ANGELINA WANG

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EDUCATION

University of California, Berkeley

B.S. Electrical Engineering and Computer Science, Minor in Philosophy

(anticipated) May 2019

Major GPA: 3.95

Honors: Mark D. Weiser Excellence in Computing Scholarship, Regents and Chancellors' Scholar (top 2% of incoming class), Member of Eta Kappa Nu (Electrical and Computer Engineering Honors Society), Member of Tau Beta Pi (Engineering Honors Society), EECS Honors Program

University of Cambridge

June 2016 - August 2016

Summer study abroad: Philosophy

TECHNICAL SKILLS

Computer Languages Software & Tools

Python, C++, C, Java, JavaScript, SQL, HTML, CSS, Swift

PyTorch, TensorFlow, Git, Unix, LaTeX, Vim, ROS (Robot Operating System)

EXPERIENCE

BAIR (Berkeley Artificial Intelligence Research) Lab Undergraduate Researcher

August 2017 - Present Berkeley, CA

Work in Robot Learning Lab, advised by Pieter Abbeel, on building interpretable machine learning algorithms

Organize all outreach and give lab tours and robot demonstrations to diverse groups

Human Rights Investigation Lab of Berkeley Law School Technical Investigator

August 2018 - Present Berkeley, CA

· Develop hate speech monitoring dashboards across platforms for teams on the ground in Sub-Saharan Africa

· Assist in content analysis of bot tweets targeting women's reproductive rights activists

Archer (Technology Nonprofit, archerimpact.com) Engineering Lead

January 2017 - October 2018

Berkeley, CA

· Use Node and React to build web app for conducting open source investigations based off user interviews

· Visualize public data and create adjacency matrix scheme to manipulate entity connections using D3

· Presented products to government officials in Washington D.C. and at RightsCon 2018 in Toronto

Google, Inc.

Engineering Practicum Intern

May 2017 - August 2017 Seattle, WA

· Worked on infrastructure team to improve Streaming Flume, the internal streaming data processing system

· Implemented hot key detection and mitigation to parallelize bottlenecks in the pipeline

PUBLICATIONS

Learning Robotic Manipulation through Visual Planning and Acting A. Wang, T. Kurutach, A. Tamar, P. Abbeel

In review for ICRA 2019

· Propose a self-supervised, data-driven approach to planning robotic manipulation on deformable objects

· Use Causal InfoGAN to generate visual plan, and use learned inverse control model to execute actions on PR2

· 4 NeurIPS (NIPS) 2018 workshop appearances: oral presentation at Modeling the Physical World (5% accept), Deep RL (9% accept), poster presentations at Causal Learning, Infer2Control

Safer Classification by Synthesis

NIPS 2017 Aligned AI Workshop

W. Wang, A. Wang, A. Tamar, X. Chen, P. Abbeel

· Propose a new computer vision method to perform image classification using generative models

· By learning distribution of known data, can threshold out-of-distribution images to perform novelty detection

TEACHING

Machine Learning @ Berkeley Education Officer

July 2018 - Present

Berkeley, CA

· Teach, develop content for, and create homeworks for introductory 2-unit deep learning course of 200 students

Prepare and host workshops and demos for the general community

Introduction to Machine Learning (CS189/289A) Academic Intern

January 2018 - May 2018 Berkeley, CA

· Help to write and debug homework problems and solutions for class of over 300 students