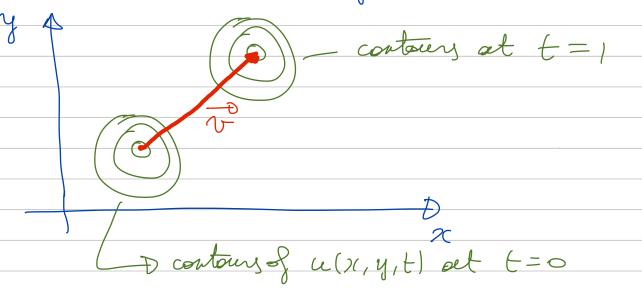


example: lineaer adviction equation in 2 spatial olimensions

find $u(\pi,y,t)$ satisfying $u_t + \alpha u_x + b u_y = 0$ (assume $\alpha > 0, b > 0$)

 $\overrightarrow{v} = (\alpha, b)$ is the eldvection speed vector in the (x, y)-plane

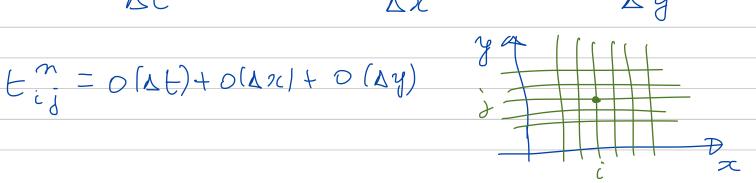


note: general solution: u (x, y, t) = f(x-at, y-vt)

Forward Upwird:

$$\frac{V_{ij} - V_{ij}}{\Delta t} + \alpha \frac{V_{ij} - V_{i-ij}}{\Delta x} + b \frac{V_{ij} - V_{i,j-i}}{\Delta y} = 0$$

$$E_{ij}^{n} = O(\Delta E) + O(\Delta x) + O(\Delta y)$$



numerical stability: Von Neumann Vj. j2 - Vn esq (i (j, 2,02+j2k2sy) and $\hat{V}_{n+1} = S(k_1, k_2) \hat{V}_n$ for stability: we require masc $S(B_1, B_2) \leq 1$ $B_1, B_2 \in \mathbb{R}$ this results in the conditions: $0 \leq \alpha \leq \frac{\Delta E}{\Delta zc} + b \leq \frac{\Delta E}{\Delta y} \leq 1$ Of DE > 0 The divination is in one of the reference textbooks & st >0 (1): $\Delta t \leq \frac{\alpha}{\Delta x} + \frac{b}{\Delta y}$

Note 5
$$\Delta x \leftarrow \Delta y$$

note 5 $\Delta t = 1 \min \left(\frac{\Delta x}{\alpha}, \frac{\Delta y}{\delta} \right)$ is

Sufficient for stability

(because $\frac{1}{2} \min \left(\frac{\Delta x}{\alpha}, \frac{\Delta y}{\delta} \right) = \frac{1}{\alpha + b}$
 $\sum_{\Delta x} \frac{\Delta y}{\Delta y}$

proof: $\frac{1}{2} \min (c, d) = \frac{cd}{c+d}$ $(c \ge 0, d \ge 0)$
 $c = 2 \ cd$ on $d \le 2 \ cd$
 $c = 2 \ cd$ on $d^2 + cd \le 2 \ cd$
 $c^2 + cd \le 2 \ cd$ on $d^2 + cd \le 2 \ cd$
 $c^2 \le cd$ on $d^2 \le cd$