

Course project

Modified DP

Instruction set

- rrr – register
- Aaaaaa –MA
- iiiiii – imm.

Instruction	Encoding	Operation	Comment
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Data movement instructions

LDA A,rrr	0001 0rrr	$A \leftarrow R[rrr]$	Load accumulator from register
STA rrr,A	0010 0rrr	$R[rrr] \leftarrow A$	Load register from accumulator
LDM A,aaaaaa	0011 0000 00aaaaaa	$A \leftarrow M[aaaaaa]$	Load accumulator from memory
STM aaaaaa,A	0100 0000 00 aaaaaa	$M[aaaaaa] \leftarrow A$	Load memory from accumulator
LDI A,iiiiiii	0101 0000 iiiiiii	$A \leftarrow iiiiii$	Load accumulator with immediate value (iiiiiii is a signed number)

Arithmetic and logical instructions

AND A,rrr	1010 0rrr	$A \leftarrow A \text{ AND } R[rrr]$	Accumulator AND register
OR A,rrr	1011 0rrr	$A \leftarrow A \text{ OR } R[rrr]$	Accumulator OR register

ADD A,rrr	1100 0rrr	$A \leftarrow A + R[rrr]$	Accumulator + register
SUB A,rrr	1101 0rrr	$A \leftarrow A - R[rrr]$	Accumulator – register
NOT A	1110 0000	$A \leftarrow \text{NOT } A$	Invert accumulator
INC A	1110 0001	$A \leftarrow A + 1$	Increment accumulator
DEC A	1110 0010	$A \leftarrow A - 1$	Decrement accumulator
SHFL A	1110 0011	$A \leftarrow A \ll 1$	Shift accumulator left
SHFR A	1110 0100	$A \leftarrow A \gg 1$	Shift accumulator right
ROTR A	1110 0101	$A \leftarrow \text{Rotate_right}(A)$	Rotate accumulator right

Instruction set

- Smmm –Sign and magn.

Jump instructions

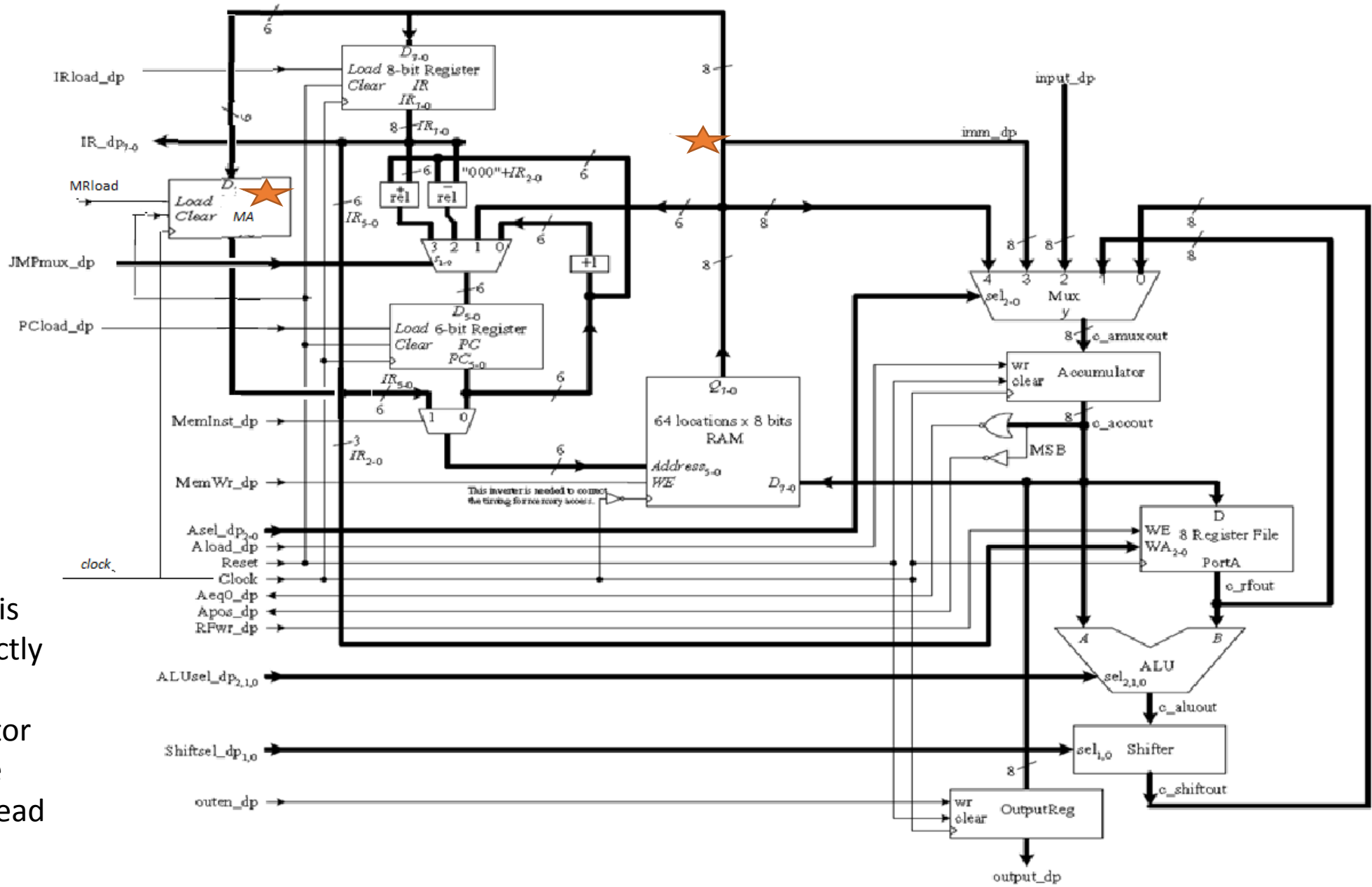
JMP absolute	0110 0000 00 aaaaaa	PC = aaaaaa	Absolute unconditional jump
JMPR relative	0110 smmm	if (smmm != 0) then if (s == 0) then PC = PC + mmm else PC = PC – mmm	Relative unconditional jump (smmm is in sign and magnitude format)
JZ absolute	0111 0000 00 aaaaaa	if (A == 0) then PC = aaaaaa	Absolute jump if A is zero
JZR relative	0111 smmm	if (A == 0 and smmm != 0) then if (s == 0) then PC = PC + mmm else PC = PC – mmm	Relative jump if A is zero (smmm is in sign and magnitude format)
JNZ absolute	1000 0000 00 aaaaaa	if (A != 0) then PC = aaaaaa	Absolute jump if A is not zero
JNZR relative	1000 smmm	if (A != 0 and smmm != 0) then if (s == 0) then PC = PC + mmm else PC = PC – mmm	Relative jump if A is not zero (smmm is in sign and magnitude format)
JP absolute	1001 0000 00 aaaaaa	if(A == positive) then PC = aaaaaa	Absolute jump if A is positive
JPR relative	1001 smmm	if(A == positive and smmm != 0) then if (s == 0) then PC = PC + mmm else PC = PC – mmm	Relative jump if A is positive (smmm is in sign and magnitude format)

Input / Output and Miscellaneous

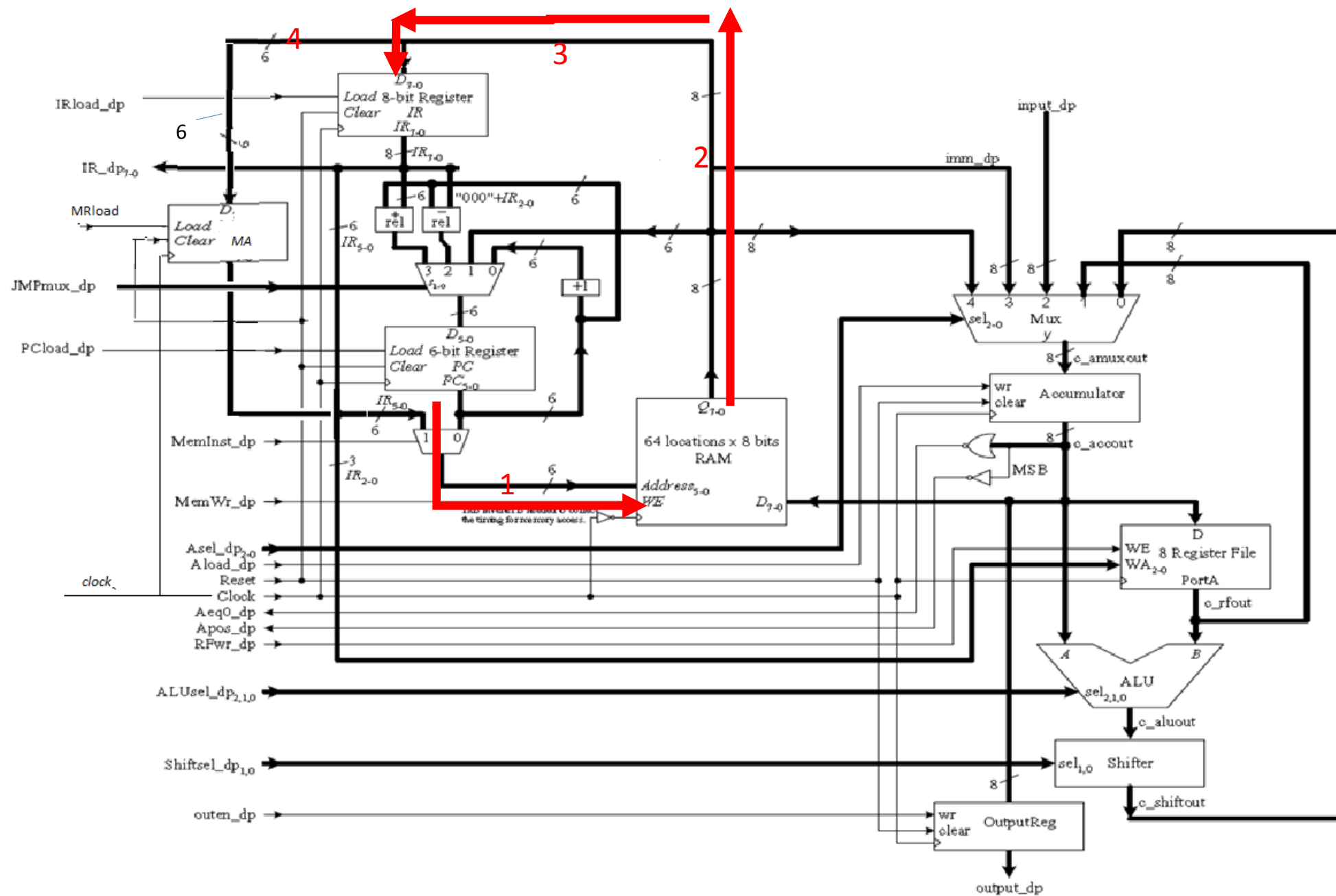
In A	1111 0000	A ← input	Input to accumulator
Out A	1111 0001	output ← A	Output from accumulator
HALT	1111 0010	Halt	Halt execution
NOP	0000 0000	no operation	No operation

Modified DP

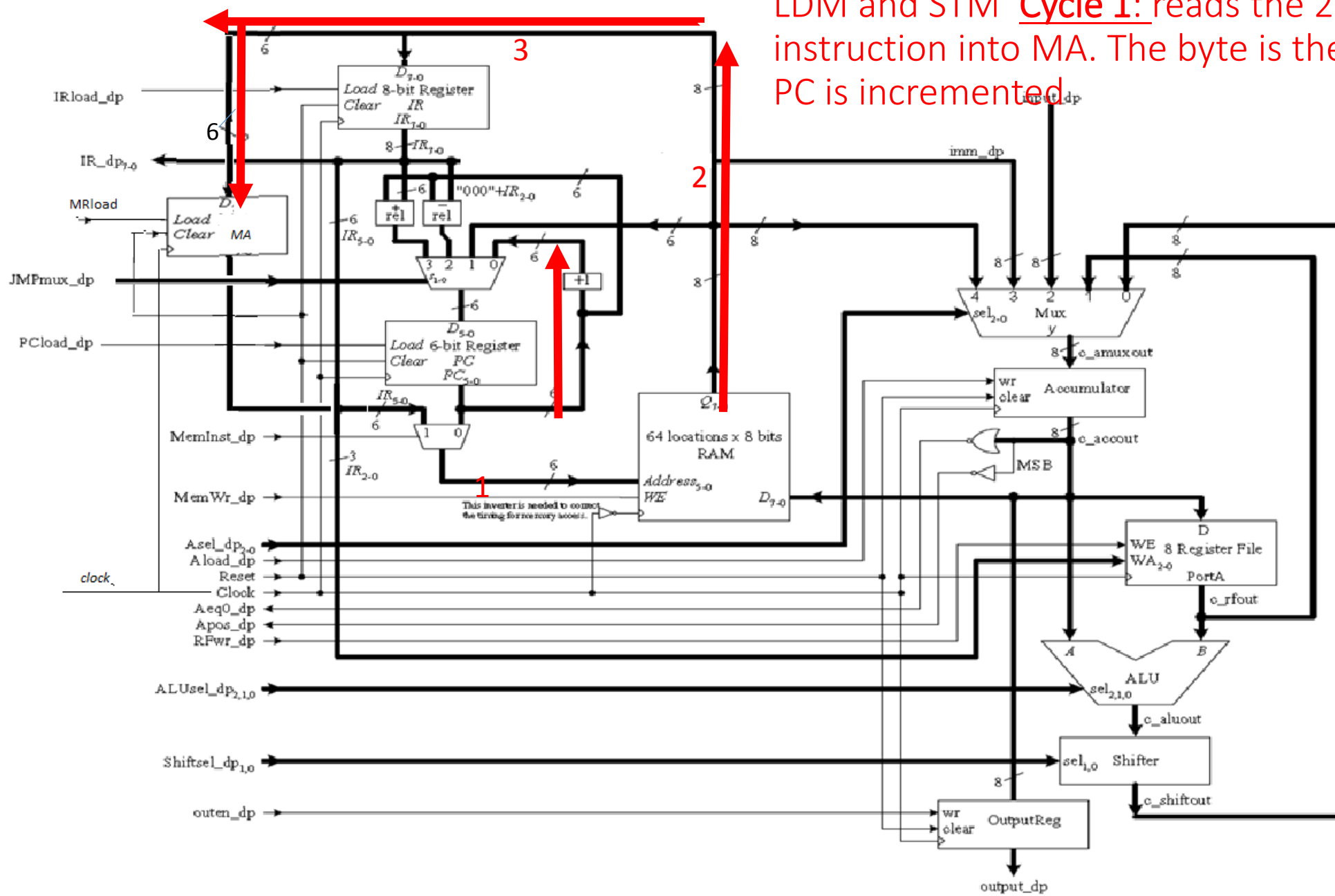
- Added memory Address register
- Imm field is given directly to the accumulator during the memory read cycle



Fetch in Cycle 0



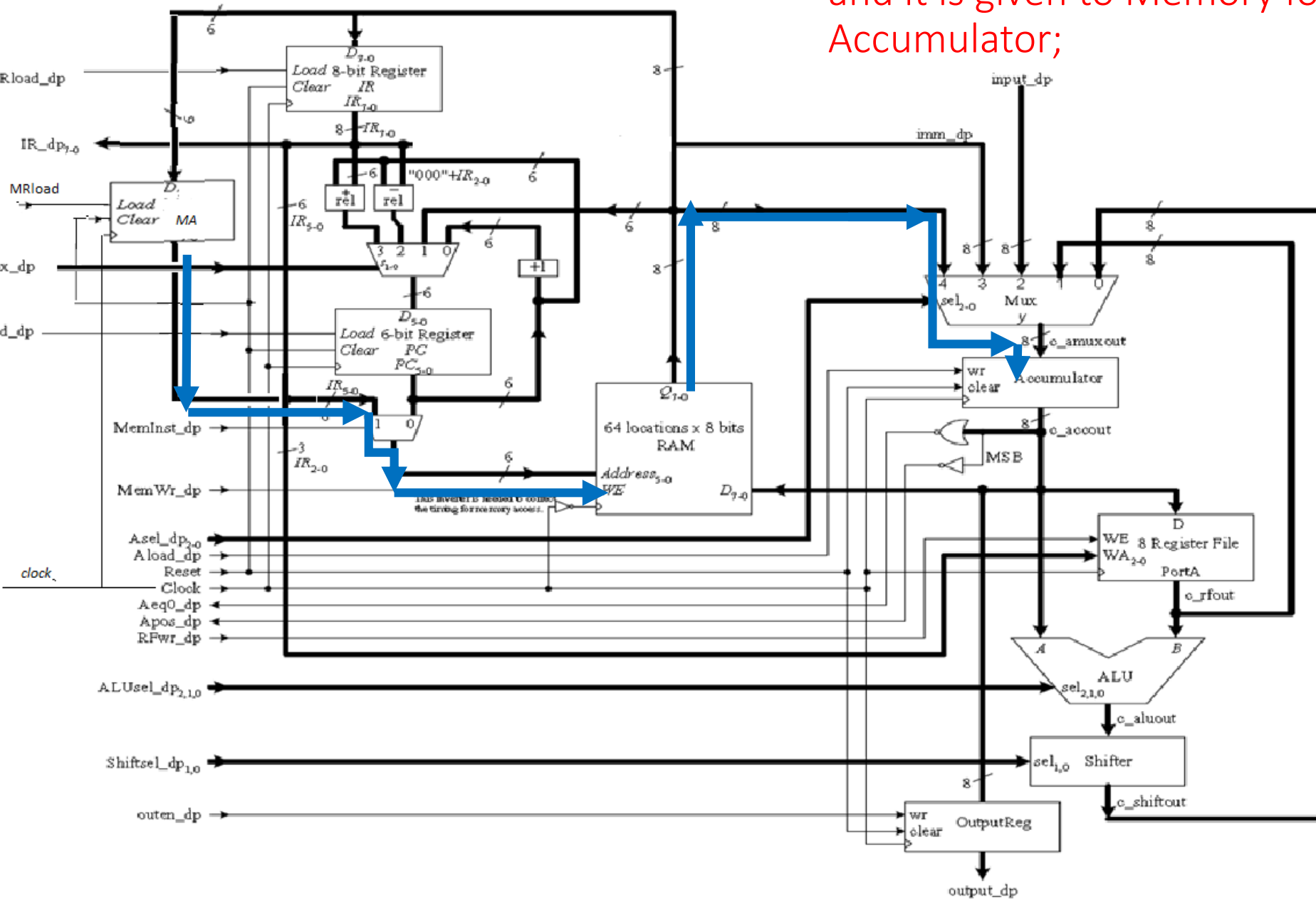
- IR loaded in **Cycle 0** with the first byte (could be the only byte) of Instruction.
- It is provided to CU in the beginning of the Cycle 1, the decode delay is included into the cycle (as in multi-cycle MIPS) and the decision is made on the control signals to assert in the second cycle: Cycle 1
- PC is incremented and loaded.



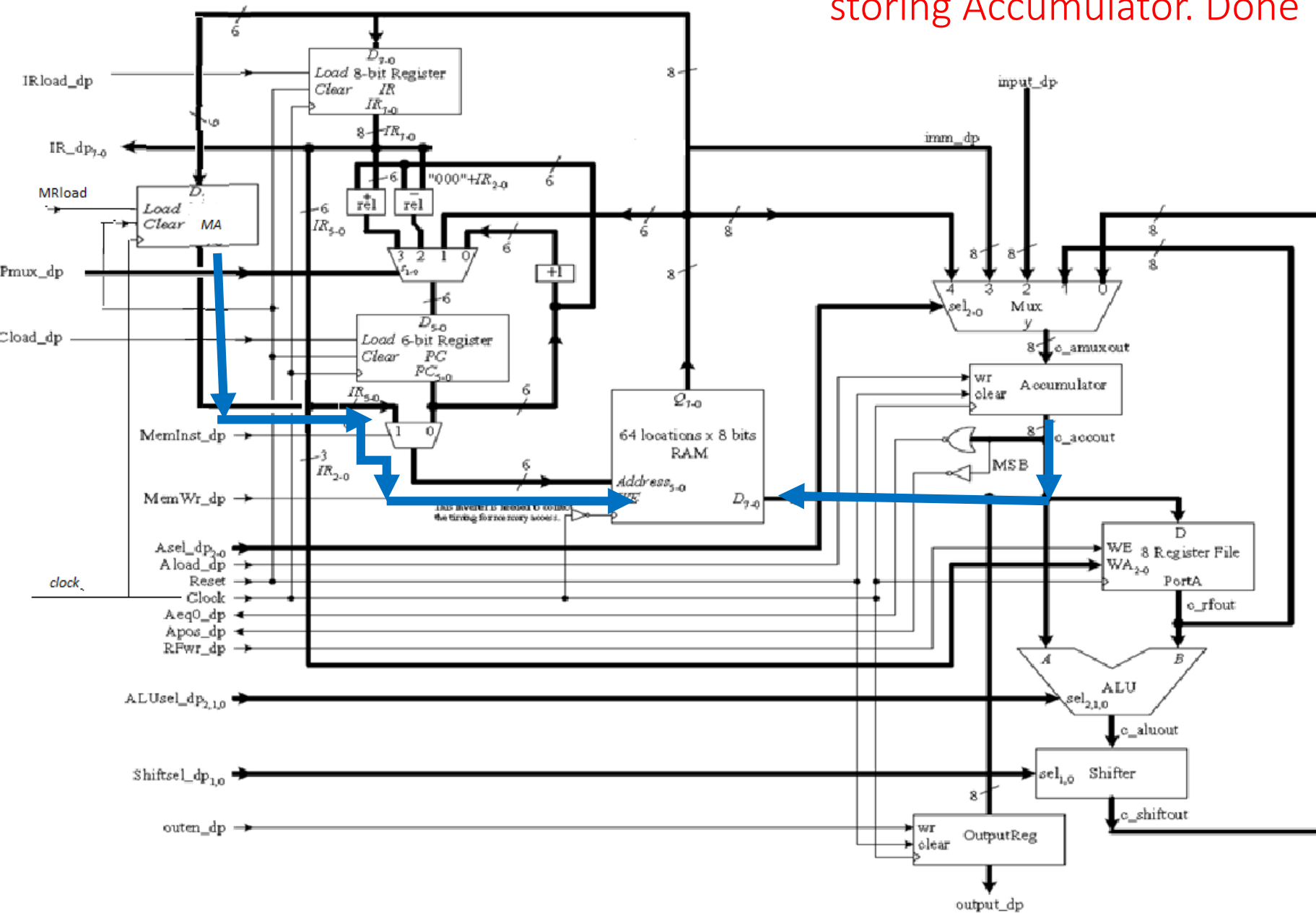
LDM and STM Cycle 1: reads the 2nd byte of the instruction into MA. The byte is the memory address. PC is incremented

LDM A,aaaaaa	0011 0000 00aaaaaa	$A \leftarrow M[aaaaaa]$
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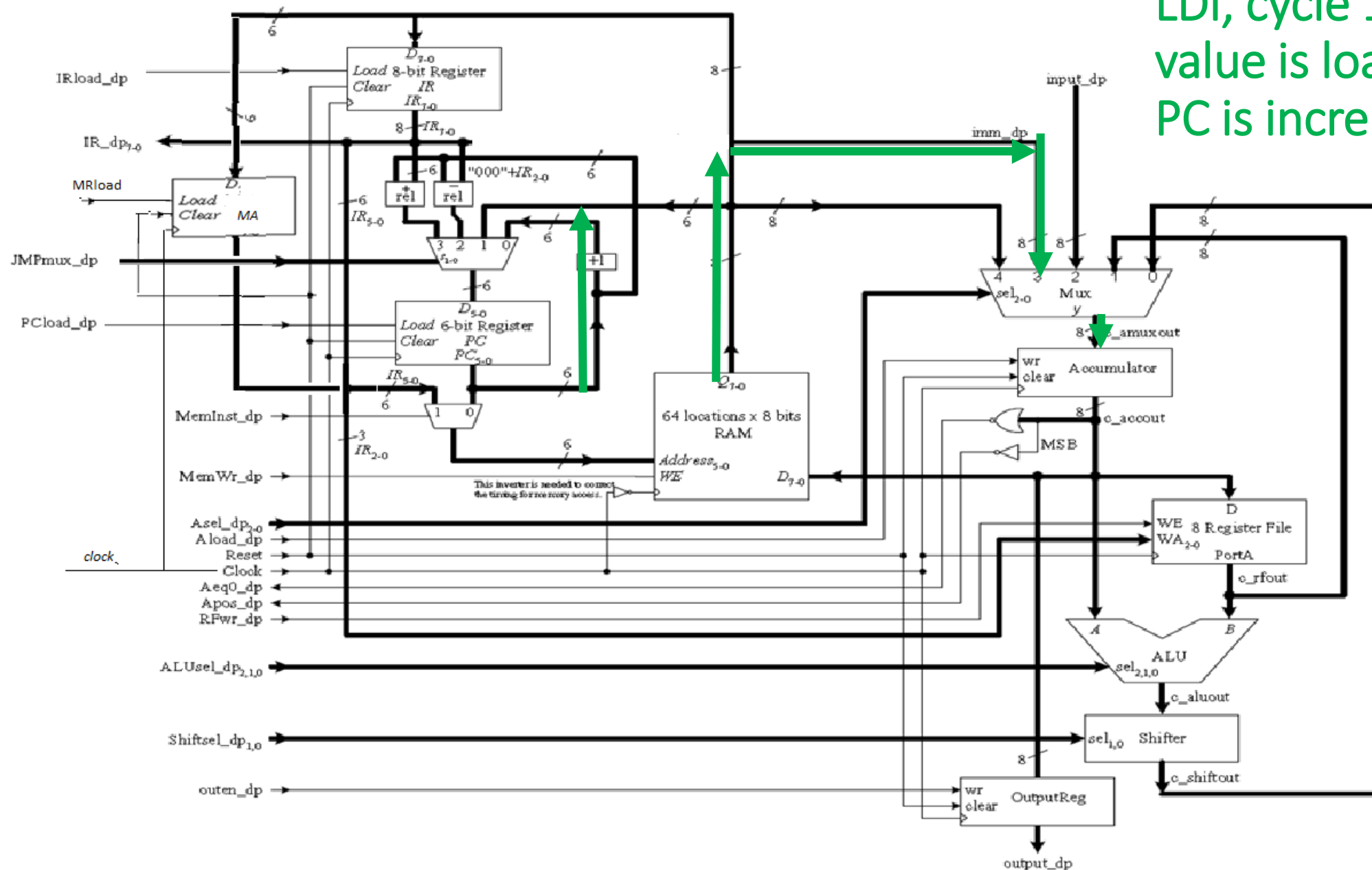
LDM Cycle 2: reads the IR. The byte is the memory address and it is given to Memory for reading data into Accumulator;



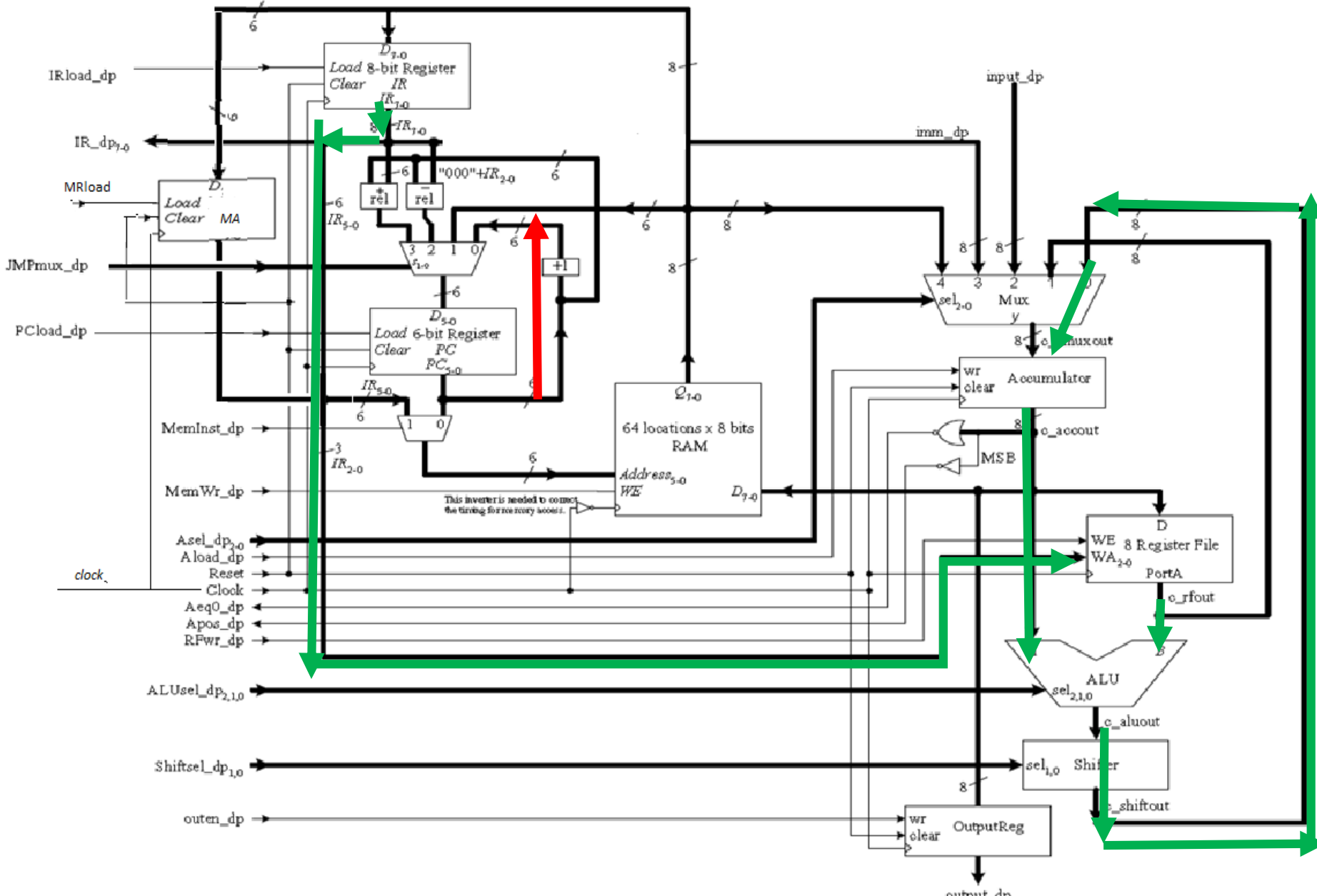
STM Cycle 2: reads Memory address is given to Memory for storing Accumulator. Done



LDI, cycle 1: immediate
value is loaded:
PC is incremented



increment PC

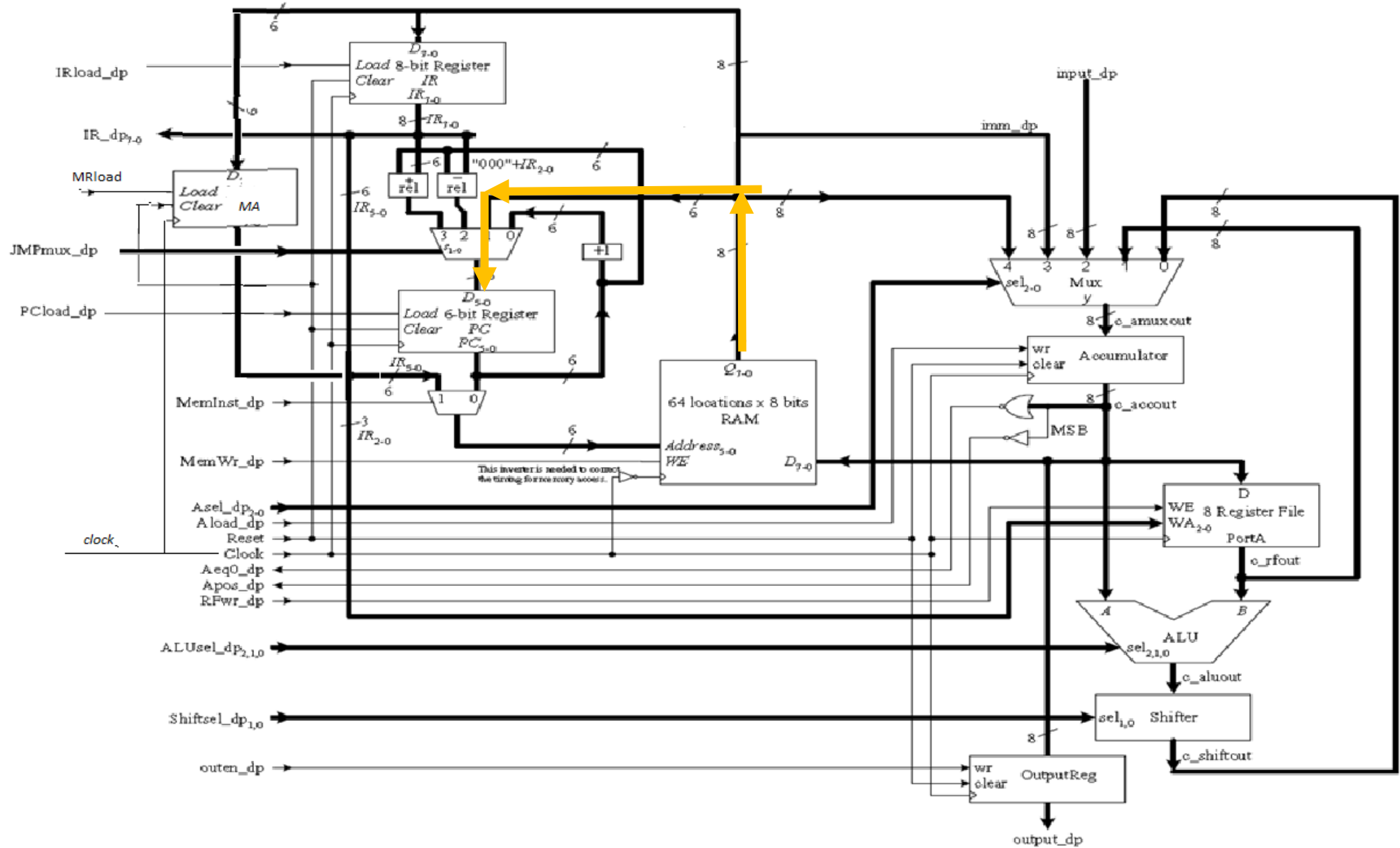


JZ

Cycle 1

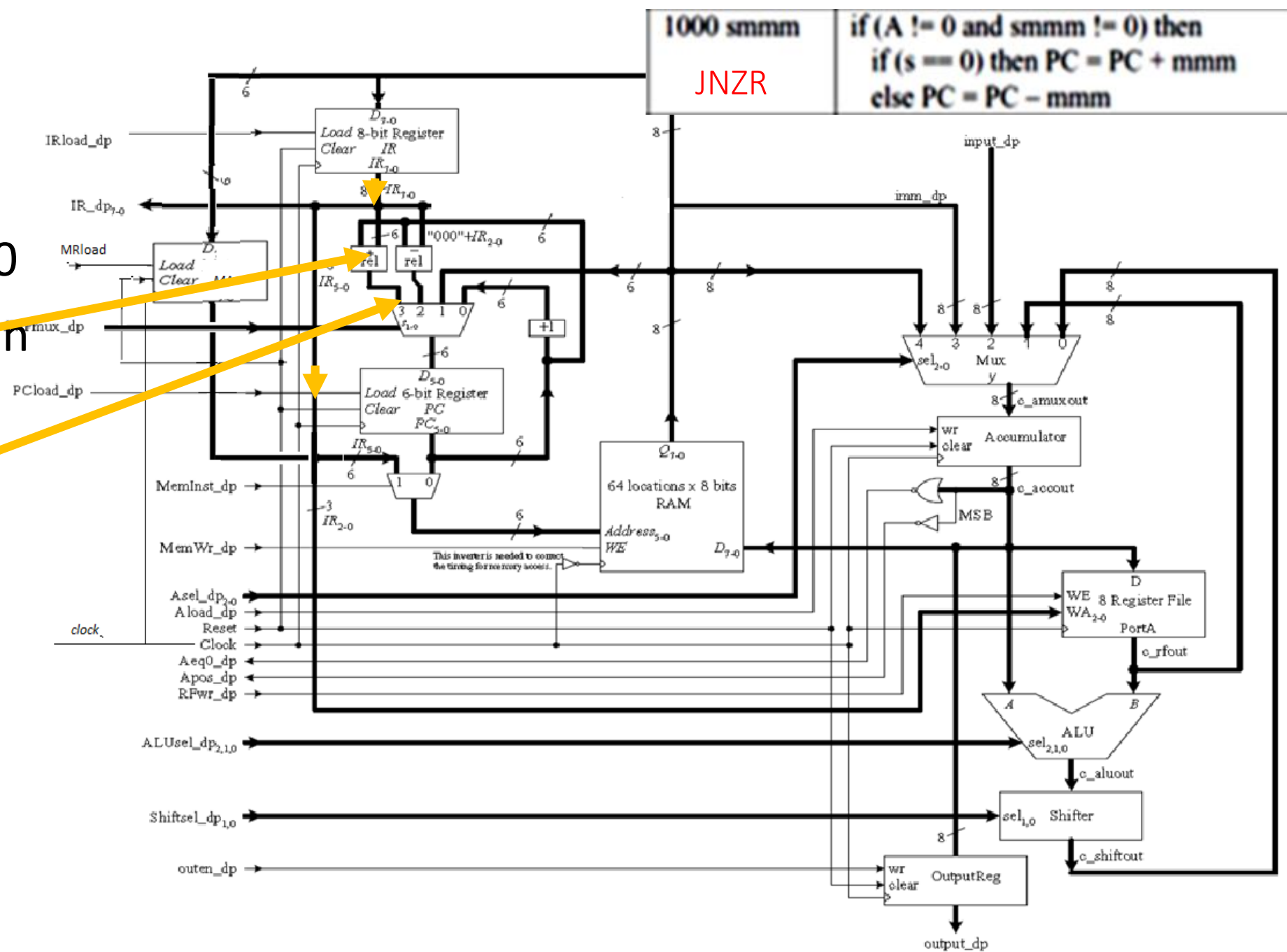
0111 0000 00 aaaaaa	if (A == 0) then PC = aaaaaa
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- Read 6 bits of the 2nd byte to PC



JNZR Cycle 1

- If $IR_{dp} < 3..0 \neq 0$
 then If $IR < 3 \geq 0$ then
 $JMP_{mux} = 11$, else
 $JMP_{mux} = 10$



1000 smmm JNZR	if (A != 0 and smmm != 0) then if (s == 0) then PC = PC + mmm else PC = PC - mmm
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Cycles per instruction

- Some instructions complete in 2 cycles , such as NOP and Halt (Fetch and Decode), jumps, arithmetic, in, out
- LDM and STM complete in 3 cycles
- Unfinished FSM is shown

