the key in clustering to find the similarity between two objects  $x_i$  and  $x'_i$ . To calculate the different clustering metrics a *distance* is used. The most common is the *Euclidean distance*  $\|x_i - x'_i\|$ . LEAC offers a module in the `dist_euclidean.hpp` file to calculate the distances and the class diagram is shown in [Figure 3.9](#)

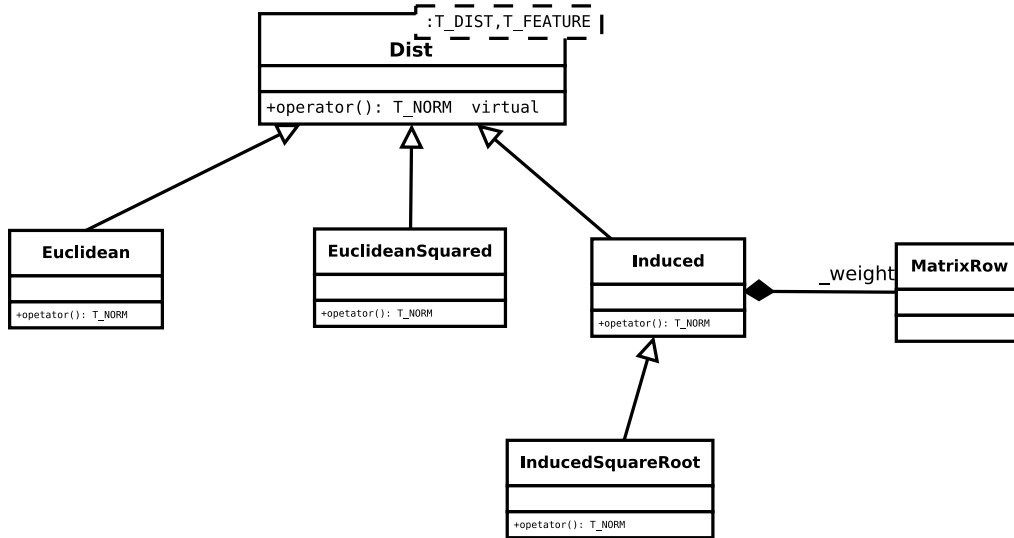


Figure 3.9: Class diagrams of the Distances.

All classes define the *function call operator* that allows you to find the distance between two  $x_i$  and  $x_{i'}$  objects:

`T_DIST operator()` [Method on `dist::Dist`]  
 (`const T_FEATURE*`, `const T_FEATURE*`, `const uintidx`)

To instantiate a `dist::Dist` object the following constructors are used

`Euclidean <T_DIST,T_FEATURE> ()` [Method on `dist::Euclidean`]

#### Example

```

dist::Dist<DATATYPE_REAL,DATATYPE_FEATURE>
    *pfunct2p_distAlg = NULL;

switch ( linparam_ClusteringGA.getOpDistance() ) {
case INPARAMCLUSTERING_DISTANCE_EUCLIDEAN:
    pfunct2p_distAlg =
        new dist::Euclidean<DATATYPE_REAL,DATATYPE_FEATURE>();
    break;
case INPARAMCLUSTERING_DISTANCE_EUCLIDEAN_SQ:
    pfunct2p_distAlg =
        new dist::EuclideanSquared<DATATYPE_REAL,DATATYPE_FEATURE>();
    break;
case INPARAMCLUSTERING_DISTANCE_EUCLIDEAN_INDUCED:

```

```

    pfunct2p_distAlg =
        new dist::Induced<DATATYPE_REAL,DATATYPE_FEATURE>
            (mat::getIdentity
                <DATATYPE_REAL>
                (data::Instance<DATATYPE_FEATURE>::getNumDimensions()));
    break;
case INPARAMCLUSTERING_DISTANCE_DIAGONAL_INDUCED:

    pfunct2p_distAlg =
        new dist::Induced<DATATYPE_REAL,DATATYPE_FEATURE>
            (stats::getMatrixDiagonal<DATATYPE_FEATURE>
                (larray_desvstdFeatures)
            );
    break;
case INPARAMCLUSTERING_DISTANCE_MAHALONOBIS_INDUCED:

    pfunct2p_distAlg =
        new dist::Induced<DATATYPE_REAL,DATATYPE_FEATURE>
            (stats::getMatrixMahalonobis
                (lvectorptinst_instances.begin(),
                 lvectorptinst_instances.end()
                )
            );
    break;
default:
    throw std::invalid_argument("main_gas_clustering: undefined norm");
    break;
}
main_gas_clustering.cpp

```

Induced<T\_DIST,T\_FEATURE> [Method on dist::Induced]  
 (const mat::MatrixRow<T\_DIST>& aimatrix\_weight)  
 See [Example dist::Induced], page 17

The *induced distance* is a generic measure obtained by multiplying the transposed vector of point  $x_i$  to  $x_{i'}$  by the *matrix of weight*  $A$  and with the vector not transposed (2.3).

$$D_{Ind}(x_i, x_{i'}) = (x_i - x_{i'})^T A (x_i - x_{i'}) \quad (2.3)$$

To calculate the *matrix of weights*  $A$  we have the following functions

mat::MatrixRow<T\_FEATURE> mat::getIdentity [Function]  
 (const uintidx aiui\_dimension)

If the *identity matrix* is used the induced distance is equivalent to the *Square Euclidean distance* ( $A = I$ ) See [Example mat::getIdentity], page 17

mat::MatrixRow<T\_FEATURE> dist::getMatrixMahalonobis [Function]  
 (INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast)

It is the inverse of the *covariance matrix*  $C_x$  of the data set  $X$ . When used as an matrix of weights at the *induced distance* is equivalent to *Mahalanobis distance* ( $A = C_x^{-1}$ ). See [Example dist::getMatrixMahalonobis], page 18

mat::MatrixRow<T\_FEATURE> dist::getMatrixDiagonal [Function]  
 (T\_FEATURE\* aiarrrayt\_varianceFeactures)

It is the inverse matrix of the variance of the attributes in the main diagonal ( $A = D_x^{-1}$ ). See [Example dist::getMatrixDiagonal], page 18

### 3.2.3.2 Unsupervised measures

This type of evaluation tries to determine the quality of a given obtained partition of the data without any external information available. This is why this unsupervised measure are sometimes called as internal measures [ABSSJF+12], page 111 All *unsupervised measures* function of the library are defined in the header file `unsupervised_measures.hpp`. You must include this in all source files using the library, either directly or through some other header file, like this:

```
#include <unsupervised_measures.hpp>
```

The measures used in genetic algorithms are described below.

#### Sum of quadratic errors (SSE)

A common clustering criterion or quality indicator is the *sum of squared error* (SSE) measure, defined in [CZZ09], page 112 as

$$SSE = \sum_{C_j} \sum_{x_i \in C_j} (x_i - \mu_j)^T (x_i - \mu_j) = \sum_{C_j} \sum_{x_i \in C_j} \|x_i - \mu_j\|^2. \quad (2.4)$$

The SSE is use in [MB00], page 113, [BM02a], page 111 and [CZZ09], page 112.

Or with some slight variation *Sum of Euclidean Distance SED*:

$$SED = \sum_{C_j} \sum_{x_i \in C_j} \|x_i - \mu_j\|, \quad (2.5)$$

SED is use in [SL04], page 113 and [LDK93], page 113.

This is probably the most straightforward and popular evaluation distance in the literature. It only considers cohesion of clusters in order to evaluate the quality of a given partition data [ABSSJF+12], page 111.

This metric generally used by different algorithms when the number of clusters  $k$  is known and is used by [BM02a], page 111 [CZZ09], page 112.

For the calculation of SSE you have three functions. Different distances can be passed as parameter `aifunc2p-dist` (See Section 3.2.3.1 [Distances], page 16), to obtain the variations of the metric:

```
std::pair<T_METRIC,bool> um::SSE [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)
    The partition is derived by aimatrixt_centroids. See [Equation (2.1)], page 4. See
    [Example um::SSE], page 77
```

Other functions for the calculation of *SSE* that depend on the way to specify the membership of an object to a cluster, are the following:

```
T_METRIC um::SSE [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     T_CLUSTERIDX *aiarraymmidx_memberShip,
     const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)

std::pair<T_METRIC,bool> um::SSE [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
     dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)
```

Depending on the encoding used, you have a set of partition clusters classes (*partition::Partition*) for calculating metrics generically. See Figure 3.10. For example, a partition based on (2.1), the constructor you can use is

```
[Method on partition::PartitionCentroids]
PartitionCentroids <T_FEATURE,T_CLUSTERIDX,T_DIST,INPUT_ITERATOR>
(mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
 const INPUT_ITERATOR aiiterator_instfirst,
 const INPUT_ITERATOR aiiterator_instlast,
 const dist::Dist<T_DIST,T_FEATURE>& aifunc2p_dist)
```

And for one based on a crisp matrix (2.1):

```
[Method on partition::PartitionCrispMatrix]
PartitionCrispMatrix <T_BITSIZE,T_CLUSTERIDX> (const
mat::CrispMatrix<T_BITSIZE,T_CLUSTERIDX> &aibitcrisp_matrix)
See [Example partition::PartitionCrispMatrix], page 98
```

To avoid defining the template parameters for the case of a partition, you can use the `makePartition`:



T\_METRIC partition::makePartition [Function]

```
(mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
const INPUT_ITERATOR aiiterator_instfirst,
const INPUT_ITERATOR aiiterator_instlast,
const T_CLUSTERIDX aimcidx_numClusters,
const dist::Dist<T_DIST,T_FEATURE> &aifunc2p_dist)
```

See [\(undefined\)](#) [Example partition::makePartition], page [\(undefined\)](#)

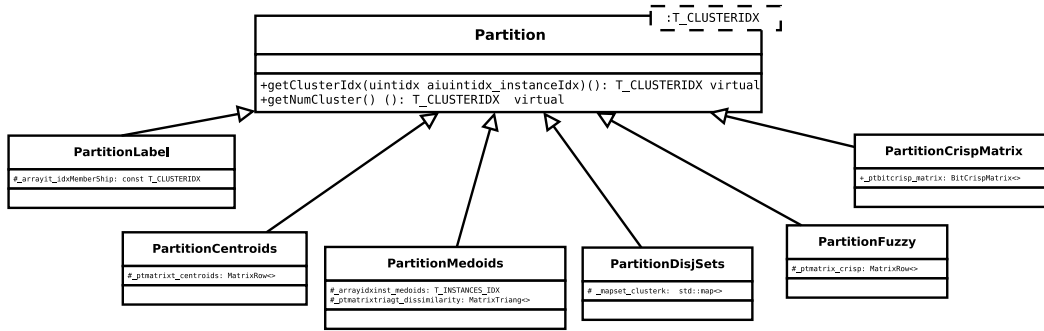


Figure 3.10: Class diagram of the partitions used to calculate the metrics.

## Least-squared errors functional

A fuzzy  $c$ -partitions is represented by a matrix ([BEF84], page 111)

$$M_{fc} = \{U_{k \times n} | u_{ji} \in [0, 1]; \sum_{i=1}^n u_{ji} > 0, \text{ for all } j, \sum_{i=1}^n u_{ji} = 1, \text{ for all } i\}, \quad (2.6)$$

Several clustering criteria have been proposed for identifying optimal fuzzy  $c$ -partitions in  $X$ , the most popular and well-studied criterion is associated with the metric of the equation (2.7) called *least-squared errors functional*, described in [BEF84], page 111

$$J_m(U, \mu) = \sum_{i=1}^n \sum_{j=1}^k u_{ji}^m D_{Ind}(x_i - \mu_j), \quad (2.7)$$

Where

$U \in M_{fc}$  (2.6) fuzzy  $c$ -partition of  $X$ ;

$\mu = [\mu_1, \mu_2, \dots, \mu_k]$  centroids,

$m$  weighting exponent;  $1 \leq m < \infty$

$D_{Ind}(x_k, \mu_i)$  is one of the *induced distances* from  $x_i$  to  $\mu_j$ . See [Induced distance], page 18

T\_METRIC um::jm [Function]  
 (mat::MatrixRow<T\_METRIC> &aimatrixt\_u,  
 mat::MatrixRow<T\_FEATURE> &aimatrixt\_centroids,  
 INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast,  
 T\_METRIC aif\_m,  
 dist::Dist<T\_METRIC,T\_FEATURE> &aifunc2p\_dist)

For hard clustering will be based on  $J_m(U, \mu)$  from (2.7), we will rewrite  $J_1$  as:

$$J_1(U, \mu) = \sum_{i=1}^n \sum_{j=1}^k u_{ji} D_{Ind}(x_i - \mu_i)$$

T\_METRIC um::j1 [Function]  
 (mat::BitMatrix<T\_BITSIZE> &aimatrix\_crisp,  
 mat::MatrixRow<T\_FEATURE> &aimatrixt\_centroids,  
 INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast,  
 dist::Dist<T\_METRIC,T\_FEATURE> &aifunc2p\_dist)

See [\(undefined\)](#) [Example um::j1], page [\(undefined\)](#)

## Sum of Euclidean Distance

For k-medoid, replacing the centroids by the most representative instance in equation (2.5), we obtain the cost function sum of Euclidean distances to the most representative instance ( $SED_{medoid}$ ). [\[SL04\]](#), page 113,

$$SED_{medoid} = \sum_{C_j} \sum_{x_i \in C_j} \|x_i - m_j\|$$

where  $m_j$  represents the *medoid* or *prototype* of cluster  $C_j$

T\_METRIC um::SSEMedoid [Function]  
 (const uintidx \*aiarrayidxinst\_medoids,  
 const T\_CLUSTERIDX aimcidx\_numClustersK,  
 const mat::MatrixTriang<T\_METRIC> &aimatrixtriagt\_dissimilarity)

The `medoids::getMatrixDissimilarity` function calculates and returns the triangular distance matrix using a specified distance measure. Used to get other measures for example `um::SSEMedoid`. This is in `medoids_clustering.hpp` file.

mat::MatrixTriang<T\_DIST> medoids::getMatrixDissimilarity [Function]  
 (INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast,  
 const dist::Dist<T\_DIST,T\_FEATURE> &aifunc2p\_dista)

## Davis-Bouldin Index

Davies–Bouldin index (DB) [DB79], page 111, is a function of the ratio of the sum of *within-cluster scatter* to *between-cluster separation*, DB index for the partitioning of  $k$  clusters is defined as

$$DB = \frac{1}{k} \sum_j R_{C_j, C_{1 \leq j' \leq k}}, \quad j' = 1, 2, \dots, k \quad \text{and} \quad j \neq j'$$

in which the index for the  $j^{th}$  cluster against all clusters least the same  $R_{C_j, C_{1 \leq j' \leq k}}$  is given by

$$R_{C_j, C_{1 \leq j' \leq k}} = \max_{j', j' \neq j} R_{C_j, C_{j'}}$$

where  $R_{C_j, C_{j'}}$  is a measure between a pair of cluster defined by

$$R_{C_j, C_{j'}} = \frac{S_{q, C_j} + S_{q, C_{j'}}}{d_{jj', t}}$$

and the scatter  $S_{q, C_j}$  within for  $j^{th}$  cluster, is computed as

$$S_{q, C_j} = \left( \frac{1}{|C_j|} \sum_{x_i \in C_j} \{|x_i - \mu_j|_2^q\} \right)^{1/q}$$

$S_q$  is the  $q^{th}$  root of the  $q^{th}$  moment of the points in cluster  $j$  with respect to their mean, and is a measure of the dispersion of the points in cluster  $j$ .  $d_{jj', t}$  is the Minkowski distance of order  $t$  between the centroids that characterize clusters  $j$  and  $j'$ .

DB use in [BM02b], page 111.

```
T_METRIC    um::DBindex [Function]
    (const mat::MatrixBase<T_FEATURE> &aimatrixt_centroids,
    INPUT_ITERATOR aiiterator_instfirst,
    const INPUT_ITERATOR aiiterator_instlast,
    const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
    const dist::Dist<T_METRIC, T_FEATURE> &aifunc2p_dist)
```

## Silhouette

This metric known as silhouette was proposed by [KR90], page 113. Consider an object  $x_i$  belonging to cluster  $C_j$ . So, the average dissimilarity of  $x_i$  to all other objects of  $C_j$ . is denoted by  $a(x_i)$ . Now let us take into account cluster  $C_{j'}$ . The average dissimilarity of  $x_i$  to all objects of  $C_{j'}$ , will be called  $D(x_i, C_{j'})$ . After computing  $D(x_i, C_{j'})$ , for all clusters  $C_j \neq C_{j'}$ , the smallest one is selected, i.e.  $b(x_i) = \min D(x_i, C_{j'})$ . This value represents the dissimilarity of  $x_i$  to its neighbor cluster, and the silhouette  $s(x_i)$  given by ([ACH06], page 111):

$$s(x_i) = \frac{b(x_i) - a(x_i)}{\max \{a(x_i), b(x_i)\}}, \quad (2.8)$$

The higher  $s(x_i)$  is better the assignment of the object  $x_i$  to a given cluster and

$$-1 \leq s(x_i) \leq 1$$

Use in [HE03], page 112 and [ABSSJF+12], page 111.

```
T_METRIC  um::silhouette [Function]
(mat::MatrixTriang<T_METRIC> &aimatrixtriagrt_dissimilarity,
 ds::PartitionLinkedNumInst<T_CLUSTERIDX,T_INSTANCES_CLUSTER_K>
 &aipartlinknuminst_memberShip)
```

### Simplified Silhouette

The silhouette proposed in [KR90], page 113 depends on the computation of all distances between objects, leading to a computational cost of  $O(n^2)$ , which is often not sufficiently efficient for real-world clustering applications (e.g. data mining, text mining, gene-expression data analysis). To circumvent this limitation, a simplified silhouette can be employed. The simplified silhouette is based on the computation of distances between objects and cluster centroids, which are the mean vectors of the clusters. More specifically, the term  $a(i)$  of equation (2.8) becomes the dissimilarity of object  $x_i$  to the centroid of its cluster ( $C_j$ ). Similarly, instead of computing  $D(x_i, C'_j)$  as the average dissimilarity of  $x_i$  to all objects of  $C'_j$ ,  $C_j \neq C'_j$ , only the distance between  $x_i$  and the centroid of  $C'_j$  must be computed. While these modifications reduce the computational cost from  $O(n^2)$  to  $O(n)$  [ACH06], page 111.

```
std::vector<T_METRIC> um::simplifiedSilhouette [Function]
(const mat::MatrixBase<T_FEATURE> &aimatrixt_centroids,
 INPUT_ITERATOR aiiterator_instfirst,
 const INPUT_ITERATOR aiiterator_instlast,
 const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
 const std::vector<T_INSTANCES_CLUSTER_K> &aivectorit_numInstClusterK,
 const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist )
```

### CS measure

The  $CS$  measure [CSL04], page 111 [DAK08], page 112 is defined as

$$CS(C) = \frac{\frac{1}{k} \sum_{j=1}^k \left\{ \frac{1}{|C_j|} \sum_{x_i \in C_j} \max_{x_{i'} \in C_j} \{D(x_j, x_{i'})\} \right\}}{\frac{1}{k} \sum_{j=1}^k \left\{ \min_{j \in k, j \neq j'} \{D(\mu_j, \mu_{j'})\} \right\}}$$

Where  $D$  is a distance function.

[CSL04], page 111 Establish that this measure is a function of the ratio of the sum of within-cluster scatter to between-cluster separation. The smallest  $CS(C)$  indicates a valid optimal partition. The  $CS$  measure has the same rationale as the  $DI$  (See [Dunn's index], page 25) and the  $DB$  (See [Davis-Bouldin Index], page 23).

```

T_METRIC um::CSmeasure [Function]
(INPUT_ITERATOR aiiterator_instfirst,
const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
const ds::PartitionLinkedNumInst<T_CLUSTERIDX,
T_INSTANCES_CLUSTER_K> &aipartlinknuminst_memberShip,
const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist )

```

## Dunn's index

A well-established hard cluster validity measure is the Dunn's index ( $DI$ ) that identifies sets of clusters that are well separated. Dunn's index is defined as ([CSL04], page 111)

$$DI(C) = \min_{j \in C} \left\{ \min_{j' \in C, j' \neq j} \left\{ \frac{\delta(C_j, C_{j'})}{\max_{j'' \in C} \{\Delta(C_{j''})\}} \right\} \right\}$$

Where

$$\delta(C_j, C_{j'}) = \min \{D(x_i, x_{i''}) | x_i \in C_j, x_{i''} \in C_{j'}\}$$

$$\Delta(C_j) = \max \{D(x_i, x_{i''}) | x_i, x_{i''} \in C_j\}$$

The main drawback with the direct implementation of Dunn's index is its computational load because calculating  $DI(C)$  becomes computationally very expensive as  $k$  and  $n$  increase. The largest  $DI(C)$  indicates a valid optimal partition [CSL04], page 111.

```

T_METRIC um::DunnIndex [Function]
(INPUT_ITERATOR aiiterator_instfirst,
const ds::PartitionLinked<T_CLUSTERIDX> &aipartlink_memberShip,
const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)

```

To avoid calculating distance between instances again and improve performance in the  $DI$  evaluation To avoid calculating the distance between the instances and improving performance in the evaluation, use the following function:

```

T_METRIC um::DunnIndex [Function]
(mat::MatrixTriang<T_METRIC> &aimatrixtriagrt_dissimilarity,
ds::PartitionLinked<T_CLUSTERIDX> &aipartlinknuminst_memberShip)

```

## Simplified Dunn's index

Just as the *silhouette* can also simplify *Dunn's measure* to reduce the computational cost of  $O(n^2)$  to  $O(n)$  using the centroids. This measure will be called *Simplified Dunn's index* ( $SDI$ ).

$$SDI(C) = \min_{j \in C} \left\{ \min_{j' \in C, j' \neq j} \left\{ \frac{\delta(C_j, C_{j'})}{\max_{j'' \in C} \{\Delta(C_{j''})\}} \right\} \right\}$$

Where

$$\delta(C_j, C_{j'}) = \min \{D(\mu_j, \mu_{j''}) | j \neq j''\}$$

$$\Delta(C_j) = \max \{D(x_i, \mu_j) | x_i \in C_j\}$$

And the function to calculate *Simplified Dunn's index*

```
T_METRIC um::simplifiedDunnIndex [Function]
    (const mat::MatrixBase<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const ds::PartitionLinked<T_CLUSTERIDX> &aipartlink_memberShip,
     const dist::Dist<T_METRIC, T_FEATURE> &aifunc2p_dist)
```

### Variance ratio criterion

The *variance ratio criterion* (VRC) sometimes called *Calinski–Harabasz index* initially proposed by [CH74], page 111 is based on the internal cluster cohesion and the external cluster isolation. The corresponding internal cohesion is calculated by the within-group sum of square distances [HT12], page 112.

The index is defined as:

$$VRC_k = \frac{SS_B}{SS_W} \cdot \frac{(n - k)}{(k - 1)}$$

Where  $SS_B$  is the overall between-cluster variance,  $SS_W$  is the overall within-cluster variance,  $k$  is the number of cluster, and  $n$  is the number of instances.

The overall between-cluster variance  $SS_B$  is defined as

$$SS_B = \sum_{j=1}^k |C_j| \|\mu_j - M\|^2$$

Where  $\mu_j$  is the centroid of cluster  $j$ ,  $M$  is the overall mean of the instances. The overall within-cluster variance  $SS_W$  is defined as

$$SS_W = \sum_{j=1}^k \sum_{x_i \in C_j} \|x_i - \mu_j\|^2$$

The VRC should be maximized. Use in [CdLM03], page 111 and [HT12], page 112.

```
T_METRIC um::VRC [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
     const dist::Dist<T_METRIC, T_FEATURE> &aifunc2p_dist)
```

## Intra- and inter-cluster distance

The definition of *intra- and inter-cluster distance* (DIIC) ([TY01], page 113) is given by the equation:

$$DIIC = \sum_{i=1}^k D_{inter}(C_j)w - D_{intra}(C_j)$$

Where  $D_{intra}(C_j)$  is the intra-cluster distance

$$D_{intra}(C_j) = \sum_{B_l \subset C_j} \|v_l - \mu_j\| \cdot |B_l|$$

and  $D_{inter}(C_j)$  is the inter-cluster distance

$$D_{inter}(C_j) = \sum_{B_l \subset C_j} \left( \min_{j \neq k} \|v_l - \mu_j\| \right) \cdot |B_l|$$

And  $w$  is a weight. If the value of  $w$  is small, we emphasize the importance of  $D_{intra}(C_j)$ . This tends to produce more clusters and each cluster tends to be compact. If the value of  $w$  is chosen to be large, we emphasize the importance of  $D_{inter}(C_j)$ . This tends to produce fewer clusters and each cluster tends to be loose. [TY01], page 113.

```

T_METRIC um::Dintra [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixrowt_S,
     const mat::MatrixRow<T_FEATURE> &aimatrixrowt_Vi,
     const std::vector<T_INSTANCES_CLUSTER_K> &aivectort_numInstBi,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clustersBkinCi,
     const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)

T_METRIC um::Dinter [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixrowt_S,
     const mat::MatrixRow<T_FEATURE> &aimatrixrowt_Vi,
     const std::vector<T_INSTANCES_CLUSTER_K> &aivectort_numInstBi,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clustersBkinCi,
     const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)

```

This metric can only be calculated when having subgroups. For a clustering  $C_1, C_2, \dots, C_k$  each  $C_j$  with  $S_j$  centroid, is constructed from the subgroups  $B_i$  with  $V_i$  centroid. This way of clustering is a characteristic particular feature of the algorithm described in [TY01], page 113.

## Validity index I

The *validity index I* or simply *Index I* described in [MB02], page 113 and [BM07], page 111. It is used as a metric to measure clustering performance. It was proposed as a measure to indicate the (goodness) validity of the solution in the cluster. It is defined as follows:

$$I(k) = \left( \frac{1}{k} \cdot \frac{E_1}{E_k} \cdot D_k \right)^p,$$

Where  $k$  is the number of clusters

$$E_k = \sum_{j=1}^k \sum_{i=1}^n u_{ji} \|x_i - \mu_j\|,$$

and

$$D_k = \max_{j,j'=1}^k \|\mu_{j'} - \mu_j\|$$

$n$  is the total number of objects.  $U(X) = [u_{kj}]_{k \times n}$  is a partition matrix of the objects and  $\mu_j$  is the centroid of cluster  $j^{th}$ . The value of  $k$  that maximizes  $I(k)$  is considered the correct number of clusters.

`T_METRIC um::indexI` [Function]  
 (const mat::MatrixRow<T\_FEATURE> &aimatrixt\_centroids,  
 INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast,  
 const partition::Partition<T\_CLUSTERIDX> &aipartition\_clusters,  
 const dist::Dist<T\_METRIC,T\_FEATURE> &aifunc2p\_dist,  
 const T\_METRIC airt\_p = 2.0)

## Xie-Beni index

The index of Xie-Beni ( $XB$ ) [XB91], page 113 is defined for *fuzzy c-partitions*. See [Definition fuzzy c-partitions], page 21. This index can be extended to a crisp partition. See [crisp partition], page 10. Note that  $M_c$  is imbedded in  $M_{fc}$ .

The Xie-Beni index is defined as the quotient of the total variance  $\sigma$ , and minimal separation of groups  $d_{min}$ .

$$XB = \frac{\sigma}{n \cdot (d_{min})^2}$$

In detail

$$\sigma = \sum_{j=1}^k \sum_{i=1}^n u_{ji}^2 \|x_i - \mu_j\|^2,$$

$$d_{min} = \min_{j,j'=1,j \neq j'}^k \|\mu_j - \mu_{j'}\|$$

$$XB = \frac{\sum_{j=1}^k \sum_{i=1}^n u_{ji}^2 \|x_i - \mu_j\|^2}{n \cdot (d_{min})^2}$$

`T_METRIC um::xb` [Function]  
 (mat::MatrixRow<T\_METRIC> &aimatrixt\_u,  
 mat::MatrixRow<T\_FEATURE> &aimatrixt\_centroids,  
 INPUT\_ITERATOR aiiterator\_instfirst,  
 const INPUT\_ITERATOR aiiterator\_instlast,  
 dist::Dist<T\_METRIC,T\_FEATURE> &aifunc2p\_dist)



And the function to calculate the XB to a hard partition (See [\[partition::Partition\]](#), page 20).

```
T_METRIC um::xb [Function]
    (const mat::MatrixRow<T_FEATURE> &aimatrixt_centroids,
     INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
     const dist::Dist<T_METRIC,T_FEATURE> &aifunc2p_dist)
```

### 3.2.3.16 Supervised measures

#### Rand Index

The *Rand Index* [\[Ran71\]](#), page 113 is defined for two partitions of the same data set  $X$ ,  $C$  in  $k$  cluster and  $R$  in  $k'$  known classes. [\[ACH06\]](#), page 111 indicate that these measures can be seen as an absolute criterion or referential standard that allows the use of classification data sets for performance assessment not only of *classifiers* with the same number of clusters and class ( $k = k'$ ), if not also different ( $k \neq k'$ ). In the same article they write it as follows:

$$\Omega(R, C) = \frac{a + d}{a + b + c + d}$$

Where:

- $a$ : Number of pairs of data objects belonging to the same class in  $R$  and to the same cluster in  $C$ .
- $b$ : Number of pairs of data objects belonging to the same class in  $R$  yet to different clusters in  $C$ .
- $c$ : Number of pairs of data objects belonging to different classes in  $R$  yet to the same cluster in  $C$ .
- $d$ : Number of pairs of data objects belonging to different classes in  $R$  and to different clusters in  $C$ .

The function in IA that obtains the rand index is

```
T_METRIC sm::randIndex [Function]
    (const sm::ConfusionMatchingMatrix<T_INSTANCES_CLUSTER_K> &aimatchmatrix_confusion)
```

To obtain the Rand Index, you must first obtain the confusion matrix:

```
sm::ConfusionMatchingMatrix<T_INSTANCES_CLUSTER_K> [Function]
    sm::getConfusionMatrix
    (INPUT_ITERATOR aiiterator_instfirst,
     const INPUT_ITERATOR aiiterator_instlast,
     const partition::Partition<T_CLUSTERIDX> &aipartition_clusters,
     const FUNCINSTFREQUENCY func_instfrequency,
     const FUNCINSTCLASS func_instclass)
```

See [\[Example sm::getConfusionMatrix\]](#), page 98

## Purity

Purity is a simple and transparent evaluation measure each cluster is assigned to the class which is most frequent in the cluster, and then the accuracy of this assignment is measured by counting the number of correctly assigned objects and dividing by  $n$  [MRS08], page 113.

$$\text{purity}(C, R) = \frac{1}{n} \sum_j \max_{j'} |C_j \cap R_{j'}|$$

Where  $C$  and  $R$  two partitions of the same data set  $X$ , of  $k$  cluster and  $k'$  known classes respectively.

T\_METRIC **sm::purity** [Function]  
(const sm::ConfusionMatchingMatrix<T\_INSTANCES\_CLUSTER\_K> &aimatchmatrix\_confusion)

## Precision

To calculate the accuracy, we use the pairs of the  $R$  and  $C$  partitions, and based on [Faw06], page 112.

$$\text{precision} = a/(a + c).$$

T\_METRIC **sm::precision** [Function]  
(const ConfusionMatchingMatrix<T\_INSTANCES\_CLUSTER\_K> &aimatchmatrix\_confusion)

## Recall

Based on [Faw06], page 112.

$$\text{recall} = a/(a + b).$$

T\_METRIC **sm::recall** [Function]  
(const ConfusionMatchingMatrix<T\_INSTANCES\_CLUSTER\_K> &aimatchmatrix\_confusion)

### 3.2.4 Stop Criterion

There exists no stopping criterion in the literature which ensures the convergence of GAs to an optimal solution. Usually, two stopping criteria are used in genetic algorithms. In the first, the process is executed for a fixed number of iterations and the best string obtained is taken to be the optimal one. In the other, the algorithm is terminated if no further improvement in the fitness value of the best string is observed for a fixed number of iterations, and the best string obtained is taken to be the optimal one [MC96], page 113.

### 3.2.5 Evolution schema

Different evolution schemes are proposed for clustering algorithms. LEAC to implement the evolution schemes is used the Standard Template Library: STL Algorithms. The header <algorithm> defines a collection of functions especially designed to be used on ranges of elements.

For example, in [BM02a], page 111 elitism has been implemented in each generation by replacing the worst chromosome (select the worst and replace it with the best chromosome See [Example elitism replace the worst], page 79) of the population with the best one seen up to the previous generation (See [Example elitism select the best], page 80).

### 3.2.6 Criterion for selecting parents

*Replacing criterion:* the offspring automatically replace their parents. To preserve elitism, if the best solution from the previous generation does not survive, the worst solution is replaced by the new one.

*Criterion for selecting parents:* in order to apply genetic operators it is necessary to select a subset of the population. The tournament selector will be used and different tournament sizes will be tested.

### 3.2.7 Crossover operator

To apply the crossover operator LEAC has two functions to iterate over the population and mating pool:

```
void gaiterator::crossover [Function]
    (INPUT_ITERATOR aiiterator_instfirstParent,
     const INPUT_ITERATOR aiiterator_instlastParent,
     INPUT_ITERATOR aiiterator_instfirstChild,
     const INPUT_ITERATOR aiiterator_instlastChild,
     const GENETIC_OPERATOR genetic_operator)
    Select a pair of parents and children consecutively from their containers.
    See [Example gaiterator::crossover], page 83
```

```
void gaiterator::crossoverRandSelect [Function]
    (INPUT_ITERATOR aiiterator_instfirstParent,
     const INPUT_ITERATOR aiiterator_instlastParent,
     INPUT_ITERATOR aiiterator_instfirstChild,
     const INPUT_ITERATOR aiiterator_instlastChild,
     const GENETIC_OPERATOR genetic_operator)
    Select a pair of parents and children randomly and consecutively respectively from
    their containers.
    See [Example gaiterator::crossoverRandSelect], page 100
```

Within the iterator function, the crossover operator is applied. In LEAC has implemented several operators of crossover and mutation proposed in the literature as *cluster-oriented* `ga_clustering_operator.hpp` or *nonoriented operators*. They are also classified according to their coding *binary*, *integer*, or *real* encodings, `ga_binary_operator.hpp`, `ga_integer_operator.hpp` and `ga_real_operator.hpp`. For a classification of operators see [HCFdC09], page 112. For implementation purposes, some integer or actual operators are programmed in the `ga_generic_operator.hpp` file.

Two examples are shown below:

```
void gagenericop::onePointCrossover [Function]
    (gaencode::ChromFixedLength<T_GENE,T_METRIC> &aochrom_child1,
     gaencode::ChromFixedLength<T_GENE,T_METRIC> &aochrom_child2,
     const gaencode::ChromFixedLength<T_GENE,T_METRIC> &aichrom_parent1,
     const gaencode::ChromFixedLength<T_GENE,T_METRIC> &aichrom_parent2)
    See [Example gagenericop::onePointCrossover], page [undefined]
```

```
void gabinaryop::onePointDistCrossover [Function]
    (mat::BitMatrix<T_BITSIZES> &aobitmatrix_child1,
     mat::BitMatrix<T_BITSIZES> &aobitmatrix_child2,
     mat::BitMatrix<T_BITSIZES> &aibitmatrix_parent1,
     mat::BitMatrix<T_BITSIZES> &aibitmatrix_parent2)
    See [Example gabinaryop::onePointDistCrossover], page 101
```

### 3.2.8 Mutation operator

Several operators for mutation are proposed in the literature on evolutionary algorithms for clustering and implemented in LEAC.

```
void gabinaryop::bitMutation [Function]
    (mat::CrispMatrix<T_BITSIZES,T_CLUSTERIDXS>
     &aioibitcrispmatrix_chrom)
    See [Example gabinaryop::bitMutation], page 101. Used in [BBHB94], page 111
```

In [BM02a], page 111 they propose a mutation operator for (2.2) chromosomes (See [centroid-based], page 11). It is located in the file `ga_clustering_operator.hpp` and called here as `gaclusteringop::biDirectionHMutation`:

$$\text{mutate}(g_{jl}) = \begin{cases} g_{jl} + \delta \times (\max(x_l) - g_{jl}) & \text{if } \delta \geq 0, \text{ for } j = 1, 2, \dots, k \text{ and } l = 1, 2, \dots, d, \\ g_{jl} + \delta \times (g_{jl} - \min(x_l)) & \text{if } \delta < 0. \end{cases}$$

Where  $\delta$  is a random number in the interval  $[-R, +R]$ :

$$R = \begin{cases} \frac{M - M_{\min}}{M_{\max} - M_{\min}} & \text{if } M_{\max} > M, \\ 1 & \text{if } M_{\min} = M_{\max}. \end{cases}$$

$M_{\min}$  and  $M_{\max}$  be the minimum and maximum values of the clustering metric, respectively, in the current population.  $M$  is the clustering metric value of the current chromosome that must be mutated.

```
void gaclusteringop::biDirectionHMutation [Function]
    (gaencode::ChromosomeString<T_GENE,T_METRIC> &aochrom_offspring,
     const T_METRIC airt_minObjectiveFunc,
     const T_METRIC airt_maxObjectiveFunc,
     const T_GENE* aiaarrayt_minFeatures,
     const T_GENE* aiaarrayt_maxFeatures)
    See [Example gaclusteringop::biDirectionHMutation], page 86
```

### 3.2.9 Other parameters

It is common for GAs and EAs for clustering to use local search. The k-means algorithm is more popular, this is a procedure of fine-tuning of maximum descent, thus speeding up its convergence. The way they apply it varies. LEAC includes an extensive list of functions for local search, some of which are discussed below:

```
void clusteringop::updateCentroids [Function]
(T_CLUSTERIDX &aocidx_numClusterNull,
 mat::MatrixRow<T_FEATURE> &aioatrixt_centroids,
 mat::MatrixRow<T_FEATURE_SUM> &aomatrixt_sumInstancesCluster,
 std::vector<T_INSTANCES_CLUSTER_K> &aovectort_numInstancesInClusterK,
 INPUT_ITERATOR aiiterator_instfirst,
 const INPUT_ITERATOR aiiterator_instlast,
 const dist::Dist<T_DIST,T_FEATURE> &aifunc2p_dist)
```

With rule (2.1) each point is assigned  $x_i$  a the clusters  $C_j$  See [Equation (2.1)], page 4. Update the centroids  $\mu_i^* = 1/n_j \sum_{x_i \in C_j} x_i, j = 1, 2, \dots, k$ , where  $n_j$  is the number of points in cluster  $C_i$ . Returns the new centroids, the sum of instances and their number per cluster. See [Example clusteringop::updateCentroids], page 76

Other algorithms propose to use the k-means algorithms as an operator ([KM99], page 112)

```
T_CLUSTERIDX clusteringop::kmeansoperator [Function]
(T_CLUSTERIDX *aioarraycidx_memberShip,
 mat::MatrixRow<T_FEATURE> &aomatrixt_centroids,
 mat::MatrixRow<T_FEATURE_SUM> &aomatrixt_sumInstancesCluster,
 std::vector<T_INSTANCES_CLUSTER_K> &aovectort_numInstancesInClusterK,
 INPUT_ITERATOR aiiterator_instfirst,
 const INPUT_ITERATOR aiiterator_instlast,
 dist::Dist<T_DIST,T_FEATURE> &aifunc2p_dist)
```

For the given partition in an array of labels, it performs an update using the k-means algorithm. Returns the membership tags, centroids, sum of instances and number of instances in each cluster.

For different representations of a partition, there are also local search procedures. By medoids [SL04], page 113 proposes a heuristic search:

```
void clusteringop::updateMedoids [Function]
(uintidx *aoarrayuiidx_medoids,
 T_CLUSTERIDX aicidx_numClusterK,
 uintidx aiuiidx_nearestNeighborsP,
 mat::MatrixTriang<T_DIST> &aimatrixtriagt_dissimilarity)
```

Update medoids [SL04], page 113

For each cluster  $C_j$  finds the most representative object

1. Assign each object in  $x_i$  to the cluster  $C_j$  with the closest medoid
2. For each cluster  $C_j$ , repeat until the medoid does not change
  - Choose a subset  $C_{subset}$  in  $C_j$  the corresponds to  $m_j$  and its  $p$  nearest neighbors of  $m_j$ .
  - Calculate the new medoid

$$m_j^* = \arg \min_{x_i \in C_{subset} \ x'_i \in C_j} \sum \|x_i - x'_i\|$$

- if  $m_j$  is different from  $m_j^*$  replace with the new medoid
3. Repat step 1 and 2 until  $k$  medoids do not change



## 4 Get and Install LEAC software

### 4.1 Getting the software LEAC

For Windows<sup>®</sup> systems, perform steps 1 through 8 and 14. For Linux systems, perform steps 1, 2 and 9 through 14.

1. Download the l2eac project from <https://github.com/hbrobles/l2eac>.
2. Unzip the file `l2eac.zip`, we recommend you in the directory `c:\l2eac` and `/home/user/l2eac` for Windows<sup>®</sup> and Linux respectively. Verify that the following directories exist within the main directory.

<code>bin</code>	This is the directory to store all EAC binary or executable programs, which result from the compilation of using LEAC.
<code>data</code>	Directory used to store the data sets to be processed.
<code>doc</code>	In the 'doc' directory you will find all the necessary documentation for the use of LEAC.
<code>eac</code>	It contains the source files of the implementations of the EAC algorithms implemented by the LEAC library.
<code>leac</code>	Contains LEAC library header files and source code.
<code>inout</code>	Contains the modules for the input of parameters and output of the EAC programs.
<code>openblas</code>	Contains only the header files needed to compile a program with some functionality of the <b>OpenBlas</b> library.

#### `sse_kernel`

`sse_kernel` is a module based on **OpenBlas** and **GotoBLAS2**, own of LEAC. The functionality of this module together with that of OpenBlas is the best performance for the processing of high-dimensional data sets. For now it only works for **x86-64** architecture.

For Linux go to [Step 9], page 37.

3. Download and install one of the two IDE with the MinGW option **Dev-C++** or **Code::Blocks**
4. Check the `PATH` where MinGW is installed, it can be `C:\Program Files (x86)\Dev-Cpp\MinGW64\bin` or `C:\Program Files (x86)\CodeBlocks\MinGW\bin` and add it to the `PATH` environment variable using the following instructions

Warning: Adding entries to the `PATH` is normally harmless. However, if you delete any existing entries, you may mess up your `PATH` string, and you could seriously compromise the functioning of your computer. Please be careful. Proceed at your own risk.

- a. Right-click on your **My Computer** icon and select **Properties**.
- b. Click on the **Advanced** tab, then on the **Environment Variables** button (Figure 4.1).

You should be presented with a dialog box with two text boxes. The top box shows your user settings. The `PATH` entry in this box is the one you want to

modify. Note that the bottom text box allows you to change the system PATH variable. You should not alter the system path variable in any manner, or you will cause all sorts of problems for you and your computer!

- c. Click on the PATH entry in the TOP box, then click on the Edit button
- d. Scroll to the end of the string and at the end add  
`'C:\Program Files (x86)\Dev-Cpp\MinGW64\bin'`
- e. press OK -> OK -> OK and you are done.
5. Download and install **gnuplot**. The recommendation for the installation is to use the file **gp530-20170911-win64-mingw.zip**. Unzip in the `c:\gnuplot` directory and add `c:\gnuplot\bin` in the environment variable PATH in the same way as in [Step 4], page 35.
6. Optionally install the **epsvviewer** file viewer, to visualize the data sets and the clusters created by the different programs
7. To generate the LEAC library documentation, download the latest version of **Doxygen**. For now you can use the file **doxygen-1.8.14.windows.x64.bin.zip**, unzip in the `C:\doxygen-1.8.14.windows.x64.bin` directory.
8. With the compiler installed See [Step 4], page 35, you can now compile the EAC applications. Open a cmd, you must change the directory to the `l2eac` directory, For example: `'cd c:\l2eac\eac'` and execute any of the following three options:

`'mingw32-make -k -f Makefile DEBUG=yes VERBOSE=yes'`

To debug and analyze the detailed execution of the programs. These options allow software engineering ilities of correctness and reliability.

`'mingw32-make -k -f Makefile DEBUG=no VERBOSE=no WITHOUT_PLOT_STAT=no'`

Optimize and obtain the evolutionary behavior of the population from the fitness function (option WITHOUT\_PLOT\_STAT) in the execution of the programs.

`'mingw32-make -k -f Makefile DEBUG=no VERBOSE=no WITHOUT_PLOT_STAT=yes'`

Versions of optimized programs to have a good performance in the data set processing.

The compilation time of all programs varies according to the capabilities of the computers, but it can be approximately 20 minutes.

To install the applications `'mingw32-make -k -f Makefile install'`

And to eliminate the applications and use another option `'mingw32-make -k -f Makefile clean'`

Go to step [Step 14], page 38.

9. Verify that the compiler is installed, on **terminal** type, if you do not install the missing packages as system administrator (root):

`'gcc -v'` ( $\geq 4.9.2-10$ ),

`'g++ -v'` ( $\geq 4.9.2-10$ ),

`'make -v'` ( $\geq 4.0-8.1$ ),



```
'gfortran -v'
(>=4.9.2-10),
```

```
'gfortran -print-file-name=libgfortran.so'
```

To verify that the `libgfortran` library is installed

If you can not find the packages, install the missing ones as system administrator (root), with your package manager, e.g. run `'apt-get install libgfortran-4.9-dev'` for `libgfortran`.

10. If you want to use compile your applications with high-performance modules `OpenBLAS` and `sse_kernel`, for now this option only works on the x86-64 architecture. For these you need to compile and get the static libraries of each of the components. If you do not want this option, go to [Step 11], page 37 and compile with the option `WITH_OPEN_BLAS = no`.

#### OpenBLAS

- a. From the <http://www.openblas.net/> page, download the source code of the latest version of `OpenBLAS`.
- b. Unzip the file with the `'tar zxvf OpenBLAS-0.2.20.tar.gz'` command.  
`'cd OpenBLAS-0.2.20'`
- c. After editing `Makefile.rule` `'NO_CBLAS=1, NO_LAPACK=1, NO_LAPACKE=1'` and run `'make FC=gfortran'`
- d. Copy `libopenblas.a` static library from the `OpenBLAS-0.2.20` directory to the `openblas` directory of `l2eac`, eg. `'cp libopenblas.a ~/l2eac/openblas'`

#### CBLAS, LAPACK and LAPACKE

- a. Download [lapack-3.8.0.tar.gz](http://www.netlib.org/lapack/lapack-3.8.0.tar.gz) from <http://www.netlib.org/lapack/>
- b. `'tar zxvf lapack-3.8.0.tar.gz'`, `'cd lapack-3.8.0'`
- c. `'cp make.inc.example make.inc'`
- d. After editing `make.inc`: `'CFLAGS = -O3 -march=native -m64 -fomit-frame-pointer -fPIC -lpthread -pthread'` and `'BLASLIB = ~/l2eac/openblas/libopenblas.a'`
- e. Then you must execute the `'make cblaslib'`, `'make lapacklib'` and `'make lapackelib'`.
- f. Copy static libraries `'cp libcblas.a ~/l2eac/openblas/'`, `'cp liblapack.a ~/l2eac/openblas/'` and `'cp liblapacke.a ~/l2eac/openblas/'`

#### sse\_kernel

- a. Change to `sse_kernel` directory, within `l2eac`
  - b. Just type `make` to compile the library and get `libssekernell.a`
11. Install `gnuplot`, as a system administrator (root), run `'apt-get install gnuplot-x1'`.
  12. Install `Doxygen` version (`>=1.8.13`), with your package manager or use the binary file provided on the page [doxygen-1.8.13](#). If you used the second option, execute the following commands `'cd ~; mv ./Downloads/doxygen-1.8.13.linux.bin.tar.gz ~; tar zxvf doxygen-1.8.13.linux.bin.tar.gz'`
  13. You can now compile the EAC applications, `'cd ~/l2eac/eac'`, Select one of the following compilation options:

```
'make -k -f Makefile DEBUG=yes VERBOSE=yes'
```

To debug and analyze the detailed execution of the programs. These options allow software engineering utilities of correctness and reliability.

```
'make -k -f Makefile DEBUG=no VERBOSE=no WITHOUT_PLOT_STAT=no'
```

Optimize and obtain the evolutionary behavior of the population from the fitness function (option WITHOUT\_PLOT\_STAT) in the execution of the programs.

```
'make -k -f Makefile DEBUG=no VERBOSE=no WITH_OPEN_BLAS=yes  
WITHOUT_PLOT_STAT=yes'
```

For the processing of the high dimensionality data set, this option is recommended to obtain good performance, for this you must complete See [Step 10], page 37

14. The API documentation of LEAC was written for **Doxygen**. To get this type 'doxygen Doxyfile' in the l2eac directory, or with the full path where the doxygen command is located, e.g. 'C:\doxygen-1.8.14.windows.x64.bin\doxygen Doxyfile' or '~/doxygen-1.8.13/bin/doxygen Doxyfile'.

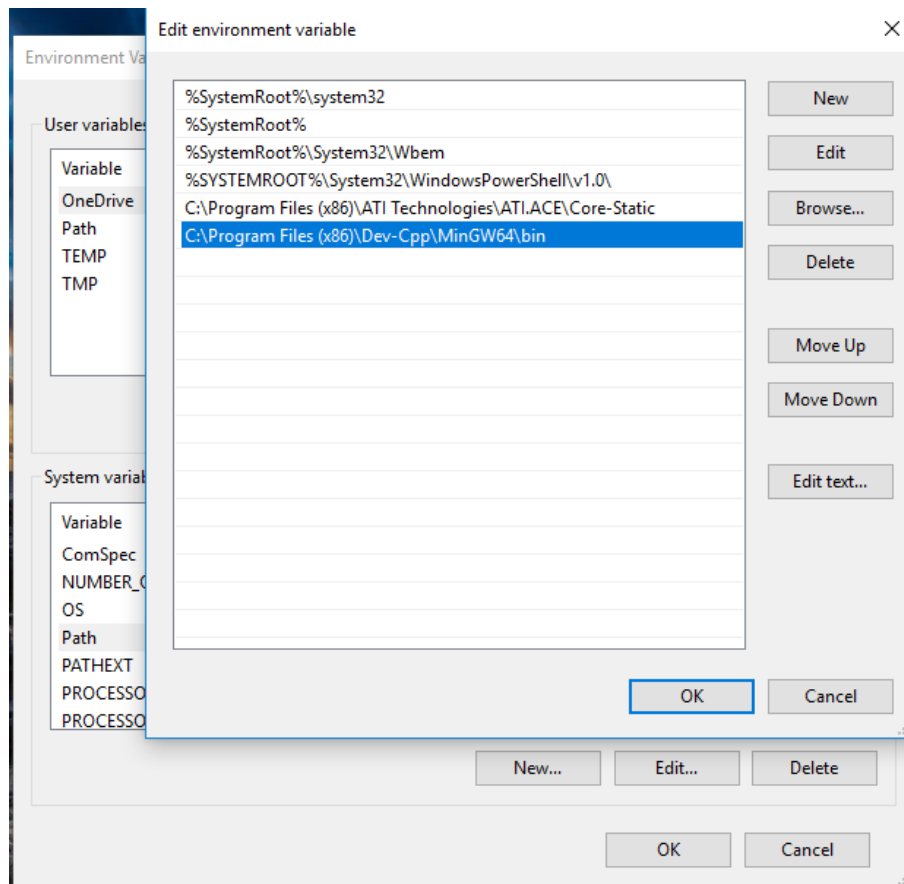


Figure 4.1: Dialog to add the MinGW compiler to the PATH environment variable

## 5 Illustrative examples

This chapter shows how to use the EAC programs located in the `eac` directory to find a solution to the problem of clustering. For the use and obtain better results, the algorithms on which the programs are based, we categorize them into three aspects: number of  $k$  defined clusters or automatic  $k$  search, the coding of the solution by the algorithm and the similarity function. The selection of one or the other depends on what you want.

First, they can be divided into those in which the number of cluster to partition a data set is known or unknown. These algorithms are known as *fixed  $k$ -cluster* or *variable  $k$ -cluster*, respectively. If you want to obtain symmetric partitions, define the  $k$  parameter; on the other hand, if you search for some structure in the data set, or make an automatic classification, the recommendation is to use the algorithms of  *$k$ -variable*, for this a measure of intra and inter-cluster distances is used.

The second aspect to consider is the way to represent a partition of a data set, for this there are three ways:

Finally the measure of similarity is another important aspect in the selection of a program. See [Section 3.2.3.2 \[Unsupervised measures\]](#), page 19, describes the most common functions mentioned in the literature. The programs also calculate other measures as a reference to achieve a more reliable grouping. These measures are known as unsupervised. There are other measures related to a previous classification of the data set by an expert, if the objects of the data set have a label for the class to which they belong, the programs calculate from the confusion matrix the supervised measures that are described in [See Section 3.2.3.16 \[Supervised measures\]](#), page 29.

The nomenclature used for the name of the programs is based on the three aspects described above. Name of the algorithm on which the program is based, defined or unknown  $k$  and the coding of the solution.

The nomenclature used for the name of the programs is based on the three aspects described above. Name of the algorithm on which the program is based, defined or variable  $k$  and the coding of the solution.

`name_[fk|vk]type of partition`

All EAC programs are executed from a terminal with online parameters. With the parameter `--help`, You will get a description of the different options, there are two types of options, those that are common for all the programs and the particular ones of each algorithm, these last ones are shown after the message `Particular options of the algorithm: [Name]`.

The following sections describe some representative program of EAC based on the previous classification,  *$k$ -fixed* vs.  *$k$ -variable* and solution encoding. In addition, a case study is included for each program.

### 5.1 Partition for fixed $k$ -cluster

Another way to classify the EA and GA algorithms, for the clustering problem, is based on the idea of representing the solution. The subsections of this chapter correspond to the different forms of coding a grouping solution, the coding together with the fitness function determine how to divide the data set into a cluster. This is another feature that helps in the selection of a certain algorithm.



```

-l, --idinstances-column[=NUMBER]
                                the input file instance is assigned a column
                                instance identifier [NUMBER=undefined]
-f, --freq-instances-column[=NUMBER]
                                the input file instance is assigned a column
                                frequency instances [NUMBER=undefined]
-r, --number-runs[=NUMBER]      number of runs or repetitions of the algorithm
                                (by default [NUMBER=1])
-R, --runtime-filename=[FILE]
                                out file of times run
-n --distance[=NAME]            euclidean, euclidean_sq, euclidean_induced,
                                diagonal_induced, or mahalonobis_induced,
                                by default euclidean
-z, --random-seed[=NUMBER]      string with integer number seed by, default
                                is random
-w, --max-execution-time[=NUMBER]
                                real number for max execution time in seconds
                                by default is 36000
-C, --centroids-outfile=[FILE]
                                print centroids, standard output FILE=stdout
--centroids-format[=yes/no]
                                print the matrices by rows and columns,
                                by default is no
-M, --membership-outfile=[FILE]
                                print membership of the instances,
                                standard output FILE=stdout
-T, --partitionstable-outfile=[FILE]
                                print partitions table of the instances,
                                standard output FILE=stdout
--table-format[=yes/no]
                                print the partitions table by rows and
                                columns, by default is no
-P, --gnuplot=FILE              file of gnuplot to graphics result
                                (compiling only with WITHOUT_PLOT_STAT)
-y, --gnuplot-styles=WORD       plot graphics with: points, lines,
                                linespoints, and dot [ARG=linespoints]

```

Particular options of the algorithm KGA

based on Bandyopadhyay and Maulik 2002

```

--number-clusters[=NUMBER]
                                number of clusters [NUMBER=3]
--generations[=NUMBER]         number of generations or iterations
                                [NUMBER=1000]
--population-size[=NUMBER]
                                size of population [NUMBER=50]
--crossover-probability[=NUMBER]
                                real number in the interval [0.25, 1]

```

```

                                [NUMBER=0.8]
--mutation-probability[=NUMBER]    real number in the interval [0, 0.5]
                                [NUMBER=0.001]

-v, --verbose[=NUMBER]            explain what is being done (compiled with
                                VERBOSE=yes)
                                NUMBER=[-1,..,9999] Quiet level -1 not,
                                verbose, default=-1
-q, --bar-progress                progress bar printing, default is not
-?, --help                        help

```

For the following example we will analyze the [wine data set](#).

First you must download the [wine.data](#) file and store it in the `data` directory, all data sets used in the following illustrative examples should be stored in this directory.

Since the domain of the attributes is different for the [wine.data](#), it is convenient to standardize them, for this the program `stdvar_milligan_cooper1988` Based on ([[MC88](#)], [page 113](#)) is available as support for the normalization of the data set.

```

'./stdvar_milligan_cooper1988 -i ../data/wine.data -a "2-14" -c 1 --std-var
Z1 > ../data/wine_std.data'

```

Copy the command and paste in the `cmd` or `terminal`. For the `cmd` copy the command and the parameters without the two symbols (`./`).

By having the data set normalized, it is possible to make some partitions to find some pattern in the data.

```

'./kga_fkcentroid -i ../data/wine_std.data -a "1-13" -c 14 --number-clusters
3 -C stdout --centroids-format yes -M stdout'

```

A possible result for a partition of three clusters (`--number-clusters 3`) by the KGA algorithm is

IN:

```

Algorithm name: KGA
    Based on: Bandyopadhyay and Maulik 2002
    Metric used: SSE

    Data set: /home/hermes/data/wine_std.data
Number of instances: 178
    Dimensions: 13

```

```

Random seed: 605281295 2141350197 2332488985 1350226326 4001754309
1842645844 2127210415 1490264447

```

OUT:

```

CROMOSOME: BEST: objective, 449.524, fitness, 0.00222458: 0.875627, -0.30372, 0.318045,
-0.662654, 0.563299, 0.87404, 0.940985, -0.583943, 0.580146, 0.166718, 0.482367,
0.764896, 1.15509, 0.164444, 0.869095, 0.186373, 0.522892, -0.0752605, -0.976575,

```







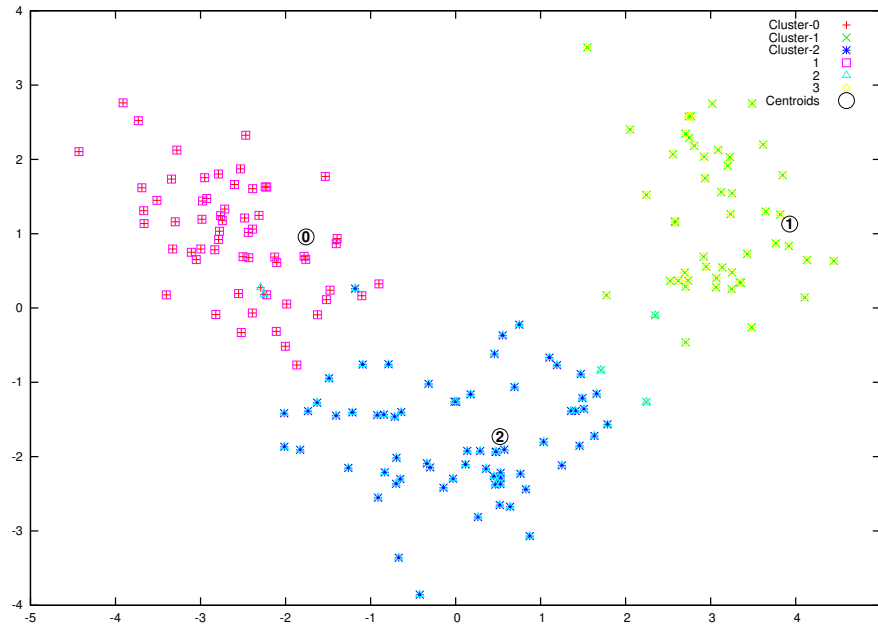


Figure 5.1: Partition for 3 clusters of Wine data set, obtained with `kga_fkcentroid`

In all programs, it is possible to use part of the data set for *training* and another part for *test*, similar to the *classification*. To determine the ownership of the test data, the equation of the nearest centroid-instance is used (2.1).

To demonstrate how to process a data set with training and test data, we use the **Libras Movement Data Set**, with the `movement_libras.data` and `movement_libras_1.data` files.

To improve the performance of the program, we will first transform the data set, transferring the movements described by the instances to the center, with the following awk script:

```
#run:
# awk -f movement_libras_trans.awk -F ',' -v OFS=','
movement_libras.data > movement_libras_trasn.data
{
    for(i=1;i< NF;i++) t1+=$i; i++; t2+=$i ;
    xd = 0.5 - 2.0 * t1/(NF-1);
    yd = 0.5 - 2.0 * t2/(NF-1);
    t1=0; t2=0
    for(i=1;i< NF;i++) $i += xd; i++; $i += yd ;
    for(i=1; i<=NF; i++) printf "%s",$i (i==NF?ORS:OFS)
}

'./kga_fkcentroid -i ../data/movement_libras_trasn.data -t ../data/movement_libras_1.data
-a "1-90" -c 91 -C c_movement_libras.data -T stdout --table-format yes
--number-cluster 15'
```

A possible result of the program is the following

IN:

Algorithm name: KGA

Based on: Bandyopadhyay and Maulik 2002

Metric used: SSE

Data set: /home/hermes/data/movement\_libras\_trasn.data

Number of instances: 360

Dimensions: 90

Data set test: /home/hermes/data/movement\_libras\_1.data

Number of instances: 45

Random seed: 2127474194 2277915873 2997828778 567204173 2395445691  
1861208675 35718978 101314263

OUT:

CROMOSOME: BEST: objective, 209.665, fitness, 0.00476951: 0.545241, 0.779453,  
0.544903, 0.779338, 0.542145, 0.778586, 0.539438, 0.776675, 0.534216, 0.773666,  
...  
0.462735, 0.320573, 0.457353, 0.311718, 0.452307, 0.306383, 0.451046, 0.302055

Cluster number (K): 15

SSE: 209.665

DB-index: 1.15626

Silhouette: 0.284789

VRC: 87.1936

CS measure: 1.36284

Dunn's index: 0.0855026

Test data SSE: 52.8738 Has group without objects

Test data DB-index: 3.59388

Test data Silhouette: -0.103324

Test data VRC: 0.721814

Test data CS measure: 1.76497

Test data Dunn's index: 0.0650252

Execution time (seg): 85.0431

Generations find the best: 56

Partition table:

Cluster: 0	1	2	3	4
Class				
1: 0	0	10	0	0
2: 0	0	11	0	0

3: 0	0	0	0	0
4: 0	0	0	0	0
5: 0	6	0	0	17
6: 0	0	0	7	0
7: 0	0	0	0	0
8: 14	0	0	0	0
9: 0	0	0	0	0
10: 0	0	0	0	0
11: 11	0	0	0	0
12: 0	0	0	0	0
13: 15	0	0	0	0
14: 0	6	0	14	1
15: 0	0	0	0	0
sum: 40	12	21	21	18
Cluster: 5	6	7	8	9
Class				
1: 0	0	0	8	0
2: 0	0	0	5	0
3: 0	0	23	0	0
4: 0	12	0	0	3
5: 1	0	0	0	0
6: 0	7	0	0	0
7: 0	0	0	0	20
8: 0	0	0	0	0
9: 0	0	0	0	0
10: 7	0	0	0	15
11: 0	0	0	0	0
12: 0	0	0	0	24
13: 0	0	0	0	0
14: 0	0	0	0	3
15: 12	0	0	0	4
sum: 20	19	23	13	69
Cluster: 10	11	12	13	14
Class				
1: 6	0	0	0	0
2: 6	0	0	2	0
3: 0	0	0	1	0
4: 0	0	8	1	0
5: 0	0	0	0	0
6: 0	0	9	1	0
7: 0	0	0	4	0
8: 0	0	0	1	9
9: 0	0	0	24	0

10: 0	0	0	2	0
11: 0	9	0	0	4
12: 0	0	0	0	0
13: 0	7	0	0	2
14: 0	0	0	0	0
15: 0	0	0	0	8
sum: 12	16	17	36	23

Cluster: sum  
Class

1: 24  
2: 24  
3: 24  
4: 24  
5: 24  
6: 24  
7: 24  
8: 24  
9: 24  
10: 24  
11: 24  
12: 24  
13: 24  
14: 24  
15: 24  
sum: 360

Rand index: 0.915877  
Purity: 0.552778  
Precision: 0.385553  
Recall: 0.527295

Partition table test:

Cluster: 0	1	2	3	4
Class				
1: 0	0	2	0	0
2: 0	0	1	0	0
3: 0	0	0	0	0
4: 0	0	0	0	0
5: 0	1	0	0	2
6: 0	0	0	0	0
7: 0	0	0	0	0
8: 1	0	0	0	0

9: 0	0	0	0	0
10: 0	0	0	0	0
11: 1	0	0	0	0
12: 0	0	0	0	0
13: 0	0	0	0	0
14: 0	0	0	0	0
15: 0	0	0	0	0
sum: 2	1	3	0	2
Cluster: 5	6	7	8	9
Class				
1: 0	0	0	1	0
2: 0	0	0	2	0
3: 0	0	3	0	0
4: 0	1	0	0	0
5: 0	0	0	0	0
6: 0	2	0	0	0
7: 0	0	0	0	3
8: 0	0	0	0	0
9: 0	0	0	0	0
10: 0	0	0	0	3
11: 0	0	0	0	0
12: 0	0	0	0	3
13: 0	0	0	0	0
14: 0	0	0	0	3
15: 0	0	0	0	3
sum: 0	3	3	3	15
Cluster: 10	11	12	13	14
Class				
1: 0	0	0	0	0
2: 0	0	0	0	0
3: 0	0	0	0	0
4: 0	0	2	0	0
5: 0	0	0	0	0
6: 0	0	1	0	0
7: 0	0	0	0	0
8: 0	0	0	0	2
9: 0	0	0	3	0
10: 0	0	0	0	0
11: 0	2	0	0	0
12: 0	0	0	0	0
13: 0	3	0	0	0
14: 0	0	0	0	0
15: 0	0	0	0	0

```

sum: 0          5          3          3          2

Cluster: sum
Class

1: 3
2: 3
3: 3
4: 3
5: 3
6: 3
7: 3
8: 3
9: 3
10: 3
11: 3
12: 3
13: 3
14: 3
15: 3
sum: 45

Test data Rand index: 0.879798
Test data Purity: 0.577778
Test data Precision: 0.227941
Test data Recall: 0.688889

```

With the option ‘-T, --partitionstable-outfile’, you get the confusion matrix and with the ‘-t’ option for training and testing, as well as measures related to the previous classification of the objects, called supervised measures.

The centroids, besides serving to represent the centers of the clusters, also have a meaning that depends on the domain of the problem, in the libras data set, represent the mean movement of the hand in a two-dimensional curve made in a period of time. The centroids obtained in the execution are shown in [Figure 5.2](#).

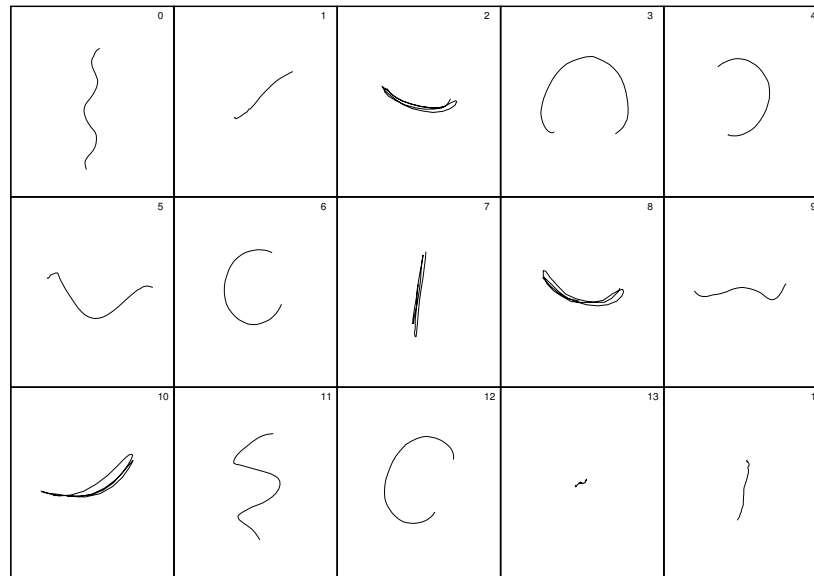


Figure 5.2: Average of the movements of the libras data set obtained with the program `kga_fkcentroid`

### 5.1.2 Based on the most representative

The problem is to find a partition based on the most representative instances, also called prototypes. A program included in EAC is `hka_fkmedoid` ([SL04], page 113). To obtain the program options ‘`hka_fkmedoid --help`’:

```
Usage: ./hka_fkmedoid [OPTION]
        About groups of instances for a set K as well as statistics
        of the algorithm used

-i, --instances=FILE or DIRECTORY
                                file or directory containing data of instances
                                to be clustered
-x, --select-instances[=PREFIX]
                                if instances is directory search files with
                                prefix for training (eg. iris-10-1tra.dat,
                                iris-10-2tra.dat,... PREFIX=tra.dat)
-t, --test[=FILE or PREFIX]    if instances is directory search files with
                                prefix for test (eg. iris-10-1tst.dat,
                                iris-10-2tst.dat,... PREFIX=tst.dat),
                                in other case only name file
-b --format-file[=NAME]        uci, or keel, by default uci
-h, --with-header[=yes/no]    file contains names of instances or a header,
                                by default is no
```

```

-u, --number-instances[=NUMBER]
    the number of instances the file contains
    instances, if not specified file is obtained
-a, --select-attributes[=ARG]
    select the attributes to be processed for
    example, "1-2,4" by default all. Also
    used to specify the number of dimensions
    of the instances, unless specified file is
    obtained instances
-d, --delimit-attributes=[ARG]
    separated file by default ","
-c, --class-column[=NUMBER] input file of instances has a class assigned
    in the column [NUMBER=undefined]
-e, --cluster-column[=NUMBER]
    input file of instances has a cluster assigned
    in the column [NUMBER=undefined]
-l, --idinstances-column[=NUMBER]
    the input file instance is assigned a column
    instance identifier [NUMBER=undefined]
-f, --freq-instances-column[=NUMBER]
    the input file instance is assigned a column
    frequency instances [NUMBER=undefined]
-r, --number-runs[=NUMBER] number of runs or repetitions of the algorithm
    (by default [NUMBER=1])
-R, --runtime-filename=[FILE]
    out file of times run
-n --distance[=NAME] euclidean, euclidean_sq, euclidean_induced,
    diagonal_induced, or mahalonobis_induced,
    by default euclidean
-z, --random-seed[=NUMBER] string with integer number seed by, default
    is random
-w, --max-execution-time[=NUMBER]
    real number for max execution time in seconds
    by default is 36000
-C, --centroids-outfile=[FILE]
    print centroids, standard output FILE=stdout
    --centroids-format[=yes/no]
    print the matrices by rows and columns,
    by default is no
-M, --membership-outfile=[FILE]
    print membership of the instances,
    standard output FILE=stdout
-T, --partitionstable-outfile=[FILE]
    print partitions table of the instances,
    standard output FILE=stdout
    --table-format[=yes/no]
    print the partitions table by rows and

```



```

                                columns, by default is no
-P, --gnuplot=FILE             file of gnuplot to graphics result
                                (compiling only with WITHOUT_PLOT_STAT)
-y, --gnuplot-styles=WORD      plot graphics with: points, lines,
                                linespoints, and dot [ARG=linespoints]

```

Particular options of the algorithm HKA  
based on Weiguo Sheng and Xiaohui Liu

```

--number-clusters[=NUMBER]     number of clusters [NUMBER=3]
--generations[=NUMBER]         number of generations or iterations
                                [NUMBER=200]
--population-size[=NUMBER]     size of population [NUMBER=200]
--mix-recombination-probability[=NUMBER]
                                real number in the interval [0.5, 0.9]
                                [NUMBER=0.95]
--point-mutation-probability[=NUMBER]
                                real number in the interval [0.2, 0.4]
                                [NUMBER=0.02]
--mix-mutation-probability[=NUMBER]
                                real number in the interval [0, 0.125]
                                [NUMBER=0.05]
--order-tournament[=NUMBER]    order of tournament [NUMBER=2]
--nearest-neighbors[=NUMBER]   number of the nearest neighbors (p)
                                [NUMBER=3]
--search-heuristic-probability[=NUMBER]
                                real number in the interval [0.0, 1.0]
                                [NUMBER=0.2]

-v, --verbose[=NUMBER]         explain what is being done (compiled with
                                VERBOSE=yes)
                                NUMBER=[-1,...,9999] Quiet level -1 not,
                                verbose, default=-1
-q, --bar-progress             progress bar printing, default is not
-?, --help                     help

```

As an example, `iris.data`, and run the command with the following parameters:

```

'hka_fkmedoid -i ../data/iris.data -a "1-4" -c 5 --number-clusters=3 -C
c_hka_iris.dat -M m_hka_iris.dat'

```

A possible exit from the program would be:

```

IN:
  Algorithm name: HKA
        Based on: Weiguo Sheng and Xiaohui Liu
        Metric used: SSE

```

```

        Data set: ../data/iris.data
Number of instances: 150
        Dimensions: 4

Random seed: 4253005715 70818531 1631842517 1223368670 2252683652
1178029056 3404574059 1048346743

OUT:

CROMOSOME: BEST: objective, 98.2137, fitness, 0.0101819: 7, 78, 112

Cluster number (K): 3
        SSE: 98.2137
        DB-index: 0.811606
        Silhouette: 0.552592
        VRC: 494.895
        CS measure: 0.155418
        Dunn's index: 0.0988074
Execution time (seg): 0.072937
Generations find the best: 69

```

For this execution, the most representative instances for each Iris cluster are:

ID	SepalLength	SepalWidth	PetalLength	PetalWidth	Class
7	5	3.4	1.5	0.2	Iris-setosa
78	6	2.9	4.5	1.5	Iris-versicolor
112	6.8	3	5.5	2.1	Iris-virginica

To visualize the results:

```

'./plot_clustering -i ../data/iris.data -a "1-4" -c 5 --centroids-infile
c_hka_iris.dat --member-infile m_hka_iris.dat --centroids-title "Medoid"
--graphics-outfile hka_iris'

```

And graphically show the prototypes and groups in [Figure 5.3](#).

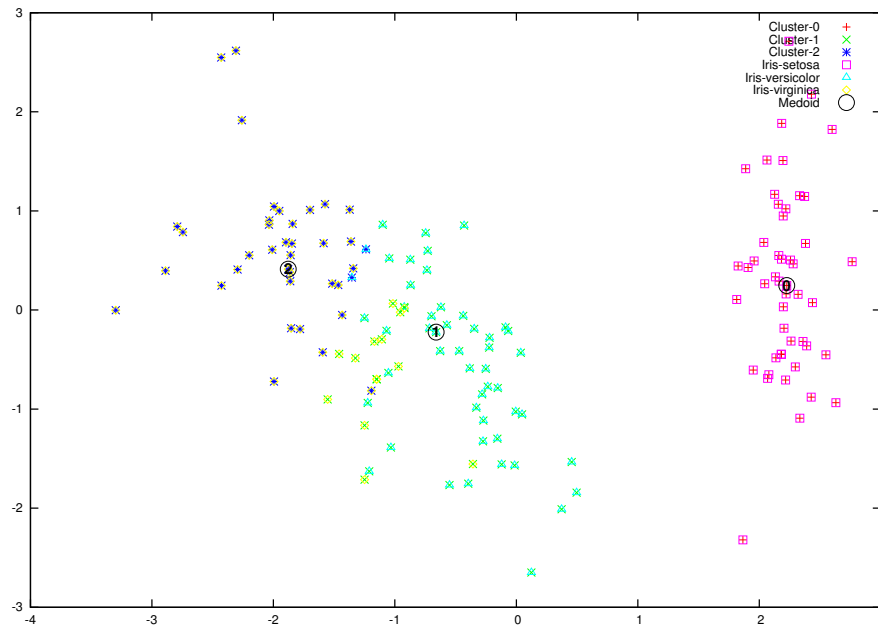


Figure 5.3: The most representative instances of the Iris data set, obtained with the program ‘hka\_fkmedoid’

## 5.2 Partition for variable k-cluster

In this case the problem to solve is search for optimal values both of cluster centers and of the number of clusters. EAC includes a wide list of algorithms to make a partition based on centroids. It is interesting to study this type of algorithm both by the intra and inter cluster metrics proposed, which produce different patterns.

### 5.2.1 Based on the centroids

**gcuk\_vkcentroid** It is a program based on the GCUK algorithm ([BM02b], page 111), This is used to automatically clustering a data set. Includes the determination of the number of clusters as well as the appropriate clustering of the data.

The clustering is an exploratory technique, which can be used to make the automatic classification. To do this, you can use an algorithm that finds the appropriate number of clusters, when an expert is not available, or also compare the clusters obtained against the predefined classes.

With the **gcuk\_vkcentroid** program, you will find an automatic classification of the Zoo data set. The data set **zoo.data** has 7 classes with 17 attributes. All attributes are binary, with the exception of number 14, which can be seen as nominal.

To process it can be transformed into binary with the following **awk** script:

```
#run:
# awk -f zoo_binary.awk -F ',' -v OFS=',' zoo.data > zoo_bin.csv
BEGIN {
```

```

h1 = "animalname";
h2 = "hair";
h3 = "feathers";
h4 = "eggs";
h5 = "milk";
h6 = "airborne";
h7 = "aquatic";
h8 = "predator";
h9 = "toothed";
h10 = "backbone";
h11 = "breathes";
h12 = "venomous";
h13 = "fins";
h14 = "legs_0,legs_2,legs_4,legs_5,legs_6,legs_8";
h15 = "tail";
h16 = "domestic";
h17 = "catsize";
h18 = "type";

print h1,h2,h3,h4,h5,h6,h7,h8,h9,h10,h11,h12,h13,h14,h15,h16,h17,h18;
}

{
# legs:Numeric (set of values: 0,2,4,5,6,8)
  if ( $14 == 0)
    $14 = "1,0,0,0,0,0";
  else if ($14 == 2)
    $14 = "0,1,0,0,0,0";
  else if ($14 == 4)
    $14 = "0,0,1,0,0,0";
  else if ($14 == 5)
    $14 = "0,0,0,1,0,0";
  else if ($14 == 6)
    $14 = "0,0,0,0,1,0";
  else if ( $14 == 8)
    $14 = "0,0,0,0,0,1";
  print $1,$2,$3,$4,$5,$6,$7,$8,$9,$10,$11,$12,$13,$14,$15,$16,$17,$18
}

'awk -f zoo_binary.awk -F ' ',' -v OFS=',' zoo.data > zoo_bin.csv'

'gcuk_vkcentroid -i ../data/zoo_bin.csv -h yes -a "2-22" -c 23 --k-minimum=2
--k-maximum=20 -C c_zoo_gcuk.data -M m_zoo_gcuk.data -T stdout --table-format
yes'
```

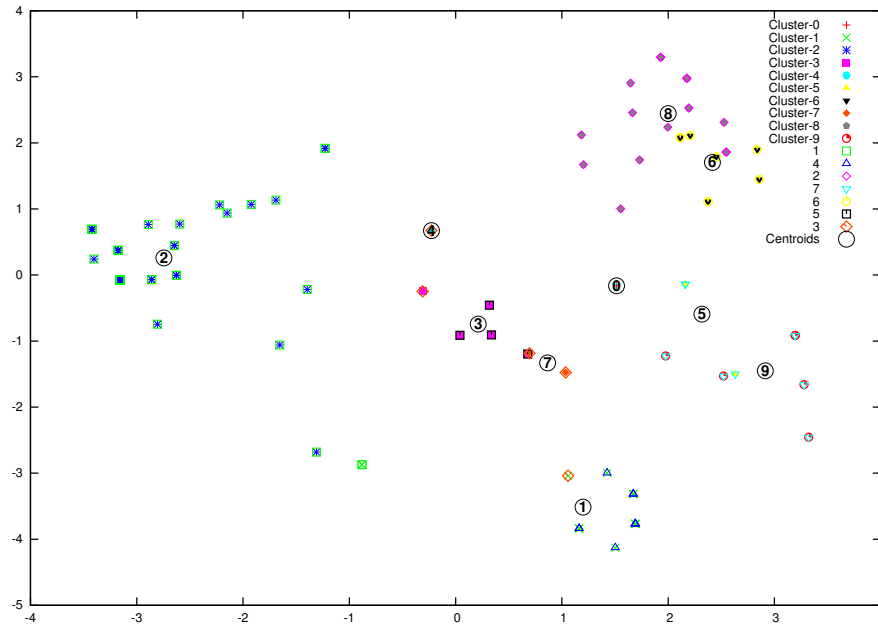


Figure 5.4: Clusters obtained in the data set Zoo with gcuk\_vkcentroid

IN:

Algorithm name: GCUK

Based on: Bandyopadhyay and Maulik 2002

Metric used: DB-index

Data set: /home/hermes/data/zoo\_bin.csv

Number of instances: 101

Dimensions: 21

Random seed: 728997733 111590912 682175903 3140775393 958797699  
 412503851 3032481805 703125621

OUT:

CROMOSOME: BEST: rows, 9, columns, 21 > 0, 1, 1, 0, 0.8, 0.3, 0.45, 0, 1, 1, 0, 0, 0, 1, 0, 0, 0, 0, 1, 0.15, 0.3; 0, 0, 0, 0, 0, 0, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0; 0.0588235, 0, 0.764706, 0.176471, 0, 1, 0.764706, 1, 1, 0.176471, 0.117647, 0.941176, 1, 0, 0, 0, 0, 0, 0.941176, 0.0588235, 0.411765; 1, 0, 0.0263158, 1, 0.0526316, 0.0789474, 0.5, 0.973684, 1, 1, 0, 0.0263158, 0, 0.184211, 0.815789, 0, 0, 0, 0.868421, 0.210526, 0.763158; 0, 0, 1, 0, 0, 0.8, 0.8, 1, 1, 1, 0.2, 0, 0, 0, 1, 0, 0, 0, 0.4, 0, 0; 0.4, 0, 1, 0, 0.6, 0, 0.1, 0, 0, 1, 0.2, 0, 0.2, 0, 0, 0, 0.8, 0, 0, 0.1, 0; 0, 0, 1, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 1, 0, 0, 0, 1, 0, 1; 0, 0, 1, 0, 0, 0, 1, 1, 1, 1, 0.5, 0, 1, 0, 0, 0, 0, 0, 1, 0, 0; 0, 0, 1, 0, 0, 0.857143, 1, 0, 0, 0, 0.142857, 0, 0.285714, 0, 0.142857, 0.142857, 0.285714, 0.142857, 0, 0, 0.142857

Cluster number (K): 9

```

DB-index: 0.855135
SSE: 98.3379
Silhouette: 0.355542
VRC: 26.5558
CS measure: 1.72969
Dunn's index: 0.57735
Execution time (seg): 0.354636
Generations find the best: 53

```

Partition table:

Cluster: 0	1	2	3	4
Class				
1: 0	0	3	38	0
4: 0	0	13	0	0
2: 20	0	0	0	0
7: 0	1	0	0	0
6: 0	0	0	0	0
5: 0	0	0	0	4
3: 0	0	1	0	1
sum: 20	1	17	38	5
Cluster: 5	6	7	8	sum
Class				
1: 0	0	0	0	41
4: 0	0	0	0	13
2: 0	0	0	0	20
7: 2	0	0	7	10
6: 8	0	0	0	8
5: 0	0	0	0	4
3: 0	1	2	0	5
sum: 10	1	2	7	101

```

Rand index: 0.956238
Purity: 0.930693
Precision: 0.932188
Recall: 0.875956

```

From the run of the program, 9 clusters were obtained, using the *DB-index* similarity measure, with very good measured values obtained. For this data set it is possible to use the centroids to obtain an association between items in the same row ([\[AIS93\]](#), [page \[HPY00\]](#), [page \[HPY00\]](#)) as shown in the [Figure 5.5](#) And the summary below:

$C_j$	$W_j$	Frequent dimension	Outliers
0	20%	95-100%: feathers eggs backbone breathes legs 2 tail 80-90%: airborne	
1	1%	90-100%: predator breathes venomous legs 8 tail	
2	17%	90-100%: aquatic backbone fins legs 0 tail	{eggs hair domestic}
3	38%	90-100%: hair milk toothed backbone breathes legs 4	{eggs airborne fins legs 4}
4	5%	90-100%: eggs toothed backbone breathes legs 4 80-90%: aquatic predator	
5	10%	90-100%: eggs breathes 80-90%: legs 6	{legs 6 domestic}
6	1%	90-100%: eggs backbone breathes legs 4 tail catsize	
7	2%	90-100%: eggs predator toothed backbone breathes legs 0 tail	
8	7%	90-100%: eggs predator 80-90%: aquatic	{aquatic venomous legs 4 legs 5 legs 8 catsize }

$$C = \begin{bmatrix} & 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ \text{hair} & 0.00 & 0.00 & 0.06 & 1.00 & 0.00 & 0.40 & 0.00 & 0.00 & 0.00 \\ \text{feathers} & 1.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ \text{eggs} & 1.00 & 0.00 & 0.76 & 0.03 & 1.00 & 1.00 & 1.00 & 1.00 & 1.00 \\ \text{milk} & 0.00 & 0.00 & 0.18 & 1.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ \text{airborne} & 0.80 & 0.00 & 0.00 & 0.05 & 0.00 & 0.60 & 0.00 & 0.00 & 0.00 \\ \text{aquatic} & 0.30 & 0.00 & 1.00 & 0.08 & 0.80 & 0.00 & 0.00 & 0.00 & 0.86 \\ \text{predator} & 0.45 & 1.00 & 0.76 & 0.50 & 0.80 & 0.10 & 0.00 & 1.00 & 1.00 \\ \text{toothed} & 0.00 & 0.00 & 1.00 & 0.97 & 1.00 & 0.00 & 0.00 & 1.00 & 0.00 \\ \text{backbone} & 1.00 & 0.00 & 1.00 & 1.00 & 1.00 & 0.00 & 1.00 & 1.00 & 0.00 \\ \text{breathes} & 1.00 & 1.00 & 0.18 & 1.00 & 1.00 & 1.00 & 1.00 & 1.00 & 0.00 \\ \text{venomous} & 0.00 & 1.00 & 0.12 & 0.00 & 0.20 & 0.20 & 0.00 & 0.50 & 0.14 \\ \text{fins} & 0.00 & 0.00 & 0.94 & 0.03 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ \text{legs 0} & 0.00 & 0.00 & 1.00 & 0.00 & 0.00 & 0.20 & 0.00 & 1.00 & 0.29 \\ \text{legs 2} & 1.00 & 0.00 & 0.00 & 0.18 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ \text{legs 4} & 0.00 & 0.00 & 0.00 & 0.82 & 1.00 & 0.00 & 1.00 & 0.00 & 0.14 \\ \text{legs 5} & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.14 \\ \text{legs 6} & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.80 & 0.00 & 0.00 & 0.29 \\ \text{legs 8} & 0.00 & 1.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.14 \\ \text{tail} & 1.00 & 1.00 & 0.94 & 0.87 & 0.40 & 0.00 & 1.00 & 1.00 & 0.00 \\ \text{domestic} & 0.15 & 0.00 & 0.06 & 0.21 & 0.00 & 0.10 & 0.00 & 0.00 & 0.00 \\ \text{catsize} & 0.30 & 0.00 & 0.41 & 0.76 & 0.00 & 0.00 & 1.00 & 0.00 & 0.14 \end{bmatrix} \quad W = \begin{bmatrix} 0.20 \\ 0.01 \\ 0.17 \\ 0.38 \\ 0.05 \\ 0.10 \\ 0.01 \\ 0.02 \\ 0.07 \end{bmatrix}$$

Figure 5.5: Clusters Zoo with gcuk\_vkcentroid





```

-e, --cluster-column[=NUMBER]
                                input file of instances has a cluster assigned
                                in the column [NUMBER=undefined]
-l, --idinstances-column[=NUMBER]
                                the input file instance is assigned a column
                                instance identifier [NUMBER=undefined]
-f, --freq-instances-column[=NUMBER]
                                the input file instance is assigned a column
                                frequency instances [NUMBER=undefined]
-r, --number-runs[=NUMBER]
                                number of runs or repetitions of the algorithm
                                (by default [NUMBER=1])
-R, --runtime-filename=[FILE]
                                out file of times run
-n --distance[=NAME]
                                euclidean, euclidean_sq, euclidean_induced,
                                diagonal_induced, or mahalonobis_induced,
                                by default euclidean
-z, --random-seed[=NUMBER]
                                string with integer number seed by, default
                                is random
-w, --max-execution-time[=NUMBER]
                                real number for max execution time in seconds
                                by default is 36000
-C, --centroids-outfile=[FILE]
                                print centroids, standard output FILE=stdout
    --centroids-format[=yes/no]
                                print the matrices by rows and columns,
                                by default is no
-M, --membership-outfile=[FILE]
                                print membership of the instances,
                                standard output FILE=stdout
-T, --partitionstable-outfile=[FILE]
                                print partitions table of the instances,
                                standard output FILE=stdout
    --table-format[=yes/no]
                                print the partitions table by rows and
                                columns, by default is no
-P, --gnuplot=FILE
                                file of gnuplot to graphics result
                                (compiling only with WITHOUT_PLOT_STAT)
-y, --gnuplot-styles=WORD
                                plot graphics with: points, lines,
                                linespoints, and dot [ARG=linespoints]

```

#### Particular options of the algorithm GGA\_SILHOUETTE

based on Agustin-Blas L.E. and Salcedo-Sanz S. and Jimenez-Fernandez S.  
and Carro-Calvo L. and Del Ser J. and Portilla-Figueras, J.A.

```

--k-minimum[=NUMBER]
                                number of clusters by default
                                [NUMBER=2]
--k-maximum[=NUMBER]
                                number of clusters if eq -1
                                k-maximum =  $N^{1/2}$  [NUMBER=-1]

```

```

--sub-population-size[=NUMBER]          size of sub-populations (islands)
                                         [NUMBER=20]
--number-island[=NUMBER]                number of sub-populations or islands
                                         [NUMBER=4]
--pe[=NUMBER]                           probability of migration
                                         good individuals between islands
                                         [0,1] [NUMBER=0.5]
--generations[=NUMBER]                  number of generations or iterations
                                         [NUMBER=100]
--pci[=NUMBER]                           initial probability crossover, real
                                         number in the interval [0,1] must be
                                         high in the first stages [NUMBER=0.8]
--pcf[=NUMBER]                           final probability crossover, real
                                         number in the interval [0,1] must
                                         moderate in the last stages [NUMBER=0.4]
--pmi[=NUMBER]                           initial probability mutation, real number
                                         in the interval [0,1] is smaller in the
                                         first generations [NUMBER=0.05]
--pmf[=NUMBER]                           final probability mutation, real number in
                                         the interval [0,1] is larger in the last
                                         ones [NUMBER=0.2]
--pbi[=NUMBER]                           initial probability local search, real
                                         number in the interval [0,1] must be
                                         high in the first stages [NUMBER=0.1]
--pbf[=NUMBER]                           final probability local search, real
                                         number in the interval [0,1] must
                                         moderate in the last stages [NUMBER=0.05]

-v, --verbose[=NUMBER]                  explain what is being done (compiled with
                                         VERBOSE=yes)
                                         NUMBER=[-1,...,9999] Quiet level -1 not,
                                         verbose, default=-1
-q, --bar-progress                       progress bar printing, default is not
-?, --help                               help

```

As an illustrative example, the **Ionosphere**, data set is used, this data set has the complexity that the instances of different classes overlap. For this case, the silhouette metric was the most appropriate.

```

'gga_vklabilsilhouette -i ../data/ionosphere.data -a "1-34" -c 35 -M
m_gga_ionosphere.data -T stdout --table-format yes'

```

IN:

```

Algorithm name: GGA_SILHOUETTE
Based on: Agustin-Blas L.E. and Salcedo-Sanz S. and
Jimenez-Fernandez S. and Carro-Calvo L. and Del Ser J.
and Portilla-Figueras, J.A.

```

Metric used: Silhouette

Data set: /home/hermes/data/ionosphere.data

Number of instances: 351

Dimensions: 34

Random seed: 389887919 3739475900 1204968903 2830340246 1365531614  
2641306820 2495066055 1120010892

OUT:

CROMOSOME: BEST: objective, 0.320094, fitness, 0.3200943, 0, 3, 1, 3, 0, 3, 1, 3, 0, 3, 3, 3,  
3, 3, 0, 3, 0, 3, 4, 3, 0, 3, 0, 3, 3, 3, 0, 3, 1, 3, 3, 3, 3, 3, 3, 4, 3, 3, 4, 2, 4, 3, 3, 4, 3, 0, 3, 0, 3,  
0, 2, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 2, 3, 3, 3, 3, 2, 3, 3, 1, 4, 0, 3, 3, 3, 4, 4, 4, 3, 3, 4, 4, 3, 3, 3, 3, 3,  
4, 3, 0, 3, 0, 3, 4, 4, 4, 0, 3, 3, 3, 0, 3, 3, 3, 0, 3, 0, 3, 3, 4, 3, 4, 0, 3, 3, 3, 0, 3, 3, 3, 0, 3, 0, 3, 3,  
3, 0, 3, 3, 3, 3, 4, 3, 4, 2, 3, 0, 3, 0, 3, 3, 0, 3, 0, 0, 3, 3, 3, 0, 3, 0, 2, 0, 3, 0, 2, 0, 2, 0, 3, 0, 2, 3,  
2, 0, 2, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 3, 2, 0, 2, 1, 3, 0, 0, 0, 3, 0, 3, 3, 3, 0, 3, 3, 3, 0,  
3, 0, 3, 0, 3, 0, 3, 0, 3, 0, 3, 3, 2, 3, 4, 4, 4, 0, 4, 3, 4, 0, 4, 0, 2, 3, 3, 0, 3, 0, 3, 3, 3, 4, 3, 0, 3, 0,  
3, 0, 3, 3, 3, 0, 3, 0, 2, 0, 2, 0, 2, 2, 2, 3, 3, 3, 3, 3, 4, 4, 4, 4, 4, 4, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 4,  
4, 4, 4, 4, 2, 0, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 4, 2, 2, 2, 2, 2, 3, 3, 3, 3, 3, 4, 4, 2, 2, 2, 3, 3, 2, 2, 2,  
3, 3, 3, 3, 3, 3, 3, 2, 2, 2, 2, 2, 3, 3, 3, 3, 3, 3, 3, 3, 2, 2, 2, 2, 0, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 0, 1, 2, 3, 4

Cluster number (K): 5

Silhouette: 0.320094

SSE: 705.646

DB-index: 1.93699

VRC: 54.7797

CS measure: 1.9306

Dunn's index: 0.0709856

Execution time (seg): 3.59483

Generations find the best: 77

Partition table:

Cluster: 0	1	2	3	4
Class				
g: 5	0	38	152	30
b: 70	5	3	38	10
sum: 75	5	41	190	40

Cluster: sum

Class

g: 225

b: 126

```

sum: 351

Rand index: 0.612291
Purity: 0.840456
Precision: 0.707252
Recall: 0.477702

'./plot_clustering -i ../data/ionosphere.data -a "1-34" -c 35 --member-infile
m_gga_ionosphere.data --graphics-outfile gga_ionosphere'
```

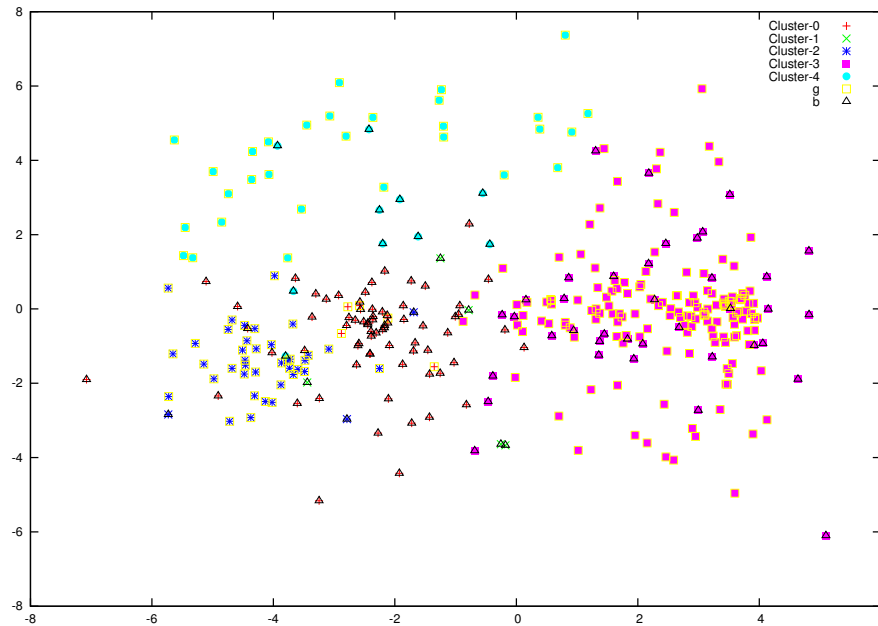


Figure 5.6: Clusters obtained with `gga_vklablesilhouette`

### 5.2.3 Based on other schemes

There are other algorithms that use different coding schemes based on graphs and trees. One of them is [CdLM03], page 111 adopt as encoding scheme based on minimum spanning tree (MST), the tree nodes represent the  $n$  instances of the data set and the edges  $(n - 1)$  correspond to the nearest instances. The algorithm first calculates the MST and creates the partitions of the data set by preserving or deleting the edges, represented by a binary string. The value 0 means that the corresponding edge remains, while the value 1 means that it is deleted. The number of elements with value 1 is equal to  $(k - 1)$ , where  $k$  is the number of clusters.

As an illustrative example, the `Ecoli`, data set was processed, in order to obtain a cluster number automatically and compare it with the classification proposed in the data set

```

'./gaclustering_vktreebinary -i ../data/ecoli.data -a "2-8" -c 9 -d " " -C
ecoli_centroids.data -M ecoli_membership.data -G ecoli_tree.data -T stdout
--table-format yes --generations=500 --notchangestop=100'
```

IN:

Purity: 0.761905

Precision: 0.687857  
Recall: 0.927444

And the results can be visualized with the following command. [Figure 5.7](#)

```
./plot_clustering -i ../data/ecoli.data -a "2-8" -c 9 -d " " --centroids-infile
ecoli_centroids.data --member-infile ecoli_membership.data --graph-infile
ecoli_tree.data --graphics-outfile ecoli_tree --centroids-size 1.5
--member-size 0.5 --size-instance 0.6'
```

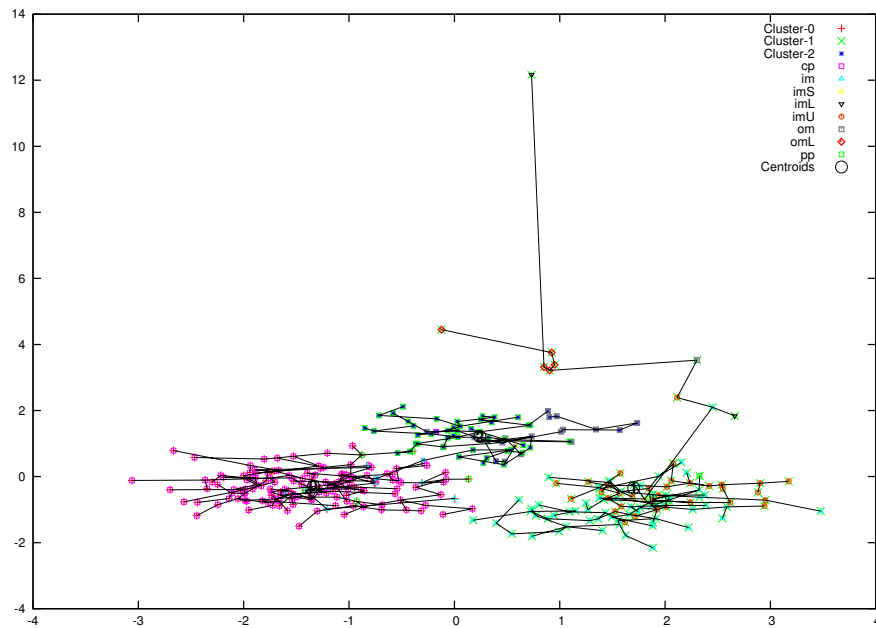


Figure 5.7: Minimum spanning tree (MST) and clusters obtained with `gaclustering_vktreebinary` program for the ecoli data set

## 6 Reporting Bugs

If you find a bug in LEAC, please send electronic mail to [hermes@uaz.edu.mx](mailto:hermes@uaz.edu.mx).





## Appendix A Example source code

The following source code show the use of the LEAC library. The files are in eac directory.

### A.1 KGA algorithm

The following encoded algorithm is the KGA (`kga_fkcentroid.hpp`), described in the paper [BM02a], page 111.

```

/*! \file kga_fkcentroid.hpp
 * This file is part of the LEAC.
 *
 * Implementation of the KGA algorithm based on the paper:
 *
 * S. Bandyopadhyay and U. Maulik. An evolutionary technique based
 * on k-means algorithm for optimal clustering in rn. Inf. Sci. Appl.,
 * 146(1-4):221--237, 2002. URL: http://www.sciencedirect.com/science/article/pii/S0020025502002086, doi:http://dx.doi.org/10.1016/S0020-0255\(02\)00208-6.
 *
 * Library Evolutionary Algorithms for Clustering (LEAC) is a library
 * for the implementation of evolutionary and genetic algorithms
 * focused on the partition type clustering problem. Based on the
 * current standards of the C++ language, as well as on Standard
 * Template Library STL and also OpenBLAS to have a better performance.
 *
 * (c) Hermes Robles Berumen <hermes@uaz.edu.mx>
 *
 * For the full copyright and license information, please view the LICENSE
 * file that was distributed with this source code.
 */

#ifndef __KGA_FKCENTROID_HPP__
#define __KGA_FKCENTROID_HPP__

#include <vector>
#include <algorithm>

#include <leac.hpp>
#include "inparam_gaclustering_pcpm_fixedk.hpp"
#include "outparam_gaclustering.hpp"

#include "plot_runtime_function.hpp"

/*! \namespace eac
    \brief Evolutionary Algorithms for Clustering
    \details Implementation of genetic and evolutionary algorithms used to
    solve the clustering problem

```

```

\author Hermes Robles Berumen
\date 2015-2017
\copyright GPLv3 license
*/

namespace eac {

/*! \fn gaencode::ChromFixedLength<T_FEATURE,T_REAL> kga_fkcentroid
(inout::OutParamGAClustering<T_REAL,T_CLUSTERIDX> &aoopcga_outParamClusteringGA,
inout::InParamGAClusteringProbCProbMFixedK<T_CLUSTERIDX,T_REAL,T_FEATURE,
T_FEATURE_SUM,T_INSTANCES_CLUSTER_K> &aiinpcgaprobfixedk_inParamKGA,
const INPUT_ITERATOR aiiterator_instfirst,
const INPUT_ITERATOR aiiterator_instlast,
const dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist)
\brief GAS, KGA
\details Implementation of KGA algorithm based on [BM02a], page 111
. Returns a
partition of a data set, encoded on a chromosome where each gene is the
coordinate of a centroid. Base to following equation:
\mathbb{f}[
x_i \in C_j \iff x_i - \mu_j \leq \min_k \|x_i - \mu_k\|, j=1,2,...,k,
\mathbb{f}]
where \mathbb{f}[m_j] represents the medoid of cluster C_j
\param aoopcga_outParamClusteringGA a outparam::OutParamGAClustering with
the output parameters of the algorithm
\param aiinpcgaprobfixedk_inParamKGA a
inout::InParamGAClusteringProbCProbMFixedK parameters required by the algorithm
\param aiiterator_instfirst an InputIterator to the initial positions of the
sequence of instances
\param aiiterator_instlast an InputIterator to the final positions of the
sequence of instances
\param aifunc2p_dist an object of type dist::Dist to calculate distances
*/
template < typename T_FEATURE,
typename T_REAL,
typename T_FEATURE_SUM,
typename T_INSTANCES_CLUSTER_K,
typename T_CLUSTERIDX, //-1, 0, 1, ..., K
typename INPUT_ITERATOR
>
gaencode::ChromFixedLength<T_FEATURE,T_REAL>
kga_fkcentroid
(inout::OutParamGAClustering
<T_REAL,
T_CLUSTERIDX>
&aoopcga_outParamClusteringGA,

```

```

    inout::InParamGAClusteringProbCProbMFixedK
    <T_CLUSTERIDX,
    T_REAL,
    T_FEATURE,
    T_FEATURE_SUM,
    T_INSTANCES_CLUSTER_K>          &aiinpcgaprobfixedk_inParamKGA,
    const INPUT_ITERATOR             aiiterator_instfirst,
    const INPUT_ITERATOR             aiiterator_instlast,
    const dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist
    )
    {
        const uintidx lconstui_numClusterFixedK =
            (uintidx) aiinpcgaprobfixedk_inParamKGA.getNumClusterK();
/*Defines the size of the chromosome
    Specifically, each chromosome is described by a sequence of
    length(Ch) =  $l \times k$  real-valued numbers where  $l$  is the dimension
    of the instances, and  $k$  is the number of clusters. That is to
    say, the chromosome of the algorithm is written as (2.2) (See
    [centroid-based], page 11)
*/
    /*ASSIGN SIZE FOR ALL CHROMOSOMES
    */

    gaencode::ChromFixedLength<T_FEATURE,T_REAL>::setStringSize
        ( lconstui_numClusterFixedK * data::Instance<T_FEATURE>::getNumDimensions() );

    gaencode::ChromFixedLength<T_FEATURE,T_REAL> lochromfixleng_best;

/*VARIABLE NEED FOR POPULATION AND MATINGPOOL GENETIC
    */

/*POPULATION CREATE-----
    */

    std::vector<gaencode::ChromFixedLength<T_FEATURE,T_REAL> >
        lvectorchromfixleng_population
        (aiinpcgaprobfixedk_inParamKGA.getSizePopulation());

/*CREATE SPACE FOR STORE MATINGPOOL-----
    */
    std::vector<gaencode::ChromFixedLength<T_FEATURE,T_REAL> >
        lvectorchromfixleng_matingPool
        (aiinpcgaprobfixedk_inParamKGA.getSizePopulation());

    std::uniform_real_distribution<T_REAL> uniformdis_real01(0, 1);

```

```

#ifdef __VERBOSE_YES

/*ID PROC
*/
geverboseui_idproc = 1;

++geinparam_verbose;
const char* lpc_labelAlgGA = "kga_fkcentroid";
if ( geinparam_verbose <= geinparam_verboseMax ) {
    std::cout
        << lpc_labelAlgGA
        << ": IN(" << geinparam_verbose << ")\n"
        << "\t(output Chromosome: lochromfixleng_best["
        << &lochromfixleng_best << "]\n"
        << "\t output outparam::OutParamGAClustering&: "
        << "aoopcga_outParamClusteringGA["
        << &aoopcga_outParamClusteringGA << "]\n"
        << "\t input  InParamGAClusteringProbCProbMFixedK&: "
        << "aiinpcgaprobfixedk_inParamKGA["
        << &aiinpcgaprobfixedk_inParamKGA << "]\n"
        << "\t input aiiterator_instfirst[" << *aiiterator_instfirst << "]\n"
        << "\t input aiiterator_instlast[" << &aiiterator_instlast << "]\n"
        << "\t input  dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist["
        << &aifunc2p_dist << ']'
        << "\n\t\tPopulation size = "
        << aiinpcgaprobfixedk_inParamKGA.getSizePopulation()
        << "\n\t\tProbCrossover = "
        << aiinpcgaprobfixedk_inParamKGA.getProbCrossover()
        << "\n\t\tProbMutation  = "
        << aiinpcgaprobfixedk_inParamKGA.getProbMutation()
        << "\n\t)"
        << std::endl;
    }
#endif /*__VERBOSE_YES*/

runtime::ListRuntimeFunction<COMMON_IDOMAIN>
    llfh_listFuntionHist
    (aiinpcgaprobfixedk_inParamKGA.getNumMaxGenerations(),
      "Iterations",
      "Clustering metrics"
    );

/*DECLARATION OF VARIABLES: COMPUTING STATISTICAL AND METRIC OF THE ALGORITHM*/
#ifndef __WITHOUT_PLOT_STAT
    std::ofstream          lfileout_plotStatObjectiveFunc;
    runtime::RuntimeFunctionValue<T_REAL> *lofh_SSE = NULL;

```

```

runtime::RuntimeFunctionStat<T_REAL>
    *lofhs_statObjectiveFunc[STATISTICAL_ALL_MEASURES];
std::vector<T_REAL>          lvectorT_statfuncObjectiveFunc;

if ( aiinpcgaprobfixedk_inParamKGA.getWithPlotStatObjectiveFunc() ) {

    lvectorT_statfuncObjectiveFunc.reserve
        ( aiinpcgaprobfixedk_inParamKGA.getSizePopulation());
    //DEFINE FUNCTION
    lofh_SSE = new runtime::RuntimeFunctionValue<T_REAL>
        ("SSE",
         aiinpcgaprobfixedk_inParamKGA.getAlgorithmoName(),
         RUNTIMEFUNCTION_NOT_STORAGE
        );

    llfh_listFuntionHist.addFuntion(lofh_SSE);

    //DEFINE FUNCTION STATISTICAL
    for (int li_i = 0; li_i < STATISTICAL_ALL_MEASURES; li_i++) {
        lofhs_statObjectiveFunc[li_i] =
            new runtime::RuntimeFunctionStat<T_REAL>
                ( (char) li_i,
                  aiinpcgaprobfixedk_inParamKGA.getAlgorithmoName(),
                  RUNTIMEFUNCTION_NOT_STORAGE
                );
        llfh_listFuntionHist.addFuntion(lofhs_statObjectiveFunc[li_i]);
    }

    //OPEN FILE STRORE FUNCTION
    aoopcga_outParamClusteringGA.setFileNameOutPlotStatObjectiveFunc
        (aiinpcgaprobfixedk_inParamKGA.getFileNamePlotStatObjectiveFunc(),
         aiinpcgaprobfixedk_inParamKGA.getTimesRunAlgorithm()
        );

    lfileout_plotStatObjectiveFunc.open
        (aoopcga_outParamClusteringGA.getFileNameOutPlotStatObjectiveFunc().c_str(),
         std::ios::out | std::ios::app
        );

    lfileout_plotStatObjectiveFunc.precision(COMMON_COUT_PRECISION);

    //FUNCTION HEADER
    lfileout_plotStatObjectiveFunc
        << llfh_listFuntionHist.getHeaderFuntions()
        << "\n";
}

```

```

#endif /*__WITHOUT_PLOT_STAT*/

/*WHEN CAN MEASURE STARTS AT ZERO INVALID OFFSPRING
*/
aoopcgga_outParamClusteringGA.setTotalInvalidOffspring(0);

/*OUT: GENETIC ALGORITHM CHARACTERIZATION*/
runtime::ExecutionTime let_executionTime = runtime::start();

T_FEATURE *larray_maxFeactures =
    new T_FEATURE[data::Instance<T_FEATURE>::getNumDimensions()];

T_FEATURE *larray_minFeactures =
    new T_FEATURE[data::Instance<T_FEATURE>::getNumDimensions()];

stats::maxFeatures
    (larray_maxFeactures,
     aiiterator_instfirst,
     aiiterator_instlast
    );

stats::minFeatures
    (larray_minFeactures,
     aiiterator_instfirst,
     aiiterator_instlast
    );

/*INITIALIZE POPULATION-----
3.1.1 POPULATION INITIALIZATION
Chosen distinct points from the data set are used to initialize
the K cluster centers encoded in each chromosome.
This is similar to the initialization of the centers
in K-Means algorithm. This process is repeated for each chromosome
in the population [BM02a], page 111
*/
{ /*BEGIN INITIALIZE POPULATION P(t)*/

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "(0) POPULATION INITIAL";
    ++geiinputparam_verbose;
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << " ": IN(" << geiinputparam_verbose << ' ' )'
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

```

```

for ( auto& lchromfixleng_iter: lvectorchromfixleng_population ) {

    /*DECODE CHROMOSOME
    */
    mat::MatrixRow<T_FEATURE>
        lmatrixrowt_centroidsChrom
        (lconstui_numClusterFixedK,
         data::Instance<T_FEATURE>::getNumDimensions(),
         lchromfixleng_iter.getString()
        );

    clusteringop::randomInitialize
        (lmatrixrowt_centroidsChrom,
         aiiterator_instfirst,
         aiiterator_instlast
        );

    lchromfixleng_iter.setFitness
        (-std::numeric_limits<T_REAL>::max());
    lchromfixleng_iter.setObjectiveFunc
        (std::numeric_limits<T_REAL>::max());

}

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ' )'
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

} /*END INITIALIZE POPULATION P(t)*/

while ( 1 ) {

    /*BEGIN ITERATION
    */
    llfh_listFuntionHist.increaseDomainUpperBound();

    /*3.1.2 CLUSTERING In this step, the cluster are formed according to the
    center encoded in the chromosome. This is done by assigning each point
     $x_i, i = 1, 2, \dots, n$  to one of the clusters  $C_j$  with center  $z_i^*$  such that

```

$$\|x_i - \mu_j\| \leq \|x_i - \mu'_{j'}\|, \quad j' = 1, 2, \dots, k, \text{ and } j \neq j'$$

All ties are resolved arbitrarily. As like the K-Means algorithm, for each cluster  $C_i$ , its new center  $\mu^*$  is computed as

$\mu_i^* = 1/n_j \sum_{x_i \in C_j} x_i, j = 1, 2, \dots, k$ , where  $n_j$  is the number of points in cluster  $C_i$ . These  $\mu^*$  now replace the previous  $\mu_i$  s in the chromosome. [BM02a], page 111  
\*/

```

    { /*BEGIN CLUSTERING*/
#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "A. THE CLUSTERS ARE FORMED";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << " : IN(" << geiinparam_verbose << ' ) '
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

    for ( auto& liter_iChrom: lvectorchromfixleng_population ) {

        /*DECODE CHROMOSOME*/
        mat::MatrixRow<T_FEATURE>
            lmatrixrowt_centroidsChrom
            (lconstui_numClusterFixedK,
             data::Instance<T_FEATURE>::getNumDimensions(),
             liter_iChrom.getString()
            );

        mat::MatrixRow<T_FEATURE_SUM>
            llmatrixrowt_sumInstancesCluster
            (lconstui_numClusterFixedK,
             data::Instance<T_FEATURE>::getNumDimensions(),
             T_FEATURE_SUM(0)
            );

        std::vector<T_INSTANCES_CLUSTER_K>
            lvectort_numInstancesInClusterK
            (lconstui_numClusterFixedK,
             T_INSTANCES_CLUSTER_K(0)
            );

        T_CLUSTERIDX lmcidx_numClusterNull;

```



```

        clusteringop::updateCentroids
        (lmcidx_numClusterNull,
         lmatrixrowt_centroidsChrom,
         llmatrixrowt_sumInstancesCluster,
         lvectort_numInstancesInClusterK,
         aiiterator_instfirst,
         aiiterator_instlast,
         aifunc2p_dist
        );
    }
#ifdef __VERBOSE_YES
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinputparam_verbose << ') '
            << std::endl;
    }
    --geiinputparam_verbose;
#endif /*__VERBOSE_YES*/

} /*END CLUSTERING*/

```

/\*FITNESS FUNCTION-----

/\* 3.1.3 Fitness computation For each chromosome, the clusters formed in the previous step are utilized computing the clustering metric, *SSE*, as follows:

$$SSE = \sum_{j=1}^k \sum_{x_i \in C_j} ||x_i - \mu_j||$$

For finding the appropriate clusters *SSE* has to be minimized. The fitness function of a chromosome is defined as  $1/SSE$ . Therefore, maximization of the fitness function will lead to minimization of the clustering metric *SSE*.

\*/

```

{ /*BEGIN COMPUTED METRIC M AND FITNESS*/

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "B. COMPUTED METRIC M AND FITNESS";
    ++geiinputparam_verbose;
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinputparam_verbose << ') '
            << std::endl;
    }
}

```

```

#endif /*__VERBOSE_YES*/

long ll_invalidOffspring = 0;

for ( auto& lchromfixleng_iter: lvectorchromfixleng_population ) {

    /*DECODE CHROMOSOME*/
    mat::MatrixRow<T_FEATURE>
        lmatrixrowt_centroidsChrom
        (lconstui_numClusterFixedK,
         data::Instance<T_FEATURE>::getNumDimensions(),
         lchromfixleng_iter.getString()
        );

    std::pair<T_REAL,bool> lpair_SSE =
        um::SSE
        (lmatrixrowt_centroidsChrom,
         aiiterator_instfirst,
         aiiterator_instlast,
         aifunc2p_dist
        );

    lchromfixleng_iter.setObjectiveFunc(lpair_SSE.first);
    lchromfixleng_iter.setFitness(1.0 / lpair_SSE.first);
    lchromfixleng_iter.setValidString(lpair_SSE.second);

    if ( lchromfixleng_iter.getValidString() == false )
        ++ll_invalidOffspring;

#ifdef __WITHOUT_PLOT_STAT
    lvectorT_statfuncObjectiveFunc.push_back
        (lchromfixleng_iter.getObjectiveFunc());
#endif /*__WITHOUT_PLOT_STAT*/

}

aooppga_outParamClusteringGA.sumTotalInvalidOffspring
    (ll_invalidOffspring);

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ')'
            << std::endl;
    }
    --geiinparam_verbose;

```

```

#endif /*__VERBOSE_YES*/

} /*END COMPUTED METRIC M AND FITNESS*/

/*ELITISM-----
Elitism has been implemented in each generation by
replacing the worst chromosome of the population with
the best one seen up to the previous generation.
[BM02a], page 111
*/
{ /*BEGIN ELITISM REPLACING THE WORST CHROMOSOME*/

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "ELITISM REPLACING THE WORST CHROMOSOME";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinparam_verbose << ' '
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

    auto lit_chromMin =
        std::min_element
            (lvectorchromfixleng_population.begin(),
             lvectorchromfixleng_population.end(),
             [](const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& x,
                const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& y
                )
            { return x.getFitness() < y.getFitness(); }
            );

    if ( lit_chromMin->getFitness() < lochromfixleng_best.getFitness() ) {
        *lit_chromMin = lochromfixleng_best;
    }

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ' '
            << std::endl;
    }
    --geiinparam_verbose;

```

```

#endif /*__VERBOSE_YES*/

    } /*END ELITISM REPLACING THE WORST CHROMOSOME*/

    /*The best string or chromosome seen up to the last generation
       provides the solution to the clustering problem.
       [BM02a], page 111
    */
    { /*BEGIN PRESERVING THE BEST STRING*/

        auto lchromfixleng_iterMax =
            std::max_element
                (lvectorchromfixleng_population.begin(),
                 lvectorchromfixleng_population.end(),
                 [](const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& x,
                    const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& y
                 )
                { return x.getFitness() < y.getFitness(); }
            );

#ifdef __VERBOSE_YES
        geverbosepc_labelstep = "ELITISM PRESERVING THE BEST";
        ++geiinparam_verbose;
        if ( geiinparam_verbose <= geiinparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ": IN(" << geiinparam_verbose << ")\tmax fitness = "
                << lchromfixleng_iterMax->getFitness()
                << std::endl;
        }
#endif /*__VERBOSE_YES*/

        if ( lochromfixleng_best.getFitness() <
            lchromfixleng_iterMax->getFitness() ) {

            /*CHROMOSOME ONE WAS FOUND IN THIS ITERATION*/
            lochromfixleng_best = *lchromfixleng_iterMax;

            aoopcga_outParamClusteringGA.setIterationGetsBest
                (llfh_listFuntionHist.getDomainUpperBound());
            aoopcga_outParamClusteringGA.setRunTimeGetsBest
                (runtime::elapsedTime(let_executionTime));
        }

#ifdef __VERBOSE_YES
        if ( geiinparam_verbose <= geiinparam_verboseMax ) {

```

```

        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinputparam_verbose << ') '
            << std::endl;
    }
    --geiinputparam_verbose;
#endif /*__VERBOSE_YES*/

} /*END PRESERVING THE BEST STRING*/

/*MEASUREMENT BEST: COMPUTING STATISTICAL AND METRIC OF THE
ALGORITHM
*/
#ifdef __WITHOUT_PLOT_STAT
    if ( aiinputpcgaprobfixedk_inParamKGA.getWithPlotStatObjectiveFunc() ) {

        lofh_SSE->setValue(lochromfixleng_best.getObjectiveFunc());

        functionhiststat_evaluateAll
            (lofhs_statObjectiveFunc,
             lvectorT_statfuncObjectiveFunc
            );
        lfileout_plotStatObjectiveFunc << llfh_listFuntionHist;
        lvectorT_statfuncObjectiveFunc.clear();
    }
#endif /*__WITHOUT_PLOT_STAT*/

/*TERMINATION CRITERION-----
3.1.5 TERMINATION CRITERION
[BM02a], page 111
*/
#ifdef __VERBOSE_YES
    /*ID PROC
    */
    ++geverboseui_idproc;

    ++geiinputparam_verbose;
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << "TERMINATION CRITERION ATTAINED?: "
            << llfh_listFuntionHist.getDomainUpperBound()
            << std::endl;
    }
    --geiinputparam_verbose;
#endif /*__VERBOSE_YES*/

```

```

if ( !(llfh_listFuntionHist.getDomainUpperBound()
      < aiinpcgaprobfixdk_inParamKGA.getNumMaxGenerations() )
    )
    break;

/*3.1.4 GENETIC OPERATIONS
  [BM02a], page 111
*/

/*SELECTION-----
  Selection. The selection process selects chromosomes from the mating pool
  directed by the survival of the fittest concept of natural genetic systems.
  In the proportional selection strategy adopted in this paper, a chromosome is
  assigned a number of copies, which is proportional to its fitness in the pop-
  ulation.
  [BM02a], page 111
*/
{ /*BEGIN SELECTION*/
#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "SELECTION";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinparam_verbose << ')'
            << std::endl;
    }
}
#endif /*__VERBOSE_YES*/

    const std::vector<T_REAL>&& lvectorT_probDistRouletteWheel =
        prob::makeDistRouletteWheel
        (lvectorchromfixleng_population.begin(),
         lvectorchromfixleng_population.end(),
         [](const gaencode::ChromFixedLength<T_FEATURE,T_REAL>&
            lchromfixleng_iter) -> T_REAL
         {
             return lchromfixleng_iter.getFitness();
         }
        );

/*COPY POPULATION TO STRING POOL FOR ROULETTE WHEEL-----
*/
for ( auto& lchromfixleng_iter: lvectorchromfixleng_matingPool ) {

    uintidx lstidx_chrom =
        gaselect::getIdxRouletteWheel
        (lvectorT_probDistRouletteWheel,

```

```

        uintidx(0)
    );

    lchromfixleng_iter = lvectorchromfixleng_population.at(lstidx_chrom);
}

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ')'
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

} /*END SELECTION*/

/*CROSSOVER-----
Crossover is a probabilistic process that exchanges information between
two parent chromosomes for generating two offspring. Here, single-point
crossover with a fixed crossover probability of  $p_c$  is used. For chromosomes
of length  $l \times k$ , a random integer, called the crossover point, is generated
in the range  $[1, l - 1]$ . The portions of the chromosomes lying to the right of
the crossover point are exchanged to produce two offspring.
*/

{ /*BEGIN CROSSOVER*/
#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "CROSSOVER";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout << geverbosepc_labelstep
            << ": IN(" << geiinparam_verbose << ')'
            << std::endl;
    }
}
#endif /*__VERBOSE_YES*/

    long ll_invalidOffspring = 0;

    gaiterator::crossover
        (lvectorchromfixleng_matingPool.begin(),
         lvectorchromfixleng_matingPool.end(),
         lvectorchromfixleng_population.begin(),
         lvectorchromfixleng_population.end(),
         [&](const gaencode::ChromFixedLength<T_FEATURE, T_REAL>&
             aichrom_parent1,
             const gaencode::ChromFixedLength<T_FEATURE, T_REAL>&

```

```

    aichrom_parent2,
    gaencode::ChromFixedLength<T_FEATURE,T_REAL>&
    aochrom_child1,
    gaencode::ChromFixedLength<T_FEATURE,T_REAL>&
    aochrom_child2
  )
{

  if ( uniformdis_real01(gmt19937_eng) <
      aiinpcgaprobfixedk_inParamKGA.getProbCrossover() ) {

    gagenericop::onePointCrossover
      (aochrom_child1,
       aochrom_child2,
       aichrom_parent1,
       aichrom_parent2
      );

    /*DECODE CHROMOSOME CHILD1*/
    mat::MatrixRow<T_FEATURE>
      lmatrixrowt_centroidsChromChild1
      (lconstui_numClusterFixedK,
       data::Instance<T_FEATURE>::getNumDimensions(),
       aochrom_child1.getString()
      );

    std::pair<T_REAL,bool>
      lpair_SSE1 =
      um::SSE
      (lmatrixrowt_centroidsChromChild1,
       aiiterator_instfirst,
       aiiterator_instlast,
       aifunc2p_dist
      );
    aochrom_child1.setObjectiveFunc(lpair_SSE1.first);
    aochrom_child1.setFitness(1.0 / lpair_SSE1.first);
    aochrom_child1.setValidString(lpair_SSE1.second);

    if ( aochrom_child1.getValidString() == false )
      ++ll_invalidOffspring;

    /*DECODE CHROMOSOME CHILD1*/
    mat::MatrixRow<T_FEATURE>
      lmatrixrowt_centroidsChromChild2
      (lconstui_numClusterFixedK,
       data::Instance<T_FEATURE>::getNumDimensions(),
       aochrom_child2.getString()

```



```

    );

    std::pair<T_REAL,bool>
    lpair_SSE2 =
    um::SSE
    (lmatrixrowt_centroidsChromChild2,
     aiiterator_instfirst,
     aiiterator_instlast,
     aifunc2p_dist
    );

    aochrom_child2.setObjectiveFunc(lpair_SSE2.first);
    aochrom_child2.setFitness(1.0 / lpair_SSE2.first);
    aochrom_child2.setValidString(lpair_SSE2.second);

    if ( aochrom_child2.getValidString() == false )
        ++ll_invalidOffspring;

    } //if Crossover
    else {
        aochrom_child1 = aichrom_parent1;
        aochrom_child2 = aichrom_parent2;
    }
}
);

aooppga_outParamClusteringGA.sumTotalInvalidOffspring
(ll_invalidOffspring);

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ') '
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    } /*END CROSSOVER*/

/*Mutation. Each liter_Chrom chromosome undergoes mutation with a fixed
probability  $p_m$  (lr_mutationProbability). Let  $M_{min}$  (lchrom_minObjFunc) and
 $M_{max}$  (lrt_maxClusteringMetric) be the minimum and maximum values of the
clustering metric, respectively, in the current population. See [Definition
gaclusteringop::biDirectionHMutation], page 32 */

{ /*BEGIN MUTATION*/

```

```

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "MUTATION";
    ++geiinputparam_verbose;
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout << geverbosepc_labelstep
                    << ": IN(" << geiinputparam_verbose << '))'
                    << std::endl;
    }
#endif /*__VERBOSE_YES*/

    auto lchrom_minObjFunc =
        std::min_element
        (lvectorchromfixleng_population.begin(),
         lvectorchromfixleng_population.end(),
         [](const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& x,
            const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& y
            )
        { return x.getObjectiveFunc() < y.getObjectiveFunc(); }
        );
    T_REAL lrt_minClusteringMetric =
        lchrom_minObjFunc->getObjectiveFunc();

    auto lchrom_maxObjFunc =
        std::max_element
        (lvectorchromfixleng_population.begin(),
         lvectorchromfixleng_population.end(),
         [](const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& x,
            const gaencode::ChromFixedLength<T_FEATURE,T_REAL>& y
            )
        { return x.getObjectiveFunc() < y.getObjectiveFunc(); }
        );

    T_REAL lrt_maxClusteringMetric =
        lchrom_maxObjFunc->getObjectiveFunc();

    for ( auto& lchromfixleng_iter: lvectorchromfixleng_population ) {

        if ( uniformdis_real01(gmt19937_eng)
            < aiinpcgaprobfixdk_inParamKGA.getProbMutation() )
        { //IF BEGIN MUTATION
            gaclusteringop::biDirectionHMutation
            (lchromfixleng_iter,
             lrt_minClusteringMetric,
             lrt_maxClusteringMetric,
             larray_minFeactures,
             larray_maxFeactures

```

```

        );
        lchromfixleng_iter.setFitness
            (-std::numeric_limits<T_REAL>::max());
        lchromfixleng_iter.setObjectiveFunc
            (std::numeric_limits<T_REAL>::max());
    } //END BEGIN MUTATION
}

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << " OUT(" << geiinparam_verbose << ' '
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    } /*END MUTATION*/

} /*END EVOLUTION While*/

/*FREE MEMORY
*/
delete [] larray_maxFeactures;
delete [] larray_minFeactures;

runtime::stop(let_executionTime);
aoopcgga_outParamClusteringGA.setNumClusterK
    (aiinpcgaprobfixdk_inParamKGA.getNumClusterK());
aoopcgga_outParamClusteringGA.setMetricFuncRun
    (lchromfixleng_best.getObjectiveFunc());
aoopcgga_outParamClusteringGA.setAlgorithmRunTime
    (runtime::getTime(let_executionTime));
aoopcgga_outParamClusteringGA.setFitness
    (lchromfixleng_best.getFitness());
aoopcgga_outParamClusteringGA.setNumTotalGenerations
    (llfh_listFuntionHist.getDomainUpperBound());

#ifdef __WITHOUT_PLOT_STAT
    if ( aiinpcgaprobfixdk_inParamKGA.getWithPlotStatObjectiveFunc() ) {
        runtime::plot_funtionHist
            (llfh_listFuntionHist,
             aiinpcgaprobfixdk_inParamKGA,
             aoopcgga_outParamClusteringGA
            );
    }
}

```

```

#endif /*__WITHOUT_PLOT_STAT*/

#ifdef __VERBOSE_YES
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        geiinputparam_verbose_labelstep = lpc_labelAlgGA;
        std::cout
            << lpc_labelAlgGA
            << ": OUT(" << geiinputparam_verbose << ")\n";
        lochromfixleng_best.print();
        std::cout << std::endl;
    }
    --geiinputparam_verbose;
#endif /*__VERBOSE_YES*/

    return lochromfixleng_best;

} /* END kga_fkcentroid */

} /*END eac */

#endif /*__KGA_FKCENTROID_HPP__*/

```

## A.2 GA algorithm

```

/*! \file gaclustering_fkcrispmatrix.hpp
 * This file is part of the LEAC.
 *
 * Implementation of the GA algorithm based on the paper:
 *
 * J.C. Bezdek, S. Boggavarapu, L.O. Hall, and A. Bensaid.
 * Genetic algorithm guided clustering. In Evolutionary Computation,
 * 1994. IEEE World Congress on Computational Intelligence., Proceed-
 * ings of the First IEEE Conference on, pages 34--39 vol.1, Jun 1994.
 * doi:10.1109/ICEC.1994.350046.
 *
 * Library Evolutionary Algorithms for Clustering (LEAC) is a library
 * for the implementation of evolutionary and genetic algorithms
 * focused on the partition type clustering problem. Based on the
 * current standards of the C++ language, as well as on Standard
 * Template Library STL and also OpenBLAS to have a better performance.
 *
 * (c) Hermes Robles Berumen <hermes@uaz.edu.mx>
 *
 * For the full copyright and license information, please view the LICENSE

```

```

    * file that was distributed with this source code.
    */

#ifndef __GACLUSTERING_FKCRISPMATRIX_HPP__
#define __GACLUSTERING_FKCRISPMATRIX_HPP__

#include <iostream>
#include <iomanip>
#include <vector>

#include <leac.hpp>

#include "plot_runtime_function.hpp"
#include "inparam_gaclustering_withoutpcpm.hpp"
#include "outparam_gaclustering.hpp"

/*! \namespace eac
    \brief Evolutionary Algorithms for Clustering
    \details Implementation of genetic and evolutionary algorithms used to solve
           the clustering problem

    \author Hermes Robles Berumen
    \date   2015-2017
    \copyright GPLv3 license
    */

namespace eac {

/*! \fn gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>
    gaclustering_fkcrispmatrix
    (inout::OutParamGAClustering<T_REAL,T_CLUSTERIDX> &aoopcga_outParamClusteringGA,
    inout::InParamGAClusteringWithoutProbCProbM<T_CLUSTERIDX,T_BITSIZE,T_FEATURE,
    T_FEATURE_SUM,T_INSTANCES_CLUSTER_K> &aainpkbezdekga_inParam,
    const INPUT_ITERATOR aiiterator_instfirst,
    const INPUT_ITERATOR aiiterator_instlast, dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist)
    \brief gaclustering_fkcrispmatrix
    \details GA clustering based on [BBHB94], page 111
    Returns a crisp matrix, which encodes a partition of a data set, for a defined k.
    \param aoopcga_outParamClusteringGA a inout::OutParamGAClustering that contains
    information relevant to program execution
    \param aainpkbezdekga_inParam a inout::InParamGAClusteringWithoutProbCProbM with
    the input parameters for the program configuration
    \param aiiterator_instfirst an InputIterator to the initial positions of the
    sequence of instances
    \param aiiterator_instlast an InputIterator to the final positions of the
    sequence of instances
    \param aipartition_clusters a partition of instances in clusters

```

```

    \param aifunc2p_dist an object of type dist::Dist to calculate distances
    */

template < typename T_BITSIZE,
           typename T_REAL,
           typename T_FEATURE,
           typename T_FEATURE_SUM,
           typename T_INSTANCES_CLUSTER_K, //0, 1, .., N
           typename T_CLUSTERIDX,         //-1, 0, 1, .., K
           typename INPUT_ITERATOR
        >
gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>
gaclustering_fkcrispmatrix
(inout::OutParamGAClustering
 <T_REAL,
 T_CLUSTERIDX>                &aoopcga_outParamClusteringGA,
 inout::InParamGAClusteringWithoutProbCProbM
 <T_CLUSTERIDX,
 T_BITSIZE,
 T_FEATURE,
 T_FEATURE_SUM,
 T_INSTANCES_CLUSTER_K>      &aiinpkbezdekga_inParam,
 const INPUT_ITERATOR        aiiterator_instfirst,
 const INPUT_ITERATOR        aiiterator_instlast,
 dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist
)
{
#ifdef __VERBOSE_YES
    /*ID PROC
    */
    geverboseui_idproc = 1;

    ++geinparam_verbose;
    const char* lpc_labelAlgGA = "gaclustering_fkcrispmatrix";
    if ( geinparam_verbose <= geinparam_verboseMax ) {
        std::cout
            << lpc_labelAlgGA
            << "  IN(" << geinparam_verbose << ")\n"
            << "\t(output outparam::OutParamGAClustering&: aoopcga_outParamClusteringGA["
            << &aoopcga_outParamClusteringGA << "]\n"
            << "\t input  InParamClusteringBezdekGA1994&: aiinpkbezdekga_inParam["
            << &aiinpkbezdekga_inParam << "]\n"
            << "\t input aiiterator_instfirst[" << *aiiterator_instfirst << "]\n"
            << "\t input aiiterator_instlast[" << &aiiterator_instlast << "]\n"
            << "\t input dist::Dist<T_REAL,T_FEATURE> &aifunc2p_dist["
            << &aifunc2p_dist << ']'
            << "\n\t\tPopulation size = "

```

```

        << aiinpkbezdekga_inParam.getSizePopulation()
        << "\n\t\tMatingPool size = "
        << aiinpkbezdekga_inParam.getSizeMatingPool()
        << "\n\t\tGenerations = "
        << aiinpkbezdekga_inParam.getNumMaxGenerations()
        << "\n\t\ttrandom-seed = "
        << aiinpkbezdekga_inParam.getRandomSeed()
        << "\n\t)"
        << std::endl;
    }
#endif /*__VERBOSE_YES*/

    const uintidx_luintidx_numClusterK =
        (uintidx) aiinpkbezdekga_inParam.getNumClusterK();
    const uintidx_luintidx_numIntances =
        uintidx(std::distance(aiiterator_instfirst,aiiterator_instlast));

    /*CONVERT INSTANCES TO FORMAT MATRIX
    */
    mat::MatrixRow<T_FEATURE>&& lmatrixt_y =
        data::toMatrixRow
        (aiiterator_instfirst,
         aiiterator_instlast
        );

    std::uniform_int_distribution<T_CLUSTERIDX> uniformdis_mmcidxOK
        (0,aiinpkbezdekga_inParam.getNumClusterK()-1);

    gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>
        lochrombitcrispmatrix_best(luintidx_numClusterK,luintidx_numIntances);

    /*STL container for storing the chromosome population
    */
    std::vector<gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* >
        lvectorchrombitcrispmatrix_population;

    /*Vector for matingpool
    */
    std::vector<gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* >
        lvectorchrombitcrispmatrix_matingPool;

    /*Vector for temporary storage when applying generic operators
    */
    std::vector<gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* >
        lvectorchromfixleng_childR;

```

```

if ( aiinpkebezdekga_inParam.getSizePopulation()
    <= aiinpkebezdekga_inParam.getSizeMatingPool() )
    throw std::invalid_argument
        ("gaclustering_fkcrispmatrix: "
         "size population should be greater than size matingpool"
        );

runtime::ListRuntimeFunction<COMMON_IDOMAIN>
    llfh_listFuntionHist
    (aiinpkebezdekga_inParam.getNumMaxGenerations(),
     "Iterations",
     "Clustering metrics"
    );

/*Declaration of variables: computing statistical
   and metric of the algorithm
*/
#ifdef __WITHOUT_PLOT_STAT
    std::ofstream                lfileout_plotStatObjectiveFunc;
    runtime::RuntimeFunctionValue<T_REAL> *lofh_J1 = NULL;
    runtime::RuntimeFunctionValue<T_INSTANCES_CLUSTER_K>
        *lofh_misclassified = NULL; /*function extra*/
    runtime::RuntimeFunctionStat<T_REAL>
        *lofhs_statObjectiveFunc[STATISTICAL_ALL_MEASURES];
    std::vector<T_REAL>          lvectorT_statfuncObjectiveFunc;

    if ( aiinpkebezdekga_inParam.getWithPlotStatObjectiveFunc() ) {

        lvectorT_statfuncObjectiveFunc.reserve
            ( aiinpkebezdekga_inParam.getSizePopulation());
        //Variable to monitor in the execution of the program
        lofh_J1 = new runtime::RuntimeFunctionValue<T_REAL>
            ("J1",
             aiinpkebezdekga_inParam.getAlgorithmoName(),
             RUNTIMEFUNCTION_NOT_STORAGE
            );

        llfh_listFuntionHist.addFuntion(lofh_J1);

        if ( aiinpkebezdekga_inParam.getClassInstanceColumn() ) {
            lofh_misclassified =
                new runtime::RuntimeFunctionValue<T_INSTANCES_CLUSTER_K>
                    ("Misclassified",
                     aiinpkebezdekga_inParam.getAlgorithmoName(),
                     RUNTIMEFUNCTION_NOT_STORAGE
                    );
            llfh_listFuntionHist.addFuntion(lofh_misclassified);
        }
    }
}

```



```

    }

    //Statistics of variable J1 in runtime
    for (int li_i = 0; li_i < STATISTICAL_ALL_MEASURES; li_i++) {
        lofhs_statObjectiveFunc[li_i] =
            new runtime::RuntimeFunctionStat
            <T_REAL>
            ( (char) li_i,
              aiinpkbezdekga_inParam.getAlgorithmoName(),
              RUNTIMEFUNCTION_NOT_STORAGE
            );
        llfh_listFuntionHist.addFuntion(lofhs_statObjectiveFunc[li_i]);
    }

    //OPEN FILE STRORE FUNCTION
    aoopcga_outParamClusteringGA.setFileNameOutPlotStatObjectiveFunc
        (aiinpkbezdekga_inParam.getFileNamePlotStatObjectiveFunc(),
         aiinpkbezdekga_inParam.getTimesRunAlgorithm()
        );

    lfileout_plotStatObjectiveFunc.open
        (aoopcga_outParamClusteringGA.getFileNameOutPlotStatObjectiveFunc().c_str(),
         std::ios::out | std::ios::app
        );

    lfileout_plotStatObjectiveFunc.precision(COMMON_COUT_PRECISION);

    //Header function
    lfileout_plotStatObjectiveFunc
        << llfh_listFuntionHist.getHeaderFuntions()
        << "\n";
    }
#endif /*__WITHOUT_PLOT_STAT*/

runtime::ExecutionTime let_executionTime = runtime::start();

/*Create space for store population
*/
lvectorchrombitcrispmatrix_population.reserve
    (aiinpkbezdekga_inParam.getSizePopulation() + 1);
for (uintidx lui_i = 0;
     lui_i < aiinpkbezdekga_inParam.getSizePopulation();
     lui_i++)
{
    lvectorchrombitcrispmatrix_population.push_back
        (new gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>

```

```

        (luintidx_numClusterK,luintidx_numIntances)
    );
}

/*Space for store matingpool
*/
lvectorchrombitcrispmatrix_matingPool.reserve
    (aiinpkbzdekga_inParam.getSizeMatingPool());

/*Space for chromosomes R
*/
lvectorchromfixleng_childR.reserve
    (aiinpkbzdekga_inParam.getSizeMatingPool() + 1 );
/*Initialization of population

    Initial population of size  $P$ , consisting of  $U$  matrices is pseudo randomly
    generated such that each has one at least one 1 in every row ( $\sum_{j=1}^n U_{ij} \geq 1 \forall i$ )
    and each column sums to 1, i.e.  $\sum_{i=1}^c U_{ij} = 1, \forall j$ .

    The partly random initialization is obtained as follows. For each
    cluster center  $v_i$ , we choose the  $k^{th}$  element of the cluster center to be
    the  $k^{th}$  feature of a randomly chosen pattern to be clustered. This is done
    for each of the  $s$  elements of a cluster center. The process is repeated
    for each cluster center. An initial  $U$  matrix is then generated from the
    cluster centers. For a GA, population  $P$  (the population size)  $U$  matrices
    are generated in this manner.
*/

    { /*BEGIN INITIALIZE POPULATION*/

#ifdef __VERBOSE_YES
        geverbosepc_labelstep = "POPULATION INITIALIZATION";
        ++geiinparam_verbose;
        if ( geiinparam_verbose <= geiinparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ":  IN(" << geiinparam_verbose << ') '
                << std::endl;
        }
#endif /*__VERBOSE_YES*/

        mat::MatrixRow<T_FEATURE>
            lmatrixt_v
            ( luintidx_numClusterK,
              data::Instance<T_FEATURE>::getNumDimensions()
            );

        for ( auto lchrombitcrispmatrix_iter: lvectorchrombitcrispmatrix_population) {

```

```

        clusteringop::randomInitialize
            (lmatrixt_v,
             aiiterator_instfirst,
             aiiterator_instlast
            );

        clusteringop::getPartition
            (*lchrombitcrispmatrix_iter,
             lmatrixt_y,
             lmatrixt_v,
             aifunc2p_dist
            );

        T_REAL lT_j1 =
            um::j1
            (*lchrombitcrispmatrix_iter,
             lmatrixt_v,
             aiiterator_instfirst,
             aiiterator_instlast,
             aifunc2p_dist
            );

        lchrombitcrispmatrix_iter->setObjectiveFunc(lT_j1);

    }

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ')'
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    } /*END INITIALIZE POPULATION*/

/*Population sort by  $J_1$ 

    The  $U$  matrices are sorted by  $J_1$  value. and the  $R$  with the lowest  $J_1$ ,
    values are choses to reproduce.
*/

    { /*BEGIN POPULATION SORT BY  $J_1$ */

        #ifdef __VERBOSE_YES
            geverbosepc_labelstep = "SORT POPULATION";
            ++geiinparam_verbose;

```

```

    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinputparam_verbose << ' '
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

    std::sort
        (lvectorchrombitcrispmatrix_population.begin(),
         lvectorchrombitcrispmatrix_population.end(),
         [](const gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* x,
            const gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* y
            )
         { return x->getObjectiveFunc() < y->getObjectiveFunc(); }
         );

#ifdef __VERBOSE_YES

    ++geiinputparam_verbose;
    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {

        for ( auto lchrombitcrispmatrix_iter: lvectorchrombitcrispmatrix_population) {

            lchrombitcrispmatrix_iter->print
                (std::cout,
                 geverbosepc_labelstep,
                 ', ',
                 '; ',
                 );
            std::cout << '\n';
        }
    }
    --geiinputparam_verbose;

    if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinputparam_verbose << ' '
            << std::endl;
    }
    --geiinputparam_verbose;
#endif /*__VERBOSE_YES*/

} /*END POPULATION SORT BY J_1*/

```

```

while( true ) {

    /*BEGIN PRESERVING THE CHROMOSOME BEST
    */

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "ELITISM PRESERVING THE BEST";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinparam_verbose << ') '
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

    if ( lvectorchrombitcrispmatrix_population[0]->getObjectiveFunc()
        < lochrombitcrispmatrix_best.getObjectiveFunc() ) {
        lochrombitcrispmatrix_best =
            *lvectorchrombitcrispmatrix_population[0];
        /*A better chromosome is found in this iteration
        */
        aoopcga_outParamClusteringGA.setIterationGetsBest
            (llfh_listFuntionHist.getDomainUpperBound());
        aoopcga_outParamClusteringGA.setRunTimeGetsBest
            (runtime::elapsedTime(let_executionTime));
    }

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ') '
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    } /*END PRESERVING THE CHROMOSOME BEST*/

    /*COMPUTING STATISTICAL OF THE ALGORITHM
    */
#ifdef __WITHOUT_PLOT_STAT

    if ( aiinpkebezdekga_inParam.getWithPlotStatObjectiveFunc() ) {

```

```

for ( auto lchrombitcrispmatrix_iter:
    lvectorchrombitcrispmatrix_population) {
    lvectorT_statfuncObjectiveFunc.push_back
        (lchrombitcrispmatrix_iter->getObjectiveFunc());
}

lofh_J1->setValue
    (lvectorchrombitcrispmatrix_population[0]->getObjectiveFunc());

if ( lofh_misclassified != NULL ) {

    partition::PartitionCrispMatrix
        <T_BITSIZE,T_CLUSTERIDX>
        lpartitionCrispMatrix_classifierU
        (*lvectorchrombitcrispmatrix_population[0]);

    sm::ConfusionMatchingMatrix<T_INSTANCES_CLUSTER_K>&&
        lmatchmatrix_confusion =
        sm::getConfusionMatrix
        (aiiterator_instfirst,
         aiiterator_instlast,
         lpartitionCrispMatrix_classifierU,
         [] (const data::Instance<T_FEATURE>* aiinst_iter )
         -> T_INSTANCES_CLUSTER_K
         {
             return  T_INSTANCES_CLUSTER_K(1);
         },
         [] (const data::Instance<T_FEATURE>* aiinst_iter )
         -> T_CLUSTERIDX
         {
             data::InstanceClass
                 <T_FEATURE,
                 T_INSTANCES_CLUSTER_K,
                 T_CLUSTERIDX>
                 *linstclass_iter =
                 (data::InstanceClass
                     <T_FEATURE,
                     T_INSTANCES_CLUSTER_K,
                     T_CLUSTERIDX>*)
                 aiinst_iter;

             return linstclass_iter->getClassIdx();
         }
        );
}

```

```

        lofh_misclassified->setValue
            (lmatchmatrix_confusion.getMisclassified());
    }
    functionhiststat_evaluateAll
        (lofhs_statObjectiveFunc,
         lvectorT_statfuncObjectiveFunc
        );
    lfileout_plotStatObjectiveFunc << llfh_listFuntionHist;
    lvectorT_statfuncObjectiveFunc.clear();
}
#endif /*__WITHOUT_PLOT_STAT*/

#ifdef __VERBOSE_YES

/*ID PROC
*/
++geverboseui_idproc;

++geinparam_verbose;
if ( geinparam_verbose <= geinparam_verboseMax ) {
    std::cout
        << "END ITERATION: "
        << llfh_listFuntionHist.getDomainUpperBound()
        << "\tobjetivoFunc = "
        << lochrombitcrispmatrix_best.getObjectiveFunc()
        << std::endl;
}
--geinparam_verbose;
#endif /*__VERBOSE_YES*/

/*Termination criterion attained?
*/
if ( (llfh_listFuntionHist.getDomainUpperBound()
    >= aiinpkbezdekga_inParam.getNumMaxGenerations()) ||
    (runtime::elapsedTime(let_executionTime) >
    aiinpkbezdekga_inParam.getMaxExecutiontime())
    )
    break;

/*Selection
    R matrices with the lowest J_1, values are choses to reproduce.
*/

/*Selection
    R matrices with the lowest J_1, values are choses to reproduce.
*/

```

```

{ /*BEGIN SELECTION
  */
  auto ichrom_population = lvectorchrombitcrispmatrix_population.begin();

  for (uintidx lui_i = 0;
        lui_i < aiinpkbezdekga_inParam.getSizeMatingPool();
        lui_i++) {
    lvectorchrombitcrispmatrix_matingPool.push_back
      (*ichrom_population);
    ++ichrom_population;
  }

} /*END SELECTION*/

/*Crossover operator

  The crossover point and number of columns in the two  $U$  matrices chosen
  for reproduction are randomly chosen. The columns of the matrices are
  combined to create the children matrices.
  */

{ /*BEGIN CROSSOVER OPERATORS*/

#ifdef __VERBOSE_YES
  geverbosepc_labelstep = "CROSSOVER OPERATORS";
  ++geiinparam_verbose;
  if ( geiinparam_verbose <= geiinparam_verboseMax ) {
    std::cout
      << geverbosepc_labelstep
      << ":  IN(" << geiinparam_verbose << ') '
      << std::endl;
  }
#endif /*__VERBOSE_YES*/

  for (uintidx lui_i = 0;
        lui_i < aiinpkbezdekga_inParam.getSizeMatingPool();
        lui_i++) {
    lvectorchromfixleng_childR.push_back
      (new gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>
        (luintidx_numClusterK,luintidx_numIntances)
      );
  }

  gaiterator::crossoverRandSelect
    (lvectorchrombitcrispmatrix_matingPool.begin(),
     lvectorchrombitcrispmatrix_matingPool.end(),
     lvectorchromfixleng_childR.begin(),

```



```

lvectorchromfixleng_childR.end(),
[&](gaencode::ChromosomeCrispMatrix
    <T_BITSIZE,T_CLUSTERIDX,T_REAL>* aichrom_parent1,
    gaencode::ChromosomeCrispMatrix
    <T_BITSIZE,T_CLUSTERIDX,T_REAL>* aichrom_parent2,
    gaencode::ChromosomeCrispMatrix
    <T_BITSIZE,T_CLUSTERIDX,T_REAL>* aochrom_child1,
    gaencode::ChromosomeCrispMatrix
    <T_BITSIZE,T_CLUSTERIDX,T_REAL>* aochrom_child2
    )
{

    gabinaryop::onePointDistCrossover
        (*aochrom_child1,
        *aochrom_child2,
        *aichrom_parent1,
        *aichrom_parent2
        );

    aochrom_child1->setObjectiveFunc(std::numeric_limits<T_REAL>::max());
    aochrom_child2->setObjectiveFunc(std::numeric_limits<T_REAL>::max());

}
);

lvectorchrombitcrispmatrix_matingPool.clear();

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ')'
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

}/*END CROSSOVER OPERATORS*/

/*Mutation consists of randomly choosing an element of a column to have
the value 1, such that it is a different element than the one currently
having a value of 1.
*/

{ /*BEGIN MUTATION OPERATOR*/
#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "MUTATION OPERATOR";
    ++geiinparam_verbose;

```

```

        if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ": IN(" << geiinputparam_verbose << ') '
                << std::endl;
        }
    #endif /*__VERBOSE_YES*/

    for ( auto ichrom_childR: lvectorchromfixleng_childR ) {
        gabinaryop::bitMutation(*ichrom_childR);
    }

    #ifdef __VERBOSE_YES
        if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ": OUT(" << geiinputparam_verbose << ') '
                << std::endl;
        }
        --geiinputparam_verbose;
    #endif /*__VERBOSE_YES*/

    } /*END MUTATION OPERATOR*/

    { /*BEGIN EVALUATE J1 FOR CHILDR*/
    #ifdef __VERBOSE_YES
        geverbosepc_labelstep = "EVALUATE J1 FOR CHILDR";
        ++geiinputparam_verbose;
        if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ": IN(" << geiinputparam_verbose << ') '
                << std::endl;
        }
    #endif /*__VERBOSE_YES*/

        mat::MatrixRow<T_FEATURE>
            lmatrixt_v
            (luintidx_numClusterK,
             data::Instance<T_FEATURE>::getNumDimensions()
            );

        mat::MatrixRow<T_FEATURE_SUM>
            lmatrixT_sumWX
            (lmatrixt_v.getNumRows(),
             lmatrixt_v.getNumColumns()
            );
    }

```

```

std::vector<T_INSTANCES_CLUSTER_K>
    lvectorT_sumWik(lmatrixt_v.getNumRows());

for ( auto ichrom_childR: lvectorchromfixleng_childR ) {

    /*Calculate the centroid associated with U_i
    */
    clusteringop::getCentroids
        (lmatrixt_v,
         lmatrixT_sumWX,
         lvectorT_sumWik,
         *ichrom_childR,
         lmatrixt_y
        );

    T_REAL lT_j1 =
        um::j1
        (*ichrom_childR,
         lmatrixt_v,
         aiiterator_instfirst,
         aiiterator_instlast,
         aifunc2p_dist
        );

    ichrom_childR->setObjectiveFunc(lT_j1);

}

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << '),'
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

} /*EVALUATE J1 FOR CHILDR*/

/*The R chuild U matrices are added to the population
with the P-R U matrices with the greatest J1 values
dropped from the population.
*/
{ /*BEGIN ADD P-R U MATRICES TO POPULATION*/
#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "ADD P-R U MATRICES TO POPULATION";

```

```

++geiinparam_verbose;
if ( geiinparam_verbose <= geiinparam_verboseMax ) {
    std::cout
        << geverbosepc_labelstep
        << " : IN(" << geiinparam_verbose << ' )'
        << std::endl;
}
#endif /*__VERBOSE_YES*/

std::sort
(lvectorchromfixleng_childR.begin(),
 lvectorchromfixleng_childR.end(),
 [](const gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* x,
     const gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* y
     )
 { return x->getObjectiveFunc() < y->getObjectiveFunc(); }
 );

std::vector<gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>* >
    lvectorchrombitcrispmatrix_tmpL;

lvectorchrombitcrispmatrix_tmpL.swap(lvectorchrombitcrispmatrix_population);

/*Insert a sentinel to merge the two vectors
*/
lvectorchrombitcrispmatrix_tmpL.push_back
    (new gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>());
lvectorchromfixleng_childR.push_back
    (new gaencode::ChromosomeCrispMatrix<T_BITSIZE,T_CLUSTERIDX,T_REAL>());

lvectorchrombitcrispmatrix_population.reserve
    (aiinpkbezdekga_inParam.getSizePopulation() + 1);

uintidx luintidx_l = 0;
uintidx luintidx_r = 0;

for (uintidx lui_i = 0;
     lui_i < aiinpkbezdekga_inParam.getSizePopulation();
     lui_i++)
{
    if ( lvectorchrombitcrispmatrix_tmpL[luintidx_l]->getObjectiveFunc() <
        lvectorchromfixleng_childR[luintidx_r]->getObjectiveFunc() )
    {
#ifdef __VERBOSE_YES
        ++geiinparam_verbose;

```

```

        if ( geiinparam_verbose <= geiinparam_verboseMax ) {
            std::cout
                << " lvectorchrombitcrispmatrix_population[" << lui_i << " ]'
                << " <-- lvectorchrombitcrispmatrix_tmpL[" << luintidx_l << " ]'
                << '[' << & lvectorchrombitcrispmatrix_population[luintidx_l] << " ]'
                << " Fitness: "
                << lvectorchrombitcrispmatrix_tmpL[luintidx_l]->getObjectiveFunc()
                << '\n';
        }
        --geiinparam_verbose;
    #endif //__VERBOSE_YES

    lvectorchrombitcrispmatrix_population.push_back
        (lvectorchrombitcrispmatrix_tmpL[luintidx_l]);
    lvectorchrombitcrispmatrix_tmpL[luintidx_l] = NULL;
    ++luintidx_l;

}
else {

#ifdef __VERBOSE_YES
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << " lvectorchrombitcrispmatrix_population[" << lui_i << " ]'
            << " <-- lvectorchromfixleng_childR[" << luintidx_r << " ]'
            << "[" << & lvectorchrombitcrispmatrix_population[luintidx_r] << " ]'
            << " Fitness: "
            << lvectorchromfixleng_childR[luintidx_r]->getObjectiveFunc()
            << '\n';
    }
    --geiinparam_verbose;
    #endif //__VERBOSE_YES

    lvectorchrombitcrispmatrix_population.push_back
        (lvectorchromfixleng_childR[luintidx_r]);
    lvectorchromfixleng_childR[luintidx_r] = NULL;
    ++luintidx_r;

}

}

for (uintidx lui_i = 0;
     lui_i < lvectorchromfixleng_childR.size();
     ++lui_i) {
    if ( lvectorchromfixleng_childR[lui_i] != NULL )

```

```

        delete lvectorchromfixleng_childR[lui_i];
    }
    lvectorchromfixleng_childR.clear();

    for (uintidx lui_i = 0;
        lui_i < lvectorchrombitcrispmatrix_tmpL.size();
        ++lui_i) {
        if ( lvectorchrombitcrispmatrix_tmpL[lui_i] != NULL )
            delete lvectorchrombitcrispmatrix_tmpL[lui_i];
    }
    lvectorchrombitcrispmatrix_tmpL.clear();

#ifdef __VERBOSE_YES
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": OUT(" << geiinparam_verbose << ' '
            << std::endl;
    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/
    } /*END ADD P-R U MATRICES TO POPULATION*/

    /*The reproduction and survival of fittest process
    continues for some set number of generations
    */

    llfh_listFuntionHist.increaseDomainUpperBound();

} /*while*/

/*FREE MEMORY*/
{ /*BEGIN FREE MEMORY OF POPULATION*/

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = "DELETEPOPULATION";
    ++geiinparam_verbose;
    if ( geiinparam_verbose <= geiinparam_verboseMax ) {
        std::cout
            << geverbosepc_labelstep
            << ": IN(" << geiinparam_verbose << ' '
            << std::endl;
    }
#endif /*__VERBOSE_YES*/

    for (uintidx lui_i = 0;
        lui_i < lvectorchrombitcrispmatrix_population.size();

```

```

        ++lui_i) {
            delete lvectorchrombitcrispmatrix_population[lui_i];
        }

#ifdef __VERBOSE_YES
        if ( geiinparam_verbose <= geiinparam_verboseMax ) {
            std::cout
                << geverbosepc_labelstep
                << ": OUT(" << geiinparam_verbose << ' '
                << std::endl;
        }
        --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    }/*END FREE MEMORY OF POPULATION*/

    runtime::stop(let_executionTime);
    aoopcga_outParamClusteringGA.setNumClusterK
        (aiinpkbezdekga_inParam.getNumClusterK());
    aoopcga_outParamClusteringGA.setMetricFuncRun
        (lochrombitcrispmatrix_best.getObjectiveFunc());
    aoopcga_outParamClusteringGA.setAlgorithmRunTime
        (runtime::getTime(let_executionTime));

    aoopcga_outParamClusteringGA.setFitness
        (lochrombitcrispmatrix_best.getObjectiveFunc());
    aoopcga_outParamClusteringGA.setNumTotalGenerations
        (llfh_listFuntionHist.getDomainUpperBound());

    /*FREE: COMPUTING STATISTICAL AND METRIC OF THE ALGORITHM
    */
#ifdef __WITHOUT_PLOT_STAT

    if ( aiinpkbezdekga_inParam.getWithPlotStatObjectiveFunc() ) {
        plot_funtionHist
            (llfh_listFuntionHist,
             aiinpkbezdekga_inParam,
             aoopcga_outParamClusteringGA
            );
    }

#endif /*__WITHOUT_PLOT_STAT*/

#ifdef __VERBOSE_YES
    geverbosepc_labelstep = lpc_labelAlgGA;

```

```

if ( geiinputparam_verbose <= geiinputparam_verboseMax ) {
    std::cout
        << lpc_labelAlgGA
        << " OUT(" << geiinputparam_verbose << ")\n";
    std::setprecision(COMMON_COUT_PRECISION);

    mat::MatrixRow<T_FEATURE>
        lmatrixt_vBestChrom
        ( luintidx_numClusterK,
          data::Instance<T_FEATURE>::getNumDimensions()
        );

    mat::MatrixRow<T_FEATURE_SUM>
        lmatrixT_sumWX
        (lmatrixt_vBestChrom.getNumRows(),
         lmatrixt_vBestChrom.getNumColumns()
        );

    std::vector<T_INSTANCES_CLUSTER_K>
        lvectorT_sumWik(lmatrixt_vBestChrom.getNumRows());

    clusteringop::getCentroids
        (lmatrixt_vBestChrom,
         lmatrixT_sumWX,
         lvectorT_sumWik,
         lochrombitcrispmatrix_best,
         lmatrixt_y
        );

    lochrombitcrispmatrix_best.print
        (std::cout,
         geiinputparam_verbosepc_labelstep,
         ', ',
         ';;',
        );

    std::cout << '\n';
    um::j1
        (lochrombitcrispmatrix_best,
         lmatrixt_vBestChrom,
         aiiterator_instfirst,
         aiiterator_instlast,
         aifunc2p_dist
        );

    std::cout << std::endl;
}

```



```
        std::setprecision(COMMON_VERBOSE_COUT_PRECISION);

    }
    --geiinparam_verbose;
#endif /*__VERBOSE_YES*/

    return lochrombitcrispmatrix_best;

} /*END gaclustering_fkcrispmatrix */

} /*END namespace alg*/

#endif /*__GACLUSTERING_FKCRISPMATRIX_HPP__*/
```



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## Appendix C Concept index

### B

biDirectionHMutation : gaclusteringop .....	32
bitMutation : gabinaryop .....	32
bugs .....	67

### C

centroid-based .....	11
centroidsInitialized : clusteringop .....	16
ChromFixedLength : gaencode .....	9
ChromosomeBitArray : gaencode .....	9
ChromVariableLength : gaencode .....	9
crisp partition .....	10
crossover : gaiterator .....	31
crossoverRandSelect : gaiterator .....	31
CSmeasure : um .....	24

### D

dbindex : um .....	23
Dinter : um .....	27
Dintra : um .....	27
directory of data sets <b>data</b> .....	35, 42
distances .....	16
DunnIndex : um .....	25

### E

EAC .....	1
elitism .....	30, 79, 80
epsviewer .....	36
Euclidean : dist .....	17

### F

fixed k-cluster .....	39
fuzzy c-partitions .....	21

### G

GA algorithm .....	88
GCUK algorithm .....	55
genetic algorithm .....	7
getConfusionMatrix : sm .....	29
getIdentity : mat .....	18
getMatrixDiagonal : dist .....	19
getMatrixDissimilarity : medoids .....	22
getMatrixMahalonobis : dist .....	19
getPartition : clusteringop .....	16
GGA algorithm .....	60

### H

HKA algorithm .....	51
---------------------	----

### I

indexI : um .....	28
Induced : dist .....	17, 18
induced distance .....	18
Iris data set .....	53

### J

j1 : um .....	22
jm : um .....	21

### K

KGA algorithm .....	40, 69
---------------------	--------

### L

LEAC .....	1
------------	---

### M

makePartition : partition .....	20
---------------------------------	----

### O

onePointCrossover : gabinaryop .....	32
onePointCrossover : gagenericop .....	31

### P

PartitionCentroids : partition .....	20
PartitionCrispMatrix : partition .....	20
precision : sm .....	30
purity : sm .....	30

### R

randIndex : sm .....	29
recall : sm .....	30

### S

simplifiedDunnIndex : um .....	26
SSE : um .....	19, 78
SSEMedoid : um .....	22

### T

training-test .....	45
---------------------	----

**U**

um::silhouette .....	24
um::simplifiedSilhouette .....	24
unsupervised measures .....	44
updateCentroids : clusteringop .....	76

**V**

variable k-cluster .....	39, 55
VRC : um .....	26

**W**

Wine data set .....	42
---------------------	----

**X**

Xie-Beni index, xb : um .....	28
-------------------------------	----

**Z**

Zoo data set .....	55
--------------------	----